

Estimating Fiscal Multipliers by Combining Statistical Identification with Potentially Endogenous Proxies

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Motivation

- Proxy VARs have become popular tool to identify the effects of fiscal policy.
- Angelini et al. (2023): Different potentially valid proxy variables lead to contradictory conclusions about the size of fiscal multipliers:
 - Fiscal proxy SVAR in Mertens and Ravn (2014):
→ tax multiplier $>$ spending multiplier
 - Non-fiscal proxy SVAR in Caldara and Kamps (2017):
→ tax multiplier $<$ spending multiplier
- Some of the exogeneity assumptions of the proxy variables are violated.

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Research Questions

- Which proxy is correct and what is the spending and tax multiplier?
- More general: How can we deal with potentially invalid proxies?

Contribution

- Technical contribution:
 - Novel Bayesian moment-based proxy SVAR estimator.
 - Combination of non-Gaussian SVAR with potentially invalid proxy variables.
- Evidence on the effects of fiscal policy:
 - Spending multiplier $>$ tax multiplier.
 - Tax proxy is negatively correlated with output shocks.

Structural Vector Autoregression

$$y_t = \sum_{i=1}^p A_i y_{t-i} + u_t \quad \text{and} \quad u_t = B_0 \varepsilon_t$$

Independent non-Gaussian: Lanne et al. (2017), Gouriéroux et al. (2017), Maxand (2020), Keweloh (2021), Hafner et al. (2022), Hafner and Herwartz (2023), Hafner et al. (2023), Herwartz and Wang (2023a), Keweloh (2023), Herwartz and Wang (2024)

Statistical & traditional identification: Bruns and Lütkepohl (2022), Schlaak et al. (2023), Drautzburg and Wright (2023), Keweloh et al. (2023), Herwartz and Wang (2023b), Crucil et al. (2023), Braun (2023), Keweloh (2024), Carriero et al. (2024), Bacchiocchi et al. (2024)

Proxy: Stock and Watson (2012), Mertens and Ravn (2013), Angelini and Fanelli (2019), Caldara and Herbst (2019), Braun and Brüggemann (2022), Jentsch and Lunsford (2022)

Proxy variable

A proxy variable z_t for a target shock ε_{1t} is valid if

1. Relevant: $E[z_t \varepsilon_{1t}] \neq 0$
2. Exogenous: $E[z_t \varepsilon_{jt}] = 0$ for $j \neq 1$

Proxy SVAR approaches

| | Frequentist | Bayesian |
|-------------------------|-----------------------------|---------------------------|
| Augmented Proxy SVAR | Angelini and Fanelli (2019) | Caldara and Herbst (2019) |
| Moment-Based Proxy SVAR | Mertens and Ravn (2013) | ? |

Linear proxy variable

A linear proxy $z_t = \Phi \varepsilon_t + \eta_t$ with $\eta_t \sim N(0, \sigma^2)$ for a target shock ε_{1t} is valid if

1. Relevant: $E[z_t \varepsilon_{1t}] \neq 0 \iff \Phi_1 \neq 0$
2. Exogenous: $E[z_t \varepsilon_{jt}] = 0$ for $j \neq 1 \iff \Phi = [\Phi_1, 0, \dots, 0]$

Augmented proxy SVAR estimator

The augment proxy SVAR can be written as

$$\begin{bmatrix} y_t \\ z_t \end{bmatrix} = \dots + \begin{bmatrix} B_0 & 0 \\ \Phi & 1 \end{bmatrix} \begin{bmatrix} \varepsilon_t \\ \eta_t \end{bmatrix}, \quad (1)$$

see Caldara and Herbst (2019) or Angelini and Fanelli (2019).

Critique: The augmented proxy approach specifies the proxy DGP. Misspecification of the proxy DGP can lead to dependent shocks in the SVAR:

For a non-linear proxy variable generated by $z_t = \psi_t(\tilde{\Phi}_i \varepsilon_{it} + \tilde{\eta}_t)$ where ψ_t is a Bernoulli random variable, the misspecified linear augmented proxy SVAR with the linear proxy specification $z_t = \Phi_i \varepsilon_{it} + \eta_t$ leads to a measurement error

$$\eta_t = \begin{cases} (\tilde{\Phi}_i - \Phi_i) \varepsilon_{it} + \tilde{\eta}_t & , \text{ if } \psi_t = 1 \\ -\Phi_i \varepsilon_{it} & , \text{ else} \end{cases}.$$

Observation: The frequentist moment-based proxy approach does not rely on specifying the DGP of the proxy, see Mertens and Ravn (2013).

