Here are the first **50 mixed-level MCQs** based on your Computer Vision syllabus, complete with answers:

Easy Level (1–20)

- 1. What does each pixel in a grayscale image represent?
 - A) A color channel
 - B) An intensity value
 - C) A depth estimate
 - D) A label
 - \rightarrow B) An intensity value
- 2. What is the typical pixel value range in a normalized image?
 - A) [0, 255]
 - B) [1, 10]
 - C) [0, 1]
 - D) [-1, 1]
 - \rightarrow C) [0, 1]
- 3. Which Python library reads images in BGR format by default?
 - A) Pillow
 - B) NumPy
 - C) OpenCV
 - D) Matplotlib
 - → C) OpenCV
- 4. Which function is used to resize an image in OpenCV?
 - A) cv2.scale()
 - B) cv2.resize()
 - C) cv2.zoom()
 - D) cv2.enlarge()
 - \rightarrow B) cv2.resize()
- 5. What is the result of applying Gaussian blur?
 - A) No change
 - B) Random pixels
 - C) Sharper edges
 - D) Smoother image
 - \rightarrow D) Smoother image

6. What does HSV stand for in color space?

- A) Hue, Saturation, Value
- B) High Saturation Variance
- C) Heat, Shadow, Vividness
- D) Hue Saturation Volume
- → A) Hue, Saturation, Value

7. Which method sharpens an image?

- A) Blurring
- B) cv2.threshold
- C) Kernel with center > surroundings
- D) Histogram equalization
- → C) Kernel with center > surroundings

8. Which operation is used for adding brightness?

- A) cv2.multiply()
- B) cv2.add()
- C) cv2.subtract()
- D) cv2.blur()
- → B) cv2.add()

9. Which operation retains only overlapping white pixels?

- A) bitwise or
- B) bitwise and
- C) bitwise_xor
- D) addWeighted
- → B) bitwise_and

10. Which module supports webcam capture in OpenCV?

- A) cv2.Image
- B) cv2.VideoWriter
- C) cv2.VideoCapture
- D) cv2.ReadVideo
- → C) cv2.VideoCapture

11. Which library is a modern fork of PIL?

- A) Pillow
- B) OpenCV
- C) SciPy
- D) TensorFlow
- \rightarrow A) Pillow

12. Which command shows an image using OpenCV?

A) plt.show()

	C) img.display() D) Image.show()
	→ B) cv2.imshow()
13.	Which method is best for reducing salt-and-pepper noise? A) Gaussian Blur B) Median Blur C) Bilateral Blur D) Laplacian Filter → B) Median Blur
14.	In image cropping, the origin (0,0) is at: A) Bottom-right B) Center C) Top-left D) Bottom-left → C) Top-left
15.	Which image format supports transparency (alpha channel)? A) JPEG B) BMP C) PNG D) ICO → C) PNG
16.	Which of the following is NOT a low-level CV task? A) Edge detection B) Thresholding C) Object classification D) Blurring → C) Object classification
17.	What data type usually stores pixel values in OpenCV? A) float64 B) uint8 C) int16 D) bool → B) uint8
18.	Which of these is NOT part of the "3 R's" of CV? A) Recognition B) Rebuilding C) Reconstruction

B) cv2.imshow()

	D) Reorganization
	→ B) Rebuilding
19.	Which one helps extract keypoints from images?
	A) ORB
	B) BGR
	C) RGB
	D) PIL
	→ A) ORB
20.	Which operation does NOT involve convolution?
	A) Blurring
	B) Thresholding
	C) Sharpening
	D) Edge Detection
	→ B) Thresholding
Mo	edium Level (21–40)
21.	What is the role of non-maximum suppression in Canny Edge Detection?
	A) Increase edges
	B) Apply threshold
	C) Remove weak edges
	D) Thins out edges
	→ D) Thins out edges
22.	Which method computes local thresholds dynamically?
	A) Otsu
	B) Global
	C) Adaptive
	D) Binary
	→ C) Adaptive
23.	Which transform keeps straight lines straight but allows skewing?
	A) Perspective

B) Affine

C) LogarithmicD) Homography→ B) Affine

24. Which filter is best for edge preservation and noise removal?

- A) Median
- B) Average
- C) Gaussian
- D) Laplacian
- → A) Median

25. Which OpenCV function changes color space to grayscale?

- A) convertGray(img)
- B) cv2.colorToGray()
- C) cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
- D) toGray(img)
- → C) cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

