

Non-Gaussian Structural Vector Autoregressions

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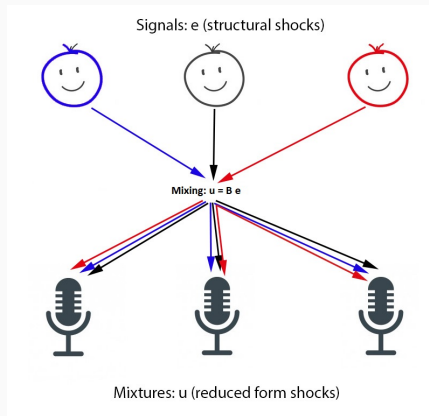
Structural Vector Autoregression

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}$$

In matrix notation:

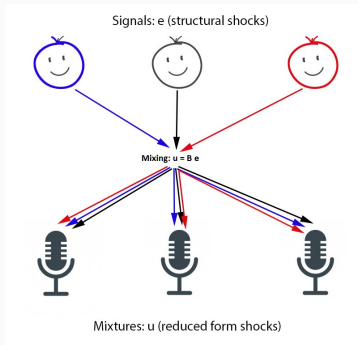
$$\underbrace{u}_{\text{observed mixtures}} = \underbrace{B_0}_{\text{mixing matrix}} \underbrace{\epsilon}_{\text{signals}}$$

The Cocktail-Party-Problem



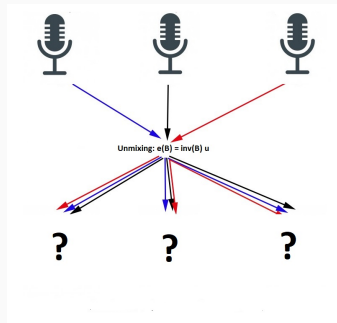
Structural Vector Autoregression

$$u = B_0 \epsilon$$



Unmixed innovations

$$e_t(B) := B^{-1} u_t \quad (1)$$



Recursive SVAR

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ b_{21} & 1 & 0 \\ b_{31} & b_{32} & 1 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}$$

Assumptions:

Mixing B_0 is recursive

Shocks ϵ are uncorrelated

Moment conditions

$$E[e_1(B)e_2(B)] = 0$$

$$E[e_1(B)e_3(B)] = 0$$

$$E[e_2(B)e_3(B)] = 0$$

Identified ✓



Keweloh, Sascha. "A Generalized Method of Moments Estimator for Structural Vector Autoregressions Based on Higher Moments." *Journal of Business & Economic Statistics* (2019)

Non-Recursive SVAR

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 1 & b_{12} & b_{13} \\ b_{21} & 1 & b_{23} \\ b_{31} & b_{32} & 1 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}$$

Assumptions:

Shocks ϵ are independent

Shocks ϵ are non-Gaussian

Moment conditions

$$\begin{aligned} E[e_1^2(B)e_2(B)] &= 0 \\ E[e_1(B)e_2^2(B)] &= 0 \\ E[e_1(B)e_2(B)] &= 0 \\ E[e_1(B)e_3(B)] &= 0 \\ E[e_2(B)e_3(B)] &= 0 \\ E[e_1^2(B)e_3(B)] &= 0 \\ E[e_1(B)e_3^2(B)] &= 0 \\ E[e_2^2(B)e_3(B)] &= 0 \\ E[e_2(B)e_3^2(B)] &= 0 \\ E[e_1(B)e_2(B)e_3(B)] &= 0 \end{aligned}$$

Identified ✓



Keweloh, "Block-Recursive SVARs."

Block-Recursive SVAR

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ b_{21} & 1 & b_{23} \\ b_{31} & b_{32} & 1 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}$$

Assumptions:

Shocks ϵ are independent

Shocks ϵ are non-Gaussian

Moment conditions

$$E[e_1(B)e_2(B)] = 0$$

$$E[e_1(B)e_3(B)] = 0$$

$$E[e_2(B)e_3(B)] = 0$$

~~$$E[e_1^2(B)e_2(B)] = 0$$~~

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~~$$E[e_1^2(B)e_3(B)] = 0$$~~

~~$$E[e_1(B)e_3^2(B)] = 0$$~~

$$E[e_2^2(B)e_3(B)] = 0$$

$$E[e_2(B)e_3^2(B)] = 0$$

~~$$E[e_1(B)e_2(B)e_3(B)] = 0$$~~

Identified ✓



Simulated recursive SVAR

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0.5 & 1 & 0 & 0 \\ 0.5 & 0.5 & 1 & 0 \\ 0.5 & 0.5 & 0.5 & 1 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \end{bmatrix}$$