Goal: Develop a Bayesian moment-based proxy estimator not rely on specifying the DGP of the proxy.

Bayesian augmented proxy SVAR estimator

Caldara and Herbst (2019) write the joint likelihood of the data y and the proxy z as

$$p(y, z|B) = p(y|B)p(z|y, B). \quad (2)$$

The conditional likelihood of the proxy $p(z|y, B)$ is derived from the augmented proxy equation $z_t = \Phi_i \varepsilon_{it} + \eta_t$ and the distribution of the proxy noise term η_t .

Intuition: Re-weights the likelihood of the data y by putting more weight to the parameters that result in target shocks equal to a scaled version of the proxy.

Bayesian moment-based proxy SVAR (for simplification $n = 2$)

Define the proxy exogeneity moment condition

$$D(z, y, B) = \frac{1}{\sqrt{T}} \sum_{t=1}^T z_t e_{2t}(B) \quad \text{with} \quad e_t(B) := B^{-1} u_t. \quad (3)$$

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The joint likelihood of the data y and the proxy exogeneity moment condition $D(z)$ is

$$p(y, D(z)|B) = p(y|B)p(D(z)|y, B). \quad (4)$$

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$$p(y, D(z)|B) = p(y|B)p(D(z)|y, B). \quad (4)$$

The conditional likelihood of the proxy moment condition follows from the CLT:

$$D(z)|y, B_0 \sim \mathcal{N}(0, \sigma_z^2) \quad (5)$$

Intuition: Re-weights the likelihood of the data y by giving more weight to parameters that result in non-target shocks that are uncorrelated with the proxy.

Bayesian moment-based (potentially invalid) proxy SVAR (for simplification $n = 2$)

Generalize the proxy exogeneity moment condition

$$D(z, y, B, \mu) = \frac{1}{\sqrt{T}} \sum_{t=1}^T (z_t e_{2t}(B) - \mu) \quad \text{with} \quad e_t(B) := B^{-1} u_t. \quad (6)$$

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The joint likelihood of the data y and the proxy exogeneity moment condition $D(z)$ is

$$p(y, D(z)|B, \mu) = p(y|B)p(D(z)|y, B, \mu). \quad (7)$$

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We propose a prior distribution for μ that reflects the belief in an exogenous proxy

$$\mu \sim N(0, \sigma_\mu^2), \quad \sigma_\mu^2 \sim IG(a, b). \quad (9)$$

Bayesian non-Gaussian SVAR

Anttonen et al. (2023): Independent and non-Gaussian shocks ε_{it} with density $f_i(\varepsilon_{it}; \lambda_i)$ yield the likelihood

$$p(y|B, \lambda) = |\det(B)|^{-T} \prod_{i=1}^n \prod_{t=1}^T f_i(e_{it}(B, y_t); \lambda_i). \quad (10)$$

We assume that each shock follows a skewed t-distribution such that the density function of the i th shock is given by

$$f_i(\varepsilon_{it}; \lambda_i, q_i) = \frac{\Gamma(0.5 + q_i)}{v(\pi q_i)^{0.5} \Gamma(q_i) \left(\frac{|\varepsilon_{it} + m|^2}{q_i v^2 (\lambda \text{sign}(\varepsilon_{it} + m) + 1)^2} \right)^{0.5 + q_i}}. \quad (11)$$

Summary: We combine a non-Gaussian SVAR with potentially invalid proxies.

Why?

- In a non-Gaussian SVAR with independent shocks, proxy variables are not required for identification.
- Our goal is to leverage prior knowledge of an exogenous proxy to enhance estimation precision.
- At the same time, we remain flexible and can disregard the proxy if the data provide evidence against its exogeneity.

