

## Assignment - 3

1) A system has a transfer function,  $G(s) = \frac{100}{s+50}$   
 Find  $T_c$  settling time  $= T_s$  &  
 rise time  $T_r$ .

$$\Rightarrow G(s) = \frac{100}{s+50} \Rightarrow a = 50$$

$$T_c = \frac{1}{a} = 0.02 \text{ s}$$

$$T_s = \frac{4}{a} = 0.08 \text{ s}$$

$$T_r = \frac{2.2}{a} = 0.044 \text{ s}$$

Q2)

$$\Rightarrow G(s) = \frac{81}{s^2 + bs + 81} = \frac{\omega_n^2}{s^2 + 2\omega_n s + \omega_n^2}$$

$$\text{Comparing} \Rightarrow [\omega_n = 9 \text{ rad/s}]$$

$$= 2\omega_n \zeta = 6$$

$$= \zeta = \frac{1}{3} = 0.333$$

as  $\zeta < 1$ , the motion is underdamped

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(3)

$$\Rightarrow G(s) = \frac{225}{s^2 + 25s + 225}$$

$$W_n = 15$$

$$\zeta = \frac{25}{30} = \boxed{\frac{5}{6}}$$

$$T_p = \frac{\pi}{w_n \sqrt{1 - \zeta^2}} = \frac{\pi}{15 \sqrt{1 - \left(\frac{5}{6}\right)^2}} = \frac{\pi}{15 \sqrt{\frac{36-25}{36}}} = \frac{\pi \times 5}{15 \sqrt{11}} = \frac{\pi}{3\sqrt{11}}$$

$$\% DS = e^{-\left(\frac{5\pi}{\sqrt{1-25/36}}\right)} \times 100$$

$$= e^{-\left(\frac{5}{6} \times \frac{\pi}{\sqrt{11}} \times 5\right)} \times 100$$

$$= \boxed{e^{-\frac{25\pi}{6\sqrt{11}} \times 100}}$$

$$T_s = \frac{4}{\zeta \times w_n} = \frac{4 \times 6}{5 \times 15} = \frac{24}{75}$$

$$T_d = \frac{\pi - \phi}{w_n \sqrt{1 - \zeta^2}} \quad \phi = \tan^{-1} \frac{\sqrt{11} \times 6}{5 \times 5}$$

$$= \phi = \tan^{-1} \left( \frac{\sqrt{11} \times 6}{5 \times 5} \right)$$

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Q4)

$$G(s) = \frac{361}{s^2 + 1bs + 361}$$

$$\omega_n = 19$$

$$\zeta = \frac{16}{38} - \frac{8}{19}$$

$$T_s = \frac{4}{\zeta \times \omega_n} = \frac{4}{16 \times 19} = \frac{1}{2}$$

$$T_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = \frac{\pi}{19 \sqrt{1 - \frac{64}{361}}} = \frac{\pi \times 19}{19 \sqrt{297}} = \frac{\pi}{\sqrt{297}}$$

$$\bar{\theta}_s = \pi - \left( \tan^{-1} \left( \frac{\sqrt{1 - \zeta^2}}{\zeta} \right) \right)$$

$$= \pi - \tan^{-1} \left( \frac{\sqrt{297} \times 19}{19 \times 8} \right) \times 19$$

$$= \pi - \tan^{-1} \left( \frac{\sqrt{297}}{8} \right)$$

$$\text{OF}_{OS} = e^{-\left(\frac{\zeta \pi}{\sqrt{1-\zeta^2}}\right)} \times 100$$

$$= e^{-\left(\frac{8}{19} \frac{\pi}{\sqrt{297}} \times 19\right)} \times 100$$

$$= 100 e^{-\frac{8\pi}{\sqrt{297}}}$$

(Q3) Find  $\zeta$ ,  $w_n$ ,  $T_p$ ,  $T_s$ , %OS &  $T_d$  for a system whose transfer function is

$$G(s) = \frac{441}{s^2 + 259s + 441}$$

$$w_n = \sqrt{b_1} \Rightarrow w_n = \sqrt{441}$$

$$\therefore w_n = 21$$

$$\zeta = \frac{a/2}{w_n} = \frac{25/2}{21} = 0.595$$

$$T_s = \frac{4}{\pi} \tan^{-1} \frac{4}{\zeta} = \frac{4}{\pi} \tan^{-1} \frac{4}{0.595} = 0.325$$