$\varepsilon_i = z\phi_1 + (1 - z)\phi_2$ with $\phi_1 \sim \mathcal{N}(-0.2, 0.7)$, $\phi_2 \sim \mathcal{N}(0.75, 1.5)$, $z \sim \mathcal{B}(0.79)$,

$\mathcal{B}(p)$ indicates a Bernoulli distribution and $\mathcal{N}(\mu, \sigma^2)$ indicates a normal distribution. The structural shocks have mean zero, unit variance, skewness equal to 0.91 and an excess kurtosis of 2.51.



Keweloh "Block-Recursive SVARs."

	Non-Recursive SVAR w. higher moments	Recursive SVAR w. second moments (Cholesky)
<i>Limit</i> (<i>Avar</i>)	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.033) & (2.450) & (2.450) & (2.450) \\ 0.5 & 1 & 0 & 0 \\ (2.585) & (1.522) & (3.192) & (3.192) \\ 0.5 & 0.5 & 1 & 0 \\ (3.265) & (3.265) & (2.076) & (3.999) \\ 0.5 & 0.5 & 0.5 & 1 \\ (4.010) & (4.010) & (4.010) & (2.695) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.128) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.282) & (1.128) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.532) & (1.282) & (1.128) & (0) \\ 0.5 & 0.5 & 0.5 & 1 \\ (1.782) & (1.532) & (1.282) & (1.128) \end{bmatrix}$



Keweloh, Seepe "Monetary policy and the stock market"

$$\begin{array}{llll} \text{output} & \rightarrow & u_t^y & \\ \text{investment} & \rightarrow & u_t^I & \\ \text{inflation} & \rightarrow & u_t^\pi & \\ \text{federal funds rate} & \rightarrow & u_t^i & \\ \text{real stock returns} & \rightarrow & u_t^s & \end{array} = \begin{bmatrix} b_{11} & b_{12} & b_{13} & 0 & 0 \\ b_{21} & b_{22} & b_{23} & 0 & 0 \\ b_{31} & b_{32} & b_{33} & 0 & 0 \\ b_{41} & b_{42} & b_{43} & b_{44} & b_{45} \\ b_{51} & b_{52} & b_{53} & b_{54} & b_{55} \end{bmatrix} \begin{bmatrix} \varepsilon_t^y \\ \varepsilon_t^I \\ \varepsilon_t^\pi \\ \varepsilon_t^s \\ \varepsilon_t^i \end{bmatrix}, \quad (2)$$



Keweloh, Seepe "Monetary policy and the stock market"

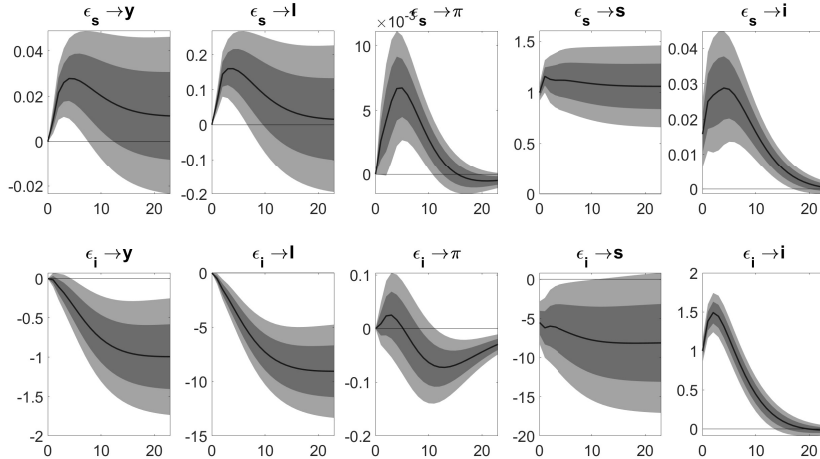


Figure 1:



Block-Recursive SVAR

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ b_{21} & 1 & 0 \\ b_{31} & b_{32} & 1 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \end{bmatrix}$$

Moment conditions

$$E[e_1(B)e_2(B)] = 0$$

$$E[e_1(B)e_3(B)] = 0$$

$$E[e_2(B)e_3(B)] = 0$$

Moment conditions

$$E[e_1^2(B)e_2(B)] = 0$$

$$E[e_1(B)e_2^2(B)] = 0$$

$$E[e_1(B)e_2(B)] = 0$$

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$$E[e_1(B)e_3(B)] = 0$$

$$E[e_1(B)e_3^2(B)] = 0$$

$$E[e_2(B)e_3(B)] = 0$$

$$E[e_2^2(B)e_3(B)] = 0$$

$$E[e_2(B)e_3^2(B)] = 0$$

$$E[e_1(B)e_2(B)e_3(B)] = 0$$

Question:

Are higher moments non-redundant?



