

# **Cyclone III Device Handbook, Volume 2**



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# **Contents**



About this Handbook	About–1
How to Contact Altera	About–1
Typographic Conventions	About–1
Chapter 1. Cyclone III Device Data Sheet	
Electrical Characteristics	
Operating Conditions	
Absolute Maximum Ratings	
Recommended Operating Conditions	
DC Characteristics	
I/O Standard Specifications	
Power Consumption	
Switching Characteristics	
Core Performance Specifications	
Clock Tree Specifications	1–15
PLL Specifications	1–15
Embedded Multiplier Specifications	
Memory Block Specifications	
Configuration and JTAG Specifications	
Periphery Performance	
High-Speed I/O Specifications	1–18
External Memory Interface Specifications	
Duty Cycle Distortion Specifications	
OCT Calibration Timing Specification	
IOE Programmable Delay	
I/O Timing	
Glossary	
Document Revision History	
,	
Chapter 2. Cyclone III LS Device Data Sheet	
Electrical Characteristics	
Operating Conditions	
Absolute Maximum Ratings	
Recommended Operating Conditions	
DC Characteristics	
I/O Standard Specifications	
Power Consumption	

Switching Characteristics	2–14
Core Performance Specifications	2–14
Clock Tree Specifications	
PLL Specifications	2–14
Embedded Multiplier Specifications	
Memory Block Specifications	2–16
Configuration and JTAG Specifications	2–16
Periphery Performance	2–17
High-Speed I/O Specification	
External Memory Interface Specifications	2–22
Duty Cycle Distortion Specification	
OCT Calibration Timing Specification	2–24
IOE Programmable Delay	2–24
I/O Timing	
Glossary	
Document Revision History	



# **Chapter Revision Dates**

The chapters in this book, *Cyclone III Device Handbook, Volume 2*, were revised on the following dates. Where chapters or groups of chapters are available separately, part numbers are listed.

Chapter 1 Cyclone III Device Data Sheet

Revised: *December* 2009 Part Number: *CIII52001-3.2* 

Chapter 2 Cyclone III LS Device Data Sheet

Revised: *December* 2009 Part Number: *CIII5*2002-1.2 vi Chapter Revision Dates

# **About this Handbook**



This handbook provides comprehensive information about the Altera® Cyclone® III device family.

# **How to Contact Altera**

For the most up-to-date information about Altera products, refer to the following table.

Contact (1)	Contact Method	Address
Technical support	Website	www.altera.com/support
Technical training	Website	www.altera.com/training
	Email	custrain@altera.com
Product literature	Website	www.altera.com/literature
Altera literature services	Email	literature@altera.com
Non-technical support (General)	Email	nacomp@altera.com
(Software Licensing)	Email	authorization@altera.com

#### Note to table:

(1) You can also contact your local Altera sales office or sales representative.

# **Typographic Conventions**

This document uses the typographic conventions shown below.

Visual Cue	Meaning
Bold Type with Initial Capital Letters	Command names, dialog box titles, checkbox options, and dialog box options are shown in bold, initial capital letters. Example: <b>Save As</b> dialog box.
bold type	External timing parameters, directory names, project names, disk drive names, filenames, filename extensions, and software utility names are shown in bold type. Examples: f <sub>MAX</sub> , \qdesigns directory, d: drive, chiptrip.gdf file.
Italic Type with Initial Capital Letters	Document titles are shown in italic type with initial capital letters. Example: AN 75: High-Speed Board Design.
Italic type	Internal timing parameters and variables are shown in italic type. Examples: <i>tPIA</i> , <i>n</i> + 1.
	Variable names are enclosed in angle brackets (< >) and shown in italic type. Example: <file name="">, <pre>, <pre>, <pre>pof</pre> file.</pre></pre></file>
Initial Capital Letters	Keyboard keys and menu names are shown with initial capital letters. Examples: Delete key, the Options menu.
"Subheading Title"	References to sections in a document and titles of on-line help topics are shown in quotation marks. Example: "Typographic Conventions."

Visual Cue	Meaning
Courier type	Signal and port names are shown in lowercase Courier type. Examples: $\mathtt{data1}$ , $\mathtt{tdi}$ , $\mathtt{input}$ . Active-low signals are denoted by $\mathtt{suffix}$ n, e.g., $\mathtt{resetn}$ .
	Anything that must be typed exactly as it appears is shown in Courier type. For example: c:\qdesigns\tutorial\chiptrip.gdf. Also, sections of an actual file, such as a Report File, references to parts of files (e.g., the AHDL keyword SUBDESIGN), as well as logic function names (e.g., TRI) are shown in Courier.
1., 2., 3., and a., b., c., etc.	Numbered steps are used in a list of items when the sequence of the items is important, such as the steps listed in a procedure.
• •	Bullets are used in a list of items when the sequence of the items is not important.
✓	The checkmark indicates a procedure that consists of one step only.
_	The hand points to information that requires special attention.
CAUTION	The caution indicates required information that needs special consideration and understanding and should be read prior to starting or continuing with the procedure or process.
WARNING	The warning indicates information that should be read prior to starting or continuing the procedure or processes.
+	The angled arrow indicates you should press the Enter key.
•••	The feet direct you to more information on a particular topic.



# Section 1. Cyclone III Device Data Sheet

This section includes the following chapter:

- Chapter 1, Cyclone III Device Data Sheet
- Chapter 2, Cyclone III LS Device Data Sheet

# **Revision History**

Refer to each chapter for its own specific revision history. For information on when each chapter was updated, refer to the Chapter Revision Dates section, which appears in the complete handbook.

# 1. Cyclone III Device Data Sheet

CIII52001-3.2

This chapter describes the electric characteristics, switching characteristics, and I/O timing for Cyclone<sup>®</sup> III devices. A glossary is also included for your reference.

# **Electrical Characteristics**

The following sections provide information about the absolute maximum ratings, recommended operating conditions, DC characteristics, and other specifications for Cyclone III devices.

# **Operating Conditions**

When Cyclone III devices are implemented in a system, they are rated according to a set of defined parameters. To maintain the highest possible performance and reliability of Cyclone III devices, system designers must consider the operating requirements in this document. Cyclone III devices are offered in commercial, industrial, and automotive grades. Commercial devices are offered in –6 (fastest), –7, and –8 speed grades. Industrial and automotive devices are offered only in –7 speed grade.



In this chapter, a prefix associated with the operating temperature range is attached to the speed grades; commercial with "C" prefix, industrial with "I" prefix, and automotive with "A" prefix. Commercial devices are therefore indicated as C6, C7, and C8 per respective speed grades. Industrial and automotive devices are indicated as I7 and A7, respectively.

#### **Absolute Maximum Ratings**

Absolute maximum ratings define the maximum operating conditions for Cyclone III devices. The values are based on experiments conducted with the device and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied at these conditions. Table 1–1 lists the absolute maximum ratings for Cyclone III devices.



Conditions beyond those listed in Table 1–1 cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time has adverse effects on the device.

**Table 1–1.** Cyclone III Devices Absolute Maximum Ratings (Note 1) (Part 1 of 2)

Symbol	Parameter	Min	Max	Unit
V <sub>CCINT</sub>	Supply voltage for internal logic	-0.5	1.8	V
V <sub>CCIO</sub>	Supply voltage for output buffers	-0.5	3.9	V
V <sub>CCA</sub>	Supply voltage (analog) for phase-locked loop (PLL) regulator	-0.5	3.75	V
V <sub>CCD_PLL</sub>	Supply voltage (digital) for PLL	-0.5	1.8	V
Vı	DC input voltage	-0.5	3.95	V

Symbol	Parameter	Min	Max	Unit	
I <sub>OUT</sub>	DC output current, per pin	-25	40	mA	
V <sub>ESDHBM</sub>	Electrostatic discharge voltage using the human body model	_	±2000	V	
V <sub>ESDCDM</sub>	Electrostatic discharge voltage using the charged device model	_	±500	V	
T <sub>STG</sub>	Storage temperature	-65	150	°C	
T <sub>J</sub>	Operating junction temperature	-40	125	°C	

**Table 1–1.** Cyclone III Devices Absolute Maximum Ratings (*Note 1*) (Part 2 of 2)

#### Note to Table 1-1:

#### **Maximum Allowed Overshoot or Undershoot Voltage**

During transitions, input signals may overshoot to the voltage listed in Table 1–2 and undershoot to –2.0 V for a magnitude of currents less than 100 mA and for periods shorter than 20 ns. Table 1–2 lists the maximum allowed input overshoot voltage and the duration of the overshoot voltage as a percentage over the lifetime of the device. The maximum allowed overshoot duration is specified as percentage of high-time over the lifetime of the device.



A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.2~V can only be at 4.2~V for 10.74% over the lifetime of the device; for device lifetime of 10~v years, this amounts to 10.74/10ths of a year.

<sup>(1)</sup> Supply voltage specifications apply to voltage readings taken at the device pins with respect to ground, not at the power supply.

**Table 1–2.** Cyclone III Devices Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame (Note 1)

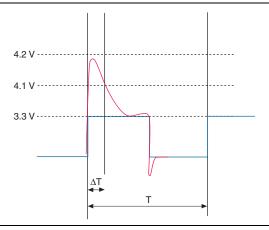
Symbol	Parameter	Condition	Overshoot Duration as % of High Time	Unit	
		V <sub>1</sub> = 3.95 V	100	%	
		V <sub>1</sub> = 4.0 V	95.67	%	
		V <sub>1</sub> = 4.05 V	55.24	%	
		V <sub>1</sub> = 4.10 V	31.97	%	
		V <sub>1</sub> = 4.15 V	18.52	%	
		V <sub>1</sub> = 4.20 V	10.74	%	
W	AC Input	V <sub>1</sub> = 4.25 V	6.23	%	
$V_{i}$	Voltage	V <sub>1</sub> = 4.30 V	3.62	%	
		V <sub>1</sub> = 4.35 V	2.1	%	
		V <sub>1</sub> = 4.40 V	1.22	%	
		V <sub>1</sub> = 4.45 V	0.71	%	
		V <sub>1</sub> = 4	V <sub>1</sub> = 4.50 V	0.41	%
		V <sub>1</sub> = 4.60 V	0.14	%	
		V <sub>1</sub> = 4.70 V	0.047	%	

#### Note to Table 1-2:

<sup>(1)</sup> Figure 1–1 shows the methodology to determine the overshoot duration. In the example in Figure 1–1, overshoot voltage is shown in red and is present on the input pin of the Cyclone III device at over 4.1 V but below 4.2 V. From Table 1–1, for an overshoot of 4.1 V, the percentage of high time for the overshoot can be as high as 31.97% over a 10-year period. Percentage of high time is calculated as ([delta T]/T) × 100. This 10-year period assumes the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

Figure 1–1 shows the methodology to determine the overshoot duration.

Figure 1–1. Cyclone III Devices Overshoot Duration



## **Recommended Operating Conditions**

This section lists the functional operation limits for AC and DC parameters for Cyclone III devices. The steady-state voltage and current values expected from Cyclone III devices are provided in Table 1–3. All supplies must be strictly monotonic without plateaus.

**Table 1–3.** Cyclone III Devices Recommended Operating Conditions (Note 1), (2) (Part 1 of 2)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CCINT</sub> (3)	Supply voltage for internal logic	_	1.15	1.2	1.25	V
	Supply voltage for output buffers, 3.3-V operation	_	3.135	3.3	3.465	V
	Supply voltage for output buffers, 3.0-V operation	_	2.85	3	3.15	V
V <sub>ccio</sub> (3), (4)	Supply voltage for output buffers, 2.5-V operation	_	2.375	2.5	2.625	V
V <sub>CCIO</sub> (3), (4)	Supply voltage for output buffers, 1.8-V operation	_	1.71	1.8	1.89	V
	Supply voltage for output buffers, 1.5-V operation	1	1.425	1.5	1.575	V
	Supply voltage for output buffers, 1.2-V operation	1	1.14	1.2	1.26	V
V <sub>CCA</sub> (3)	Supply (analog) voltage for PLL regulator	_	2.375	2.5	2.625	V
V <sub>CCD_PLL</sub> (3)	Supply (digital) voltage for PLL	_	1.15	1.2	1.25	V
Vi	Input voltage	_	-0.5	_	3.6	V
Vo	Output voltage	_	0	_	V <sub>ccio</sub>	V

<b>Table 1–3.</b> Cyclone III Devices Recommended Operating Conditions (Note 1), (2) (Part 2 of 2)	Table 1-3. (	Cyclone III Devices	Recommended Ope	erating Conditions	(Note 1), (2)	(Part 2 of 2)
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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
		For commercial use	0	_	85	°C
TJ		For industrial use	-40	_	100	°C
	Operating junction temperature	For extended temperature (5)	-40	_	125	°C
		For automotive use	-40	_	125	°C
t <sub>RAMP</sub>	Power supply ramp time	Standard power-on reset (POR) (6)	50 μs	_	50 ms	_
*RAMP		Fast POR (7)	50 μs		3 ms	_
I <sub>Diode</sub>	Magnitude of DC current across PCI-clamp diode when enabled	_	_	_	10	mA

#### Notes to Table 1-3:

- (1) V<sub>CCIO</sub> for all I/O banks must be powered up during device operation. All V<sub>CCA</sub> pins must be powered to 2.5 V (even when PLLs are not used), and must be powered up and powered down at the same time.
- (2)  $V_{CCD\_PLL}$  must always be connected to  $V_{CCINT}$  through a decoupling capacitor and ferrite bead.
- (3) The V<sub>CC</sub> must rise monotonically.
- (4) All input buffers are powered by the  $V_{\text{CCIO}}$  supply.
- (5) The I7 devices support extended operating junction temperature up to 125°C (usual range is -40°C to 100°C). When using I7 devices at the extended junction temperature ranging from -40°C to 125°C, select C8 as the target device when designing in the Quartus® II software. The I7 devices meet all C8 timing specifications when I7 devices operate beyond 100°C and up to 125°C.
- (6) POR time for Standard POR ranges between 50–200 ms. Each individual power supply should reach the recommended operating range within 50 ms.
- (7) POR time for Fast POR ranges between 3-9 ms. Each individual power supply should reach the recommended operating range within 3 ms.

#### **DC** Characteristics

This section lists the I/O leakage current, pin capacitance, on-chip termination (OCT) tolerance, and bus hold specifications for Cyclone III devices.

#### **Supply Current**

Standby current is the current the device draws after the device is configured with no inputs or outputs toggling and no activity in the device. Use the Excel-based early power estimator (EPE) to get the supply current estimates for your design because these currents vary largely with the resources used. Table 1–4 lists I/O pin leakage current for Cyclone III devices.

**Table 1–4.** Cyclone III Devices I/O Pin Leakage Current (Note 1), (2) (Part 1 of 2)

Symbol	Parameter	Conditions	Device	Min	Тур	Max	Unit
I <sub>t</sub>	Input pin leakage current	$V_{I} = 0 V to V_{CCIOMAX}$	_	-10	_	10	μΑ
I <sub>oz</sub>	Tristated I/O pin leakage current	V <sub>0</sub> = 0 V to V <sub>CCIOMAX</sub>	_	-10	_	10	μΑ

**Table 1–4.** Cyclone III Devices I/O Pin Leakage Current (Note 1), (2) (Part 2 of 2)

Vocam supply current (standby)	Symbol	Parameter	Conditions	Device	Min	Тур	Max	Unit
Vocate Supply current (standby)   Voca				EP3C5	_	1.7		mA
Vocation				EP3C10	_	1.7		mA
Common   C			$V_{i} = \text{ground, no} \\ load, no toggling \\ inputs, T_{J} = 25^{\circ}\text{C} \\ \hline \\ EP3C25 \\ \hline \\ EP3C40 \\ \hline \\ EP3C55 \\ \hline \\ EP3C80 \\ \hline \\ EP3C120 \\ \hline \\ EP3C10 \\ \hline \\ EP3C25 \\ \hline \\ EP3C40 \\ \hline \\ EP3C25 \\ \hline \\ EP3C40 \\ \hline \\ EP3C25 \\ \hline \\ EP3C10 \\ \hline \\$		mA			
Standard	1	V <sub>CCINT</sub> supply current		EP3C25	_	3.5	77	mA
Voca Supply current (standby)   V_i= ground, no load, no toggling inputs, T_j = 25°C   EP3C120	I <sub>CCINTO</sub>	(standby)		EP3C40	_	4.3	(3)	mA
Page 120   Repair				EP3C55	_	5.2		mA
Voca supply current (standby)				EP3C80	_	6.5		mA
Voca Supply current (standby)   Voca Supply current (standby				EP3C120	_	8.4		mA
$\begin{array}{c} V_{\text{CCA}} \text{ supply current} \\ \text{ (standby)} \end{array} \begin{array}{c} V_{\text{i}} = \text{ ground, no load, no toggling inputs,} \\ T_{\text{j}} = 25^{\circ}\text{C} \end{array} \begin{array}{c} EP3C16 \\ EP3C25 \\ EP3C40 \\ EP3C40 \\ EP3C55 \\ \\ 18.7 \\ EP3C80 \\ \\ 18.9 \\ EP3C120 \\ \\ 19.2 \end{array} \begin{array}{c} \text{mA} \\ \text{mA} \\ \text{mA} \\ \text{mA} \\ \text{mA} \end{array} \\ \\ EP3C120 \\ \\ 19.2 \end{array} \\ \begin{array}{c} \text{mA} \\ mA$				EP3C5	_	11.3		mA
$\begin{array}{c} V_{\text{CCO_PLLO}} \\ V_{\text{CCO_PLO}} \\ V_{\text{CCO_PLLO}} \\ V_{\text{CCO_PLO}} \\ V_{CCO_PLO$				EP3C10	_	11.3	(3)	mA
$ \begin{array}{c} V_{\text{Cod. PLLO}} \\ V_{\text{Cod. PLLO}} \\ V_{\text{Cool. PLLO}} \\ $				EP3C16	_	11.4		mA
Colon   Colo	1	V <sub>CCA</sub> supply current		EP3C25	_	18.4	(2)	mA
$V_{\text{CCO_PLLO}} = V_{\text{CCO_PLL}} = V_{\text{CCO_PLL}} = V_{\text{CCO_PLLO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLCO_PLCO}} = V_{\text{CCO_PLO_PLCO}} = V_{\text{CCO_PLO_PLO_PLO_PLO_PLOCO}} = V_{\text{CCO_PLO_PLO_PLOCO}} = V_{\text{CCO_PLO_PLOCO}} = V_{\text{CCO_PLO_PLOCO}} = V_{\text{CCO_PLOCO}} = V_{CCO_PLOCO$	I <sub>CCA0</sub>	(standby)		EP3C40	_	18.6	(3)	mA
Part				EP3C55	_	18.7	(3) m/A	mA
$V_{\text{CCD_PLLO}} = V_{\text{CCD_PLL}} = V_{\text{L}} = V_{\text{L}$				EP3C80	_	18.9		mA
$V_{\text{CCD-PLLO}} = V_{\text{CCD-PLL}} = V_{\text{CCD-PLLO}} = V_{\text{L}} = $				EP3C120	_	19.2	(3)	mA
$V_{\text{CCD_PLLO}} = V_{\text{CCD_PLL}} = V_{\text{CDD_PLLO}} = V_{\text{LCD_PLLO}} = V_{\text{LCD_PLO_PLO_PLO}} = V_{LCD_PLO_PLO_PLO_PLO_PLO_PLO_PLO_PLO_PLO_PLO$				EP3C5	_	4.1		mA
$ \begin{array}{c} V_{\text{CCD\_PLLO}} \\ V_{\text{CCD\_PLL}} \\ V_{\text{Standby}} \\ \end{array} \begin{array}{c} V_{\text{I}} = \operatorname{ground}, \operatorname{no} \operatorname{load}, \\ \operatorname{no} \operatorname{toggling} \operatorname{inputs}, \\ T_{\text{J}} = 25^{\circ} \text{C} \\ \end{array} \begin{array}{c} EP3C25 \\ EP3C40 \\ EP3C55 \\ - \\ EP3C80 \\ - \\ EP3C120 \\ - \\ EP3C10 \\ - \\ EP3C1$				EP3C10	_	4.1		mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				EP3C16	_	8.2		mA
$V_{ccio}  supply  current  (standby) \begin{tabular}{ll} & T_J = 25^{\circ}C \\ & EP3C40 & - & 8.2 \\ & EP3C55 & - & 8.2 \\ & EP3C80 & - & 8.2 \\ & EP3C120 & - & 8.2 \\ & EP3C120 & - & 8.2 \\ & EP3C120 & - & 0.6 \\ & EP3C10 & - & 0.6 \\ & EP3C10 & - & 0.6 \\ & EP3C10 & - & 0.9 \\ & EP3C16 & - & 0.9 \\ & EP3C25 & - & 0.9 \\ & EP3C25 & - & 0.9 \\ & EP3C40 & - & 1.3 \\ & EP3C55 & - & 1.3 \\ & EP3C80 &$	ı	V <sub>CCD_PLL</sub> supply current		EP3C25	_	8.2	(2)	mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	CCD_PLL0	(standby)		EP3C40		8.2	(3)	mA
$V_{\text{colo}} \text{ supply current} \\ \text{(standby)} \\ V_{\text{l}} = \text{ground, no load, no toggling inputs,} \\ T_{\text{J}} = 25 ^{\circ} \text{C} \\ \\ V_{\text{EP3C120}} \\ \hline \\ EP3C120 \\ \hline \\ EP3C55 \\ \hline \\ EP3C10 \\ \hline \\ EP3C10 \\ \hline \\ \\ EP3C10 \\ \hline \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $				EP3C55	-	8.2		mA
$V_{\text{ccio}} \text{ supply current} \\ \text{(standby)} \\ V_{\text{l}} = \text{ground, no load, no toggling inputs,} \\ T_{\text{J}} = 25 ^{\circ}\text{C} \\ \\ V_{\text{l}} = \text{ground, no load, no toggling inputs,} \\ T_{\text{J}} = 25 ^{\circ}\text{C} \\ \\ EP3C10 \\ EP3C10 \\ EP3C10 \\ - 0.9 \\ EP3C25 \\ - 0.9 \\ EP3C25 \\ - 1.3 \\ EP3C40 \\ - 1.3 \\ EP3C80 \\ - 1.3$				EP3C80	_	8.2		mA
$V_{\text{coio}} \text{ supply current} \\ \text{(standby)} \\ V_{\text{l}} = \text{ground, no load, no toggling inputs,} \\ T_{\text{J}} = 25 ^{\circ} \text{C} \\ \\ EP3C16 \\ EP3C25 \\ EP3C25 \\ EP3C40 \\ EP3C40 \\ EP3C55 \\ - \\ 1.3 \\ EP3C80 \\ - \\ 1.3 \\ \hline \text{mA} \\ \hline \text{mB} \\ \hline $				EP3C120	_	8.2		mA
$ V_{\text{ccio}} \text{ supply current} \\ \text{(standby)} \\ V_{\text{l}} = \text{ground, no load, no toggling inputs,} \\ T_{\text{J}} = 25 ^{\circ} \text{C} \\ \hline \\ EP3C40 \\ EP3C55 \\ EP3C80 \\ \hline \\ EP3C80 \\ \hline \\ MA \\ \hline \\ \\ MA \\ \hline \\ \\ MA \\ \hline \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $				EP3C5		0.6		mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				EP3C10		0.6		mA
				EP3C16		0.9		mA
(Standby) $T_J = 25^{\circ}C$ $EP3C40$ — 1.3 $MA$ $MA$ $EP3C80$ — 1.3 $MA$	ı			EP3C25		0.9	(3)	mA
EP3C55     —     1.3     mA       EP3C80     —     1.3     mA	CC100	(standby)		EP3C40		1.3	(0)	mA
				EP3C55		1.3		mA
EP3C120 — 1.2 mA				EP3C80		1.3		mA
				EP3C120		1.2		mA