$$T_p = \frac{\pi}{w_n \sqrt{1-\zeta^2}} = \frac{\pi}{21 \sqrt{1-(0.595)^2}} = 0.1869$$

$$T_d = \frac{\pi - \phi}{w_n \sqrt{1-\zeta^2}}$$

$$\therefore \phi = \tan^{-1} \left( \frac{\sqrt{1-\zeta^2}}{\zeta^2} \right) = \phi \tan^{-1} \left( \frac{\sqrt{1-(0.595)^2}}{0.595} \right)$$

$$= [53 - 48] \rightarrow ①$$

$$T_d = \frac{\pi - 53 - 48}{w_n \sqrt{1-\zeta^2}} = \frac{\pi - 853 - 487}{21 \times \sqrt{1-(0.595)^2}}$$

$$T_d = [-2.983] \checkmark$$

$$\% OS = 9.77 \%$$

Q6) Determine the validity of second order approximation for each of these two transfer

a)  $G(s) = \frac{700}{(s+15)(s^2 + 4s + 100)}$   $\rightarrow s+15, s = -15$   
 $s^2 + 4s + 100$   
 $s = -4 \pm \sqrt{4^2 - 4 \times 100}$   
 $s = -2 \pm \sqrt{384}$

Dominant poles have real part of -2 & the higher order pole is at -1s i.e. more than 5 times further

$\Rightarrow$  second order approximation is valid

b)  $G(s) = \frac{360}{(s+4)(s^2 + 2s + 90)}$   $\rightarrow s+4 = 0 \Rightarrow s = -4$   
 $s^2 + 2s + 90, s = -2 \pm \sqrt{2^2 - 4 \times 90}$   
 $s = -1 \pm \sqrt{356}$

Dominant poles have a real part of -1 & the higher order pole is at -4 i.e. not more than 5 times  
 $\Rightarrow$  second order is Not valid

Q7) Determine the validity of a second order step-response approximation for each transfer function shown below

$$g) G(s) = \frac{185.71(s+7)}{(s+6.5)(s+10)(s+20)}$$

Expanding  $G(s)$

$$G(s) = \frac{1}{s} + \frac{0.8942}{s+20} - \frac{1.5918}{s+10} - \frac{0.3023}{s+6.5}$$

But  $-0.3023$  is not an order of magnitude less than residues of second order term

$\Rightarrow$  Second order approximation is not valid

$$h) G(s) = \frac{197.14(s+7)}{(s+6.9)(s+10)(s+20)}$$

Expanding

$$G(s) = \frac{1}{s} + \frac{0.9782}{s+20} - \frac{1.9078}{s+10} - \frac{0.0704}{s+6.5}$$

$0.0704$  is an order of magnitude less than residue of second order terms i.e term  $2^{\text{nd}}$

$\Rightarrow$  Second order approximation is valid

Q8)

⇒ For 1(a)

$$G(s) = \frac{a}{s+a} = \frac{5}{s+5} = \frac{1}{s} - \frac{1}{s+5}$$

$$C(t) = 1 - e^{-at} \quad \text{output response}$$

$$C(t) = 1 - e^{-5t}$$

$$\text{and time constant } T_0 = \frac{1}{a}$$

$$\therefore T_0 = \frac{1}{5} = 0.2$$

$$T_0 = 0.2$$

$$\text{Rise time } T_R = \frac{2.2}{a} = \frac{2.2}{5} = 0.44$$

$$T_R = 0.44$$

$$\text{Settling time } T_S = \frac{4}{a} = \frac{4}{5} = 0.8$$

For 1(b)

$$G(s) = \frac{a}{s+a} = \frac{20}{s+20} = \frac{1}{s} = \frac{1}{s+20}$$

$$C(t) = 1 - e^{-at}$$

$$= 1 - e^{-20t}$$

$$T_C = \frac{1}{a} = \frac{1}{20} = 0.05$$

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$$\text{Rise time } (T_R) = \frac{2.2}{a} = \frac{2.2}{20} = 0.11 \text{ (unit: sec)}$$

$$\text{Settling time } (T_S) = \frac{4}{a} = \frac{4}{20} = \frac{1}{5} = 0.2 \text{ (unit: sec)}$$

Q3)

