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Class: TY-IT A B3

8-Puzzle using AStar :

```
#include <bits/stdc++.h>
using namespace std;

static const auto init = []
{
    std::ios_base::sync_with_stdio(false);
    std::cin.tie(nullptr);
    std::cout.tie(nullptr);
    return false;
}();

class Node
{
public:
    Node *parent;
    int cost;
    int hval;
    vector<vector<int>> board;
    vector<Node> Children;
    void Hfun(Node &Goal)
    {
        int count = 0;
        for (int i = 0; i < 3; i++)
        {
            for (int j = 0; j < 3; j++)
            {
                if (board[i][j] != Goal.board[i][j])
                {
                    count++;
                }
            }
        }
        hval = count;
    }
    void PrintBoard()
    {
        for (int i = 0; i < 3; i++)
        {
```

```

        for (int j = 0; j < 3; j++)
        {
            cout << board[i][j] << " ";
        }
        cout << "\n";
    }
    cout << endl;
}

void GenerateChildren(int x, int y, Node &Goal)
{
    Node child;
    child.parent = this;
    child.board = board;
    child.cost = cost + 1;
    if (x + 1 < 3)
    {
        swap(child.board[x + 1][y], child.board[x][y]);
        child.Hfun(Goal);
        Children.push_back(child);
    }
    if (y + 1 < 3)
    {
        child.board = board;
        swap(child.board[x][y + 1], child.board[x][y]);
        child.Hfun(Goal);
        Children.push_back(child);
    }
    if (x - 1 >= 0)
    {
        child.board = board;
        swap(child.board[x - 1][y], child.board[x][y]);
        child.Hfun(Goal);
        Children.push_back(child);
    }
    if (y - 1 >= 0)
    {
        child.board = board;
        swap(child.board[x][y - 1], child.board[x][y]);
        child.Hfun(Goal);
        Children.push_back(child);
    }
}
};

```

```

class Position

```

```

{
public:
    int x;
    int y;
    void zeroposition(vector<vector<int>> &temp)
    {
        int i, j;
        for (i = 0; i < 3; i++)
        {
            for (j = 0; j < 3; j++)
            {
                if (temp[i][j] == 0)
                {
                    x = i;
                    y = j;
                    break;
                }
            }
        }
    }
};

void PrintList(list<Node> List, string Type)
{
    cout << Type << " List\n";
    for (int i = 0; i < 3; i++)
    {
        for (auto j : List)
        {
            cout << j.board[i][0] << " " << j.board[i][1] << " " <<
j.board[i][2] << " ";
        }
        cout << "\n";
    }
    cout << "*****\n";
}

int main()
{
    // Goal State
    Node Goal;
    Goal.board = {{1, 2, 3}, {4, 8, 5}, {0, 7, 6}};
    Goal.hval = 0;

    // Intial State
    Node Intial;
    Intial.board = {{1,2,3}, {4,5,6}, {7, 8, 0}};
}

```

```

Initial.Hfun(Goal);
Initial.parent = NULL;
Initial.cost = 0;

int minf = INT_MAX;
Position curr; // empty tile position
Node Parent, Child;

list<Node> Open;
list<Node> Closed;

// Push Initial Node in Open List
Open.push_front(Initial);
PrintList(Open, "OPEN");
PrintList(Closed, "CLOSED");

while (!Open.empty())
{
    // Pick Node with Least f value
    minf = INT_MAX;
    std::list<Node>::iterator minIt = Open.begin();
    for (auto i = Open.begin(); i != Open.end(); ++i)
    {
        if (i->cost + i->hval < minf)
        {
            minf = i->cost + i->hval;
            minIt = i;
        }
    }

    // Pop Node with least f-value
    Parent = *minIt;
    Open.erase(minIt);

    // Generate Child Nodes of Parent Node
    curr.zeroposition(Parent.board);
    Parent.GenerateChildren(curr.x, curr.y, Goal);
    bool goalflag = false;
    Closed.push_back(Parent);
    // Evaluate each sucessor of parent
    for (auto i : Parent.Children)
    {
        i.PrintBoard();
        if (i.board == Goal.board)
        {
            cout << "\nGoal Reached\n";

```

```

        cout << "Cost = " << i.cost << "\n";
        Closed.push_back(i);
        goalflag = true;
        break;
    }
    minf = i.hval + i.cost;
    bool flag = true;
    // check for child node in Open List with same position with
lower cost
    for (auto j : Open)
    {
        if (i.board == j.board && i.cost < j.cost)
        {
            j = i;
            break;
        }
    }

    // check for child node in Closed List with same position with
lower cost
    for (auto j : Closed)
    {
        if (i.board == j.board && i.cost > j.cost)
        {
            flag = false;
            break;
        }
    }
    if (flag)
    {
        Open.push_back(i);
    }
}
cout << "*****" << endl;
PrintList(Open, "OPEN");
PrintList(Closed, "CLOSED");
if (goalflag)
{
    break;
}
}

return 0;
}

```

Output:

OPEN List

1 2 3

4 5 6

7 8 0

CLOSED List

1 2 3

4 5 0

7 8 6

1 2 3

4 5 6

7 0 8

OPEN List

1 2 3 1 2 3

4 5 0 4 5 6

7 8 6 7 0 8

CLOSED List

1 2 3

4 5 6

7 8 0

1 2 3

4 5 6

7 8 0

1 2 0

4 5 3

7 8 6

1 2 3
4 0 5
7 8 6

OPEN List

1 2 3 1 2 0 1 2 3
4 5 6 4 5 3 4 0 5
7 0 8 7 8 6 7 8 6

CLOSED List

1 2 3 1 2 3
4 5 6 4 5 0
7 8 0 7 8 6

1 2 3
4 8 5
7 0 6

1 2 3
4 5 0
7 8 6

1 0 3
4 2 5
7 8 6

1 2 3
0 4 5
7 8 6

OPEN List

1 2 3 1 2 0 1 2 3 1 0 3 1 2 3
4 5 6 4 5 3 4 8 5 4 2 5 0 4 5
7 0 8 7 8 6 7 0 6 7 8 6 7 8 6

CLOSED List

1 2 3 1 2 3 1 2 3
4 5 6 4 5 0 4 0 5

7 8 0 7 8 6 7 8 6

1 2 3

4 8 5

7 6 0

1 2 3

4 0 5

7 8 6

1 2 3

4 8 5

0 7 6

Goal Reached

Cost = 4

OPEN List

1 2 3 1 2 0 1 0 3 1 2 3 1 2 3

4 5 6 4 5 3 4 2 5 0 4 5 4 8 5

7 0 8 7 8 6 7 8 6 7 8 6 7 6 0

CLOSED List

1 2 3 1 2 3 1 2 3 1 2 3 1 2 3

4 5 6 4 5 0 4 0 5 4 8 5 4 8 5

7 8 0 7 8 6 7 8 6 7 0 6 0 7 6
