CS 771A:	Intro to Machine Learning, IIT Kanpur Mi	dsem Exam (15 Sep 2019)
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Instructions:

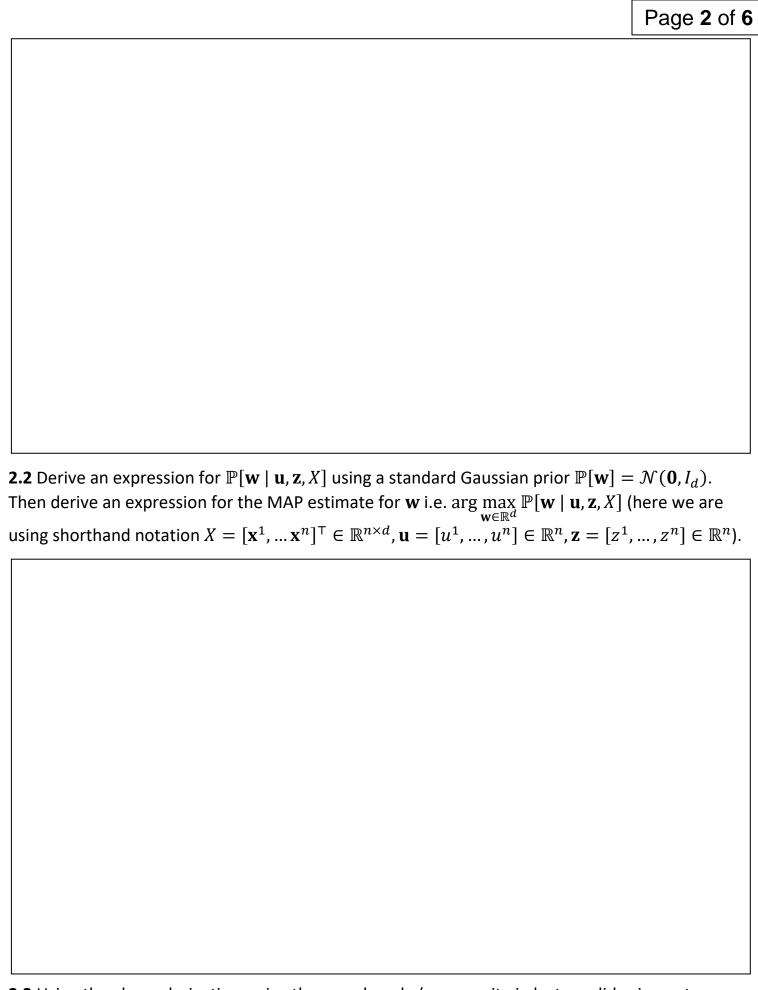
- 1. This question paper contains 3 pages (6 sides of paper). Please verify.
- 2. Write your name, roll number, department in **block letters neatly** with ink **on each page** of this question paper.
- 3. If you don't write your name and roll number on all pages, pages may get lost when we unstaple to scan pages
- 4. Write your final answers neatly with a blue/black pen. Pencil marks may get smudged.
- 5. Don't overwrite/scratch answers especially in MCQ and T/F. We will entertain no requests for leniency.

Q1. Write T or F for True/False (write only in the box on the right hand side) (10x2=20 marks)

1	When using kNN to do classification, using a large value of k always gives better performance since more training points are used to decide label of the test point	
2	Cross validation means taking a small subset of the test data and using it to get an estimate of how well will our algorithm perform on the entire test dataset	
3	The EM algo does not require a careful initialization of model parameters since it anyway considers all possible assignments of latent variables with different weights	
4	If X and Y are two real-valued random variables such that $Cov(X,Y) < 0$ then at least one of X or Y must have negative variance i.e. either $\mathbb{V}X < 0$ or $\mathbb{V}Y < 0$	
5	If $\mathbf{a} \in \mathbb{R}^2$ is a constant vector and $f: \mathbb{R}^2 \to \mathbb{R}$ is such that $g(\mathbf{x}) = f(\mathbf{x}) + \mathbf{a}^T \mathbf{x}$ is a non-convex function, then $h(\mathbf{x}) = f(\mathbf{x}) - \mathbf{a}^T \mathbf{x}$ must be a non-convex function too	
6	The SVM is so named because the decision boundary of the SVM classifier passes through the data points which are marked as being support vectors	
7	Suppose X is a real valued random variable with variance $\mathbb{V}X=9$. Then the random variable Y defined as $Y=X-2$ will always satisfy $\mathbb{V}Y=\mathbb{V}X-2^2=5$	
8	The LwP algorithm for binary classification always gives linear decision boundary if we use one prototype per class and Euclidean distance to measure distances	
9	If $f, g: \mathbb{R}^2 \to \mathbb{R}$ are two non-convex functions, then the function $h: \mathbb{R}^2 \to \mathbb{R}$ defined as $h(\mathbf{x}) = f(\mathbf{x}) + g(\mathbf{x})$ must always be non-convex too	
10	If we learn models $\{\mathbf{w}^c\}_{c=1}^C$ for multiclassification using the Crammer-Singer loss function, these models can be used to assign a PMF over the class labels $[C]$	