$\Rightarrow$  Using voltage division rule,  $(ed + em)$

$$V_C(s) = \left( \frac{1/Cs}{R + 1/Cs} \right) \cdot V(s)$$

$$= \frac{1/Rc}{s + 1/Rc} \cdot V(s)$$

$$U(t) = 5$$

$$Vi(s) = \frac{5}{9}$$

$$\frac{0.703}{s + 0.703} = \frac{(e)x_2}{(e)7}$$

$$V_C(s) = \frac{5}{9} \left( \frac{0.703}{s + 0.703} \right) = \frac{5}{9} = \frac{5}{s + 0.703}$$

$$V_C(t) = 5 - 5e^{-0.703t}$$

$$T_C = \frac{1}{a} = \frac{1}{0.703} = 1.422$$

$$T_R = \frac{2.2}{a} = \frac{2.2}{0.703} = 3.129$$

$$T_S = \frac{4}{a} = \frac{4}{0.703} = 5.69$$

$\therefore$  Time constant = 1.422 Rise time 3.129 and  
 Setting time = 5.695

(Q10)

$\Rightarrow$  writing the equation of motion

$$(ms^2 + bs) \times (s) = F(s)$$

Then the transfer function  $= \frac{X(s)}{F(s)} = \frac{1}{ms^2 + bs}$

differentiating

$$\frac{sX(s)}{F(s)} = \frac{1}{ms + b} = \frac{Vm}{s + \frac{b}{m}}$$

thus

$$\text{Settling-time } T(s) = \frac{4}{a} = \frac{4}{b/m} = \frac{2}{3} m = 0.66667 m$$

(Q11)

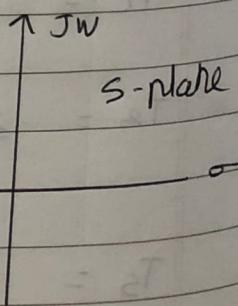
$$q) T(s) = \frac{2}{s+2}$$

For the given transfer function  
 the pole is at -2

Pole: -2

Output response  $C(t) = (A + Be^{-2t}) U(t)$

$\therefore$  It is a first order response



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$$b) T(s) = \frac{5}{(s+3)(s+6)}$$

For the given transfer function  
there are 2 real poles at

-3 & -6

Poles : -3, -6

$$\therefore \text{output response } c(t) = (K_1 + K_2 e^{-3t} + K_3 e^{-6t}) u(t)$$

$$\text{or } c(t) = (A + Be^{-3t} + C e^{-6t}) u(t)$$

i.e

The nature of response of the system is overdamped response

$$c) T(s) = \frac{10(s+7)}{(s+10)(s+20)}$$

For the given transfer function

there are 2 real poles at -10

and -20 & zero at -7

Poles -10, -20

zero : -7

$$\text{Output response } c(t) = (K_1 + K_2 e^{-10t} + K_3 e^{-20t}) u(t)$$

$$\text{or } c(t) = (A + Be^{-10t} + C e^{-20t}) u(t)$$

$\therefore$  the response is overdamped response

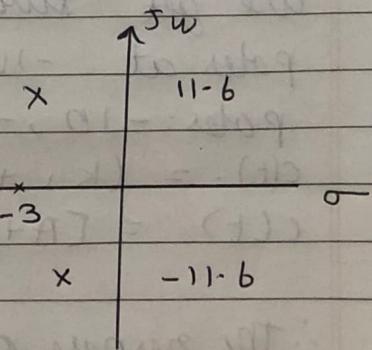
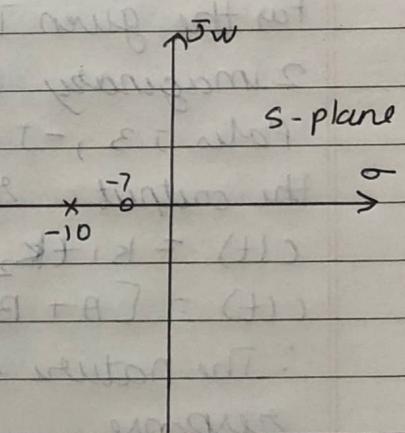
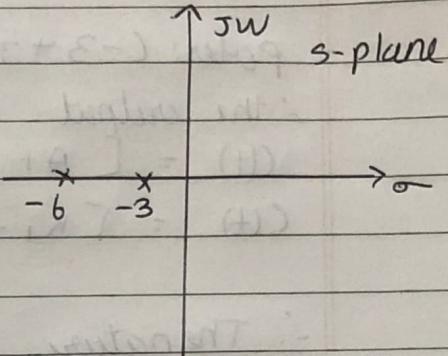
$$d) T(s) = \frac{20}{s^2 + 6s + 144}$$