Finite sample performance

$$\begin{bmatrix} u_{g,t} \\ u_{y,t} \\ u_{\tau,t} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0.15 & 1 & -0.5 \\ 0 & 1.5 & 1 \end{bmatrix} \begin{bmatrix} \varepsilon_{g,t} \\ \varepsilon_{y,t} \\ \varepsilon_{\tau,t} \end{bmatrix}. \quad (12)$$

The variable z_t is a proxy variable for $\varepsilon_{\tau,t}$. We consider two scenarios:

1. Exogenous proxy: $z_t = \varepsilon_{\tau,t} + \eta_t$
2. Endogenous proxy: $z_t = \varepsilon_{\tau,t} - 0.37\varepsilon_{y,t} + \eta_t$

Table 1: Median and MSE of estimated impact of $\varepsilon_{\tau t}$ ($T = 250$).

| | exogenous proxy $z_{\tau t} = \varepsilon_{\tau t} + \eta_t$ | endogenous proxy $z_{\tau t} = \varepsilon_{\tau t} - 0.37\varepsilon_{Yt} + \eta_t$ |
|-------------------|---|---|
| proxy (augmented) | $\begin{bmatrix} 0.00 & -0.50 & 1.00 \\ (0.008) & (0.009) & (0.022) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.81 & 0.42 \\ (0.008) & (0.106) & (0.363) \end{bmatrix}'$ |

Note: The true impact of the shock $\varepsilon_{\tau t}$ is $\begin{bmatrix} 0 & -0.5 & 1 \end{bmatrix}'$.

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| non-Gaussian | $\begin{bmatrix} 0.00 & -0.49 & 0.95 \\ (0.017) & (0.021) & (0.051) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.48 & 0.95 \\ (0.018) & (0.019) & (0.046) \end{bmatrix}'$ |

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| non-Gaussian proxy moment | $\begin{bmatrix} 0.00 & -0.50 & 1.00 \\ (0.007) & (0.009) & (0.021) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.59 & 0.82 \\ (0.009) & (0.026) & (0.081) \end{bmatrix}'$ |

Note: The true impact of the shock $\varepsilon_{\tau t}$ is $\begin{bmatrix} 0 & -0.5 & 1 \end{bmatrix}'$.

Table 2: Median and MSE of estimated impact of $\varepsilon_{\tau t}$ ($T = 800$).

| | exogenous proxy $z_{\tau t} = \varepsilon_{\tau t} + \eta_t$ | endogenous proxy $z_{\tau t} = \varepsilon_{\tau t} - 0.37\varepsilon_{y_t} + \eta_t$ |
|------------------------------|---|--|
| proxy (augmented) | $\begin{bmatrix} 0.00 & -0.50 & 1.00 \\ (0.002) & (0.003) & (0.007) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.82 & 0.41 \\ (0.002) & (0.103) & (0.355) \end{bmatrix}'$ |
| proxy (moments) | $\begin{bmatrix} 0.00 & -0.50 & 1.00 \\ (0.002) & (0.003) & (0.007) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.82 & 0.41 \\ (0.002) & (0.102) & (0.353) \end{bmatrix}'$ |
| non-Gaussian | $\begin{bmatrix} 0.00 & -0.49 & 0.99 \\ (0.005) & (0.005) & (0.012) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.49 & 0.99 \\ (0.005) & (0.005) & (0.012) \end{bmatrix}'$ |
| non-Gaussian proxy moment | $\begin{bmatrix} 0.00 & -0.50 & 1.00 \\ (0.002) & (0.003) & (0.006) \end{bmatrix}'$ | $\begin{bmatrix} 0.00 & -0.52 & 0.96 \\ (0.003) & (0.006) & (0.017) \end{bmatrix}'$ |

Note: The true impact of the shock $\varepsilon_{\tau t}$ is $\begin{bmatrix} 0 & -0.5 & 1 \end{bmatrix}'$.