#### Notes to Table 1-4:

<sup>(1)</sup> This value is specified for normal device operation. The value varies during device power-up. This applies for all V<sub>CCIO</sub> settings (3.3, 3.0, 2.5, 1.8, 1.5, and 1.2 V).

<sup>(2) 10</sup> µA I/O leakage current limit is applicable when the internal clamping diode is off. A higher current can be the observed when the diode is on.

<sup>(3)</sup> Maximum values depend on the actual T<sub>J</sub> and design utilization. For maximum values, refer to the Excel-based PowerPlay EPE (www.altera.com/support/devices/estimator/cy3-estimator/cy3-power\_estimator.html) or the Quartus II PowerPlay power analyzer feature. For more information about power consumption, refer to "Power Consumption" on page 1–14 for more information.

#### **Bus Hold**

Bus hold retains the last valid logic state after the source driving it either enters the high impedance state or is removed. Each I/O pin has an option to enable bus hold in user mode. Bus hold is always disabled in configuration mode.

Table 1–5 lists bus hold specifications for Cyclone III devices.

**Table 1–5.** Cyclone III Devices Bus Hold Parameter (Note 1)

							V <sub>CCIO</sub>	(V)						
Parameter	Condition	1.2		1	.5	1	.8	2	.5	3	.0	3	.3	Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus-hold low, sustaining current	V <sub>IN</sub> > V <sub>IL</sub> (maximum)	8	_	12	_	30	_	50	_	70	_	70	_	μА
Bus-hold high, sustaining current	V <sub>IN</sub> < V <sub>IL</sub> (minimum)	-8	_	-12	_	-30	_	-50	_	-70	_	-70	_	μА
Bus-hold low, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	_	125	_	175	_	200	_	300	_	500	_	500	μА
Bus-hold high, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	_	-125	_	-175	_	-200	_	-300	_	-500	_	-500	μА
Bus-hold trip point	_	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2	0.8	2	V

#### Note to Table 1-5:

# **OCT Specifications**

Table 1–6 lists the variation of OCT without calibration across process, temperature, and voltage.

Table 1-6. Cyclone III Devices Series OCT without Calibration Specifications

		Resist	ance Tolerance	
Description	V <sub>ccio</sub> (V)	Commercial Max	Industrial and Automotive Max	Unit
	3.0	±30	±40	%
Series OCT without	2.5	±30	±40	%
	1.8	+40	±50	%
Canoration	1.5	+50	±50	%
3.0	%			

OCT calibration is automatically performed at device power-up for OCT enabled I/Os.

<sup>(1)</sup> The bus-hold trip points are based on calculated input voltages from the JEDEC standard.

Table 1–7 lists the OCT calibration accuracy at device power-up.
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Table 1–7. Cyclone III Devices Series OCT with Calibration at Device Power-Up Specifications

		Calibr	ation Accuracy	
Description	V <sub>ccio</sub> (V)	Commercial Max	Industrial and Automotive Max	Unit
	3.0	±10	±10	%
Series OCT with	2.5	±10	±10	%
calibration at device	1.8	±10	±10	%
power-up	1.5	±10	±10	%
	1.2	±10	±10	%

The OCT resistance may vary with the variation of temperature and voltage after calibration at device power-up. Use Table 1–8 and Equation 1–1 to determine the final OCT resistance considering the variations after calibration at device power-up. Table 1–8 lists the change percentage of the OCT resistance with voltage and temperature.

**Table 1–8.** Cyclone III Devices OCT Variation After Calibration at Device Power-Up

Nominal Voltage	dR/dT (%/°C)	dR/dV (%/mV)
3.0	0.262	-0.026
2.5	0.234	-0.039
1.8	0.219	-0.086
1.5	0.199	-0.136
1.2	0.161	-0.288

# **Equation 1–1.** (Note 1), (2), (3), (4), (5), (6)

$$\Delta R_v = (V_2 - V_1) \times 1000 \times dR/dV - (7)$$

$$\Delta R_T = (T_2 - T_1) \times dR/dT - (8)$$

For 
$$\Delta R_x < 0$$
;  $MF_x = 1/(|\Delta R_x|/100 + 1)$  ——— (9)

For 
$$\Delta R_x > 0$$
;  $MF_x = \Delta R_x/100 + 1$  ———— (10)

$$MF = MF_v \times MF_T ---- (11)$$

$$R_{\text{final}} = R_{\text{initial}} \times MF - (12)$$

## Notes to Equation 1–1:

- (1)  $T_2$  is the final temperature.
- (2)  $T_1$  is the initial temperature.
- (3) MF is multiplication factor.
- (4) R<sub>final</sub> is final resistance.
- (5) R<sub>initial</sub> is initial resistance.
- (6) Subscript  $\times$  refers to both  $_{V}$  and  $_{T}$ .
- (7)  $\Delta R_V$  is variation of resistance with voltage.
- (8)  $\Delta R_T$  is variation of resistance with temperature.
- (9) dR/dT is the change percentage of resistance with temperature after calibration at device power-up.
- (10) dR/dV is the change percentage of resistance with voltage after calibration at device power-up.
- (11) V<sub>2</sub> is final voltage.
- (12)  $V_1$  is the initial voltage.

Example 1–1 shows you the example to calculate the change of 50  $\Omega$  I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V:

## Example 1-1.

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because  $\Delta R_V$  is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because  $\Delta R_T$  is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{final} = 50 \times 1.114 = 55.71 \Omega$$

#### Pin Capacitance

Table 1–9 lists the pin capacitance for Cyclone III devices.

Table 1-9. Cyclone III Devices Pin Capacitance

Symbol	Parameter	Typical – QFP	Typical – FBGA	Unit
$C_{IOTB}$	Input capacitance on top/bottom I/O pins	7	6	pF
C <sub>IOLR</sub>	Input capacitance on left/right I/O pins	7	5	pF
C <sub>LVDSLR</sub>	Input capacitance on left/right I/O pins with dedicated LVDS output	8	7	pF
C <sub>VREFLR</sub> (1)	Input capacitance on left/right dual-purpose $\mathtt{VREF}$ pin when used as $V_{\mathtt{REF}}$ or user I/O pin	21	21	pF
C <sub>VREFTB</sub> (1)	Input capacitance on top/bottom dual-purpose $\mathtt{VREF}$ pin when used as $V_{\mathtt{REF}}$ or user I/O pin	23 (2)	23 (2)	pF
Сськтв	Input capacitance on top/bottom dedicated clock input pins	7	6	pF
C <sub>CLKLR</sub>	Input capacitance on left/right dedicated clock input pins	6	5	pF

#### Notes to Table 1-9:

- (1) When VREF pin is used as regular input or output, a reduced performance of toggle rate and  $t_{\text{CO}}$  is expected due to higher pin capacitance.
- (2)  $C_{VREFTB}$  for EP3C25 is 30 pF.

#### Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1–10 lists the weak pull-up and pull-down resistor values for Cyclone III devices.

**Table 1–10.** Cyclone III Devices Internal Weak Pull-Up and Weak Pull-Down Resistor (Note 1)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
		$V_{CCIO} = 3.3 \text{ V} \pm 5\% (2), (3)$	7	25	41	kΩ
	Value of I/O pin pull-up resistor before	$V_{CCIO} = 3.0 \text{ V} \pm 5\% (2), (3)$	7	28	47	kΩ
R <sub>PU</sub>	and during configuration, as well as	$V_{CCIO} = 2.5 \text{ V} \pm 5\% (2), (3)$	8	35	61	kΩ
11_PU	user mode if the programmable	$V_{CCIO} = 1.8 \text{ V} \pm 5\% (2), (3)$	10	57	108	kΩ
	pull-up resistor option is enabled	$V_{CCIO} = 1.5 \text{ V} \pm 5\% (2), (3)$	13	82	163	kΩ
		V <sub>CCIO</sub> = 1.2 V ± 5% (2), (3)	19	143	351	kΩ
		$V_{CCIO} = 3.3 \text{ V} \pm 5\% (4)$	6	19	30	kΩ
	Naha at 1/0 min and danna maiatan	$V_{CCIO} = 3.0 \text{ V} \pm 5\% (4)$	6	22	36	kΩ
$R_{\_PD}$	Value of I/O pin pull-down resistor before and during configuration	$V_{CCIO} = 2.5 \text{ V} \pm 5\% (4)$	6	25	43	kΩ
	25.5.5 and daring configuration	V <sub>CCIO</sub> = 1.8 V ± 5% (4)	7	35	71	kΩ
		$V_{CCIO} = 1.5 \text{ V} \pm 5\% (4)$	8	50	112	kΩ

#### Notes to Table 1-10:

- (1) All I/O pins have an option to enable weak pull-up except configuration, test, and JTAG pin. Weak pull-down feature is only available for JTAG
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V<sub>CCIO</sub>.
- (3)  $R_{PU} = (V_{CCIO} V_I)/I_{R_{PU}}$  Minimum condition:  $-40^{\circ}\text{C}$ ;  $V_{CCIO} = V_{CC} + 5\%$ ,  $V_I = V_{CC} + 5\% 50$  mV;

Typical condition: 25°C;  $V_{\text{CCIO}} = V_{\text{CC}}$ ,  $V_{\text{I}} = 0$  V; Maximum condition: 125°C;  $V_{\text{CCIO}} = V_{\text{CC}} - 5\%$ ,  $V_{\text{I}} = 0$  V; in which  $V_{\text{I}}$  refers to the input voltage at the I/O pin.

(4)  $R_{PD} = V_i / I_{R_PD}$ Minimum condition: -40°C;  $V_{CCIO} = V_{CC} + 5\%$ ,  $V_1 = 50$  mV;

Typical condition: 25°C;  $V_{\text{CCIO}} = V_{\text{CC}}$ ,  $V_{\text{I}} = V_{\text{CC}} - 5\%$ ; Maximum condition: 125°C;  $V_{\text{CCIO}} = V_{\text{CC}} - 5\%$ ,  $V_{\text{I}} = V_{\text{CC}} - 5\%$ ; in which  $V_{\text{I}}$  refers to the input voltage at the I/O pin.

#### **Hot Socketing**

Table 1–11 lists the hot-socketing specifications for Cyclone III devices.

Table 1-11. Cyclone III Devices Hot-Socketing Specifications

Symbol	Parameter	Maximum
I <sub>IOPIN(DC)</sub>	DC current per I/O pin	300 μΑ
I <sub>IOPIN(AC)</sub>	AC current per I/O pin	8 mA <i>(1)</i>

#### Note to Table 1-11:

(1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |IIOPIN| = C dv/dt, in which C is I/O pin capacitance and dv/dt is the slew rate.

#### Schmitt Trigger Input

Cyclone III devices support Schmitt trigger input on TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signal with slow edge rate. Table 1–12 lists the hysteresis specifications across supported V<sub>CCIO</sub> range for Schmitt trigger inputs in Cyclone III devices.

Table 1–12. Hysteresis Specifications for Schmitt Trigger Input in Cyclone III Devices

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
		$V_{ccio} = 3.3 \text{ V}$	200	_	_	mV
Hystere	Hysteresis for Schmitt trigger	V <sub>ccio</sub> = 2.5 V	200	_	_	mV
V <sub>SCHMITT</sub>	input	V <sub>CCIO</sub> = 1.8 V	140	_	_	mV
		V <sub>ccio</sub> = 1.5 V	110	_	_	mV

### I/O Standard Specifications

The following tables list input voltage sensitivities ( $V_{IH}$  and  $V_{IL}$ ), output voltage ( $V_{OH}$  and  $V_{OL}$ ), and current drive characteristics ( $I_{OH}$  and  $I_{OL}$ ) for various I/O standards supported by Cyclone III devices. Table 1–13 through Table 1–18 provide the I/O standard specifications for Cyclone III devices.

**Table 1–13.** Cyclone III Devices Single-Ended I/O Standard Specifications (Note 1), (2)

I/O Ctondord		V <sub>ccio</sub> (V)		V	ւ (V)	V	/ <sub>н</sub> (V)	V <sub>ol</sub> (V)	V <sub>oh</sub> (V)	I <sub>oL</sub>	I <sub>OH</sub>
I/O Standard	Min	Тур	Max	Min	Max	Min	Max	Max	Min	(mA)	(mA)
3.3-V LVTTL (3)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.45	2.4	4	-4
3.3-V LVCMOS (3)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.2	V <sub>CC10</sub> - 0.2	2	-2
3.0-V LVTTL (3)	2.85	3.0	3.15	-0.3	0.8	1.7	V <sub>cc10</sub> + 0.3	0.45	2.4	4	-4
3.0-V LVCMOS (3)	2.85	3.0	3.15	-0.3	0.8	1.7	V <sub>cc10</sub> + 0.3	0.2	V <sub>cc10</sub> - 0.2	0.1	-0.1
2.5-V LVTTL and LVCMOS (3)	2.375	2.5	2.625	-0.3	0.7	1.7	V <sub>ccio</sub> + 0.3	0.4	2.0	1	-1
1.8-V LVTTL and LVCMOS	1.71	1.8	1.89	-0.3	0.35 * V <sub>ccio</sub>	0.65 * V <sub>ccio</sub>	2.25	0.45	V <sub>ccio</sub> - 0.45	2	-2
1.5-V LVCMOS	1.425	1.5	1.575	-0.3	0.35 * V <sub>ccio</sub>	0.65 * V <sub>ccio</sub>	V <sub>CCIO</sub> + 0.3	0.25 * V <sub>CCIO</sub>	0.75 * V <sub>ccio</sub>	2	-2
1.2-V LVCMOS	1.14	1.2	1.26	-0.3	0.35 * V <sub>ccio</sub>	0.65 * V <sub>ccio</sub>	V <sub>CCIO</sub> + 0.3	0.25 * V <sub>CCIO</sub>	0.75 * V <sub>ccio</sub>	2	-2
3.0-V PCI	2.85	3.0	3.15	_	0.3 * V <sub>ccio</sub>	0.5 * V <sub>ccio</sub>	V <sub>CC10</sub> + 0.3	0.1 * V <sub>CCIO</sub>	0.9 * V <sub>CCIO</sub>	1.5	-0.5
3.0-V PCI-X	2.85	3.0	3.15	_	0.35* V <sub>CCIO</sub>	0.5 * V <sub>ccio</sub>	V <sub>cc10</sub> + 0.3	0.1 * V <sub>cc10</sub>	0.9 * V <sub>ccio</sub>	1.5	-0.5

## Notes to Table 1-13:

<sup>(1)</sup> For voltage referenced receiver input waveform and explanation of terms used in Table 1–13, refer to "Single-ended Voltage referenced I/O Standard" in "Glossary" on page 1–29.

<sup>(2)</sup> AC load CL = 10 pF.

<sup>(3)</sup> For more detail about interfacing Cyclone III devices with 3.3/3.0/2.5-V LVTTL/LVCMOS I/O standards, refer to AN 447: Interfacing Cyclone III Devices with 3.3/3.0/2.5-V LVTTL and LVCMOS I/O Systems.

**Table 1–14.** Cyclone III Devices Single-Ended SSTL and HSTL I/O Reference Voltage Specifications (Note 1)

I/O		V <sub>ccio</sub> (V)		$V_{REF}(V)$			<b>V</b> <sub>π</sub> ( <b>V</b> ) <i>(Note 2)</i>				
Standard	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max		
SSTL-2 Class I, II	2.375	2.5	2.625	1.19	1.25	1.31	V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04		
SSTL-18 Class I, II	1.7	1.8	1.9	0.833	0.9	0.969	V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04		
HSTL-18 Class I, II	1.71	1.8	1.89	0.85	0.9	0.95	0.85	0.9	0.95		
HSTL-15 Class I, II	1.425	1.5	1.575	0.71	0.75	0.79	0.71	0.75	0.79		
HSTL-12 Class I, II	1.14	1.2	1.26	0.48 * V <sub>CCIO</sub> (3) 0.47 * V <sub>CCIO</sub> (4)	0.5 * V <sub>CCIO</sub> (3) 0.5 * V <sub>CCIO</sub> (4)	0.52 * V <sub>CCIO</sub> (3) 0.53 * V <sub>CCIO</sub> (4)	_	0.5 * V <sub>ccio</sub>	_		

#### Notes to Table 1-14:

- (1) For an explanation of terms used in Table 1–14, refer to "Glossary" on page 1–29.
- (2)  $V_{TT}$  of transmitting device must track  $V_{REF}$  of the receiving device.
- (3) Value shown refers to DC input reference voltage,  $V_{REF(DC)}$ .
- (4) Value shown refers to AC input reference voltage,  $V_{\text{REF(AC)}}$ .