For the given transfer function

we get 2 complex poles

of the system at  $(-3 + j3\sqrt{5})$

&  $(-3 - j3\sqrt{5})$



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Poles:  $(-3 + j3\sqrt{5})$ ,  $(-3 - j3\sqrt{5})$

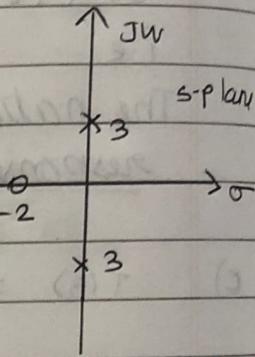
∴ the output response is

$$c(t) = [A + e^{-3t}(B \cos 3\sqrt{5}t) + C \sin(3\sqrt{5}t)] u(t)$$

$$c(t) = [K_1 + e^{-3t}(K_2 \cos 3\sqrt{5}t) + K_3 \sin 3\sqrt{5}t] u(t)$$

∴ The nature of response of the system is underdamped

e)  $T(s) = \frac{s+2}{s^2+9}$



For the given T.F there are

2 imaginary poles at  $\pm j3$

Poles  $j3, -j3$  and zero:  $-2$

The output response  $c(t) =$

$$c(t) = K_1 + K_2 \cos(3t) + K_3 \sin(3t) u(t)$$

$$c(t) = [A + B \cos(3t) + C \sin(3t)] u(t)$$

∴ The nature of response of the system is undamped response

b)  $T(s) = \frac{s+5}{(s+10)^2}$

For the given transfer function

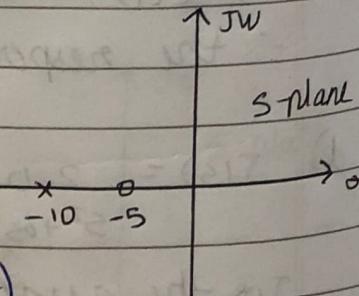
We get two multiple real

poles at  $-10, -10$  and 0 at  $-5$

Poles:  $-10, -10$  & zero:  $-5$

$$c(t) = (K_1 + K_2 e^{-3t} + K_3 e^{-10t}) u(t)$$

$$c(t) = [A + B e^{-10t} + (e^{-10t})] u(t)$$



∴ The response of the system is critically damped

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Q12)

$\Rightarrow$  writing the node eq at capacitor V

$$V_C(s) \left( \frac{1}{R^2} + \frac{1}{Ls} + (s) \right) + \frac{V_C(s) - V_E(s)}{R_1} = 0$$

Hence

$$\frac{V_C(s)}{V(s)} = \frac{\frac{1}{R_1}}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{Ls} + s} = \frac{10s}{s^2 + 20s + 500}$$

The step response is

$$\frac{10}{s^2 + 20s + 500}$$

The poles are at  $-10 \pm j20$ 

$$\therefore V(t) = Ae^{-10t} \cos(20t + \phi)$$

Q13)

$\rightarrow$  The eq of motion  $(Ms^2 + bys + ks) X(s) = F(s)$

$$\text{Therefore } \frac{X(s)}{F(s)} = \frac{1}{Ms^2 + bys + ks} = \frac{1}{s^2 + s + 5}$$

$$\begin{aligned} \text{Step response now evaluated: } X(s) &= \frac{1}{s(s^2 + s + 5)} \\ &= \frac{1/s}{s} - \frac{1/s + 1/s}{(s + 1/2) + 19/4} \end{aligned}$$

$$= \frac{\frac{1}{5}(s+1/2) + \frac{1}{5\sqrt{9}} - \frac{\sqrt{19}}{2}}{(s + \frac{1}{2})^2 + 19/4}$$

Taking the inverse Laplace transform

$$\begin{aligned} X(t) &= \frac{1}{5} - \frac{1}{5} e^{-0.5t} \left( \cos \frac{\sqrt{19}}{2} t + \frac{1}{\sqrt{19}} \sin \frac{\sqrt{19}}{2} t \right) \\ &= \frac{1}{5} \left[ 1 - 2 \sqrt{\frac{s}{19}} e^{-0.5t} \cos \left( \frac{\sqrt{19}}{2} t - 12.92^\circ \right) \right] \end{aligned}$$