26. Which interpolation is used by default in cv2.resize()?

- A) INTER_LINEAR
- B) INTER_NEAREST
- C) INTER CUBIC
- D) INTER_AREA
- \rightarrow A) INTER_LINEAR

27. Which function in OpenCV draws a rectangle?

- A) draw.rect()
- B) cv2.drawRect()
- C) cv2.rectangle()
- D) image.rectangle()
- → C) cv2.rectangle()

28. Which is a high-level vision task?

- A) Blurring
- B) Thresholding
- C) Scene Understanding
- D) Gaussian Blur
- → C) Scene Understanding

29. What does cv2.addWeighted() do?

- A) Blend two images
- B) Threshold
- C) Match template
- D) Crop image
- → A) Blend two images

30. What does SIFT detect?

A) Corners

- B) Blobs
- C) Keypoints
- D) Faces
- → C) Keypoints

31. Which function is used to compute contours in OpenCV?

- A) cv2.findContours()
- B) cv2.edgeDetect()
- C) cv2.drawContours()
- D) cv2.getContours()
- → A) cv2.findContours()

32. Which method helps in matching keypoints across two images?

- A) ORB + BFMatcher
- B) Thresholding
- C) Cropping
- D) Interpolation
- → A) ORB + BFMatcher

33. Which OpenCV function reads from a webcam?

- A) VideoInput()
- B) cv2.VideoRead()
- C) cv2.VideoCapture(0)
- D) ReadCam()
- → C) cv2.VideoCapture(0)

34. Which deep learning-based technique detects objects in real-time?

- A) Haar Cascades
- B) YOLO
- C) Hough Transform
- D) ORB
- → B) YOLO

35. Which interpolation is best for downscaling?

- A) INTER_CUBIC
- B) INTER LINEAR
- C) INTER_AREA
- D) INTER NEAREST
- \rightarrow C) INTER_AREA

36. Which edge detector uses double thresholding?

- A) Sobel
- B) Laplacian
- C) Canny

- D) Harris
- \rightarrow C) Canny

37. Why is sharpening risky on noisy images?

- A) It ignores edges
- B) It smoothens noise
- C) It amplifies noise
- D) It skips pixels
- \rightarrow C) It amplifies noise

38. Which operation is best for combining masks?

- A) addWeighted
- B) bitwise or
- C) blur
- D) subtract
- → B) bitwise_or

39. What does Otsu's method optimize?

- A) Maximum edge contrast
- B) Minimum intra-class variance
- C) Maximum brightness
- D) Highest keypoint match
- \rightarrow B) Minimum intra-class variance

40. Which interpolation uses 16-pixel neighbors?

- A) Nearest
- B) Bilinear
- C) Bicubic
- D) Area
- \rightarrow C) Bicubic

Hard Level (41–70)

41. Which of the following is true for Affine Transformations?

- A) Preserves angles
- B) Curves become straight lines
- C) Preserves parallelism
- D) All edges become orthogonal
- → C) Preserves parallelism

42. Which algorithm uses hysteresis in edge detection? A) Harris B) Laplacian C) Sobel

- D) Canny
- → D) Canny
- 43. What's the drawback of nearest-neighbor interpolation?
 - A) Slow speed
 - B) Blurred output
 - C) Pixelation/blocky edges
 - D) Excessive memory use
 - → C) Pixelation/blocky edges
- 44. Which method best handles images with shadows and bright spots?
 - A) Binary Thresholding
 - B) Otsu Thresholding
 - C) Adaptive Thresholding
 - D) Fixed Thresholding
 - → C) Adaptive Thresholding
- 45. Which function applies a user-defined convolution kernel?
 - A) cv2.kernelApply()
 - B) cv2.customBlur()
 - C) cv2.filter2D()
 - D) cv2.applyKernel()
 - → C) cv2.filter2D()
- 46. In OpenCV, why are RGB values stored as BGR?
 - A) Better compression
 - B) Legacy C++ memory alignment
 - C) GPU optimization
 - D) To reduce image size
 - → B) Legacy C++ memory alignment
- 47. Which method calculates gradient magnitude and direction?
 - A) Gaussian
 - B) Sobel
 - C) Median
 - D) Area
 - → B) Sobel
- 48. Which OpenCV method detects corners accurately?
 - A) cv2.findContours()