Table 1-15. Cyclone III Devices Single-Ended SSTL and HSTL I/O Standards Signal Specifications

I/O	VIL	<sub>(DC)</sub> (V)	V	<sub>H(DC)</sub> <b>(V)</b>	V <sub>IL</sub>	(AC) <b>(V)</b>	V <sub>IH</sub>	<sub>(AC)</sub> (V)	V <sub>oL</sub> (V)	V <sub>oH</sub> (V)	I <sub>oL</sub>	I <sub>oh</sub>
Standard	Min	Max	Min	Max	Min	Max	Min	Max	Max	Min	(mA)	(mA)
SSTL-2 Class I	_	V <sub>REF</sub> – 0.18	V <sub>REF</sub> + 0.18	_	_	V <sub>REF</sub> – 0.35	V <sub>REF</sub> + 0.35	_	$V_{\pi}$ – 0.57	V <sub>π</sub> + 0.57	8.1	-8.1
SSTL-2 Class II	_	V <sub>REF</sub> – 0.18	V <sub>REF</sub> + 0.18	_	_	V <sub>REF</sub> – 0.35	V <sub>REF</sub> + 0.35	_	V <sub>π</sub> – 0.76	V <sub>ττ</sub> + 0.76	16.4	-16.4
SSTL-18 Class I	_	V <sub>REF</sub> – 0.125	V <sub>REF</sub> + 0.125	_	_	V <sub>REF</sub> – 0.25	V <sub>REF</sub> + 0.25	_	V <sub>π</sub> – 0.475	V <sub>π</sub> + 0.475	6.7	-6.7
SSTL-18 Class II	_	V <sub>REF</sub> – 0.125	V <sub>REF</sub> + 0.125	_	_	V <sub>REF</sub> – 0.25	V <sub>REF</sub> + 0.25	_	0.28	V <sub>ccio</sub> – 0.28	13.4	-13.4
HSTL-18 Class I	_	V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> - 0.4	8	-8
HSTL-18 Class II	_	V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	16	-16
HSTL-15 Class I	_	V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	8	-8
HSTL-15 Class II	_	V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	16	-16
HSTL-12 Class I	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>ccio</sub> + 0.15	-0.24	V <sub>REF</sub> – 0.15	V <sub>REF</sub> + 0.15	V <sub>ccio</sub> + 0.24	0.25 × V <sub>ccio</sub>	0.75 × V <sub>ccio</sub>	8	-8
HSTL-12 Class II	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>ccio</sub> + 0.15	-0.24	V <sub>REF</sub> – 0.15	V <sub>REF</sub> + 0.15	V <sub>CCIO</sub> + 0.24	0.25 × V <sub>ccio</sub>	0.75 × V <sub>ccio</sub>	14	-14



For more illustrations of receiver input and transmitter output waveforms, and for other differential I/O standards, refer to the *High-Speed Differential Interfaces in Cyclone III Devices* chapter.

 Table 1–16.
 Cyclone III Devices Differential SSTL I/O Standard Specifications

I/O Standard	V <sub>CCIO</sub> (V) V <sub>Swing(DC)</sub> (		<sub>(DC)</sub> (V)	V <sub>x(AC)</sub> (V)			V <sub>Swing(AC)</sub> (V)		V <sub>ox(AC)</sub> (V)				
i/O Stanuaru	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Max	Min	Тур	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.36	V <sub>ccio</sub>	V <sub>ccio</sub> /2 - 0.2	_	V <sub>ccio</sub> /2 + 0.2	0.7	V <sub>ccio</sub>	V <sub>ccio</sub> /2 – 0.125	_	V <sub>cc10</sub> /2 + 0.125
SSTL-18 Class I, II	1.7	1.8	1.90	0.25	V <sub>ccio</sub>	V <sub>ccio</sub> /2 - 0.175	_	V <sub>ccio</sub> /2 + 0.175	0.5	V <sub>ccio</sub>	V <sub>ccio</sub> /2 – 0.125	_	V <sub>cc10</sub> /2 + 0.125

Table 1–17. Cyclone III Devices Differential HSTL I/O Standard Specifications

V <sub>ccio</sub> (V)			V <sub>DIF(DC)</sub> (V)		<b>V</b> <sub>x(AC)</sub> <b>(V)</b>			V <sub>CM(DC)</sub> (V)				<sub>F(AC)</sub> (V)	
I/O Standard	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Тур	Max	Mi n	Max
HSTL-18 Class I, II	1.71	1.8	1.89	0.2	_	0.85	_	0.95	0.85	_	0.95	0.4	_
HSTL-15 Class I, II	1.425	1.5	1.575	0.2		0.71	_	0.79	0.71	_	0.79	0.4	_
HSTL-12 Class I, II	1.14	1.2	1.26	0.16	V <sub>ccio</sub>	0.48 * V <sub>CCIO</sub>	_	0.52 * V <sub>ccio</sub>	0.48 * V <sub>ccio</sub>		0.52 * V <sub>ccio</sub>	0.3	0.48 * V <sub>ccio</sub>

Table 1–18. Cyclone III Devices Differential I/O Standard Specifications (Note 1) (Part 1 of 2)

1/0	,	V <sub>ccio</sub> (V	)	V <sub>ID</sub> (I	mV)		<b>V</b> <sub>IcM</sub> (V) (2)		V <sub>o</sub>	ը(mV)	(3)	V <sub>os</sub> (V) (3)		
Standard	Min	Тур	Max	Min	Max	Min	Condition	Max	Min	Тур	Max	Min	Тур	Max
LV/DEQ1						0.05	$D_{\text{MAX}} \leq 500 \; \text{Mbps}$	1.80						
LVPECL (Row I/Os) (4)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{c} 500 \; Mbps \leq  D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.80	_	_	_	_	_	_
( '/						1.05	D <sub>MAX</sub> > 700 Mbps	1.55						
LVDEOL						0.05	$D_{\text{MAX}} \leq 500 \text{ Mbps}$	1.80						
LVPECL (Column I/Os) <i>(4)</i>	2.375	2.5	2.625	100	_	0.55	$\begin{array}{c} 500 \; Mbps \leq D_{\text{MAX}} \leq \\ 700 \; Mbps \end{array}$	1.80	_	_	_	_	_	_
1/03) (4)						1.05	D <sub>MAX</sub> > 700 Mbps	1.55						
						0.05	$D_{\text{MAX}} \leq 500 \; \text{Mbps}$	1.80						
LVDS (Row I/Os)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{c} 500 \; Mbps \leq D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.80	247	_	600	1.125	1.25	1.375
						1.05	$D_{MAX} > 700 \text{ Mbps}$	1.55						
11/00						0.05	$D_{\text{MAX}} \leq 500 \text{ Mbps}$	1.80						
LVDS (Column I/Os)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{c} 500 \; Mbps \leq D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.80	247	_	600	1.125	1.25	1.375
1,00)						1.05	$D_{MAX} > 700 \text{ Mbps}$	1.55						
BLVDS (Row I/Os) (5)	2.375	2.5	2.625	100	_	_	_	_	_	_	_	_	_	_
BLVDS (Column I/Os) (5)	2.375	2.5	2.625	100	_	_	_	_	_	_	_	_	_	_

I/O		V <sub>ccio</sub> (V	)	V <sub>10</sub> (1	V <sub>ID</sub> (mV)		<b>V</b> <sub>IcM</sub> (V) (2)		V.	o(mV)	(3)	V	os (V) (	3)
Standard	Min	Тур	Max	Min	Max	Min	Condition	Max	Min	Тур	Max	Min	Тур	Max
mini-LVDS (Row I/Os) (6)	2.375	2.5	2.625	_	_	_	_	_	300	_	600	1.0	1.2	1.4
mini-LVDS (Column I/Os) (6)	2.375	2.5	2.625	_	_	_	_	_	300	_	600	1.0	1.2	1.4
RSDS® (Row I/Os)(6)	2.375	2.5	2.625	_	_	_	_	_	100	200	600	0.5	1.2	1.5
RSDS (Column I/Os) (6)	2.375	2.5	2.625	_	_	_	_	_	100	200	600	0.5	1.2	1.5
PPDS® (Row I/Os) (6)	2.375	2.5	2.625	_	_	_	_	_	100	200	600	0.5	1.2	1.4
PPDS (Column I/Os) (6)	2.375	2.5	2.625	_	_	_	_	_	100	200	600	0.5	1.2	1.4

**Table 1–18.** Cyclone III Devices Differential I/O Standard Specifications (*Note 1*) (Part 2 of 2)

#### Notes to Table 1-18:

- (1) For an explanation of terms used in Table 1–18, refer to "Transmitter Output Waveform" in "Glossary" on page 1–29.
- (2)  $V_{IN}$  range:  $0 \text{ V} \le V_{IN} \le 1.85 \text{ V}$ .
- (3)  $R_L$  range:  $90 \le R_L \le 110 \Omega$ .
- (4) LVPECL input standard is only supported at clock input. Output standard is not supported.
- (5) No fixed  $V_{IN}$ ,  $V_{OD}$ , and  $V_{OS}$  specifications for BLVDS. They are dependent on the system topology.
- (6) Mini-LVDS, RSDS, and PPDS standards are only supported at the output pins for Cyclone III devices.

# **Power Consumption**

You can use the following methods to estimate power for a design:

- the Excel-based EPE.
- the Quartus II PowerPlay power analyzer feature.

The interactive Excel-based EPE is used prior to designing the device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities which, combined with detailed circuit models, can yield very accurate power estimates.



For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

# **Switching Characteristics**

This section provides the performance characteristics of the core and periphery blocks for Cyclone III devices. All data is final and is based on actual silicon characterization and testing. These numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions.

# **Core Performance Specifications**

## **Clock Tree Specifications**

Table 1–19 lists the clock tree specifications for Cyclone III devices.

**Table 1–19.** Cyclone III Devices Clock Tree Performance

Dovice		Performance					
Device	C6	<b>C</b> 7	C8	- Unit			
EP3C5	500	437.5	402	MHz			
EP3C10	500	437.5	402	MHz			
EP3C16	500	437.5	402	MHz			
EP3C25	500	437.5	402	MHz			
EP3C40	500	437.5	402	MHz			
EP3C55	500	437.5	402	MHz			
EP3C80	500	437.5	402	MHz			
EP3C120	(1)	437.5	402	MHz			

#### Note to Table 1-19:

#### **PLL Specifications**

Table 1–20 describes the PLL specifications for Cyclone III devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (-40°C to 100°C), and the automotive junction temperature range (-40°Cto 125°C). For more information about PLL block, refer to "PLL Block" in "Glossary" on page 1–29.

**Table 1–20.** Cyclone III Devices PLL Specifications (*Note 1*) (Part 1 of 2)

Symbol	Parameter	Min	Тур	Max	Unit
f <sub>IN</sub> (2)	Input clock frequency	5	_	472.5	MHz
f <sub>INPFD</sub>	PFD input frequency	5	_	325	MHz
f <sub>vco</sub> (3)	PLL internal VCO operating range	600	_	1300	MHz
f <sub>INDUTY</sub>	Input clock duty cycle	40	_	60	%
t <sub>INJITTER_CCJ</sub> (4)	Input clock cycle-to-cycle jitter F <sub>REF</sub> ≥ 100 MHz	_	_	0.15	UI
	F <sub>REF</sub> < 100 MHz		_	±750	ps
$f_{\text{OUT\_EXT}}$ (external clock output) (2)	PLL output frequency	_	_	472.5	MHz

<sup>(1)</sup> EP3C120 offered in C7, C8, and I7 grades only.

**Table 1–20.** Cyclone III Devices PLL Specifications (*Note 1*) (Part 2 of 2)

Symbol	Parameter	Min	Тур	Max	Unit
	PLL output frequency (-6 speed grade)			472.5	MHz
f <sub>out</sub> (to global clock)	PLL output frequency (-7 speed grade)	_	_	450	MHz
	PLL output frequency (-8 speed grade)	_	_	402.5	MHz
toutduty	Duty cycle for external clock output (when set to 50%)	45	50	55	%
t <sub>lock</sub>	Time required to lock from end of device configuration	_	_	1	ms
t <sub>DLOCK</sub>	Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or areset is deasserted)		_	1	ms
t <sub>outjitter_period_dedclk</sub> (5)	Dedicated clock output period jitter $F_{\text{out}} \ge 100 \text{ MHz}$	_	_	300	ps
	F <sub>out</sub> < 100 MHz	_	_	30	mUI
toutjitter ccj dedclk (5)	Dedicated clock output cycle-to-cycle jitter $F_{\text{out}} \ge 100 \text{ MHz}$	_	_	300	ps
	F <sub>out</sub> < 100 MHz	_	_	30	mUI
t <sub>outjitter period 10</sub> (5)	Regular I/O period jitter F <sub>ouт</sub> ≥ 100 MHz	_	_	650	ps
	F <sub>out</sub> < 100 MHz	_	_	75	mUI
toutjitter ccj io (5)	Regular I/O cycle-to-cycle jitter $F_{\text{OUT}} \ge 100 \text{ MHz}$	_	_	650	ps
	F <sub>out</sub> < 100 MHz	_	_	75	mUI
t <sub>PLL_PSERR</sub>	Accuracy of PLL phase shift	_	_	±50	ps
t <sub>ARESET</sub>	Minimum pulse width on areset signal.	10	_	_	ns
t <sub>configpll</sub>	Time required to reconfigure scan chains for PLLs	_	3.5 (6)	_	SCANCLK cycles
f <sub>scanclk</sub>	scanclk frequency	_	_	100	MHz

#### Notes to Table 1-20:

- (1)  $V_{\text{CCD\_PLL}}$  should always be connected to  $V_{\text{CCINT}}$  through decoupling capacitor and ferrite bead.
- (2) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (3) The  $V_{CO}$  frequency reported by the Quartus II software in the PLL summary section of the compilation report takes into consideration the  $V_{CO}$  post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the  $f_{VCO}$  specification.
- (4) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source, which is less than 200 ps.
- (5) Peak-to-peak jitter with a probability level of 10<sup>-12</sup> (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL, when an input jitter of 30 ps is applied.
- (6) With 100 MHz scanclk frequency.

## **Embedded Multiplier Specifications**

Table 1–21 describes the embedded multiplier specifications for Cyclone III devices.

Table 1-21. Cyclone III Devices Embedded Multiplier Specifications

Mada	Resources Used		Performance		llmit
Mode	Number of Multipliers	C6	C7, I7, A7	C8	Unit
9 × 9-bit multiplier	1	340	300	260	MHz
18 × 18-bit multiplier	1	287	250	200	MHz

## **Memory Block Specifications**

Table 1–22 describes the M9K memory block specifications for Cyclone III devices.

Table 1–22. Cyclone III Devices Memory Block Performance Specifications

		Resour	ces Used	Performance					
Memory	Mode	LEs	M9K Memory	C6	C7, I7, A7	C8	Unit		
	FIFO 256 × 36	47	1	315	274	238	MHz		
M9K Block	Single-port 256 × 36	0	1	315	274	238	MHz		
INISK DIOCK	Simple dual-port 256 × 36 CLK	0	1	315	274	238	MHz		
	True dual port 512 × 18 single CLK	0	1	315	274	238	MHz		

# **Configuration and JTAG Specifications**

Table 1–23 lists the configuration mode specifications for Cyclone III devices.

Table 1–23. Cyclone III Devices Configuration Mode Specifications

Programming Mode	DCLK F <sub>max</sub>	Unit
Passive Serial (PS)	133	MHz
Fast Passive Parallel (FPP) (1)	100	MHz

#### Note to Table 1-23:

(1) EP3C40 and smaller density members support 133 MHz.

Table 1–24 lists the active configuration mode specifications for Cyclone III devices.

**Table 1–24.** Cyclone III Devices Active Configuration Mode Specifications

Programming Mode	DCLK Range	Unit
Active Parallel (AP)	20 – 40	MHz
Active Serial (AS)	20 – 40	MHz

Table 1–25 lists the JTAG timing parameters and values for Cyclone III devices.

**Table 1–25.** Cyclone III Devices JTAG Timing Parameters (Note 1)

Symbol	Parameter	Min	Max	Unit
$t_{\text{JCP}}$	TCK clock period	40	_	ns
t <sub>JCH</sub>	TCK clock high time	20	_	ns
$t_{ extsf{JCL}}$	TCK clock low time	20	_	ns
t <sub>JPSU_TDI</sub>	JTAG port setup time for TDI (2)	1	_	ns
t <sub>JPSU_TMS</sub>	JTAG port setup time for TMS (2)	3	_	ns
t <sub>JPH</sub>	JTAG port hold time	10	_	ns
t <sub>JPCO</sub>	JTAG port clock to output (2)	_	15	ns
t <sub>JPZX</sub>	JTAG port high impedance to valid output (2)	_	15	ns
t <sub>JPXZ</sub>	JTAG port valid output to high impedance (2)	_	15	ns
t <sub>JSSU</sub>	Capture register setup time (2)	5	_	ns
t <sub>JSH</sub>	Capture register hold time	10	_	ns
t <sub>JSCO</sub>	Update register clock to output	_	25	ns
t <sub>JSZX</sub>	Update register high impedance to valid output	_	25	ns
t <sub>JSXZ</sub>	Update register valid output to high impedance	_	25	ns

#### Notes to Table 1-25:

- (1) For more information about JTAG waveforms, refer to "JTAG Waveform" in "Glossary" on page 1–29.
- (2) The specification is shown for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the JTAG port clock to output time is 16 ns.

# **Periphery Performance**

## **High-Speed I/O Specifications**

Table 1–26 through Table 1–31 list the high-speed I/O timing for Cyclone III devices. For definitions of high-speed timing specifications, refer to "Glossary" on page 1–29.

**Table 1–26.** Cyclone III Devices RSDS Transmitter Timing Specifications (Note 1), (2) (Part 1 of 2)

Cumbol	Modes		C6			C7, I7			C8, A7			
Symbol	iwoues	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit	
	×10	10	_	180	10	_	155.5	10	_	155.5	MHz	
	×8	10	_	180	10	_	155.5	10	_	155.5	MHz	
f <sub>HSCLK</sub> (input clock	×7	10	_	180	10	_	155.5	10	_	155.5	MHz	
frequency)	×4	10	_	180	10	_	155.5	10	_	155.5	MHz	
. 2,	×2	10	_	180	10	_	155.5	10	_	155.5	MHz	
	×1	10	_	360	10	_	311	10	_	311	MHz	

**Table 1–26.** Cyclone III Devices RSDS Transmitter Timing Specifications (Note 1), (2) (Part 2 of 2)

Cumbal	Madaa		C6			C7, I7			C8, A7	,	Unit
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	UIIIL
	×10	100	_	360	100	_	311	100	_	311	Mbps
	×8	80	_	360	80	_	311	80	_	311	Mbps
Device operation in	×7	70	_	360	70	_	311	70	_	311	Mbps
Mbps	×4	40	_	360	40	_	311	40	_	311	Mbps
	×2	20	_	360	20	_	311	20	_	311	Mbps
	×1	10	_	360	10	_	311	10	_	311	Mbps
t <sub>DUTY</sub>	_	45	_	55	45	_	55	45	_	55	%
TCCS	_	_	_	200	_	_	200		_	200	ps
Output jitter (peak to peak)	_		_	500		_	500	_	_	550	ps
t <sub>RISE</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	_	500	_	ps
t <sub>FALL</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	—	500	_	_	500	_	ps
t <sub>LOCK</sub> (3)			_	1	_		1	—	_	1	ms

#### Notes to Table 1-26:

- (1) Applicable for true RSDS and emulated RSDS\_E\_3R transmitter.
- (2) True RSDS transmitter is only supported at output pin of Row I/O (Banks 1, 2, 5, and 6). Emulated RSDS transmitter is supported at the output pin of all I/O banks.
- (3)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 1–27.** Cyclone III Devices Emulated RSDS\_E\_1R Transmitter Timing Specifications (Note 1) (Part 1 of 2)

			C6			C7, I7			C8, A7		
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
	×10	10	_	85	10	_	85	10	_	85	MHz
	×8	10	_	85	10	_	85	10	_	85	MHz
f <sub>HSCLK</sub> (input	×7	10	_	85	10	_	85	10	_	85	MHz
clock frequency)	×4	10	_	85	10	_	85	10	_	85	MHz
	×2	10	_	85	10	_	85	10	_	85	MHz
	×1	10	_	170	10	_	170	10	_	170	MHz
	×10	100	_	170	100	_	170	100	_	170	Mbps
	×8	80	_	170	80	_	170	80	_	170	Mbps
Device	×7	70	_	170	70	_	170	70	_	170	Mbps
operation in Mbps	×4	40	_	170	40	_	170	40	_	170	Mbps
	×2	20	_	170	20	_	170	20	_	170	Mbps
	×1	10	_	170	10	_	170	10	_	170	Mbps
t <sub>DUTY</sub>	_	45	_	55	45	_	55	45	_	55	%
TCCS	_	_	_	200	_	_	200	_	_	200	ps
Output jitter (peak to peak)	_	_	_	500	_	_	500	_	_	550	ps

<b>Table 1–27.</b> (	Cyclone III Devices	Emulated RSDS 1	F 1R	Transmitter 1	Timina S	Specifications	(Note 1)	) (	Part 2 of 2)

Cumbal	Modes		C6			C7, I7			Unit		
Symbol	Mones	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	UIIIL
t <sub>RISE</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	_	500	_	ps
t <sub>FALL</sub>	$20 - 80\%$ , $C_{LOAD} = 5 \text{ pF}$	_	500	_	_	500	_	_	500		ps
t <sub>lock</sub> (2)	_	_	_	1	_	_	1	_	_	1	ms

