# SARTHAK VORA

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### **EDUCATION**

## University of California, Los Angeles (UCLA)

Master of Science in Electrical and Computer Engineering

## Indian Institute of Technology (IIT) Madras, Chennai, India

Bachelor of Technology in Electrical Engineering

June 2023 CGPA 8.98/10

#### **SKILLS**

- Programming Languages Python, C, Linux, MATLAB, Verilog
- Frameworks PyTorch, TensorFlow, OpenCV, Numpy, Pandas, Scikit-Learn, Matplotlib
- Other skills Git, Critical-Thinking, Problem-Solving, Collaborative

#### PROFESSIONAL EXPERIENCE

## Resilience Business Grids (RBG.AI), Coimbatore, India

June 2023 – August 2023

**Expected Date: March 2025** 

Artificial Intelligence Intern

- Integrated Segment-Anything (SAM) with SegFormer model for improved Floorplan Image segmentation.
- Utilized OpenCV's contour detection method to transform segments within the semantic map into polygons.
- Crafted a 3D model of the FloorPlan Image in Blender by extruding walls and objects from 2D polygons.

## Vision and AI Lab (VAL), Indian Institute of Science (IISc) Bangalore, India

June 2022 – March 2023

Research Intern – Computational and Data Science (CDS) Department

- Modelled the latent space of StyleGAN2 with a Denoising Diffusion Model to generate attribute variations.
- Generated a dataset of attribute edit directions by encoding synthetic image pairs into the W+ latent space.
- Improved FID metric by 3.7 units on average across hairstyle, eyeglass, and smile attributes in FFHQ dataset.

### **PUBLICATIONS**

- "Exploring Attribute Variations in Style-based GANs using Diffusion Models", NeurIPS 2023 Diffusion Workshop Proceedings, NeurIPS 2023
- "3D-ADAP: Advancing Object Detection through 3D-Aware Placement Augmentation", *Proceedings of the AAAI conference on Artificial Intelligence, 2024 (under review)*

#### **PROJECTS**

# Road Scene Completion with Geometry-Aware 3D Vehicle Placement

Vision and AI Lab (VAL), Indian Institute of Science (IISc) Bangalore, India

- Collaborated with two researchers to design a VAE-based placement module for dense 3D bounding boxes.
- Designed an augmentation strategy for localizing plausible locations leveraged as sparse input distribution.
- Achieved road scene completion by rendering copy-paste cars at sampled box locations in the original scene.
- Showcased 22.6% improvement in Average Precision (AP<sub>40</sub>) metric on KITTI3D Object Detection benchmark.

# Learning Projections from Single Photon Cameras (SPC) for Stereo Depth Estimation

Undergraduate Thesis, Guided by Prof. Kaushik Mitra (IIT Madras) and Prof. Mohit Gupta (UW Madison)

- Formulated a projection method for estimating depth using deep stereo networks with SPC photon cube.
- Incorporated exposure bracketing into ACVNet by selectively using multiple exposures for depth prediction.
- Reduced D1 error by nearly 2% with learned-mask aided video compressive projection over multi-exposure.

## 3D BlobGAN: Enhancing Generative Models for Controlled 3D Scene Generation

- Enhanced BlobGAN framework to support 3D blobs in latent space, enabling controlled 3D scene generation.
- Conducted experiments with the PatchGAN Discriminator to ensure consistent generation of multiple views.
- Independently synthesized top and front view for CleVr dataset by projecting volumetric blob distributions.

### **EXTRACURRICULAR ACTIVITIES**

- Acted as the Co-Head of The Fifth Estate 2021-22, Official Student News Body of IIT Madras. Co-led a team of 5 members to conduct surveys and present them as institute newsletters.
- Facilitated a Prototyping session for nearly 30 participants from SQIL NGO (Non-governmental organization).