- B) cv2.cornerHarris()
- C) cv2.GaussianBlur()
- D) cv2.canny()
- → B) cv2.cornerHarris()

49. Which method finds pixel-wise difference between two images?

- A) cv2.add()
- B) cv2.multiply()
- C) cv2.subtract()
- D) cv2.blur()
- → C) cv2.subtract()

50. Which feature-matching technique works best with rotation?

- A) Template Matching
- B) ORB + BFMatcher
- C) Histogram Comparison
- D) Thresholding
- → B) ORB + BFMatcher

51. Why do we use normalization before feeding images to CNNs?

- A) Reduce image size
- B) Improve contrast
- C) Reduce data range for stability
- D) Convert RGB to grayscale
- → C) Reduce data range for stability

52. Which blurring method uses actual pixel values, not averages?

- A) Gaussian
- B) Average
- C) Median
- D) Area
- → C) Median

53. Which layer in CNN handles edge-like filters in early stages?

- A) Dense Layer
- B) Activation Layer
- C) Pooling Layer
- D) Convolutional Layer
- → D) Convolutional Layer

54. Which framework uses dynamic computation graphs?

- A) Keras
- B) TensorFlow
- C) PyTorch

A) Region Proposals
B) Bounding Subdivision
C) Anchor Boxes
D) S × S Grid Assignment
→ D) S × S Grid Assignment
56. Which interpolation is most likely to cause aliasing in downsampling?
A) Bilinear
B) Bicubic
C) Nearest
D) Area
→ C) Nearest
57. What's the main drawback of template matching?
A) Slow execution
B) Works only with gray images
C) No scale/rotation invariance
D) Requires labeled data
→ C) No scale/rotation invariance
58. Which feature is ignored in template matching?
A) Size
B) Semantics
C) Pixel intensity
D) Location
→ B) Semantics
59. Which edge detector uses second derivative?
A) Sobel
B) Laplacian
C) Canny
D) Harris
→ B) Laplacian
60. Which component of HSV represents brightness?
A) Hue
B) Saturation
C) Value
D) Alpha

55. Which method in YOLO divides the image into grid cells?

D) Scikit-image \rightarrow C) PyTorch

→ C) Value

61. Which is true about cv2.imread()?

- A) It loads as RGB by default
- B) It compresses images
- C) It returns a NumPy array
- D) It displays the image
- → C) It returns a NumPy array

62. What does cv2.addWeighted() enable?

- A) Histogram equalization
- B) Image blending
- C) Image thresholding
- D) Denoising
- → B) Image blending

63. In corner detection, what does a high gradient in both X and Y imply?

- A) A flat region
- B) An edge
- C) A corner
- D) Background noise
- \rightarrow C) A corner

64. Which model is used in OpenCV face detection?

- A) CNN
- B) YOLO
- C) Haar Cascade
- D) FAST
- → C) Haar Cascade

65. Which pixel operation is NOT allowed directly on uint8 without clipping?

- A) Addition
- B) Subtraction
- C) Multiplication
- D) All are safe
- \rightarrow B) Subtraction

66. Which function dynamically resizes a window for display?

- A) cv2.namedWindow(window, cv2.WINDOW_NORMAL)
- B) cv2.autoResize()
- C) cv2.flexWindow()
- D) imresize()
- → A) cv2.namedWindow(window, cv2.WINDOW_NORMAL)

67. Which function provides pixel-wise logical AND?

- A) bitwise_and()
- B) logicalAnd()
- C) cv2.compare()
- D) andPixels()
- → A) bitwise_and()

68. Why is float32 used in some image operations?

- A) More accurate intensity values
- B) Faster computation
- C) Required for integer arithmetic
- D) Supports only grayscale
- → A) More accurate intensity values

69. Which method computes histogram-based thresholding automatically?

- A) Binary
- B) Adaptive
- C) Otsu
- D) Gaussian
- \rightarrow C) Otsu

70. What would happen if a large kernel is used in cv2.blur()?

- A) Noise increase
- B) Sharpened image
- C) More blurring
- D) Smaller file size
- \rightarrow C) More blurring

Out-of-the-box Conceptual (71–90)

71. You apply median blur to a binary image. What could go wrong?

- A) Too much smoothing
- B) Converts black/white to gray
- C) Removes sharp contrast
- D) All of the above
- \rightarrow D) All of the above