#### Notes to Table 1-27:

- (1) Emulated RSDS\_E\_1R transmitter is supported at the output pin of all I/O banks.
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 1–28.** Cyclone III Devices Mini-LVDS Transmitter Timing Specifications (Note 1), (2)

Chal	Madaa		C6			C7, I7			C8, A7		Unit
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
	×10	10	_	200	10	_	155.5	10	_	155.5	MHz
	×8	10	_	200	10	_	155.5	10	_	155.5	MHz
f <sub>HSCLK</sub> (input clock	×7	10	—	200	10	_	155.5	10	_	155.5	MHz
frequency)	×4	10	—	200	10	_	155.5	10	_	155.5	MHz
- 1 5/	×2	10	_	200	10	_	155.5	10	_	155.5	MHz
	×1	10	_	400	10	_	311	10	_	311	MHz
	×10	100	_	400	100	_	311	100	_	311	Mbps
	×8	80	_	400	80	_	311	80	_	311	Mbps
Device	×7	70	—	400	70	_	311	70	_	311	Mbps
operation in Mbps	×4	40	_	400	40	_	311	40	_	311	Mbps
•	×2	20	_	400	20	_	311	20	_	311	Mbps
	×1	10	—	400	10	_	311	10	_	311	Mbps
t <sub>DUTY</sub>	_	45	_	55	45	_	55	45	_	55	%
TCCS	_	_	_	200		_	200	_	_	200	ps
Output jitter (peak to peak)	_	_	_	500	_	_	500	_	_	550	ps
t <sub>rise</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$		500	_		500	_		500		ps
$t_{\scriptscriptstyleFALL}$	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	_	500	_	ps
t <sub>LOCK</sub> (3)	_	_	_	1	_	_	1		_	1	ms

#### Notes to Table 1-28:

- (1) Applicable for true and emulated mini-LVDS transmitter.
- (2) True mini-LVDS transmitter is only supported at the output pin of Row I/O (Banks 1, 2, 5, and 6). Emulated mini-LVDS transmitter is supported at the output pin of all I/O banks.
- (3)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

ms

C6 C7, 17 C8, A7 **Symbol Modes** Unit Min Min Max Max Min Max ×10 10 420 10 370 10 320 MHz ×8 10 420 10 370 10 320 MHz ×7 10 420 10 370 10 320 MHz  $f_{\mbox{\tiny HSCLK}}$  (input clock frequency) 10 370 420 10 10 320 MHz ×4 10 ×2 420 10 370 10 320 MHz 402.5 402.5 ×1 10 420 10 10 MHz100 100 740 Mbps ×10 840 100 640 ×8 80 840 80 740 80 640 Mbps 70 840 70 740 70 640 ×7 Mbps **HSIODR** ×4 40 840 40 740 40 640 Mbps 20 20 740 20 ×2 840 640 Mbps 10 420 10 402.5 10 ×1 402.5 Mbps 45 45 55 % 55 45 55  $t_{DUTY}$ TCCS 200 200 200 ps Output jitter 500 550 500 ps (peak to peak)  $t_{\text{LOCK}}(2)$ 

**Table 1–29.** Cyclone III Devices True LVDS Transmitter Timing Specifications (*Note 1*)

#### Notes to Table 1-29:

- (1) True LVDS transmitter is only supported at the output pin of Row I/O (Banks 1, 2, 5, and 6).
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

Table 1–30. Cyclone III Devices Emulated LVDS Transmitter Timing Specifications (Note 1) (Part 1 of 2)

Cumbal	Modes	C	6	<b>C</b> 7	, 17	C8,	, <b>A</b> 7	II-ait
Symbol	Modes	Min	Max	Min	Max	Min	Max	Unit
	×10	10	320	10	320	10	275	MHz
	×8	10	320	10	320	10	275	MHz
f <sub>HSCLK</sub> (input clock	×7	10	320	10	320	10	275	MHz
frequency)	×4	10	320	10	320	10	275	MHz
	×2	10	320	10	320	10	275	MHz
	×1	10	402.5	10	402.5	10	402.5	MHz
	×10	100	640	100	640	100	550	Mbps
	×8	80	640	80	640	80	550	Mbps
HSIODR	×7	70	640	70	640	70	550	Mbps
HOIODK	×4	40	640	40	640	40	550	Mbps
	×2	20	640	20	640	20	550	Mbps
	×1	10	402.5	10	402.5	10	402.5	Mbps
t <sub>DUTY</sub>	_	45	55	45	55	45	55	%

**Table 1–30.** Cyclone III Devices Emulated LVDS Transmitter Timing Specifications (*Note 1*) (Part 2 of 2)

Cumbol	Modes	C	6	C7	, <b>I</b> 7	C8,	Unit	
Symbol	Mones	Min	Max	Min	Max	Min	Max	UIIIL
TCCS	_	_	200	_	200	_	200	ps
Output jitter (peak to peak)	_	_	500	_	500	_	550	ps
t <sub>LOCK</sub> (2)	_	_	1	_	1	_	1	ms

#### Notes to Table 1-30:

- (1) Emulated LVDS transmitter is supported at the output pin of all I/O banks.
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 1–31.** Cyclone III Devices LVDS Receiver Timing Specifications (Note 1)

Combal	Modes	C	6	C7	, 17	C8,	, A7	II-ait
Symbol	Modes	Min	Max	Min	Max	Min	Max	Unit
	×10	10	437.5	10	370	10	320	MHz
	×8	10	437.5	10	370	10	320	MHz
f <sub>HSCLK</sub> (input clock	×7	10	437.5	10	370	10	320	MHz
frequency)	×4	10	437.5	10	370	10	320	MHz
	×2	10	437.5	10	370	10	320	MHz
	×1	10	437.5	10	402.5	10	402.5	MHz
	×10	100	875	100	740	100	640	Mbps
	×8	80	875	80	740	80	640	Mbps
HSIODR	×7	70	875	70	740	70	640	Mbps
поиии	×4	40	875	40	740	40	640	Mbps
	×2	20	875	20	740	20	640	Mbps
	×1	10	437.5	10	402.5	10	402.5	Mbps
SW	_	_	400	_	400	_	400	ps
Input jitter tolerance	_	_	500	_	500	_	550	ps
t <sub>lock</sub> (2)	_		1	_	1	_	1	ms

#### Notes to Table 1-31:

- (1) LVDS receiver is supported at all banks.
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

#### **External Memory Interface Specifications**

Cyclone III devices support external memory interfaces up to 200 MHz. The external memory interfaces for Cyclone III devices are auto-calibrating and easy to implement.

Table 1–32 through Table 1–35 list the external memory interface specifications for Cyclone III devices and are useful when performing memory interface timing analysis.

**Table 1–32.** Cyclone III Devices Maximum Clock Rate Support for External Memory Interfaces with Half-Rate Controller (*Note 1*),(2)

	C6 S <sub>l</sub>	peed G (MHz)			C7 Speed Grade (MHz)			C8 Speed Grade (MHz)			17 Speed Grade (MHz)			A7 Speed Grade (MHz)		
Memory Standard	Column I/O Banks	Row I/O Banks	Wraparound Mode	Column I/O Banks	Row I/O Banks	Wraparound Mode	Column I/O Banks	Row I/O Banks	Wraparound Mode	Column I/O Banks	Row I/O Banks	Wraparound Mode	Column I/O Banks	Row I/O Banks	Wraparound Mode	
DDR2 SDRAM (3),(4)	200	167	167	167	150	133	167	133	125	167	150	133	167	133	125	
DDR SDRAM (3)	167	150	133	150	133	125	133	125	100	150	133	125	133	125	100	
QDRII SRAM (5)	167	167	150	150	150	133	133	133	125	150	150	133	133	133	125	

#### Notes to Table 1-32:

- (1) Column I/O banks refer to top and bottom I/Os. Row I/O banks refer to right and left I/Os. Wraparound mode refers to combination of column and row I/Os.
- (2) The supported operating frequencies listed here are memory interface maximums for the FPGA device. The actual achievable performance of your design is based on the design and system specific factors, as well as static timing analysis of the completed design.
- (3) The values apply for interfaces with both modules and components.
- (4) For more information on the required DDR2 memory device speed grade for external memory interface to achieve performance as stated in this table, refer to AN445: Design Guidelines for Implementing DDR and DDR2 SDRAM Interfaces in Cyclone III Devices.
- (5) QDRII SRAM also supports the 1.5-V HSTL I/O standard. However, Altera recommends using the 1.8-V HSTL I/O standard for maximum performance because of the higher I/O drive strength.

**Table 1–33.** Cyclone III Devices Maximum Clock Rate Support for External Memory Interfaces with Full-Rate Controller (Note 1),(2) (Part 1 of 2)

		ed Grade Hz)	C7 Speed (MH		C8 Speed (MH		17 Speed (MH		A7 Speed (MH	
Memory Standard	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks
DDR2 SDRAM (3),(4),(5)	200	167	167	150	167	133	167	150	167	133

**Table 1–33.** Cyclone III Devices Maximum Clock Rate Support for External Memory Interfaces with Full-Rate Controller (Note 1),(2) (Part 2 of 2)

		ed Grade Hz)	C7 Speed (MH		C8 Speed (MH		17 Speed (MH		A7 Speed (MH	
Memory Standard	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks	Column I/O Banks	Row I/O Banks
DDR SDRAM (3)	167	150	150	133	133	125	150	133	133	125

#### Notes to Table 1-33:

- (1) Column I/O banks refer to top and bottom I/Os. Row I/O banks refer to right and left I/Os.
- (2) The supported operating frequencies listed here are memory interface maximums for the FPGA device. The actual achievable performance of your design is based on the design and system specific factors, as well as static timing analysis of the completed design.
- (3) The values apply for interfaces with both modules and components.
- (4) We recommend the use of ALTMEMPHY AFI mode to achieve these quoted maximum clock rate due to lower performance of Non-AFI mode.
- (5) For the required DDR2 memory device speed grade for external memory interface to achieve performance as stated in this table, refer to AN445: Design Guidelines for Implementing DDR and DDR2 SDRAM Interfaces in Cyclone III Devices.

Table 1–34. Cyclone III Devices FPGA Sampling Window (SW) Requirement – Read Side (Note 1) (Part 1 of 2)

Manager Olandard	Colun	ın I/Os	Row	ı I/Os	Wraparound Mode		
Memory Standard	Setup	Hold	Setup	Hold	Setup	Hold	
	ч	•	<i>C6</i>	•	•	•	
DDR2 SDRAM	580	550	690	640	850	800	
DDR SDRAM	585	535	700	650	870	820	
QDRII SRAM	785	735	805	755	905	855	
	1	•	<b>C</b> 7	•			
DDR2 SDRAM	705	650	770	715	985	930	
DDR SDRAM	675	620	795	740	970	915	
QDRII SRAM	900	845	910	855	1085	1030	
	4	•	С8			•	
DDR2 SDRAM	785	720	930	870	1115	1055	
DDR SDRAM	800	740	915	855	1185	1125	
QDRII SRAM	1050	990	1065	1005	1210	1150	
	1	•	17	•			
DDR2 SDRAM	765	710	855	800	1040	985	
DDR SDRAM	745	690	880	825	1000	945	
QDRII SRAM	945	890	955	900	1130	1075	
	•		A7		•	•	
DDR2 SDRAM	805	745	1020	960	1145	1085	
DDR SDRAM	880	820	955	935	1220	1160	

**Table 1–34.** Cyclone III Devices FPGA Sampling Window (SW) Requirement – Read Side (*Note 1*) (Part 2 of 2)

Momery Standard	Colum	ın I/Os	Row	I/Os	Wraparound Mode		
Memory Standard	Setup	Hold	Setup	Hold	Setup	Hold	
QDRII SRAM	1090	1030	1105	1045	1250	1190	

#### Note to Table 1-34:

**Table 1–35.** Cyclone III Devices Transmitter Channel-to-Channel Skew (TCCS) – Write Side (*Note 1*) (Part 1 of 2)

Memory	1/0 01 - 1 - 1	Column	I/Os (ps)	Row I/	'Os (ps)	Wraparoun	Wraparound Mode (ps)		
Standard	I/O Standard	Lead	Lag	Lead	Lag	Lead	Lag		
	1	1	C6	<u>l</u>	J.	· ·			
DDR2 SDRAM	SSTL-18 Class I	790	380	790	380	890	480		
DDRZ SDRAM	SSTL-18 Class II	870	490	870	490	970	590		
	SSTL-2 Class I	750	320	750	320	850	420		
DDR SDRAM	SSTL-2 Class II	860	350	860	350	960	450		
ODDII CDAM	1.8 V HSTL Class I	780	410	780	410	880	510		
QDRII SRAM	1.8 V HSTL Class II	830	510	830	510	930	610		
		1	<b>C</b> 7	•	•	•	•		
	SSTL-18 Class I	915	410	915	410	1015	510		
DDR2 SDRAM	SSTL-18 Class II	1025	545	1025	545	1125	645		
DDR SDRAM	SSTL-2 Class I	880	340	880	340	980	440		
DUN SUNAIVI	SSTL-2 Class II	1010	380	1010	380	1110	480		
	1.8 V HSTL Class I	910	450	910	450	1010	550		
QDRII SRAM	1.8 V HSTL Class II	1010	570	1010	570	1110	670		
			C8			•			
DDR2 SDRAM	SSTL-18 Class I	1040	440	1040	440	1140	540		
DDNZ SDNAM	SSTL-18 Class II	1180	600	1180	600	1280	700		
DDR SDRAM	SSTL-2 Class I	1010	360	1010	360	1110	460		
DUN SUNAIVI	SSTL-2 Class II	1160	410	1160	410	1260	510		
QDRII SRAM	1.8 V HSTL Class I	1040	490	1040	490	1140	590		
QDNII SNAW	1.8 V HSTL Class II	1190	630	1190	630	1290	730		
			17						
DDR2 SDRAM	SSTL-18 Class I	961	431	961	431	1061	531		
DDINZ SDINAINI	SSTL-18 Class II	1076	572	1076	572	1176	672		
DDR SDRAM	SSTL-2 Class I	924	357	924	357	1024	457		
ואואחתפ חחת	SSTL-2 Class II	1061	399	1061	399	1161	499		
QDRII SRAM	1.8 V HSTL Class I	956	473	956	473	1056	573		
ואואחט ווחטא	1.8 V HSTL Class II	1061	599	1061	599	1161	699		

<sup>(1)</sup> Column I/Os refer to top and bottom I/Os. Row I/Os refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.

Switching Characteristics
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<b>Table 1–35.</b> Cyclone III Devices Trans	smitter Channel-to-Channel Skew (TCCS	S) – Write Side (Note 1)	(Part 2 of 2)
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Memory	I/O Standard	Column I/Os (ps)		Row I/	Os (ps)	Wraparound Mode (ps)				
Standard	I/O Standard	Lead	Lag	Lead	Lag	Lead	Lag			
A7										
DDR2 SDRAM	SSTL-18 Class I	1092	462	1092	462	1192	562			
	SSTL-18 Class II	1239	630	1239	630	1339	730			
	SSTL-2 Class I	1061	378	1061	378	1161	478			
DDR SDRAM	SSTL-2 Class II	1218	431	1218	431	1318	531			
QDRII SRAM	1.8 V HSTL Class I	1092	515	1092	515	1192	615			
	1.8 V HSTL Class II	1250	662	1250	662	1350	762			

#### Notes to Table 1-35:

- (1) Column I/O banks refer to top and bottom I/Os. Row I/O banks refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.
- (2) For DDR2 SDRAM write timing performance on Columns I/O for C8 and A7 devices, 97.5 degree phase offset is required.

Table 1-36. Cyclone III Devices Memory Output Clock Jitter Specifications (Note 1), (2)

Parameter	Symbol	Min	Max	Unit
Clock period jitter	t <sub>JIT(per)</sub>	-125	125	ps
Cycle-to-cycle period jitter	t <sub>JIT(cc)</sub>	-200	200	ps
Duty cycle jitter	t <sub>JIT(duty)</sub>	-150	150	ps

#### Notes to Table 1-36:

- (1) The memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock network.

#### **Duty Cycle Distortion Specifications**

Table 1–37 lists the worst case duty cycle distortion for Cyclone III devices.

**Table 1–37.** Duty Cycle Distortion on Cyclone III Devices I/O Pins (Note 1), (2)

Sumbal	C6		C7, I7		C8, A7		Unit	
Symbol	Min	Max	Min	Max	Min	Max	UNIT	
Output Duty Cycle	45	55	45	55	45	55	%	

#### Notes to Table 1-37:

- (1) Duty cycle distortion specification applies to clock outputs from PLLs, global clock tree, and IOE driving dedicated and general purpose I/O pins.
- (2) Cyclone III devices meet specified duty cycle distortion at maximum output toggle rate for each combination of I/O standard and current strength.

## **OCT Calibration Timing Specification**

Table 1–38 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone III devices.

**Table 1–38.** Cyclone III Devices Timing Specification for Series OCT with Calibration at Device Power-Up (Note 1)

Symi	bol	Description	Maximum	Unit
toctcal		Duration of series OCT with calibration at device power-up	20	μs

### Notes to Table 1-38:

(1) OCT calibration takes place after device configuration, before entering user mode.

## **IOE Programmable Delay**

Table 1–39 and Table 1–40 list IOE programmable delay for Cyclone III devices.

**Table 1–39.** Cyclone III Devices IOE Programmable Delay on Column Pins (Note 1), (2)

		Number				N	Nax Offse	t				
Parameter	Paths Affected	Number of	Min Offset	Fast 0	Corner	Slow Corner		Unit				
Andoteu	Settings		A7, I7	C6	C6	<b>C</b> 7	C8	17	A7			
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.211	1.314	2.175	2.32	2.386	2.366	2.49	ns	
Input delay from pin to input register	Pad to I/O input register	8	0	1.203	1.307	2.19	2.387	2.54	2.43	2.545	ns	
Delay from output register to output pin	I/O output register to pad	2	0	0.479	0.504	0.915	1.011	1.107	1.018	1.048	ns	
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.664	0.694	1.199	1.378	1.532	1.392	1.441	ns	

### Notes to Table 1-39:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting '0' as available in the Quartus II software.

		Number				ľ	/lax Offse	t			
Parameter	Paths Affected	of	Min Offset	Fast (	orner	r Slow Corner				Unit	
Anotou		Settings		A7, I7	C6	C6	<b>C</b> 7	C8	17	A7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.209	1.314	2.174	2.335	2.406	2.381	2.505	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.207	1.312	2.202	2.402	2.558	2.447	2.557	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.51	0.537	0.962	1.072	1.167	1.074	1.101	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.669	0.698	1.207	1.388	1.542	1.403	1.45	ns

**Table 1–40.** Cyclone III Devices IOE Programmable Delay on Row Pins (Note 1), (2)

### Notes to Table 1-40:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting '0' as available in the Quartus II software

## I/O Timing

You can use the following methods to determine the I/O timing:

- the Excel-based I/O Timing.
- the Quartus II timing analyzer.

The Excel-based I/O Timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II timing analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.



The Excel-based I/O Timing spreadsheet is downloadable from Cyclone III Devices Literature website.

# Glossary

Table 1–41 lists the glossary for this chapter.