The Effects of Fiscal Policy

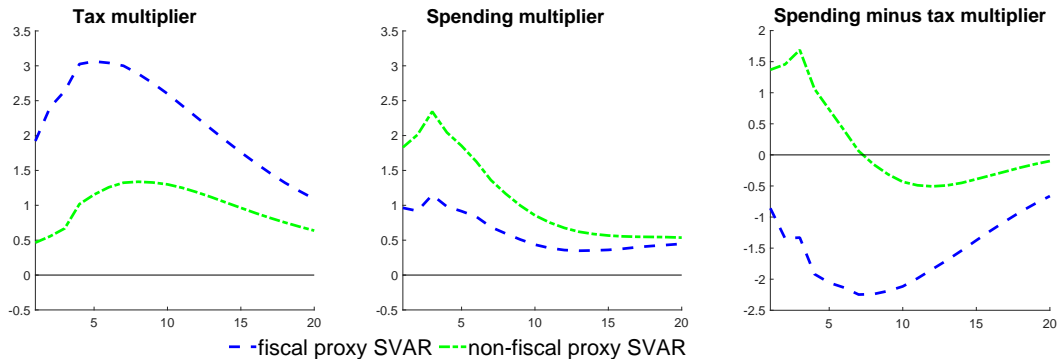
Quarterly data from 1950 to 2006 analogous to Mertens and Ravn (2014) with

$$\begin{bmatrix} \tau_t \\ g_t \\ y_t \end{bmatrix} = \gamma X_t + \sum_{i=1}^4 A_i \begin{bmatrix} \tau_{t-i} \\ g_{t-i} \\ y_{t-i} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix} \begin{bmatrix} \varepsilon_{\tau,t} \\ \varepsilon_{g,t} \\ \varepsilon_{y,t} \end{bmatrix}$$

Proxies:

- Tax proxy $z_{\tau,t}$ used in fiscal proxy VAR in Mertens and Ravn (2014):
 $E[z_{\tau,t}\varepsilon_{g,t}] = 0$ and $E[z_{\tau,t}\varepsilon_{y,t}] = 0$
- TFP proxy $z_{y,t}$ used in non-fiscal proxy VAR in Caldara and Kamps (2017):
 $E[z_{y,t}\varepsilon_{\tau,t}] = 0$ and $E[z_{y,t}\varepsilon_{g,t}] = 0$
- Military spending $z_{g,t}$ proxy for spending shocks:
 $E[z_{g,t}\varepsilon_{\tau,t}] = 0$ and $E[z_{g,t}\varepsilon_{y,t}] = 0$