72. Why is BGR preferred in OpenCV over RGB?

- A) Easier to compute edges
- B) Hardware compatibility legacy
- C) B has less memory load

•	RGB is outdated
\rightarrow E	B) Hardware compatibility legacy
73. If an	image has uneven lighting, which threshold method fails most?
A) A	Adaptive
B) C	Otsu
C) F	Fixed
,	None
\rightarrow C	C) Fixed
74. Why	might YOLO misclassify an occluded object?
-	t detects color
B) It	t assumes full visibility
C) It	t works only on grayscale
D) It	t's not trained on occlusion
\rightarrow E	3) It assumes full visibility
75. Whi e	ch technique would help if the object is tilted and rotated?
	emplate Matching
B) S	SIFT/ORB
C) S	Simple Thresholding
D) N	Morphological Dilation
\rightarrow E	B) SIFT/ORB
76. In a	low-light condition, which enhancement is most effective?
A) F	listogram Equalization
B) E	Blurring
C) N	Morphology
D) F	Resizing
→ A	A) Histogram Equalization
77. In re	esizing a face image, which interpolation method retains features?
A) A	Area
B) N	Nearest Search S
C) E	Bicubic
D) (Gaussian
\rightarrow C	C) Bicubic
78. Whi e	ch format supports animation in Pillow?
A) F	• •
B) E	
c) c	
D) T	TIFF
,	

\rightarrow C) GIF

79. Why might median blur outperform Gaussian on salt-and-pepper noise?

- A) It's faster
- B) It keeps edges better
- C) Gaussian adds noise
- D) Gaussian is not for binary
- → B) It keeps edges better

80. Why does template matching fail at detecting faces with different angles?

- A) Templates are grayscale
- B) OpenCV can't rotate
- C) Pixel mismatch due to viewpoint change
- D) Feature mismatch
- → C) Pixel mismatch due to viewpoint change

81. What happens if kernel sum ≠ 1 in a convolution filter?

- A) Nothing changes
- B) Image gets darker/brighter
- C) Noise increases
- D) Filter fails
- → B) Image gets darker/brighter

82. If pixel values overflow uint8, what happens in OpenCV?

- A) Wraps around
- B) Clips to 255
- C) Crashes
- D) Converts to float
- \rightarrow B) Clips to 255

83. What's the output of img[50:250, 100:400] in OpenCV?

- A) Cropped image
- B) Rotated image
- C) Resized image
- D) Filtered image
- \rightarrow A) Cropped image

84. Which of these is best for zoom-in without distortion?

- A) cv2.resize with INTER LINEAR
- B) cv2.resize with INTER_CUBIC
- C) cv2.blur()
- D) Thresholding
- → B) cv2.resize with INTER_CUBIC

85. You apply cv2.add() to two images. What happens to overflow?

- A) Error
- B) Wrap-around
- C) Clipped to 255
- D) Divided
- \rightarrow C) Clipped to 255

86. Why is Gaussian blur considered more "natural"?

- A) Uses median
- B) Weights center pixels
- C) Has higher contrast
- D) Sharper edges
- → B) Weights center pixels

87. Which task benefits least from Canny edge detection?

- A) Text segmentation
- B) Object tracking
- C) Contour finding
- D) Face classification
- \rightarrow D) Face classification

88. Why use float32 instead of uint8 in high-contrast operations?

- A) Compatibility with OpenCV
- B) Reduced computation
- C) Prevent clipping and allow decimals
- D) Faster GPU support
- → C) Prevent clipping and allow decimals

89. How to detect only red objects using HSV?

- A) Threshold RGB
- B) Convert to BGR
- C) Use hue range for red
- D) Use grayscale
- \rightarrow C) Use hue range for red

90. Which method best tracks fast-moving objects?

- A) ORB
- B) Optical Flow
- C) Template Matching
- D) DNN
- \rightarrow B) Optical Flow

Here's the continuation — final 110 MCQs (91-200) with mixed difficulty, covering remaining advanced, practical, and conceptual aspects of Computer Vision:

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Ad	Ivanced & Practical MCQs (91–130)
91.	<pre>Which OpenCV function reads an image from disk? A) cv2.openImage() B) cv2.imread() C) cv2.readImage() D) cv2.imageRead() → B) cv2.imread()</pre>
92.	Which format is best for storing images without compression loss? A) JPEG B) BMP C) PNG D) TIFF → D) TIFF
93.	Which function shows image color values when clicked (mouse)? A) cv2.imshowColor() B) opencv_show_pixel_color_in_new_window.py C) cv2.colorPicker() D) cv2.getColor() → B)
94.	Which model outputs object class + bounding box? A) Canny B) CNN only C) YOLO D) SIFT → C) YOLO
95.	Which technique is best for perspective transformation? A) Affine Transform B) Harris Detection C) Hamagraphy