Table 1-41. Glossary (Part 1 of 5)

Letter	Term	Definitions
Α	_	_
В	_	_
C	_	_
D	_	_
E	_	_
F	f <sub>HSCLK</sub>	HIGH-SPEED I/O Block: High-speed receiver/transmitter input and output clock frequency.
C	GCLK	Input pin directly to Global Clock network.
G	GCLK PLL	Input pin to Global Clock network through PLL.
Н	HSIODR	HIGH-SPEED I/O Block: Maximum/minimum LVDS data transfer rate (HSIODR = 1/TUI).
I	Input Waveforms for the SSTL Differential I/O Standard	Vswing V <sub>IH</sub>
J	JTAG Waveform	TDI  TDI  TDI  TJCP  TJCP  TJCH  TJC
K	_	_
L	_	_
M	_	_
N	_	_
0		

Table 1-41. Glossary (Part 2 of 5)

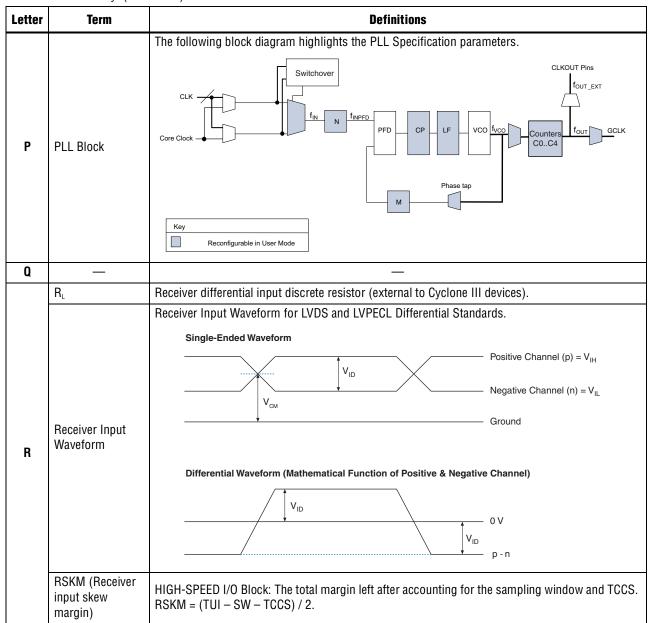


Table 1-41. Glossary (Part 3 of 5)

Letter	Term	Definitions						
S	Single-ended Voltage referenced I/O Standard	The JEDEC standard for SSTI and HSTL I/O standards defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform <i>ringing</i> .						
	SW (Sampling Window)	HIGH-SPEED I/O Block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window.						
	t <sub>c</sub> TCCS (Channel-to-channel-skew)	High-speed receiver/transmitter input and output clock period.  HIGH-SPEED I/O Block: The timing difference between the fastest and slowest output edges, including t <sub>co</sub> variation and clock skew. The clock is included in the TCCS measurement.  Delay from clock pad to I/O input register.						
	t <sub>co</sub>	Delay from clock pad to I/O output.						
	tcout	Delay from clock pad to I/O output register.  HIGH-SPEED I/O Block: Duty cycle on high-speed transmitter output clock.						
т	t <sub>FALL</sub>	Signal High-to-low transition time (80–20%).						
•	t <sub>H</sub>	Input register hold time.						
	Timing Unit Interval (TUI)	HIGH-SPEED I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = 1/(Receiver Input Clock Frequency Multiplication Factor) = t <sub>c</sub> /w).						
	t <sub>INJITTER</sub>	Period jitter on PLL clock input.						
	t <sub>outjitter_dedclk</sub>	Period jitter on dedicated clock output driven by a PLL.						
	t <sub>outjitter_io</sub>	Period jitter on general purpose I/O driven by a PLL.						
	tpllcin	Delay from PLL inclk pad to I/O input register.						
	tpllcout	Delay from PLL inclk pad to I/O output register.						

**Table 1-41.** Glossary (Part 4 of 5)

Letter	Term	Definitions
	Transmitter Output Waveform	Transmitter Output Waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards  Single-Ended Waveform  Positive Channel (p) = V <sub>OH</sub> Negative Channel (n) = V <sub>OL</sub> Ground
		Differential Waveform (Mathematical Function of Positive & Negative Channel)  V <sub>OD</sub> 0 V  p - n
	t <sub>RISE</sub>	Signal Low-to-high transition time (20–80%).
	t <sub>su</sub>	Input register setup time.
U	_	_

**Table 1–41.** Glossary (Part 5 of 5)

Letter	Term	Definitions
	V <sub>CM(DC)</sub>	DC Common Mode Input Voltage.
	V <sub>DIF(AC)</sub>	AC differential Input Voltage: The minimum AC input differential voltage required for switching.
	V <sub>DIF(DC)</sub>	DC differential Input Voltage: The minimum DC input differential voltage required for switching.
	V <sub>ICM</sub>	Input Common Mode Voltage: The common mode of the differential signal at the receiver.
	V <sub>ID</sub>	Input differential Voltage Swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
	V <sub>IH</sub>	Voltage Input High: The minimum positive voltage applied to the input which is accepted by the device as a logic high.
	V <sub>IH(AC)</sub>	High-level AC input voltage.
	V <sub>IH(DC)</sub>	High-level DC input voltage.
	V <sub>IL</sub>	Voltage Input Low: The maximum positive voltage applied to the input which is accepted by the device as a logic low.
	V <sub>IL (AC)</sub>	Low-level AC input voltage.
	V <sub>IL (DC)</sub>	Low-level DC input voltage.
	V <sub>IN</sub>	DC input voltage.
	V <sub>OCM</sub>	Output Common Mode Voltage: The common mode of the differential signal at the transmitter.
V	V <sub>OD</sub>	Output differential Voltage Swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the transmitter. $V_{\text{OD}} = V_{\text{OH}} - V_{\text{OL}}$ .
	V <sub>OH</sub>	Voltage Output High: The maximum positive voltage from an output which the device considers is accepted as the minimum positive high level.
	V <sub>OL</sub>	Voltage Output Low: The maximum positive voltage from an output which the device considers is accepted as the maximum positive low level.
	V <sub>os</sub>	Output offset voltage: $V_{OS} = (V_{OH} + V_{OL}) / 2$ .
	V <sub>OX (AC)</sub>	AC differential Output cross point voltage: The voltage at which the differential output signals must cross.
	$V_{REF}$	Reference voltage for SSTL, HSTL I/O Standards.
	V <sub>REF (AC)</sub>	AC input reference voltage for SSTL, HSTL I/O Standards. $V_{REF(AC)} = V_{REF(DC)} + noise$ . The peak-to-peak AC noise on $V_{REF}$ should not exceed 2% of $V_{REF(DC)}$ .
	V <sub>REF (DC)</sub>	DC input reference voltage for SSTL, HSTL I/O Standards.
	V <sub>SWING (AC)</sub>	AC differential Input Voltage: AC Input differential voltage required for switching. For the SSTL Differential I/O Standard, refer to Input Waveforms.
	V <sub>SWING (DC)</sub>	DC differential Input Voltage: DC Input differential voltage required for switching. For the SSTL Differential I/O Standard, refer to Input Waveforms.
	V <sub>TT</sub>	Termination voltage for SSTL, HSTL I/O Standards.
	V <sub>x (AC)</sub>	AC differential Input cross point Voltage: The voltage at which the differential input signals must cross.
W	_	
Х		_
Υ	_	_
Z		_

# **Document Revision History**

Table 1–42 lists the revision history for this chapter.

**Table 1–42.** Document Revision History (Part 1 of 3)

Date	Version	Changes Made
December 2009	3.2	Minor changes to the text.
July 2009	3.1	Minor edit to the hyperlinks.
		<ul> <li>Changed chapter title from DC and Switching Characteristics to "Cyclone III Device Data Sheet" on page 1–1.</li> </ul>
		■ Updated (Note 1) to Table 1–23 on page 1–17.
		<ul> <li>Updated "External Memory Interface Specifications" on page 1–23.</li> </ul>
		■ Replaced Table 1–32 on page 1–23.
June 2009	3.0	■ Replaced Table 1–33 on page 1–23.
		<ul> <li>Added Table 1–36 on page 1–26.</li> </ul>
		■ Updated "I/O Timing" on page 1–28.
		<ul><li>Removed "Typical Design Performance" section.</li></ul>
		Removed "I/O Timing" subsections.
		<ul> <li>Updated chapter to new template.</li> </ul>
		■ Updated Table 1–1, Table 1–3, and Table 1–18.
October 2008	2.2	<ul><li>Added (Note 7) to Table 1–3.</li></ul>
		<ul><li>Added the "OCT Calibration Timing Specification" section.</li></ul>
		<ul><li>Updated "Glossary" section.</li></ul>
		■ Updated Table 1–38.
		<ul> <li>Added BLVDS information (I/O standard) into Table 1–39, Table 1–40,</li> <li>Table 1–41, Table 1–42.</li> </ul>
July 2008	2.1	■ Updated Table 1–43, Table 1–46, Table 1–47, Table 1–48, Table 1–49, Table 1–50, Table 1–51, Table 1–52, Table 1–53, Table 1–54, Table 1–55, Table 1–56, Table 1–57, Table 1–58, Table 1–59, Table 1–60, Table 1–61, Table 1–62, Table 1–63, Table 1–68, Table 1–69, Table 1–74, Table 1–75, Table 1–80, Table 1–81, Table 1–86, Table 1–87, Table 1–92, Table 1–93, Table 1–94, Table 1–95, Table 1–96, Table 1–97, Table 1–98, and Table 1–99.

**Table 1–42.** Document Revision History (Part 2 of 3)

Date	Version	Changes Made			
		<ul> <li>Updated "Operating Conditions" section and included information on automotive device.</li> </ul>			
		<ul> <li>Updated Table 1–3, Table 1–6, and Table 1–7, and added automotive information.</li> </ul>			
		■ Under "Pin Capacitance" section, updated Table 1–9 and Table 1–10.			
		■ Added new "Schmitt Trigger Input" section with Table 1–12.			
		■ Under "I/O Standard Specifications" section, updated Table 1–13, 1–12 and 1–12.			
May 2008	2.0	■ Under "Switching Characteristics" section, updated Table 1–19, 1–15, 1–16, 1–16, 1–17, 1–18, 1–19, 1–20, 1–21, 1–21, 1–23, 1–23, 1–23, 1–24, and 1–25.			
		■ Updated Figure 1–5 and 1–29.			
		Deleted previous Table 1-35 "DDIO Outputs Half-Period Jitter".			
		<ul> <li>Under "I/O Timing" section, updated Table 1–38, 1–29, 1–32, 1–33, 1–26, and 1–26.</li> </ul>			
		<ul> <li>Under "Typical Design Performance" section updated Table 1–46 through 1–145.</li> </ul>			
		Under "Core Performance Specifications", updated Tables 1-18 and 1-19.			
December 2007	1.5	<ul><li>Under "Preliminary, Correlated, and Final Timing", updated Table 1-37.</li></ul>			
		<ul> <li>Under "Typical Design Performance", updated Tables 1-45, 1-46, 1-51, 1-52, 1-57, 1-58, Tables 1-63 through 1-68. 1-69, 1-70, 1-75, 1-76, 1-81, 1-82, Tables 1-87 through 1-92, Tables 1-99, 1-100, 1-107, and 1-108.</li> </ul>			
		■ Updated the C <sub>VREFTB</sub> value in Table 1-9.			
		■ Updated Table 1-21.			
		<ul> <li>Under "High-Speed I/O Specification" section, updated Tables 1-25 through 1-30.</li> </ul>			
		<ul><li>Updated Tables 1-31 through 1-38.</li></ul>			
		Added new Table 1-32.			
October 2007	1.4	<ul> <li>Under "Maximum Input and Output Clock Toggle Rate" section, updated Tables 1-40 through 1-42.</li> </ul>			
		<ul> <li>Under "IOE Programmable Delay" section, updated Tables 1-43 through 1- 44.</li> </ul>			
		<ul> <li>Under "User I/O Pin Timing Parameters" section, updated Tables 1-45 through 1-92.</li> </ul>			
		<ul> <li>Under "Dedicated Clock Pin Timing Parameters" section, updated Tables 1-93 through 1-108.</li> </ul>			
		■ Updated Table 1-1 with V <sub>ESDHBM</sub> and V <sub>ESDCDM</sub> information.			
		■ Updated R <sub>CONF_PD</sub> information in Tables 1-10.			
July 2007	1.3	Added <i>Note (3</i> ) to Table 1-12.			
	1.3	■ Updated t <sub>DLOCK</sub> information in Table 1-19.			
		■ Updated Table 1-43 and Table 1-44.			
		<ul> <li>Added "Document Revision History" section.</li> </ul>			
June 2007	1.2	Updated Cyclone III graphic in cover page.			

**Table 1–42.** Document Revision History (Part 3 of 3)

Date	Version	Changes Made
		Corrected current unit in Tables 1-1, 1-12, and 1-14.
		Added <i>Note (3)</i> to Table 1-3.
		■ Updated Table 1-4 with I <sub>CCINTO</sub> , I <sub>CCAO</sub> , I <sub>CCD_PLLO</sub> , and I <sub>CCIOO</sub> information.
		<ul><li>Updated Table 1-9 and added Note (2).</li></ul>
		<ul><li>Updated Table 1-19.</li></ul>
		<ul><li>Updated Table 1-22 and added Note (1).</li></ul>
May 2007	1.1	<ul> <li>Changed I/O standard from 1.5-V LVTTL/LVCMOS and 1.2-V LVTTL/LVCMOS to 1.5-V LVCMOS and 1.2-V LVCMOS in Tables 1-41, 1-42, 1-43, 1-44, and 1- 45.</li> </ul>
		<ul> <li>Updated Table 1-43 with changes to LVPEC and LVDS and added Note (5).</li> </ul>
		<ul><li>Updated Tables 1-46, 1-47, Tables 1-54 through 1-95, and Tables 1-98 through 1-111.</li></ul>
		<ul> <li>Removed speed grade –6 from Tables 1-90 through 1-95, and from Tables 1- 110 through 1-111.</li> </ul>
		<ul> <li>Added a waveform (Receiver Input Waveform) in glossary under letter "R" (Table 1-112).</li> </ul>
March 2007	1.0	Initial release.



## 2. Cyclone III LS Device Data Sheet

CIII52002-1.2

This chapter describes the electric characteristics, switching characteristics, and I/O timing for Cyclone<sup>®</sup> III LS devices. A glossary is also included for your reference.

## **Electrical Characteristics**

The following sections provide information about the absolute maximum ratings, recommended operating conditions, DC characteristics, and other specifications for Cyclone III LS devices.

## **Operating Conditions**

When Cyclone III LS devices are implemented in a system, they are rated according to a set of defined parameters. To maintain the highest possible performance and reliability of Cyclone III LS devices, you must consider the operating requirements in this chapter. Cyclone III LS devices are offered in commercial and industrial grades. Commercial devices are offered in –7 (fastest) and –8 speed grades. Industrial devices are offered only in –7 speed grade.



In this chapter, a prefix associated with the operating temperature range is attached to the speed grades—commercial with a "C" prefix; industrial with an "I" prefix. For example, commercial devices are described as C7 and C8 per respective speed grades. Industrial devices are described as I7.

### **Absolute Maximum Ratings**

Absolute maximum ratings define the maximum operating conditions for Cyclone III LS devices. The values are based on experiments conducted with the device and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied at these conditions. Table 2–1 lists the absolute maximum ratings for Cyclone III LS devices.



Conditions beyond those listed in Table 2–1 may cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time may have adverse effects on the device. All parameters representing voltages are measured with respect to ground.

**Table 2–1.** Cyclone III LS Devices Absolute Maximum Ratings (*Note 1*) (Part 1 of 2)

Symbol	Parameter	Min	Max	Unit
V <sub>CCINT</sub>	Supply voltage for internal logic	-0.5	1.8	V
V <sub>ccio</sub>	Supply voltage for output buffers	-0.5	3.9	V
V <sub>CCA</sub>	Supply (analog) voltage for PLL regulator	-0.5	3.75	V
V <sub>CCD_PLL</sub>	Supply (digital) voltage for PLL	-0.5	1.8	V
V <sub>CCBAT</sub>	Battery back-up power supply for design security volatile key register	-0.5	3.75	V
Vı	DC input voltage	-0.5	3.95	V

			,	
Symbol	Parameter	Min	Max	Unit
I <sub>out</sub>	DC output current, per pin	-25	40	mA
V <sub>ESDHBM</sub>	Electrostatic discharge voltage using the human body model	_	±2000	V
V <sub>ESDCDM</sub>	Electrostatic discharge voltage using the charged device model	_	±500	V
T <sub>STG</sub>	Storage temperature	-65	150	°C
TJ	Operating junction temperature	-40	100	°C

**Table 2–1.** Cyclone III LS Devices Absolute Maximum Ratings (Note 1) (Part 2 of 2)

#### Note to Table 2-1:

### **Maximum Allowed Overshoot or Undershoot Voltage**

During transitions, input signals may overshoot to the voltage listed in Table 2–2 and undershoot to -2.0 V for a magnitude of currents less than 100 mA and for periods shorter than 20 ns.

Table 2-2 lists the maximum allowed input overshoot voltage and the duration of the overshoot voltage as a percentage over the lifetime of the device. The maximum allowed overshoot duration is specified as percentage of high-time over the lifetime of the device.



A DC signal is equivalent to 100% of the duty cycle. For example, a signal that overshoots to 4.2 V can only be at 4.2 V for 10.74% over the lifetime of the device; for a device lifetime of 10 years, this is equivalent to 10.74% of ten years, which is 12.89 months.

Table 2-2. Cyclone III LS Devices Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame

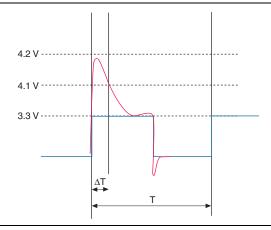
Symbol	Parameter	Condition	Overshoot Duration as % of High Time	Unit
		V <sub>i</sub> = 3.95 V	100	%
		V <sub>1</sub> = 4.0 V	95.67	%
		V <sub>1</sub> = 4.05 V	55.24	%
		V <sub>1</sub> = 4.10 V	31.97	%
		V <sub>1</sub> = 4.15 V	18.52	%
		V <sub>1</sub> = 4.20 V	10.74	%
M	AC Input	V <sub>1</sub> = 4.25 V	6.23	%
$V_{i}$	Voltage	V <sub>1</sub> = 4.30 V	3.62	%
		V <sub>1</sub> = 4.35 V	2.1	%
		V <sub>1</sub> = 4.40 V	1.22	%
		V <sub>1</sub> = 4.45 V	0.71	%
		V <sub>1</sub> = 4.50 V	0.41	%
		V <sub>1</sub> = 4.60 V	0.14	%
		V <sub>1</sub> = 4.70 V	0.047	%

<sup>(1)</sup> Supply voltage specifications apply to voltage readings taken at the device pins with respect to ground, not at the power supply.

Figure 2–1 shows the methodology to determine the overshoot duration. In this example, overshoot voltage is shown in red and is present on the input pin of the Cyclone III LS device at over 4.1 V but below 4.2 V. From Table 2–1, for an overshoot of 4.1 V, the percentage of high time for the overshoot can be as high as 31.97% over a 10-year period. Percentage of high time is calculated as ([delta T]/T)  $\times$  100. This 10-year period assumes the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is

Figure 2-1. Cyclone III LS Devices Overshoot Duration

in an idle state, lifetimes are increased.



### **Recommended Operating Conditions**

This section lists the functional operation limits for AC and DC parameters for Cyclone III LS devices.

The steady-state voltage and current values expected from Cyclone III LS devices are provided in Table 2–3. All supplies must be strictly monotonic without plateaus.

Table 2-3. Cyclone III LS Devices Recommended Operating Conditions (Note 1), (2) (Part 1 of 2)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CCINT</sub> (3)	Supply voltage for internal logic	_	1.15	1.2	1.25	V
	Supply voltage for output buffers, 3.3-V operation	I	3.135	3.3	3.465	V
	Supply voltage for output buffers, 3.0-V operation	_	2.85	3.0	3.15	V
V <sub>ccio</sub> (3), (6)	Supply voltage for output buffers, 2.5-V operation	_	2.375	2.5	2.625	V
V <sub>CCIO</sub> (3), (0)	Supply voltage for output buffers, 1.8-V operation	_	1.71	1.8	1.89	V
	Supply voltage for output buffers, 1.5-V operation	_	1.425	1.5	1.575	V
	Supply voltage for output buffers, 1.2-V operation		1.14	1.2	1.26	V
V <sub>CCA</sub> (3)	Supply (analog) voltage for PLL regulator	_	2.375	2.5	2.625	V
V <sub>CCD_PLL</sub> (3)	Supply (digital) voltage for PLL	_	1.15	1.2	1.25	V

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CCBAT</sub>	Battery back-up power supply for design security volatile key register	_	1.2	3.0	3.3	V
Vı	Input voltage	_	-0.5	_	3.6	V
V <sub>0</sub>	Output voltage	_	0	_	V <sub>ccio</sub>	V
т	Operating junction temperature	For commercial use	0	_	85	°C
$T_J$	Operating junction temperature	For industrial use	-40	_	100	°C
+	Dower cumby remntime	Standard POR (4)	50 μs	_	50 ms	_
t <sub>RAMP</sub>	Power supply ramptime	Fast POR (5)	50 μs	_	3 ms	_
l <sub>Diode</sub>	Magnitude of DC current across PCI-clamp diode when enabled	_	_	_	10	mA

Table 2-3. Cyclone III LS Devices Recommended Operating Conditions (Note 1), (2) (Part 2 of 2)

### Notes to Table 2-3:

- (1) V<sub>CCIO</sub> for all I/O banks must be powered up during device operation. All V<sub>CCA</sub> pins must be powered to 2.5 V (even when you do not use phase locked-loops [PLLs}), and must be powered up and powered down at the same time.
- (2)  $V_{CCD\_PLL}$  must always be connected to  $V_{CCINT}$  through a decoupling capacitor and ferrite bead.
- (3) V<sub>cc</sub> must rise monotonically.
- (4) Power-on reset (POR) time for Standard POR ranges from 50 to 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (5) POR time for Fast POR ranges from 3 to 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.
- (6) All input buffers are powered by the  $V_{ccio}$  supply.