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Are higher moments non-redundant?

Proposition

In a block-recursive SVAR with non-Gaussian and independent shocks, higher moments are non-redundant.

Corollary

In a non-Gaussian recursive SVAR with independent shocks, the frequently used estimator obtained by applying the Cholesky decomposition to the variance covariance matrix of the reduced form shocks is inefficient.



Keweloh "Block-Recursive SVARs."

Asymptotic performance

	Recursive SVAR w. second moments (Cholesky)	Recursive SVAR w. higher moments
<i>Limit</i> (<i>Avar</i>)	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.128) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.282) & (1.128) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.532) & (1.282) & (1.128) & (0) \\ 0.5 & 0.5 & 0.5 & 1 \\ (1.782) & (1.532) & (1.282) & (1.128) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.021) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.033) & (1.019) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.232) & (1.033) & (1.017) & (0) \\ 0.5 & 0.5 & 0.5 & 1 \\ (1.438) & (1.232) & (1.033) & (1.016) \end{bmatrix}$



Keweloh "Block-Recursive SVARs."

Small sample performance - Many moments problem

T=150	Recursive SVAR w. second moments (Cholesky)				Recursive SVAR w. higher moments 2-step			
<i>mean</i> (<i>std</i>)	1	0	0	0	0.95	0	0	0
	(1.138)	(0)	(0)	(0)	(7.50)	(0)	(0)	(0)
	0.5	1	0	0	0.47	1.00	0	0
	(1.300)	(1.048)	(0)	(0)	(49.2)	(828)	(0)	(0)
	0.5	0.5	1	0	-19.9	-26.2	158	0
	(1.499)	(1.263)	(1.126)	(0)	(-)	(-)	(-)	(0)
	0.5	0.5	0.5	0.99	-287	31	-145	506
	(1.784)	(1.539)	(1.275)	(1.096)	(-)	(-)	(-)	(-)



Keweloh "Block-Recursive SVARs."

Optimal weighting

The GMM estimator with $W = S^{-1}$ has the smallest asymptotic variance.

$$S = E \left[\begin{bmatrix} e_1(B_0)e_2(B_0) \\ e_1(B_0)e_3(B_0) \\ e_2(B_0)e_3(B_0) \\ \vdots \end{bmatrix} \begin{bmatrix} e_1(B_0)e_2(B_0) \\ e_1(B_0)e_3(B_0) \\ e_2(B_0)e_3(B_0) \\ \vdots \end{bmatrix}' \right] \quad (3)$$

$$\rightarrow \hat{S}_T = \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} e_{1,t}(\hat{B})e_{2,t}(\hat{B}) \\ e_{1,t}(\hat{B})e_{3,t}(\hat{B}) \\ e_{2,t}(\hat{B})e_{3,t}(\hat{B}) \\ \vdots \end{bmatrix} \begin{bmatrix} e_{1,t}(\hat{B})e_{2,t}(\hat{B}) \\ e_{1,t}(\hat{B})e_{3,t}(\hat{B}) \\ e_{2,t}(\hat{B})e_{3,t}(\hat{B}) \\ \vdots \end{bmatrix}' \quad (4)$$



Keweloh "Block-Recursive SVARs."

The true mixing matrix B_0 is unknown, but a B_0 it holds: $e(B_0) = \epsilon$

$$S = E \left[\begin{bmatrix} \epsilon_1 \epsilon_2 \\ \epsilon_1 \epsilon_3 \\ \epsilon_2 \epsilon_3 \\ \epsilon_1^2 - 1 \\ \vdots \end{bmatrix} \begin{bmatrix} \epsilon_1 \epsilon_2 \\ \epsilon_1 \epsilon_3 \\ \epsilon_2 \epsilon_3 \\ \epsilon_1^2 - 1 \\ \vdots \end{bmatrix}' \right] \stackrel{\epsilon \text{ independent}}{=} \begin{bmatrix} 1 & 0 & 0 & 0 & \dots \\ 0 & 1 & 0 & 0 & \dots \\ 0 & 0 & 1 & 0 & \dots \\ 0 & 0 & 0 & E[\epsilon_1^4] - 1 & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix} \quad (5)$$

Parametric estimator

$\hat{S}_T^{para} \rightarrow$ use (5) and replace values like $E[\epsilon_1^4]$ with estimates $1/T \sum_{t=1}^T e_1(\hat{B}^4)$.