- C) Homography
- D) Sobel Filter
- \rightarrow C) Homography
- 96. Which type of blur is typically used before edge detection?
 - A) Average

- B) Gaussian C) Median
- D) Bilateral
- → B) Gaussian

97. What is the primary use of cv2.waitKey()?

- A) Detect mouse
- B) Pause for key input
- C) Exit display
- D) Track object
- \rightarrow B) Pause for key input

98. Which tool helps reduce aliasing in downscaling?

- A) Nearest Interpolation
- B) INTER CUBIC
- C) INTER_AREA
- D) INTER_LINEAR
- \rightarrow C) INTER_AREA

99. Which method draws over an image using Pillow?

- A) PILDraw
- B) ImageEnhance
- C) ImageDraw
- D) PixelPainter
- → C) ImageDraw

100. Which kernel can enhance edges in an image?

- A) [[0, 0, 0], [0, 1, 0], [0, 0, 0]]
- B) [[1, 1, 1], [1, 1, 1], [1, 1, 1]]
- C) [[0, -1, 0], [-1, 5, -1], [0, -1, 0]]
- D) Identity kernel
- \rightarrow C)

101. Which interpolation is most precise but slowest?

- A) Nearest
- B) Linear
- C) Cubic
- D) Area
- → C) Cubic

102. Which OpenCV function returns keypoints + descriptors?

- A) ORB.detect()
- B) ORB.compute()
- C) ORB.detectAndCompute()

D) ORB.findFeatures() → C) ORB.detectAndCompute()
 103. Which method is used for panoramic image stitching? A) Template Matching B) SIFT/ORB with Feature Matching C) Cropping and merging D) Edge Detection → B)
 104. Which component of OpenCV helps create a thumbnail? A) ThumbnailGenerator B) ImageCropper C) Resize D) opencv_thumbnail_generator.py → D)
 105. Which framework is best suited for custom segmentation models? A) OpenCV B) Pillow C) PyTorch D) PIL → C) PyTorch
 106. Which OpenCV module works with webcam feed? A) cv2.VideoInput B) cv2.VideoCapture C) cv2.VideoFeed D) cv2.InputDevice → B) cv2.VideoCapture
 107. What is the effect of applying cv2.bitwise_not() to an image? A) No change B) All black pixels become white and vice versa C) Image rotation D) Blurring → B)
108. Which function in OpenCV detects object boundaries?A) cv2.drawContoursB) cv2.matchTemplate

C) cv2.findContours D) cv2.detectEdges

\rightarrow	· C)
B) C) D)	Which OpenCV module detects face using Haar features? HaarCascade CascadeClassifier CNNClassifier HaarFeatureDetector B)
B) C) D)	What is the result of histogram equalization? Pixel smoothing Color conversion Contrast enhancement Denoising C)
	ied + Reasoning-Based (131–170)
B) C) D)	If an image is 300x300x3, how many bytes in memory (uint8)? 300 900 270,000 900,000 C) 270,000
B) C) D)	You apply median blur with a large kernel. What risk arises? Sharp noise increases Image gets sharper Excessive detail loss Rotation C) Excessive detail loss
	What happens if you apply cv2.imshow() without waitKey()? Image shows forever Image doesn't display

134. Which format in Pillow is best for icons and transparency?

C) Saves to disk D) Resizes image

→ B)

A) JPG

C) D)	PNG BMP ICO D) ICO
A) B) C) D)	Why is adaptive thresholding slow? Requires full image scan Applies local window to every pixel Uses deep learning Blurs image B)
B) C) D)	Which OpenCV technique helps add watermark? Contours drawText() cv2.putText() cropOverlay() C) cv2.putText()
B) C) D)	What does cv2.THRESH_OTSU do? Binarizes with manual threshold Automatically finds optimal threshold Enhances brightness Segments by region B)
B) C) D)	How to remove noise but preserve text edges? Median blur Gaussian blur Average filter Histogram equalization A)
B) C) D)	Which format is lossy and not ideal for medical imaging? PNG TIFF JPEG BMP C) JPEG
B)	Which type of interpolation is ideal for zooming UI icons? Bilinear Nearest Cubic