### **DC Characteristics**

This section lists the I/O leakage current, pin capacitance, on-chip termination (OCT) tolerance, and bus hold specifications for Cyclone III LS devices.

### **Supply Current**

Supply current is the current the device draws after the device is configured with no inputs or outputs toggling and no activity in the device. Use the Excel-based Early Power Estimator (EPE) to get the supply current estimates for your design because these currents vary largely with the resources you use.

Table 2-4 lists the I/O pin leakage current for Cyclone III LS devices.

**Table 2–4.** Cyclone III LS Devices I/O Pin Leakage Current (Note 1), (2)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>1</sub>	Input Pin Leakage Current	$V_{I} = V_{CCIOMAX}$ to 0 V	-10	_	10	μΑ
I <sub>oz</sub>	Tri-stated I/O Pin Leakage Current	V <sub>0</sub> = V <sub>CCIOMAX</sub> to 0 V	-10	_	10	μА

### Notes to Table 2-4:

- (1) This value is specified for normal device operation. The value varies during device power-up. This applies for all V<sub>CCIO</sub> settings (3.3, 3.0, 2.5, 1.8, 1.5, and 1.2 V).
- (2) The 10  $\mu$ A I/O leakage current limit is applicable when the internal clamping diode is off. A higher current can be observed when the diode is on.

### **Bus Hold**

Bus hold retains the last valid logic state after the source driving it either enters the high impedance state or is removed. Each I/O pin has an option to enable bus hold in user mode. Bus hold is always disabled in configuration mode.

Table 2–5 lists the bus hold specifications for Cyclone III LS devices. Also listed are the input pin capacitances and OCT tolerance specifications.

**Table 2–5.** Cyclone III LS Devices Bus Hold Parameters (*Note 1*)

							V <sub>ccio</sub> (	V)						
Parameter	Condition	1	.2	1	.5	1	.8	2	2.5	3	3.0	3	.3	Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus-hold low, sustaining current	V <sub>IN</sub> > V <sub>IL</sub> (maximum)	8	_	12	_	30	_	50	_	70	_	70	_	μА
Bus-hold high, sustaining current	V <sub>IN</sub> < V <sub>IL</sub> (minimum)	-8	_	-12	_	-30	_	-50	_	-70	_	-70	_	μА
Bus-hold low, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	_	125	_	175	_	200	_	300	_	500	_	500	μА
Bus-hold high, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	_	-125	_	-175	_	-200		-300		-500		-500	μА
Bus-hold trip point	_	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2.0	0.8	2.0	V

### Note to Table 2-5:

### **OCT Specifications**

Table 2–6 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

**Table 2–6.** Cyclone III LS Devices Series OCT without Calibration Specifications

Description	v 00	Resistance Tole	rance	Ileit
Description	V <sub>CCIO</sub> (V)	Commercial Max	Industrial Max	Unit
	3.0	±30	±40	%
0 : 00T '''	2.5	±30	±40	%
Series OCT without calibration	1.8	±40	±50	%
Canstation	1.5	±50	±50	%
	1.2	±50	±50	%

<sup>(1)</sup> Bus-hold trip points are based on calculated input voltages from the JEDEC standard.

OCT calibration is automatically performed at device power-up for OCT enabled I/Os.

Table 2–7 lists the OCT calibration accuracy at device power-up.

**Table 2–7.** Cyclone III LS Devices Series OCT with Calibration at Device Power-Up Specifications

Description	V 00	Calibration Accuracy			
Description	V <sub>ccio</sub> (V)	Commercial Max	Industrial Max	Unit	
	3.0	±10	±10	%	
0	2.5	±10	±10	%	
Series Termination with power-up calibration	1.8	±10	±10	%	
potrot ap cambration	1.5	±10	±10	%	
	1.2	±10	±10	%	

OCT resistance may vary with the variation of temperature and voltage after power-up calibration. Use Table 2–8 and Equation 2–1 to determine the final OCT resistance considering the variations after power-up calibration.

Table 2–8 lists the percentage change of the OCT resistance with voltage and temperature.

**Table 2–8.** Cyclone III LS Devices OCT Variation After Calibration at Device Power-Up (*Note 1*)

Nominal Voltage	dR/dT (%/°C)	dR/dV (%/mV)
3.0	0.262	-0.026
2.5	0.234	-0.039
1.8	0.219	-0.086
1.5	0.199	-0.136
1.2	0.161	-0.288

### Note to Table 2-8:

(1) Use this table to calculate the final OCT resistance with the variation of temperature and voltage.

$$\Delta R_V = (V_2 - V_1) \times 1000 \times dR/dV - (7)$$

$$\Delta R_T = (T_2 - T_1) \times dR/dT - (8)$$

For 
$$\Delta R_x < 0$$
;  $MF_x = 1/(|\Delta R_x|/100 + 1)$  ——— (9)

For 
$$\Delta R_x > 0$$
;  $MF_x = \Delta R_x/100 + 1 - (10)$ 

$$MF = MF_V \times MF_T ---- (11)$$

$$R_{final} = R_{initial} \times MF - (12)$$

### Notes to Equation 2-1:

- (1)  $T_2$  is the final temperature.
- (2)  $T_1$  is the initial temperature.
- (3) MF is multiplication factor.
- (4) R<sub>final</sub> is final resistance.
- (5) R<sub>initial</sub> is initial resistance.
- (6) Subscript  $\times$  refers to both  $_V$  and  $_T$ .
- (7)  $\Delta R_V$  is variation of resistance with voltage.
- (8)  $\Delta R_T$  is variation of resistance with temperature.
- (9) dR/dT is the percentage change of resistance with temperature.
- (10) dR/dV is the percentage change of resistance with voltage.
- (11) V<sub>2</sub> is final voltage.
- (12)  $V_1$  is the initial voltage.

Example 2–1 shows you how to calculate the change of 50  $\Omega$  I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V.

## Example 2-1.

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because  $\Delta R_V$  is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because  $\Delta R_T$  is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{\text{final}} = 50 \times 1.114 = 55.71~\Omega$$

### Pin Capacitance

Table 2–9 lists the pin capacitance for Cyclone III LS devices.

**Table 2–9.** Cyclone III LS Devices Pin Capacitance (Part 1 of 2)

Symbol	Parameter	Typical – QFP	Typical – FBGA	Unit
C <sub>IOTB</sub>	Input capacitance on top/bottom I/O pins	7	6	pF
C <sub>IOLR</sub>	Input capacitance on left/right I/O pins	7	5	pF
C <sub>LVDSLR</sub>	Input capacitance on left/right I/O pins with true LVDS output	8	7	pF

**Table 2–9.** Cyclone III LS Devices Pin Capacitance (Part 2 of 2)

Symbol	Parameter	Typical – QFP	Typical – FBGA	Unit
C <sub>VREFLR</sub> (1)	Input capacitance on left/right dual-purpose $\mathtt{VREF}$ pin when used as $V_{\mathtt{REF}}$ or user I/O pin	21	21	pF
C <sub>VREFTB</sub> (1)	Input capacitance on top/bottom dual-purpose $\mathtt{VREF}$ pin when used as $V_{\mathtt{REF}}$ or user I/O pin	23	23	pF
Сськтв	Input capacitance on top/bottom dedicated clock input pins	7	6	pF
C <sub>CLKLR</sub>	Input capacitance on left/right dedicated clock input pins	6	5	pF

### Note to Table 2-9:

<sup>(1)</sup> When you use the VREF pin as a regular input or output, you can expect a reduced performance of toggle rate and  $t_{c0}$  due to higher pin capacitance.

### Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 2–10 lists the weak pull-up and pull-down resistor values for Cyclone III LS devices.

Table 2-10. Cyclone III LS Devices Internal Weak Pull-Up Weak and Pull-Down Resistor (Note 1)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
		$V_{CCIO} = 3.3 \text{ V} \pm 5\% (2), (3)$	7	25	41	kΩ
	Value of I/O pin pull-up resistor before	$V_{CCIO} = 3.0 \text{ V} \pm 5\% (2), (3)$	7	28	47	kΩ
R <sub>PU</sub>	and during configuration, as well as	$V_{CCIO} = 2.5 \text{ V} \pm 5\% (2), (3)$	8	35	61	kΩ
11_PU	user mode if the programmable pull-up resistor option is enabled	$V_{CCIO} = 1.8 \text{ V} \pm 5\% (2), (3)$	10	57	108	kΩ
		$V_{CCIO} = 1.5 \text{ V} \pm 5\% (2), (3)$	13	82	163	kΩ
		$V_{CCIO} = 1.2 \text{ V} \pm 5\% (2), (3)$	19	143	351	kΩ
		$V_{CCIO} = 3.3 \text{ V} \pm 5\% (4)$	6	19	30	kΩ
	Web and 1/O alternative and a second	$V_{CCIO} = 3.0 \text{ V} \pm 5\% (4)$	6	22	36	kΩ
$R_{\_PD}$	Value of I/O pin pull-down resistor before and during configuration	$V_{CCIO} = 2.5 \text{ V} \pm 5\% (4)$	6	25	43	kΩ
		$V_{CCIO} = 1.8 \text{ V} \pm 5\% \ (4)$	7	35	71	kΩ
		$V_{CCIO} = 1.5 \text{ V} \pm 5\% (4)$	8	50	112	kΩ

### Notes to Table 2-10:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than  $V_{\text{CCIO}}$ .

(3)  $R_{PU} = (V_{CCIO} - V_I)/I_{R_PU}$ Minimum condition:  $-40^{\circ}\text{C}$ ;  $V_{CCIO} = V_{CC} + 5\%$ ,  $V_I = V_{CC} + 5\% - 50 \text{ mV}$ ; Typical condition:  $25^{\circ}\text{C}$ ;  $V_{CCIO} = V_{CC}$ ,  $V_I = 0$  V; Maximum condition:  $125^{\circ}\text{C}$ ;  $V_{CCIO} = V_{CC} - 5\%$ ,  $V_I = 0$  V; in which  $V_I$  refers to the input voltage at the I/O pin.

(4)  $R_{PD} = V_1/I_{R_PD}$ Minimum condition: -40°C;  $V_{CCID} = V_{CC} + 5\%$ ,  $V_1 = 50$  mV;

Typical condition: 25°C;  $V_{\text{CCIO}} = V_{\text{CC}}$ ,  $V_{\text{I}} = V_{\text{CC}} - 5\%$ ; Maximum condition: 125°C;  $V_{\text{CCIO}} = V_{\text{CC}} - 5\%$ ,  $V_{\text{I}} = V_{\text{CC}} - 5\%$ ; in which  $V_{\text{I}}$  refers to the input voltage at the I/O pin.

### **Hot Socketing**

Table 2–11 lists the hot-socketing specifications for Cyclone III LS devices.

Table 2-11. Cyclone III Devices LS Hot-Socketing Specifications

	-	
Symbol	Parameter	Maximum
I <sub>IOPIN(DC)</sub>	DC current per I/O pin	300 μΑ
I <sub>IOPIN(AC)</sub>	AC current per I/O pin	8 mA <i>(1)</i>

### Note to Table 2-11:

(1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |IIOPIN| = C dv/dt, in which C is I/O pin capacitance and dv/dt is the slew rate.

### **Electrical Characteristics**

### **Schmitt Trigger Input**

Cyclone III LS devices support Schmitt trigger input on TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF\_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with a slow edge rate. Table 2–12 lists the hysteresis specifications across supported  $V_{\text{CCIO}}$  range for Schmitt trigger inputs in Cyclone III LS devices.

Table 2-12. Hysteresis Specifications for Schmitt Trigger Input in Cyclone III LS Devices

Symbol	Parameter	Conditions	Minimum	Typical	Maximum	Unit
		$V_{\text{CCIO}} = 3.3 \text{ V}$	200	_	_	mV
V <sub>SCHMITT</sub>	Hysteresis for Schmitt trigger	V <sub>ccio</sub> = 2.5 V	200	_	_	mV
VSCHMITT	input	V <sub>ccio</sub> = 1.8 V	140	_	_	mV
		V <sub>CCIO</sub> = 1.5 V	110	_	_	mV

## I/O Standard Specifications

The following tables list input voltage sensitivities ( $V_{IH}$  and  $V_{IL}$ ), output voltage ( $V_{OH}$  and  $V_{OL}$ ), and current drive characteristics ( $I_{OH}$  and  $I_{OL}$ ) for various I/O standards supported by Cyclone III LS devices.

Table 2–13 through Table 2–18 provide Cyclone III LS devices I/O standard specifications.

**Table 2–13.** Cyclone III LS Devices Single-Ended I/O Standard Specifications (*Note 1*)

I/O Standard		V <sub>ccio</sub> (V)		V	(V)	,	<b>/</b> <sub>ін</sub> (V)	V <sub>ol</sub> (V)	V <sub>oh</sub> (V)	I <sub>oL</sub>	I <sub>oh</sub>
I/O Standard	Min	Тур	Max	Min	Max	Min	Max	Max	Min	(mA)	(mA)
3.3-V LVTTL (2)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.45	2.4	4	-4
3.3-V LVCMOS (2)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.2	V <sub>ccio</sub> - 0.2	2	-2
3.0-V LVTTL (2)	2.85	3.0	3.15	-0.3	0.8	1.7	V <sub>ccio</sub> + 0.3	0.45	2.4	4	-4
3.0-V LVCMOS (2)	2.85	3.0	3.15	-0.3	0.8	1.7	V <sub>ccio</sub> + 0.3	0.2	V <sub>ccio</sub> - 0.2	0.1	-0.1
2.5-V LVTTL and LVCMOS (2)	2.375	2.5	2.625	-0.3	0.7	1.7	V <sub>ccio</sub> + 0.3	0.4	2.0	1	-1
1.8-V LVTTL and LVCMOS	1.71	1.8	1.89	-0.3	0.35 * V <sub>cc10</sub>	0.65 * V <sub>ccio</sub>	2.25	0.45	V <sub>ccio</sub> - 0.45	2	-2
1.5-V LVCMOS	1.425	1.5	1.575	-0.3	0.35 * V <sub>cc10</sub>	0.65 * V <sub>ccio</sub>	V <sub>ccio</sub> + 0.3	0.25 * V <sub>ccio</sub>	0.75 * V <sub>ccio</sub>	2	-2
1.2-V LVCMOS	1.14	1.2	1.26	-0.3	0.35 * V <sub>cc10</sub>	0.65 * V <sub>ccio</sub>	V <sub>CCIO</sub> + 0.3	0.25 * V <sub>ccio</sub>	0.75 * V <sub>CCIO</sub>	2	-2
PCI	2.85	3.0	3.15	_	0.30* V <sub>cc10</sub>	0.50* V <sub>ccio</sub>	V <sub>CCIO</sub> + 0.3	0.1 * V <sub>CCIO</sub>	0.9 * V <sub>CCIO</sub>	1.5	-0.5
PCI-X	2.85	3.0	3.15	_	0.35* V <sub>cc10</sub>	0.50* V <sub>ccio</sub>	V <sub>CCIO</sub> + 0.3	0.1 * V <sub>ccio</sub>	0.9 * V <sub>ccio</sub>	1.5	-0.5

### Notes to Table 2-13:

<sup>(1)</sup> AC load CL = 10 pF.

<sup>(2)</sup> For more information about interfacing Cyclone III LS devices with 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS I/O standards, refer to AN 447: Interfacing Cyclone III and Cyclone iV Devices with 3.3/3.0/2.5-V LVTTL and LVCMOS I/O Systems.

Table 2-14. Cyclone III LS Devices Single-Ended SSTL and HSTL I/O Reference Voltage Specifications (Note 4)

1/0		V <sub>ccio</sub> (V)	)		$V_{REF}(V)$			<b>V</b> <sub>π</sub> ( <b>V</b> ) (3)	(3)	
Standard	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	
SSTL-2 Class I, II	2.375	2.5	2.625	1.19	1.25	1.31	V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04	
SSTL-18 Class I, II	1.7	1.8	1.9	0.833	0.9	0.969	V <sub>REF</sub> - 0.04	$V_{REF}$	V <sub>REF</sub> + 0.04	
HSTL-18 Class I, II	1.71	1.8	1.89	0.85	0.9	0.95	0.85	0.9	0.95	
HSTL-15 Class I, II	1.425	1.5	1.575	0.71	0.75	0.79	0.71	0.75	0.79	
HSTL-12 Class I, II	1.14	1.2	1.26	0.48 * V <sub>ccio</sub> (1) 0.47 * V <sub>ccio</sub> (2)	0.5 * V <sub>ccio</sub> (1) 0.5 * V <sub>ccio</sub> (2)	0.52 * V <sub>ccio</sub> (1) 0.53 * V <sub>ccio</sub> (2)	_	0.5 * V <sub>CCIO</sub>	_	

### Notes to Table 2-14:

- (1) The value shown refers to the DC input reference voltage,  $V_{\text{REF(DC)}}$ .
- (2) The value shown refers to the AC input reference voltage,  $V_{\text{REF(AC)}}\!.$
- (3)  $V_{TT}$  of the transmitting device must track  $V_{REF}$  of the receiving device.
- (4) For an explanation of the terms used in Table 2–14, refer to "Glossary" on page 2–26.

Table 2-15. Cyclone III LS Devices Single-Ended SSTL and HSTL I/O Standards Signal Specifications

1/0	V <sub>IL(E</sub>	<sub>nc)</sub> (V)	V	<sub>H(DC)</sub> <b>(V)</b>	VILL	<sub>AC)</sub> (V)	V,	<sub>H(AC)</sub> (V)	V <sub>ol</sub> (V)	V <sub>OH</sub> (V)	I <sub>oL</sub>	I <sub>OH</sub>
Standard	Min	Max	Min	Max	Min	Max	Min	Max	Max	Min	(mA)	(mA)
SSTL-2 Class I	_	V <sub>REF</sub> – 0.18	V <sub>REF</sub> + 0.18	_	_	V <sub>REF</sub> – 0.35	V <sub>REF</sub> + 0.35	_	V <sub>π</sub> – 0.57	V <sub>π</sub> + 0.57	8.1	-8.1
SSTL-2 Class II		V <sub>REF</sub> – 0.18	V <sub>REF</sub> + 0.18	_	_	V <sub>REF</sub> – 0.35	V <sub>REF</sub> + 0.35	_	V <sub>π</sub> – 0.76	V <sub>π</sub> + 0.76	16.4	-16.4
SSTL-18 Class I		V <sub>REF</sub> – 0.125	V <sub>REF</sub> + 0.125	_	_	V <sub>REF</sub> – 0.25	V <sub>REF</sub> + 0.25	_	V <sub>π</sub> – 0.475	V <sub>π</sub> + 0.475	6.7	-6.7
SSTL-18 Class II		V <sub>REF</sub> – 0.125	V <sub>REF</sub> + 0.125	_	_	V <sub>REF</sub> – 0.25	V <sub>REF</sub> + 0.25	_	0.28	V <sub>cc10</sub> - 0.28	13.4	-13.4
HSTL-18 Class I		V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> - 0.4	8	-8
HSTL-18 Class II		V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	16	-16
HSTL-15 Class I		V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	8	-8
HSTL-15 Class II		V <sub>REF</sub> – 0.1	V <sub>REF</sub> + 0.1	_	_	V <sub>REF</sub> – 0.2	V <sub>REF</sub> + 0.2	_	0.4	V <sub>ccio</sub> – 0.4	16	-16
HSTL-12 Class I	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>ccio</sub> + 0.15	-0.24	V <sub>REF</sub> – 0.15	V <sub>REF</sub> + 0.15	V <sub>ccio</sub> + 0.24	0.25 × V <sub>CCIO</sub>	0.75 × V <sub>cc10</sub>	8	-8
HSTL-12 Class II	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>ccio</sub> + 0.15	-0.24	V <sub>REF</sub> – 0.15	V <sub>REF</sub> + 0.15	V <sub>ccio</sub> + 0.24	0.25 × V <sub>CCIO</sub>	0.75 × V <sub>cc10</sub>	14	-14





For more information about receiver input and transmitter output waveforms, and for other differential I/O standards, refer to the *High-Speed Differential Interfaces in Cyclone III Devices* chapter.