(n4)

$$\Rightarrow G(s) / T(s) = \frac{-b}{s^2 + 9s + b}$$

$$b = \omega_n^2$$

$$\omega_n^2 = 16$$

$$\omega_n = \sqrt{b} = 4$$

$$\alpha = 2\zeta\omega_n$$

$$\beta = 2\zeta\omega_n$$

$$\beta = 2\zeta 4$$

$$\zeta = \frac{3}{2 \times 4} = \frac{3}{8} = 0.375$$

$$T_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = \frac{\pi}{4 \sqrt{1 - 0.375^2}} = 0.8472 \text{ s}$$

$$T_s = \frac{4}{\zeta w_n} = \frac{4}{0.375(4)} = \underline{2.6675}$$

$$\% DS = e^{-\left(\frac{4\pi}{\sqrt{1-\zeta^2}}\right)} \times 100 = e^{-\left(\frac{0.375\pi}{\sqrt{1-0.375^2}}\right)^2} \times 100 = -28.0596\% = \underline{28.06\%}$$

$$T_s = (1 - 76\zeta^3 - 0.417\zeta^2 + 1.039\zeta + 1) = 1.4238$$

$$T_s = \frac{1.4238}{w_n} = \frac{1.4238}{4} = \underline{0.3565}$$

b)  $T(s) = \frac{0.04}{s^2 + 0.02s + 0.04}$

$$G(s) / T(s) = \frac{b}{s^2 + as + b}$$

$$w_n^2 = b$$

$$w_n^2 = 0.04$$

$$w_n = \sqrt{0.04} = 0.2$$

$$a = 2\zeta w_n$$

$$0.02 = 2\zeta 0.2$$

$$\zeta = \underline{0.02}$$

$$2 \times 0.2$$

$$\zeta = 0.05$$

$$T_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}} = \frac{\pi}{0.2 \sqrt{1-0.05^2}} = 15.727 \text{ s} = 15.73 \text{ s}$$

$$T_s = \frac{4}{\zeta \omega_n} = \frac{4}{0.05(0.2)} = \frac{400 \text{ s}}{0.05(0.2)}$$

$$\% \text{OS} = e^{-\left(\zeta \omega_n / \sqrt{1-\zeta^2}\right)} \times 100 = e^{-\left(0.05\pi / \sqrt{1-(0.05)^2}\right)} \times 100$$

$$= 85.45 \%$$

$$\omega_n T_s = (1.76 \zeta^3 + 0.417 \zeta^2 + 1.039 \zeta + 1) \\ = 1.05112$$

$$T_s = \frac{1.05112}{\omega_n} = \frac{5.26 \text{ s}}{0.05(0.2)}$$

c)  $T(s) = \frac{1.05 \times 10^7}{s^2 + 1.6 + 10^3 s + 1.05 \times 10^7}$

Comparing with

$$G(s) = \frac{a^4 q b}{s^2 + as + b}$$

$$\omega_n^2 = b$$

$$\omega_n^2 = 1.05 \times 10^7$$

$$\omega_n = \sqrt{1.05 \times 10^7}$$

$$\omega_n = 3240.370$$

$$\underline{\omega_n = 3240}$$

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$$\omega = 2 \zeta \omega_n$$

$$1.6 \times 10^3 = 2 \zeta 3240$$

$$\zeta = \frac{1.6 \times 10^3}{2 \times 3240}$$

$$\zeta = 0.2469$$

$$\zeta = 0.247$$

$$T_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = \frac{\pi}{3240 \sqrt{1 - (0.247)^2}} = 1.00 \times 10^{-3} = 0.001 s$$

$$T_s =$$

$$T_s = \frac{4}{\zeta \omega_n} = \frac{4}{0.247 \times 3240} = 4.99 \times 10^{-3} = 0.005 s$$

$$\% OS = e^{-(\zeta \pi / \sqrt{1 - \zeta^2})} \times 100$$

$$= e^{-(0.247 \pi / \sqrt{1 - (0.247)^2})} \times 100 = 44.89 \%$$

$$\omega_{nts} = (1.76 \zeta^3 - 0.417 \zeta^2 + 1.039 \zeta + 1) = 1.257$$

$$T_g = \frac{1.257}{3240} = 3.88 \times 10^{-4} s$$