Q2 Phase retrieval is used in X-ray crystallography. Let $\mathbf{x}^i \in \mathbb{R}^d$, $i \in [n]$ be features and $y^i \in \mathbb{R}$ be labels. All data points are independent. However, we only get to see the absolute value of labels, i.e. the train data is $\left\{ (\mathbf{x}^i, u^i) \right\}_{i=1}^n$ where $u^i = |y^i|$. Let $z^i \in \{-1,1\}$ be latent variables for missing label signs (aka *phases*). Use the data likelihood function $\mathbb{P}[u^i \mid z^i, \mathbf{x}^i, \mathbf{w}] = \mathcal{N}(u^i z^i ; \mathbf{w}^\top \mathbf{x}^i, 1)$. Note that this is a discriminative setting (i.e. \mathbf{x}^i are constants). Expressions in your answers may contain unspecified normalization constants. Give only brief derivations. **(8+6+6=20 marks) 2.1** Assuming $\mathbb{P}[z^i = c \mid \mathbf{x}^i, \mathbf{w}] = \mathbb{P}[z^i = c] = 0.5$ for $c \in \{-1,1\}$ (i.e. uniform prior on z^i that does not depend on features or model), derive an expression for $\mathbb{P}[z^i = 1 \mid u^i, \mathbf{x}^i, \mathbf{w}]$. Using this,

derive an expression for the MAP estimate $\underset{c \in \{-1,+1\}}{\arg\max} \mathbb{P} \big[z^i = c \mid u^i, \mathbf{x}^i, \mathbf{w} \big]$



2.3 Using the above derivations, give the pseudocode (as we write in lecture slides i.e. not necessarily Python code or C code but sufficient details of the algorithm updates) for an alternating optimization algorithm for estimating the model **w** in the presence of the latent variables. Give precise update expressions in your pseudocode and not just vague statements.

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Q3 We have	re seen that algorithms such as the EM require weig	hted optimization	problems to be
	ere different data points may have different weights		
_	arized squared hinge loss minimization but with diffs are $\mathbf{x}^i \in \mathbb{R}^d$ and the labels are $y^i \in \{-1,1\}$. The w	- -	-
	and are all strictly positive i.e. $q_i > 0$, $q_i \neq 0$ for all		own (n.e. are 3+2+5=10 marks)
,	$\arg\min_{\mathbf{w}\in\mathbb{R}^{d}}\frac{1}{2}\ \mathbf{w}\ _{2}^{2}+\sum_{i=1}^{n}q_{i}\cdot\left(\left[1-y^{i}\right]\right)$		·
2 1 As wo			om that has
	did in assignment 1, rewrite the above problem as a constraints in it (the above problem does not have a	-	em mat nas
		,	
1			

uce dual variables ax-min problem (n			
dual by eliminatin Show only brief de	ariables and wri	te down the expre	ession for the

Q4 Recall the uniform distribution over an interval $[a,b] \subset \mathbb{R}$ where a < b. Just two parameters, namely a,b, are required to define this distribution (no restrictions on a,b being positive/non-zero etc, just that we must have a < b. Note this implies $a \neq b$). The PDF of this distribution is

$$\mathbb{P}[x \mid a, b] = \mathcal{U}(x; a, b) \triangleq \begin{cases} 0 & x < a \\ 1/(b-a) & x \in [a, b] \\ 0 & x > b \end{cases}$$

Given n independent samples $x^1, ..., x^n \in \mathbb{R}$ (assume w.l.o.g. that not all samples are the same number) we wish to learn a uniform distribution as a generative distribution using these samples using the MLE technique i.e. we wish to find

$$\underset{a < b, a \neq b}{\operatorname{arg max}} \ \mathbb{P}[x^1, ..., x^n \mid a, b]$$

Give a brief derivation for, and the final values of, \hat{a}_{MLE} and \hat{b}_{MLE} .

(5+5=10 marks)

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. Fill the circle (don't	tick) next to all the correct option	ons (many may be correct) .(2x3=6 mar l
.1 The use of the Lapla	nce (aka Laplacian) prior and Lap	lace (aka Laplacian) likelihood r
oblem that requ	ires us to solve an optimization	problem whose objective function is

Α

В

C

D

Always convex and always differentiable

Always convex but possibly non-differentiable

Possibly non-convex but always differentiable

Always non-convex and always non-differentiable

[Α	The mode of that PMF should have a probability value much larger than 0							\bigcirc	
	В	The mode of that PMF should have a probability value very close to 0							$\tilde{\bigcirc}$	
•	С	The ML algorithm is very confident about its prediction on that data point							Ŏ	
	D	The ML algor								$\tilde{\bigcirc}$
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-		as support on				-				marks)
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5.2 In probabilistic multiclassification with ${\it C}$ classes, if for a test data point, the ML algorithm

predicts a PMF over the classes with an extremely small variance, then it means that