If ϵ has mutually independent components with zero mean and unit variance, it holds that

$$\hat{S}_T^{para} \xrightarrow[T \rightarrow \infty]{} S.$$



(6)

Keweloh "Block-Recursive SVARs."

Small sample performance - Many moments problem (Solution part 1)

T=150	Recursive SVAR w. second moments (Cholesky)				Recursive SVAR w. higher moments 2-step parametric			
<i>mean</i> (<i>std</i>)	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.138) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.300) & (1.048) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.499) & (1.263) & (1.126) & (0) \\ 0.5 & 0.5 & 0.5 & 0.99 \\ (1.784) & (1.539) & (1.275) & (1.096) \end{bmatrix}$				$\begin{bmatrix} 1.14 & 0 & 0 & 0 \\ (2.609) & (0) & (0) & (0) \\ 0.57 & 1.13 & 0 & 0 \\ (1.914) & (2.687) & (0) & (0) \\ 0.57 & 0.56 & 1.12 & 0 \\ (2.157) & (1.785) & (2.289) & (0) \\ 0.56 & 0.56 & 0.56 & 1.12 \\ (2.686) & (2.204) & (1.786) & (2.307) \end{bmatrix}$			



Keweloh "Block-Recursive SVARs."

Small sample performance - Many moments problem (Solution part 2)

T=150	Recursive SVAR w. second moments (Cholesky)				Recursive SVAR w. higher moments 2-step parametric (scaled)			
<i>mean</i> (<i>std</i>)	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.138) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.300) & (1.048) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.499) & (1.263) & (1.126) & (0) \\ 0.5 & 0.5 & 0.5 & 0.99 \\ (1.784) & (1.539) & (1.275) & (1.096) \end{bmatrix}$				$\begin{bmatrix} 1.00 & 0 & 0 & 0 \\ (1.136) & (0) & (0) & (0) \\ 0.50 & 1.00 & 0 & 0 \\ (1.209) & (1.051) & (0) & (0) \\ 0.50 & 0.50 & 1.00 & 0 \\ (1.414) & (1.185) & (1.131) & (0) \\ 0.50 & 0.50 & 0.50 & 0.99 \\ (1.726) & (1.478) & (1.208) & (1.104) \end{bmatrix}$			







Keweloh, Hetzenecker "Soft restrictions in SVARs via Lasso"

T=5000	Recursive SVAR w. second moments (Cholesky)	non-Recursive SVAR w. higher moments	Soft-Restrictions SVAR w. higher moments (Lasso)
	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.1) & (0) & (0) & (0) \\ 0.5 & 1 & 0 & 0 \\ (1.3) & (1.1) & (0) & (0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.5) & (1.3) & (1.1) & (0) \\ 0.5 & 0.5 & 0.5 & 1 \\ (1.8) & (1.5) & (1.3) & (1.1) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.0) & (2.7) & (2.6) & (2.6) \\ 0.5 & 1 & 0 & 0 \\ (2.7) & (1.6) & (3.4) & (3.6) \\ 0.5 & 0.5 & 1 & 0 \\ (3.4) & (3.4) & (2.2) & (4.4) \\ 0.5 & 0.5 & 0.5 & 1 \\ (4.2) & (4.3) & (4.4) & (2.9) \end{bmatrix}$	$\begin{bmatrix} 1 & 0 & 0 & 0 \\ (1.0) & (0.1) & (0.1) & (0.1) \\ 0.5 & 1 & 0 & 0 \\ (1.1) & (1.1) & (0.1) & (0.0) \\ 0.5 & 0.5 & 1 & 0 \\ (1.4) & (1.3) & (1.0) & (0.1) \\ 0.5 & 0.5 & 0.5 & 1 \\ (1.6) & (1.3) & (1.2) & \end{bmatrix}$

mean
(*std*)



References