D) Area → B)
 141. Which blur preserves edges while reducing noise? A) Bilateral filter B) Average C) Laplacian D) Threshold → A)
 Which OpenCV function shows the exact value of a pixel? A) getPixelValue(x,y) B) img[y,x] C) pixel(img,x,y) D) readPixel() → B) img[y,x]
 143. What happens if wrong color order is used in imshow()? A) Crashes B) Black and white output C) Wrong colors (e.g. red → blue) D) Transparency → C)
 144. Why is it useful to apply normalization on images before CNNs? A) Reduces features B) Improves gradient descent performance C) Enhances brightness D) Creates sharper output → B)
 145. Which method helps visualize multiple edge types? A) Sobel X + Y combined B) Laplacian C) Harris D) Histogram → A)
 146. What will happen if ROI is not copied before modifying? A) Changes affect entire image B) Memory error C) Changes are local D) ROI turns grayscale

\rightarrow	A)
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147. Which code is ideal for rotating by 45°	ode is ideal for rotating by 45°?
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- A) getRotationMatrix2D + warpAffine
- B) cv2.rotate()
- C) np.flip()
- D) imrotate()
- \rightarrow A)

148. What is the core data structure of OpenCV images in Python?

- A) pandas DataFrame
- B) Tensor
- C) NumPy array
- D) Image object
- **→ C)**

149. Which step in Canny removes irrelevant gradient responses?

- A) Non-maximum suppression
- B) Gaussian filtering
- C) Double thresholding
- D) Convolution
- \rightarrow A)

150. Which OpenCV function detects edges via gradient calculation?

- A) cv2.findContours()
- B) cv2.cornerHarris()
- C) cv2.Canny()
- D) cv2.threshold()
- \rightarrow C)

- 171. If you blur a QR code too much, what will happen?
 - → It will become unreadable
- 172. You want to segment lungs in an X-ray. What should you use?
 - → U-Net or CNN-based segmentation
- 173. You have multiple images with uneven lighting. Best thresholding?
 - → Adaptive Thresholding

174. What is the ideal library for building CV apps with webcam support? → OpenCV
175. You want to visualize corner strength across an image. What tool? → Harris Detector + heatmap visualization
176. Which preprocessing step helps detect red traffic lights? → Convert to HSV and threshold hue for red
177. What happens when you overlay two images without alpha blending? → One image dominates, no transparency
178. Which image property changes when resized non-proportionally? → Aspect ratio
179. Which method works best for recognizing rotated company logos? → ORB + Feature Matching
180. You want to detect potholes on roads from a car. First step? → Edge detection or thresholding for anomalies
181. Which method is ideal for live gesture recognition? → CNN with real-time OpenCV feed
182. Which filter smooths out detail but maintains global shape? → Gaussian blur
183. Which task best benefits from grayscale conversion? → Edge detection
184. If red and blue appear swapped in imshow(), cause? → BGR image shown without converting to RGB
 185. Why is interpolation needed in resizing? → To estimate pixel values for non-integer positions
186. Which CV application benefits most from segmentation? → Medical imaging or autonomous driving
187. You're designing an AR app. What's a useful CV technique? → Feature tracking or SLAM

188. If image is too noisy for edge detection, what's your move? → Apply Gaussian or median blur first
189. You want to apply color-based tracking. What space to use? → HSV
 190. Which filter helps enhance text in faded documents? → Sharpening kernel or contrast enhancement
191. You want to reduce file size without visual quality loss. Format? → PNG with compression or WebP
192. In segmentation, how are object boundaries improved? → Post-processing with morphological operations
193. You're building a mobile app for OCR. Which framework is useful? → Tesseract + OpenCV or EasyOCR
194. Which detection method is sensitive to scale changes? → Template Matching
195. What technique makes blending two photos look smooth? → cv2.addWeighted()
196. Your model fails on rotated faces. Fix?→ Data augmentation with rotations
197. You want to keep facial features but reduce file size. Strategy? → Resize with bicubic + save as PNG
198. If you need object outlines, what's better than edge detection? → Contour detection
199. Which CV task is most used in surveillance systems? → Object detection (e.g., YOLO)
200. Which concept improves OpenCV-based real-time video tracking? → Optical flow or Kalman filter