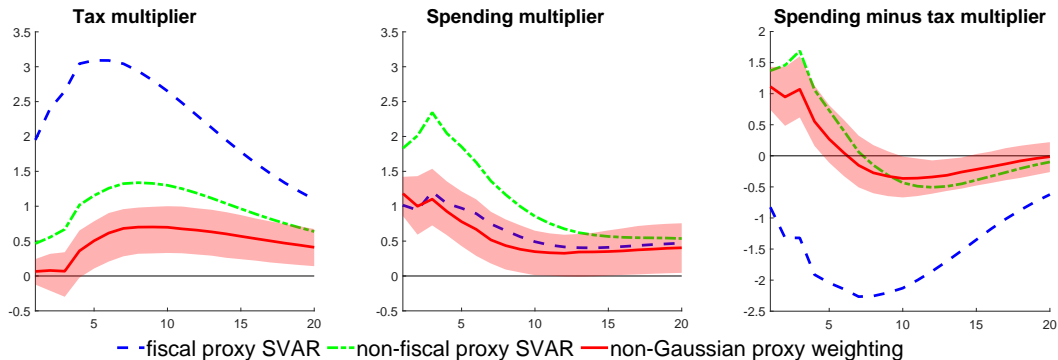
Figure 1: Output multipliers



Fiscal proxy VAR: Gaussian SVAR with the tax proxy and $b_{23} = 0$

Non-fiscal proxy VAR: Gaussian SVAR with the TFP proxy and $b_{21} = 0$

Figure 2: Comparison of output multipliers



Fiscal proxy VAR: Gaussian SVAR with the tax proxy and $b_{23} = 0$

Non-fiscal proxy VAR: Gaussian SVAR with the TFP proxy and $b_{21} = 0$

Non-Gaussian proxy weighting: Non-Gaussian SVAR with three proxies and shrinkage

Figure 3: Posterior of the exogeneity moment conditions

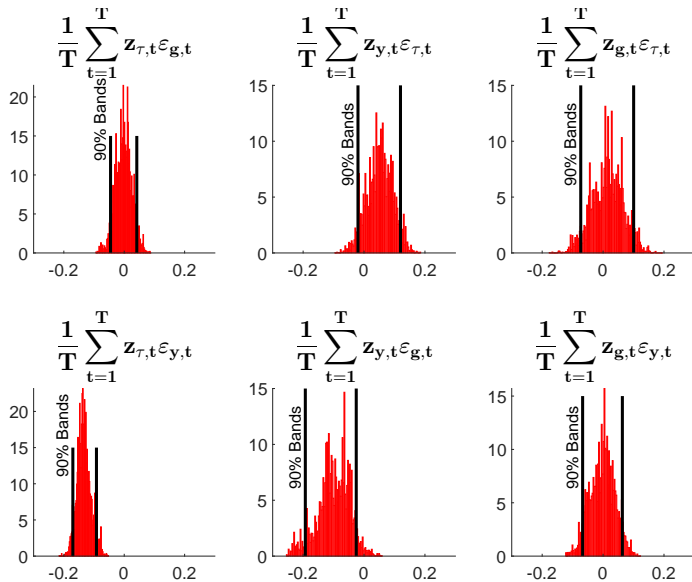
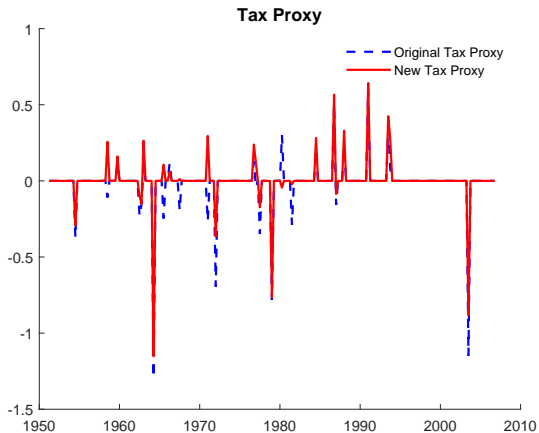
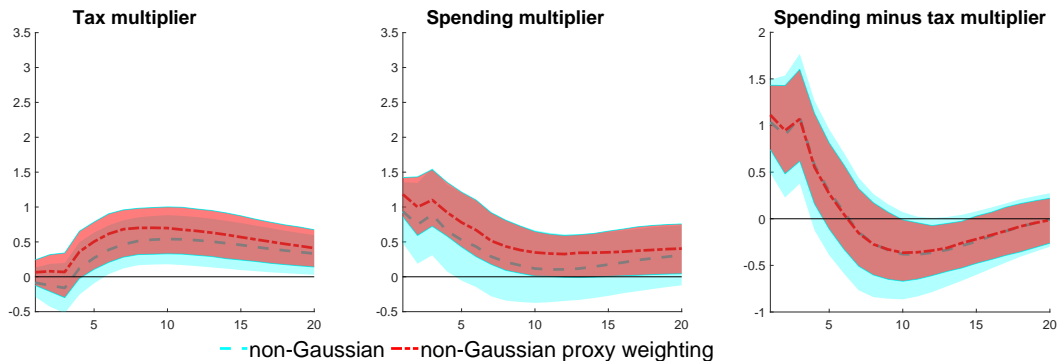


Figure 4: New tax proxy



Note: The new tax proxy is the residual of the regression $z_{\tau,t} = \beta_0 + \beta_1 \varepsilon_{g,t} + \beta_2 \varepsilon_{y,t} + u_t$.

Figure 5: Comparison of output multipliers



Non-Gaussian VAR: Non-Gaussian SVAR without proxies

Non-Gaussian proxy weighting: Non-Gaussian SVAR with three proxies and shrinkage

Summary

- Question: How can we deal with potentially invalid proxies?
→ We propose a novel approach to include potentially invalid proxies into a Bayesian non-Gaussian SVAR using a shrinkage approach. Including valid proxies increases the performance of the non-Gaussian estimator.
- Question: Which proxy is valid / what is the spending and tax multiplier?
→ We find that increasing government spending is a more effective tool to stimulate the economy than reducing taxes. We find that the tax proxy is negatively correlated with output shocks and the TFP proxy is negatively correlated with government spending shocks.

Thank you!

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