 Table 2–16.
 Cyclone III LS Devices Differential SSTL I/O Standard Specifications

I/O Standard	Standard V <sub>ccio</sub> (V)		)	V <sub>Swing(DC)</sub> (V)		V <sub>x(A</sub>	V <sub>x(AC)</sub> (V)		V <sub>Swing(AC)</sub> (V)		V <sub>OX(AC)</sub> (V)		
i/U Stanuaru	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Max	Min	Тур	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.36	V <sub>ccio</sub>	V <sub>ccio</sub> /2 - 0.2	_	V <sub>ccio</sub> /2 + 0.2	0.7	V <sub>ccio</sub>	V <sub>ccio</sub> /2 – 0.125	_	V <sub>ccio</sub> /2 + 0.125
SSTL-18 Class I, II	1.7	1.8	1.90	0.25	V <sub>ccio</sub>	V <sub>cc10</sub> /2 - 0.175	_	V <sub>ccio</sub> /2 + 0.175	0.5	V <sub>ccio</sub>	V <sub>ccio</sub> /2 – 0.125	_	V <sub>ccio</sub> /2 + 0.125

Table 2-17. Cyclone III LS Devices Differential HSTL I/O Standard Specifications

I/O Stondord	V <sub>ccio</sub> (V)		)	V <sub>DIF(</sub>	<sub>DC)</sub> (V)	<b>V</b> <sub>X(AC)</sub> ( <b>V</b> )			1	I <sub>CM(DC)</sub> (	V)	V <sub>DIF(AC)</sub> (V)	
i/O Stanuaru	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Тур	Max	Min	Max
HSTL-18 Class I, II	1.71	1.8	1.89	0.2	_	0.85	_	0.95	0.85	_	0.95	0.4	_
HSTL-15 Class I, II	1.425	1.5	1.575	0.2	_	0.71	_	0.79	0.71	_	0.79	0.4	_
HSTL-12 Class I, II	1.14	1.2	1.26	0.16	V <sub>ccio</sub>	0.48 * V <sub>CCIO</sub>		0.52 * V <sub>ccio</sub>	0.48 * V <sub>ccio</sub>		0.52 * V <sub>ccio</sub>	0.3	0.48 * V <sub>CCIO</sub>

**Table 2–18.** Differential I/O Standard Specifications (Note 1) (Part 1 of 2)

1/0	,	V <sub>ccio</sub> (V	)	V <sub>ID</sub> (	mV)		V <sub>ICM</sub> (V)		V <sub>o</sub>	o (mV)	(2)	V	os (V) (2	2)
Standard	Min	Тур	Max	Min	Max	Min	Condition	Max	Min	Тур	Max	Min	Тур	Max
LVDEOL						0	$D_{\text{MAX}} \leq 500 \text{ Mbps}$	1.85						
LVPECL (Row I/Os) (3)	2.375	2.5	2.625	100	_	0.5	$\begin{array}{l} 500 \; Mbps \leq \; D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.85	_	_	_	_	_	_
1,00,00						1	D <sub>MAX</sub> > 700 Mbps	1.6						
LVDEOL						0	$D_{MAX} \leq 500 \text{ Mbps}$	1.85						
LVPECL (Column I/Os) (3)	2.375	2.5	2.625	100	_	0.5	$\begin{array}{l} 500 \; Mbps \leq D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.85	_	_	_	_	_	_
1, 55, (5)						1	D <sub>MAX</sub> > 700 Mbps	1.6						
LVDC						0	$D_{\text{MAX}} \leq 500 \text{ Mbps}$	1.85						
LVDS (Row I/Os)	2.375	2.5	2.625	100	_	0.5	$\begin{array}{l} 500 \; Mbps \leq D_{MAX} \leq \\ 700 \; Mbps \end{array}$	1.85	247	_	600	1.125	1.25	1.375
,,,,,						1	$D_{\text{MAX}} > 700 \text{ Mbps}$	1.6						
LVDC						0	$D_{\text{MAX}} \leq \ 500 \ Mbps$	1.85						
LVDS (Column I/Os)	2.375	2.5	2.625	100	_	0.5	$\begin{array}{c} 500 \; Mbps \leq D_{\text{MAX}} \leq \\ 700 \; Mbps \end{array}$	1.85	247	_	600	1.125	1.25	1.35
., 55)						1	$D_{MAX} > 700 \text{ Mbps}$	1.6						

**Table 2–18.** Differential I/O Standard Specifications (Note 1) (Part 2 of 2)

I/O	,	V <sub>ccio</sub> (V	)	V <sub>ID</sub> (	mV)		V <sub>ICM</sub> (V)		V <sub>o</sub>	<sub>D</sub> (mV)	(2)	V	os (V) (2	2)
Standard	Min	Тур	Max	Min	Max	Min	Condition	Max	Min	Тур	Max	Min	Тур	Max
BLVDS (Row I/Os) (4)	2.375	2.5	2.625	100	_		_	_	_	_	_	_	_	_
BLVDS (Column I/Os) (4)	2.375	2.5	2.625	100	_		_	_	_	_		_	_	_
mini-LVDS (Row I/Os) (5)	2.375	2.5	2.625	_	_		_	_	300	_	600	1.0	1.2	1.4
mini-LVDS (Column I/Os) (5)	2.375	2.5	2.625	_	_		_	_	300	_	600	1.0	1.2	1.4
RSDS (Row I/Os) (5)	2.375	2.5	2.625	_	_		_	_	100	200	600	0.5	1.2	1.5
RSDS (Column I/Os) (5)	2.375	2.5	2.625	_	_		_	_	100	200	600	0.5	1.2	1.5
PPDS (Row I/Os) (5)	2.375	2.5	2.625	_	_		_	_	100	200	600	0.5	1.2	1.4
PPDS (Column I/Os) (5)	2.375	2.5	2.625	_	_	_	_	_	100	200	600	0.5	1.2	1.4

### Notes to Table 2–18:

- (1) For an explanation of the terms used in Table 2–18, refer to "Transmitter Output Waveform" in "Glossary" on page 2–26.
- (2)  $R_L$  range:  $90 \le R_L \le 110 \Omega$ .
- (3) The LVPECL input standard is only supported at clock input. The output standard is not supported.
- (4) There is no fixed  $V_{\text{ICM}}$ ,  $V_{\text{OD}}$ , and  $V_{\text{OS}}$  specification for BLVDS. They are dependent on the system topology.
- (5) Mini-LVDS, RSDS, and PPDS standards are only supported at output pins of Cyclone III LS devices.

## **Power Consumption**

Use the following methods to estimate power for your design:

- The Excel-based EPE
- The Quartus II<sup>®</sup> PowerPlay power analyzer feature

Use the interactive Excel-based EPE before designing your device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities which, combined with detailed circuit models, can yield very accurate power estimates.



For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

## **Switching Characteristics**

This section describes performance characteristics of the core and periphery blocks for Cyclone III LS devices. These characteristics are designated as **Preliminary** or **Final**, as indicated in the title of each table. The designations are defined as follows:

- **Preliminary**—Preliminary characteristics are created using simulation results, process data, and other known parameters.
- **Final**—Final numbers are based on actual silicon characterization and testing. These numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions.

## **Core Performance Specifications**

Table 2–19 through Table 2–25 describe the core performance specifications for Cyclone III LS devices.

## **Clock Tree Specifications**

Table 2–19 lists the clock tree specifications for Cyclone III LS devices.

Table 2-19.	Cyclone III LS Devi	ces Clock Tree Perfori	mance (Preliminary)
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Davisa		Performance		11!1
Device	C7	C8	17	Unit
EP3CLS70	437.5	402	437.5	MHz
EP3CLS100	437.5	402	437.5	MHz
EP3CLS150	437.5	402	437.5	MHz
EP3CLS200	437.5	402	437.5	MHz

### **PLL Specifications**

Table 2–20 lists the PLL specifications for Cyclone III LS devices when operating in the commercial junction temperature range (0°C to 85°C) and the industrial junction temperature range (-40°C to 100°C). For more information about the PLL block, refer to "PLL Block" in "Glossary" on page 2–26.

**Table 2–20.** Cyclone III LS Devices PLL Specifications (*Note 4*) (Part 1 of 2) (Preliminary)

Symbol	Parameter	Min	Тур	Max	Unit
f <sub>IN</sub> (1)	Input clock frequency	_	_	450	MHz
f <sub>INPFD</sub>	PFD input frequency	5	_	325	MHz
f <sub>vco</sub> (6)	PLL internal VCO operating range	600	_	1300	MHz
f <sub>INDUTY</sub>	Input clock duty cycle	40	_	60	%
+ (5)	Input clock cycle-to-cycle jitter F <sub>REF</sub> ≥ 100 MHz	_	_	0.15	UI
t <sub>injitter_ccj</sub> (5)	F <sub>REF</sub> < 100 MHz	_	_	±750	ps

 Table 2-20.
 Cyclone III LS Devices PLL Specifications (Note 4) (Part 2 of 2) (Preliminary)

Symbol	Parameter	Min	Тур	Max	Unit
f <sub>OUT_EXT</sub> (external clock output) (1)	PLL output frequency	_	_	450	MHz
f <sub>out</sub> (to global clock)	PLL output frequency (-7 speed grade)	426	_	450	MHz
	PLL output frequency (-8 speed grade)	379	_	402.5	MHz
toutduty	Duty cycle for external clock output (when set to 50%)	45	50	55	%
t <sub>lock</sub>	Time required to lock from end of device configuration	_	_	1	ms
t <sub>dlock</sub>	Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or areset is deasserted)	_	_	1	ms
+ (2)	Dedicated clock output period jitter $F_{out} \ge 100 \text{ MHz}$	_	_	300	ps
t <sub>outjitter_period_dedclk</sub> (3)	F <sub>out</sub> < 100 MHz	_	_	30	mUI
toutjitter ccj dedclk (3)	Dedicated clock output cycle-to-cycle jitter $F_{\text{out}} \ge 100 \text{ MHz}$	_	_	300	ps
	F <sub>out</sub> < 100 MHz	_	_	30	mUI
+ (2)	Regular I/O period jitter F <sub>out</sub> ≥ 100 MHz	_	_	650	ps
t <sub>outjitter_period_io</sub> (3)	F <sub>out</sub> < 100 MHz	_	_	75	mUI
+ (2)	Regular I/O cycle-to-cycle jitter F <sub>out</sub> ≥ 100 MHz	_	_	650	ps
t <sub>outjitter_ccj_io</sub> (3)	F <sub>out</sub> < 100 MHz	_	_	75	mUI
t <sub>PLL_PSERR</sub>	Accuracy of PLL phase shift	_	_	±50	ps
t <sub>ARESET</sub>	Minimum pulse width on areset signal.	10	_	_	ns
t <sub>configell</sub>	Time required to reconfigure scan chains for PLLs	_	3.5 <i>(2)</i>	_	scanclk cycles
f <sub>scanclk</sub>	scanclk frequency	_	_	100	MHz

### Notes to Table 2-20:

- (1) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (2) With 100-MHz scanclk frequency.
- (3) Peak-to-peak jitter with a probability level of 10<sup>-12</sup> (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL, when an input jitter of 30 ps is applied.
- (4)  $V_{CCD\_PLL}$  must be connected to  $V_{CCINT}$  through the decoupling capacitor and ferrite bead.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source, which is less than 200 ps.
- (6) The  $V_{CO}$  frequency reported by the Quartus II software in the PLL summary section of the compilation report takes into consideration the  $V_{CO}$  post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the  $f_{VCO}$  specification.

## **Embedded Multiplier Specifications**

Table 2–21 lists the embedded multiplier specifications for Cyclone III LS devices.

**Table 2–21.** Cyclone III LS Devices Embedded Multiplier Specifications (Preliminary)

Mode	Resources Used	EP3CLS70, I EP3CLS150, a Perfor	nd EP3CLS200	Unit
	Number of Multipliers	C7 and I7	C8	
9 × 9-bit multiplier	1	300	260	MHz
18 × 18-bit multiplier	1	250	200	MHz

## **Memory Block Specifications**

Table 2–22 lists the M9K memory block and logic element (LE) specifications for Cyclone III LS devices.

 Table 2–22.
 Cyclone III LS Devices Memory Block Performance Specifications (Preliminary)

Memory	ory Mode		Resources Used Mode		EP3CLS70, EP3CLS100, EP3CLS150, and EP3CLS200 Performance		
,		LEs	M9K Memory	C7 and I7	C8		
	FIFO 256 × 36	47	1	274	238	MHz	
M9K Block	Single-port 256 × 36	0	1	274	238	MHz	
WISK Block	Simple dual-port 256 × 36 CLK	0	1	274	238	MHz	
	True dual port 512 × 18 single CLK	0	1	274	238	MHz	

## **Configuration and JTAG Specifications**

Table 2–23 lists the configuration mode specifications for Cyclone III LS devices.

Table 2–23. Cyclone III LS Devices Configuration Mode Specifications (Preliminary)

Programming Mode	DCLK f <sub>max</sub>	Unit
Passive Serial (PS)	133	MHz
Fast Passive Parallel (FPP)	100	MHz

Table 2–24 lists the active configuration mode specifications for Cyclone III LS devices.

Table 2-24. Cyclone III LS Devices Active Configuration Mode Specifications (Preliminary)

Programming Mode	DCLK Range	Unit
Active Serial (AS)	20 to 40	MHz

Table 2–25 lists the JTAG timing parameters and values for Cyclone III LS devices.

**Table 2–25.** Cyclone III LS Devices JTAG Timing Parameters (*Note 2*) (Preliminary)

Symbol	Parameter	Min	Max	Unit
$t_{\text{JCP}}$	TCK clock period	40	_	ns
t <sub>JCH</sub>	TCK clock high time	20	_	ns
t <sub>JCL</sub>	TCK clock low time	20	_	ns
t <sub>JPSU_TDI</sub>	JTAG port setup time for TDI (1)	2	_	ns
t <sub>JPSU_TMS</sub>	JTAG port setup time for TMS (1)	3	_	ns
t <sub>JPH</sub>	JTAG port hold time	10	_	ns
t <sub>JPCO</sub>	JTAG port clock to output (1)	_	16	ns
t <sub>JPZX</sub>	JTAG port high impedance to valid output (1)	_	15	ns
t <sub>JPXZ</sub>	JTAG port valid output to high impedance (1)	_	15	ns
t <sub>JSSU</sub>	Capture register setup time (1)	5	_	ns
t <sub>JSH</sub>	Capture register hold time	10	_	ns
t <sub>JSCO</sub>	Update register clock to output	_	25	ns
t <sub>JSZX</sub>	Update register high impedance to valid output	_	25	ns
t <sub>JSXZ</sub>	Update register valid output to high impedance	_	25	ns

### Notes to Table 2-25:

- (1) The specification shown is for the 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of the JTAG pins. For the 1.8-V LVTTL/LVCMOS and the 1.5-V LVCMOS, the JTAG port clock to output time is 16 ns.
- (2) For more information, refer to "JTAG Waveform" in "Glossary" on page 2-26.

## **Periphery Performance**

This section describes periphery performance, including high-speed I/O, external memory interface, and IOE programmable delay.

I/O performance supports several systems interfacing, for example, the high-speed I/O interface, external memory interface, and PCI/PCI-X bus interface. I/O using SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speed with typical DDR2 SDRAM memory interface setup. I/O using general purpose I/O standards such as 3.0, 2.5, 1.8, or 1.5 LVTTL/LVCMOS are capable of typical 200 MHz interfacing frequency with 10 pF load.



Your actual achievable frequency depends on design- and system-specific factors. You should perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

### **High-Speed I/O Specification**

Table 2–26 through Table 2–31 list the high-speed I/O timing for Cyclone III LS devices. For more information about the definitions of high-speed timing specifications, refer to "Glossary" on page 2–26.

Table 2–26. Cyclone	III LS Devices RSDS	Transmitter Timing Specification	(Note 1), (2)	(Preliminary)
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Ohal	Mada		C7 and I7			C8		11
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Unit
	×10	10	_	155.5	10	_	155.5	MHz
	×8	10	_	155.5	10	_	155.5	MHz
f <sub>HSCLK</sub>	×7	10	_	155.5	10	_	155.5	MHz
(input clock frequency)	×4	10	_	155.5	10	_	155.5	MHz
. 4	×2	10	_	155.5	10	_	155.5	MHz
	×1	10	_	311	10	_	311	MHz
	×10	100	_	311	100	_	311	Mbps
	×8	80	_	311	80	_	311	Mbps
Device operation	×7	70	_	311	70	_	311	Mbps
in Mbps	×4	40	_	311	40	_	311	Mbps
	×2	20	_	311	20	_	311	Mbps
	×1	10	_	311	10	_	311	Mbps
t <sub>duty</sub>	_	45	_	55	45	_	55	%
TCCS	_	_	_	200	_	_	200	ps
Output jitter (peak to peak)	_	_	_	500	_	_	550	ps
t <sub>RISE</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	ps
t <sub>FALL</sub>	$20 - 80\%,$ $C_{LOAD} = 5 \text{ pF}$	_	500	_	_	500	_	ps
t <sub>LOCK</sub> (3)	_	_	_	1	_	_	1	ms

### Notes to Table 2-26:

- (1) Applicable for true RSDS and Emulated RSDS with three-resistor network transmitters.
- (2) True RSDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6). Emulated RSDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
- (3)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 2–27.** Cyclone III LS Devices Emulated RSDS with One-Resistor Network Transmitter Timing Specifications (*Note 1*) (Part 1 of 2) (Preliminary)

Symbol Modes	Modoo		C7 and I7	7	C8			Unit
	Mones	Min	Тур	Max	Min	Тур	Max	Oiiit
	×10	10	_	85	10	_	85	MHz
	×8	10		85	10	_	85	MHz
f <sub>HSCLK</sub> (input clock	×7	10	_	85	10	_	85	MHz
frequency)	×4	10	_	85	10	_	85	MHz
,	×2	10	_	85	10	_	85	MHz
	×1	10		170	10	_	170	MHz

<b>Table 2–27.</b> Cyclone III LS Devices Emulated RSDS with One-Resist	or Network 1	Transmitter	Timing
Specifications (Note 1) (Part 2 of 2) (Preliminary)			

Cumbal	Madaa		C7 and I7	7		C8		llmit
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Unit
	×10	100	_	170	100	_	170	Mbps
	×8	80	_	170	80	_	170	Mbps
Device	×7	70	_	170	70	_	170	Mbps
operation in Mbps	×4	40	_	170	40	_	170	Mbps
'	×2	20	_	170	20	_	170	Mbps
	×1	10	_	170	10	_	170	Mbps
t <sub>DUTY</sub>	_	45	_	55	45	_	55	%
TCCS	_	_	_	200	_	_	200	ps
Output jitter (peak to peak)	_	_	_	500	_	_	550	ps
t <sub>RISE</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	ps
t <sub>FALL</sub>	$20 - 80\%$ , $C_{LOAD} = 5 pF$	_	500	_	_	500	_	ps
t <sub>LOCK</sub> (2)	_	_	_	1	_	_	1	ms

### Notes to Table 2-27:

- $(1) \quad \text{Emulated RSDS with one-resistor network transmitter is supported at the output pin of all I/O banks.}$
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 2–28.** Cyclone III LS Devices Mini-LVDS Transmitter Timing Specification (*Note 1*), (2) (Part 1 of 2) (Preliminary)

Ohal	Mada	C	7 and 17			Unit		
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Unit
	×10	10	_	155.5	10	_	155.5	MHz
	×8	10	—	155.5	10	_	155.5	MHz
f <sub>HSCLK</sub> (input clock	×7	10	_	155.5	10	_	155.5	MHz
frequency)	×4	10	_	155.5	10	_	155.5	MHz
	×2	10	_	155.5	10	_	155.5	MHz
	×1	10	_	311	10	_	311	MHz
	×10	100	_	311	100	_	311	Mbps
	×8	80	_	311	80	_	311	Mbps
Device operation	×7	70	_	311	70	_	311	Mbps
in Mbps	×4	40	—	311	40	_	311	Mbps
	×2	20	_	311	20	_	311	Mbps
	×1	10	_	311	10	_	311	Mbps
t <sub>duty</sub>	_	45	_	55	45	_	55	%
TCCS	_	_	_	200	_	_	200	ps

1

500

500

 $t_{\scriptscriptstyle \text{RISE}}$ 

 $t_{FALL}$ 

 $t_{LOCK}(3)$ 

ps

ps

ms

Cumbal	Madaa	(	C7 and I7			C8		Unit
Symbol Modes		Min	Тур	Max	Min	Тур	Max	Unit
Output jitter (peak to peak)	_	_	_	500	_	_	550	ps
	20 – 80%,							

500

500

**Table 2–28.** Cyclone III LS Devices Mini-LVDS Transmitter Timing Specification (Note 1), (2) (Part 2 of 2) (Preliminary)

### Notes to Table 2-28:

(1) Applicable for true and emulated mini-LVDS with three-resistor network transmitter.

 $C_{LOAD} = 5 pF$ 20 - 80%

 $C_{LOAD} = 5 pF$ 

- (2) True mini-LVDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6). Emulated mini-LVDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
- (3)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 2–29.** Cyclone III LS Devices True LVDS Transmitter Timing Specifications (Note 1) (Preliminary)

1

0h-al	Madas	C7 a	nd 17	C	8	11!4
Symbol	Modes	Min Max		Min	Unit	
	×10	10	370	10	320	MHz
	×8	10	370	10	320	MHz
f <sub>HSCLK</sub> (input clock	×7	10	370	10	320	MHz
frequency)	×4	10	370	10	320	MHz
	×2	10	370	10	320	MHz
	×1	10	402.5	10	402.5	MHz
	×10	100	740	100	640	Mbps
	×8	80	740	80	640	Mbps
HSIODR	×7	70	740	70	640	Mbps
HOIODA	×4	40	740	40	640	Mbps
	×2	20	740	20	640	Mbps
	×1	10	402.5	10	402.5	Mbps
t <sub>DUTY</sub>	_	45	55	45	55	%
TCCS	_	_	200	_	200	ps
Output jitter (peak to peak)		_	500		550	ps
t <sub>LOCK</sub> (2)	_	_	1	_	1	ms

### Notes to Table 2-29:

- (1) True LVDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6).
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 2–30.** Cyclone III LS Devices Emulated LVDS with Three-Resistor Network Transmitter Timing Specifications (*Note 1*) (Preliminary)

Cumbal	Madaa	C7 a	nd 17	C	8	II-a!A
Symbol	Modes	Min Max		Min	Unit	
	×10	10	320	10	275	MHz
	×8	10	320	10	275	MHz
f <sub>HSCLK</sub> (input clock	×7	10	320	10	275	MHz
frequency)	×4	10	320	10	275	MHz
	×2	10	320	10	275	MHz
	×1	10	402.5	10	402.5	MHz
	×10	100	640	100	550	Mbps
	×8	80	640	80	550	Mbps
HSIODR	×7	70	640	70	550	Mbps
HOIODA	×4	40	640	40	550	Mbps
	×2	20	640	20	550	Mbps
	×1	10	402.5	10	402.5	Mbps
t <sub>DUTY</sub>	_	45	55	45	55	%
TCCS	_	_	200	_	200	ps
Output jitter (peak to peak)	_	_	500	_	550	ps
t <sub>LOCK</sub> (2)	_		1	_	1	ms

### Notes to Table 2-30:

- (1) Emulated LVDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

**Table 2–31.** Cyclone III LS Devices LVDS Receiver Timing Specifications (*Note 1*) (Part 1 of 2) (Preliminary)

Cumbal	Modes	C7 and I7		C	8	Hait
Symbol	Modes	Min	Max	Min	Max	Unit
	×10	10	370	10	320	MHz
	×8	10	370	10	320	MHz
f <sub>HSCLK</sub> (input clock	×7	10	370	10	320	MHz
frequency)	×4	10	370	10	320	MHz
	×2	10	370	10	320	MHz
	×1	10	402.5	10	402.5	MHz
	×10	100	740	100	640	Mbps
	×8	80	740	80	640	Mbps
HSIODR	×7	70	740	70	640	Mbps
HOIODH	×4	40	740	40	640	Mbps
	×2	20	740	20	640	Mbps
	×1	10	402.5	10	402.5	Mbps
SW	_	_	400	_	400	%

Cumbal	Madaa	C7 a	nd 17	C	Unit	
Symbol	Modes	Min	Max	Min	Max	Unit
Input jitter tolerance	_	_	500	_	550	ps
t <sub>LOCK</sub> (2)	_	_	1	_	1	ps

**Table 2–31.** Cyclone III LS Devices LVDS Receiver Timing Specifications (*Note 1*) (Part 2 of 2) (Preliminary)

### Notes to Table 2-31:

- (1) True LVDS receiver is supported at all banks.
- (2)  $t_{LOCK}$  is the time required for the PLL to lock from the end of device configuration.

### **External Memory Interface Specifications**

Cyclone III LS devices support external memory interfaces up to 200 MHz. The external memory interfaces for Cyclone III LS devices are auto-calibrating and easy to implement.

Table 2–32 and Table 2–33 list the external memory interface specifications for Cyclone III LS devices and are useful when performing memory interface timing analysis.



For more information about external memory system specifications, refer to the *External Memory Interface Handbook*.

**Table 2–32.** FPGA Sampling Window (SW) Requirement—Read Side (Note 1) (Preliminary)

Momenty Ctondord	Column	I/Os (ps)	Row I	/Os (ps)	Wraparound Mode (	
Memory Standard	Setup	Hold	Setup	Hold	Setup	Hold
	<del>- !</del>	C	7	<del>'</del>	<del>!</del>	!
DDR2 SDRAM	705	650	770	715	985	930
DDR SDRAM	675	620	795	740	970	915
QDRII SRAM	900	845	910	855	1085	1030
		C	8			
DDR2 SDRAM	785	720	930	870	1115	1055
DDR SDRAM	800	740	915	855	1185	1125
QDRII SRAM	1050	990	1065	1005	1210	1150
		ľ	7			
DDR2 SDRAM	765	710	855	800	1040	985
DDR SDRAM	745	690	880	825	1000	945
QDRII SRAM	945	890	955	900	1130	1075

### Note to Table 2-32:

<sup>(1)</sup> Column I/Os refer to top and bottom I/Os. Row I/Os refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.

Table 2-33. Cyclone III LS Devices Transmitter Channel-to-Channel Skew (TCCS)—Write Side (Note 1)

Managa Olaydayl	1/0 0111	Column	I/Os (ps)	Row I/	Os (ps)	Wraparoun	d Mode (ps)
Memory Standard	I/O Standard	Lead	Lag	Lead	Lag	Lead	Lag
	<del>!</del>		<b>C</b> 7	<u> </u>		-	<u> </u>
DDR2 SDRAM	SSTL-18 Class I	915	410	915	410	1015	510
DDD2 3DDAIVI	SSTL-18 Class II	1025	545	1025	545	1125	645
	SSTL-2 Class I	880	340	880	340	980	440
DDR SDRAM	SSTL-2 Class II	1010	380	1010	380	1010	480
	1.8-V HSTL Class I	910	450	910	450	1010	550
QDRII SRAM	1.8-V HSTL Class II	1010	570	1010	570	1110	670
			C8	1		•	•
DDR2 SDRAM	SSTL-18 Class I	1040	440	1040	440	1140	540
DDN2 3DNAW	SSTL-18 Class II	1180	600	1180	600	1280	700
DDR SDRAM	SSTL-2 Class I	1010	360	1010	360	1110	460
DUN SUNAWI	SSTL-2 Class II	1160	410	1160	410	1260	510
QDRII SRAM	1.8-V HSTL Class I	1040	490	1040	490	1140	590
UDNII SNAWI	1.8-V HSTL Class II	1190	630	1190	630	1290	730
			17	1		•	•
DDR2 SDRAM	SSTL-18 Class I	961	431	961	431	1061	531
DDD2 3DDAIVI	SSTL-18 Class II	1076	572	1076	572	1176	672
	SSTL-2 Class I	924	357	924	357	1024	457
DDR SDRAM	SSTL-2 Class II	1061	399	1061	399	1161	499
QDRII SRAM	1.8-V HSTL Class I	956	473	956	473	1056	573
ווואחט ווחעש	1.8-V HSTL Class II	1061	599	1061	599	1161	699

### Note to Table 2-33:

Table 2–34 lists the Cyclone III LS devices memory ouput clock jitter specifications.

Table 2-34. Cyclone III LS Devices Memory Output Clock Jitter Specifications (Note 1), (2)

Parameter	Symbol	Min	Max	Unit
Clock period jitter	t <sub>JIT</sub> (per)	-125	125	ps
Cycle-to-cycle period jitter	t <sub>JIT</sub> (CC)	-200	200	ps
Duty cycle jitter	t <sub>JIT</sub> (duty)	-150	150	ps

### Notes to Table 2-34:

- (1) The memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock network.

<sup>(1)</sup> Column I/O banks refer to top and bottom I/Os. Row I/O banks refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.

## **Duty Cycle Distortion Specification**

Table 2–35 lists the worst case duty cycle distortion for Cyclone III LS devices.

Table 2-35. Duty Cycle Distortion on Cyclone III LS Devices I/O Pins (Note 1), (2) (Preliminary)

Cumbol	C7, I7		C	Unit	
Symbol	Min	Max	Min	Max	UIIIL
Output Duty Cycle	45	55	45	55	%

### Notes to Table 2-35:

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and I/O element (IOE) driving the dedicated and general purpose I/O pins.
- (2) Cyclone III LS devices meet the DCD specifications at the maximum output toggle rate for each combination of the I/O standard and current strength.

## **OCT Calibration Timing Specification**

Table 2–36 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone III LS devices.

**Table 2–36.** Cyclone III LS Devices Timing Specification for Series OCT with Calibration at Device Power-Up (Note 1) (Preliminary)

Symbol	Description	Maximum	Unit
toctcal	Duration of series OCT with calibration at device power-up	20	μs

### Note to Table 2-36:

(1) OCT calibration takes place after device configuration, before entering user mode.

### **IOE Programmable Delay**

Table 2–37 and Table 2–38 list the IOE programmable delay for Cyclone III LS devices.

**Table 2–37.** Cyclone III LS Devices IOE Programmable Delay on the Column Pins (Note 1), (2)

		Number			N	lax Offs	et		
Parameter	Paths Affected	of	Min Offset	Fast (	Corner	SI	ow Corn	er	Unit
		setting		17	<b>C</b> 7	<b>C</b> 7	C8	17	
Input delay from the pin to the internal cells	Pad to I/O dataout to core	7	0	1.211	1.314	2.339	2.416	2.397	ns
Input delay from the pin to the input register	Pad to I/O input register	8	0	1.203	1.307	2.387	2.540	2.430	ns
Delay from the output register to the output pin	I/O output register to pad	2	0	0.518	0.559	1.065	1.151	1.082	ns
Input delay from the dual-purpose clock pin to the fan-out destinations	Pad to global clock network	12	0	0.533	0.56	1.077	1.182	1.087	ns

### Notes to Table 2-37:

- (1) The incremental values for the settings are generally linear. For the exact values of each setting, use the latest version of the Quartus II software.
- $(2) \quad \text{The minimum and maximum offset timing numbers refer to the } \textbf{0} \text{ setting available in the Quartus II software}.$

**Max Offset** Number Min **Parameter Paths Affected** of **Fast Corner Slow Corner** Unit **Offset** setting C7 17 **C7** C8 17 Input delay from the pin to the Pad to I/O 7 0 1.209 1.314 2.352 2.514 2.432 ns internal cells dataout to core Input delay from the pin to the Pad to I/O input 8 0 1.207 1.312 2.402 2.558 2.447 ns input register register Delay from the output register to I/O output 2 0 0.549 0.595 1.135 1.226 1.151 ns the output pin register to pad Input delay from the Pad to global dual-purpose clock pin to the 12 0 0.52 0.54 1.052 1.061 1.16 ns clock network fan-out destinations

**Table 2–38.** Cyclone III LS Devices IOE Programmable Delay on Row Pins (Note 1), (2)

### Notes to Table 2-38:

- (1) The incremental values for the settings are generally linear. For the exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers refer to the 0 setting available in the Quartus II software.

## I/O Timing

DirectDrive technology and MultiTrack interconnect ensure predictable performance, accurate simulation, and accurate timing analysis across all Cyclone III LS device densities and speed grades.

Use the following methods to determine I/O timing:

- The Excel-based I/O timing
- The Quartus II Timing Analyzer

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used before designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II Timing Analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.



For more information about the Excel-based I/O timing spreadsheet, refer to the *Cyclone III Devices* Literature page on the Altera website.

All specifications are representative of worst-case supply voltage and junction temperature conditions. Altera characterizes timing delays at the worst-case process, minimum voltage, and maximum temperature for input register setup time  $(t_{\text{SU}})$  and hold time  $(t_{\text{H}})$ .



For more information about timing delay from the FPGA output to the receiving device for system-timing analysis, refer to *AN 366: Understanding I/O Output Timing for Altera Devices*.

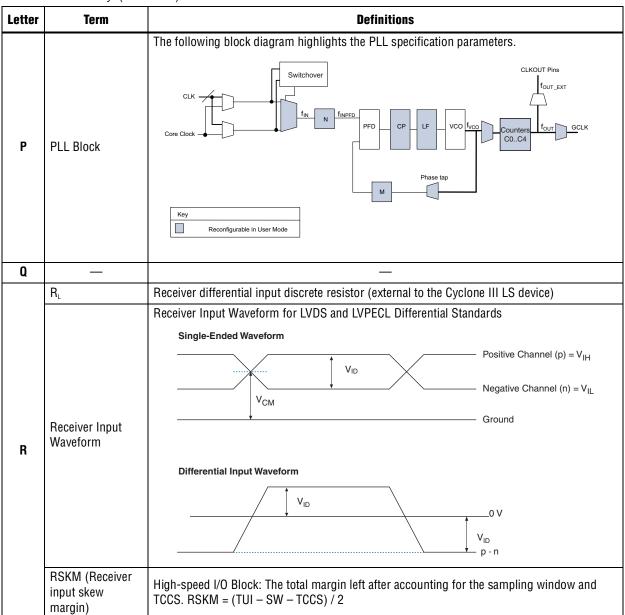
# Glossary

Table 2–39 lists the glossary for this chapter.

**Table 2–39.** Glossary (Part 1 of 5)

Letter	Term	Definitions
Α	_	_
В	_	_
С	_	_
D	_	_
E	_	_
F	f <sub>HSCLK</sub>	High-speed I/O Block: High-speed receiver and transmitter input and output clock frequency.
	GCLK	Input pin directly to the global clock network.
G	GCLK PLL	Input pin to the global clock network through the PLL.
Н	HSIODR	High-speed I/O Block: Maximum and minimum LVDS data transfer rate (HSIODR = 1/TUI).
I	Input Waveforms for the SSTL Differential I/O Standard	Vswing V <sub>IH</sub> Vswing V <sub>REF</sub>
J	JTAG Waveform	TDI  TDI  TDI  TCK  TDI  TCK  TDO  TJPSU_TDI  TJPSU_TDI  TJPSU_TMS  TJPSU_TMS  TJPSU_TMS  TJPSU_TMS  TJPSU_TMS  TJPSU_TMS  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TDI  TJPSU_TMS  TJPSU_TMS
K	_	-
L	_	_
M	_	_
M N	<u> </u>	

**Table 2–39.** Glossary (Part 2 of 5)



**Table 2–39.** Glossary (Part 3 of 5)

Letter	Term	Definitions		
S	Single-ended Voltage referenced I/O Standard	V <sub>IL(AC)</sub> The AC values indicate the voltage levels at which the receiver must meet its timing specifications.  The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined.  After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform		
	SW (Sampling Window)	ringing.  High-speed I/O Block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window.		
	t <sub>c</sub>	High-speed receiver and transmitter input and output clock period.		
	TCCS (Channel- to-channel-skew)	High-speed I/O Block: The timing difference between the fastest and slowest output edges, including $t_{\rm co}$ variation and clock skew. The clock is included in the TCCS measurement.		
	tcin	Delay from the clock pad to the I/O input register.		
	t <sub>co</sub>	Delay from the clock pad to the I/O output.		
	tcout	Delay from the clock pad to the I/O output register.		
	t <sub>DUTY</sub>	High-speed I/O Block: Duty cycle on the high-speed transmitter output clock.		
т	t <sub>FALL</sub>	Signal high-to-low transition time (80 to 20%).		
•	t <sub>H</sub>	Input register hold time.		
	Timing Unit Interval (TUI)	High-speed I/O block: The timing budget allowed for skew, propagation delays, and the data sampling window. (TUI = $1/(Receiver\ Input\ Clock\ Frequency\ Multiplication\ Factor) = t_c/w)$ .		
	t <sub>INJITTER</sub>	Period jitter on the PLL clock input.		
	t <sub>outjitter_dedclk</sub>	Period jitter on the dedicated clock output driven by a PLL.		
	t <sub>outjitter_io</sub>	Period jitter on the general purpose I/O driven by a PLL.		
	tpllcin	Delay from the PLL inclk pad to the I/O input register.		
	tpllcout	Delay from the PLL inclk pad to the I/O output register.		

**Table 2–39.** Glossary (Part 4 of 5)

Letter	Term	Definitions		
		Transmitter output waveforms for the LVDS, mini-LVDS, PPDS, and RSDS differential I/O standards  Single-Ended Waveform		
		Positive Channel (p) = V <sub>OH</sub>		
		Vos Negative Channel (n) = V <sub>OL</sub>		
	Transmitter Output Waveform	Ground		
		Differential Waveform (Mathematical Function of Positive & Negative Channel)		
		V <sub>OD</sub> 0 V		
		V <sub>OD</sub> p-n (1)		
	t <sub>RISE</sub>	Signal low-to-high transition time (20–80%).		
	t <sub>su</sub>	Input register setup time.		
U	_	_		

**Table 2–39.** Glossary (Part 5 of 5)

Letter	Term	Definitions		
	V <sub>CM(DC)</sub>	DC common mode input voltage.		
	V <sub>DIF(AC)</sub>	AC differential Input Voltage—The minimum AC input differential voltage required for switching.		
	V <sub>DIF(DC)</sub>	DC differential Input Voltage—The minimum DC input differential voltage required for switching.		
	V <sub>ICM</sub>	Input Common Mode Voltage—The common mode of the differential signal at the receiver.		
	V <sub>ID</sub>	Input differential Voltage Swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.		
	V <sub>IH</sub>	Voltage Input High—The minimum positive voltage applied to the input that is accepted by the device as a logic high.		
	V <sub>IH(AC)</sub>	High-level AC input voltage.		
	V <sub>IH(DC)</sub>	High-level DC input voltage.		
	V <sub>IL</sub>	Voltage Input Low—The maximum positive voltage applied to the input that is accepted by the device as a logic low.		
	V <sub>IL (AC)</sub>	Low-level AC input voltage.		
	V <sub>IL (DC)</sub>	Low-level DC input voltage.		
	V <sub>IN</sub>	DC input voltage.		
	V <sub>OCM</sub>	Output Common Mode Voltage—The common mode of the differential signal at the transmitter.		
V	V <sub>od</sub>	Output differential Voltage Swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the transmitter. $V_{\text{OD}} = V_{\text{OH}} - V_{\text{OL}}$ .		
	V <sub>OH</sub>	Voltage Output High—The maximum positive voltage from an output that the device considers will be accepted as the minimum positive high level.		
,	V <sub>oL</sub>	Voltage Output Low—The maximum positive voltage from an output that the device considers will be accepted as the maximum positive low level.		
	V <sub>os</sub>	Output offset voltage— $V_{OS} = (V_{OH} + V_{OL}) / 2$ .		
	V <sub>OX (AC)</sub>	AC differential Output cross point voltage—The voltage at which the differential output signals must cross.		
	V <sub>REF</sub>	Reference voltage for the SSTL and HSTL I/O standards.		
,	V <sub>REF (AC)</sub>	AC input reference voltage for the SSTL and HSTL I/O standards. $V_{REF(AC)} = V_{REF(DC)} + noise$ . The peak-to-peak AC noise on $V_{REF}$ must not exceed 2% of $V_{REF(DC)}$ .		
	V <sub>REF (DC)</sub>	DC input reference voltage for the SSTL and HSTL I/O standards.		
,	V <sub>SWING (AC)</sub>	AC differential Input Voltage—AC Input differential voltage required for switching. Refer to Input Waveforms for the SSTL Differential I/O Standard.		
	V <sub>SWING (DC)</sub>	DC differential Input Voltage—DC Input differential voltage required for switching. Refer to Input Waveforms for the SSTL Differential I/O Standard.		
]	Vπ	Termination voltage for the SSTL and HSTL I/O standards.		
	V <sub>X (AC)</sub>	AC differential Input cross point Voltage—The voltage at which the differential input signals must cross.		
W	_	_		
Х	_	_		
Υ	_	<del>-</del>		
Z		_		

# **Document Revision History**

Table 2–40 lists the revision history for this chapter.

Table 2-40. Document Revision History

Date	Version	Changes Made
		■ Updated Table 2–19 through Table 2–34, Table 2–37, and Table 2–38.
December 2009	1.2	<ul><li>Updated the "Periphery Performance" on page 2–17 section.</li></ul>
		<ul><li>Minor changes to the text.</li></ul>
July 2009	1.1	Minor edit to the hyperlinks.
June 2009	1.0	Initial release.