Time Evolution of a 2D Gaussian Wave Packet

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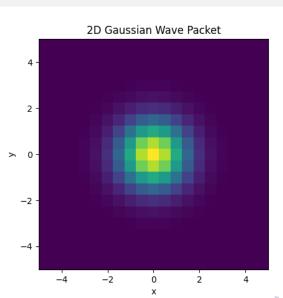
2D Gaussian Wave Packet

$$\Psi(x, y, t) = A \exp \left[-\frac{1}{2\sigma_x^2} (x - x_0)^2 - \frac{1}{2\sigma_y^2} (y - y_0)^2 + i(k_x x + k_y y - \omega t) \right]$$

- Parameters: σ_x , σ_y , x_0 , y_0 , k_x , k_y .
- Discretization. $\delta x, \delta t = 0.5, 0.5$

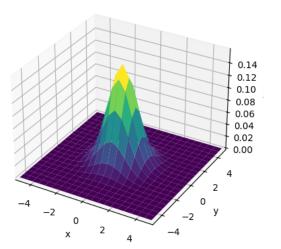


Plots at t = 0



Plots at t = 0

2D Gaussian Wave Packet

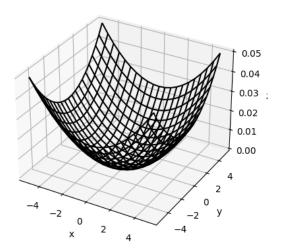


Schroedinger Equation in two dimensions

$$i\frac{\partial \psi(x,y,t)}{\partial t} = -\nabla^2 \psi(x,y,t) + V(x,y,t) \psi(x,y,t).$$

• Choice of Potential : Infinite square well, parabolic potential

Parabolic Potential



Numerical Methods

- Crank-Nicolson Method.
- Finite Difference Method.
- Why these methods for the simulation?

Consider the time derivative of ψ as a function of ${\it F}$ discretized on the 2D plane.

- Forward euler method: $\frac{\psi_{i,j}^{n+1}-\psi_{i,j}^n}{\Delta t}=F_{i,j}^n$.
- Backward euler method: $\frac{\psi_{i,j}^{n+1}-\psi_{i,j}^n}{\Delta t}=F_{i,j}^{n+1}$.
- $\frac{\psi_{i,j}^{n+1} \psi_{i,j}^n}{\Delta t} = \frac{1}{2} \left[F_{i,j}^{n+1} + F_{i,j}^n \right]$.

$$\begin{split} \frac{\partial \psi(x,y,t)}{\partial t} &= \frac{\psi_{i,j}^{n+1} - \psi_{i,j}^{n}}{\Delta t} \\ \frac{\partial^{2} \psi(x,y,t)}{\partial x^{2}} &= \frac{1}{2(\Delta x)^{2}} \left[\left(\psi_{i,j+1}^{n+1} - 2\psi_{i,j}^{n+1} + \psi_{i,j-1}^{n+1} \right) + \left(\psi_{i,j+1}^{n} - 2\psi_{i,j}^{n} + \psi_{i,j-1}^{n} \right) \right] \\ \frac{\partial^{2} \psi(x,y,t)}{\partial y^{2}} &= \frac{1}{2(\Delta y)^{2}} \left[\left(\psi_{i-1,j}^{n+1} - 2\psi_{i,j}^{n+1} + \psi_{i+1,j}^{n+1} \right) + \left(\psi_{i-1,j}^{n} - 2\psi_{i,j}^{n} + \psi_{i+1,j}^{n} \right) \right] \\ V(x,y,z) \, \psi(x,y,z) &= \frac{1}{2} \left[V_{i,j}^{n+1} \psi_{i,j}^{n+1} + V_{i,j}^{n} \psi_{i,j}^{n} \right] \\ \text{Let } r_{x} &= -\frac{\Delta t}{2i(\Delta x)^{2}} \,, \quad r_{y} &= -\frac{\Delta t}{2i(\Delta y)^{2}} \,. \end{split}$$

$$-r_{y}\psi_{i+1,j}^{n+1} - r_{y}\psi_{i-1,j}^{n+1} + a_{i,j}\psi_{i,j}^{n+1} - r_{x}\psi_{i,j+1}^{n+1} - r_{x}\psi_{i,j-1}^{n+1}$$

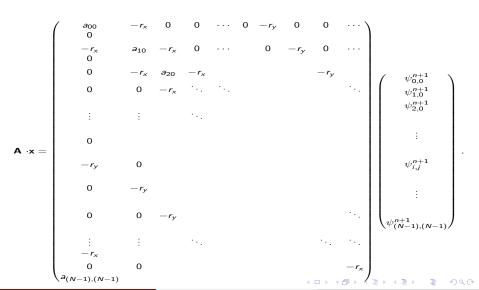
$$= r_{y}\psi_{i+1,j}^{n} + r_{y}\psi_{i-1,j}^{n} + b_{i,j}\psi_{i,j}^{n} + r_{x}\psi_{i,j+1}^{n} + r_{x}\psi_{i,j-1}^{n}$$

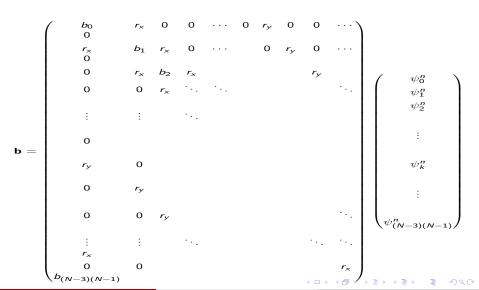
Switch to matrix form

$$Ax = b$$

.







Finite difference algorithm

Time evolution operator :
$$\psi(t+\Delta t)=U(\Delta t)\psi(t)$$
 where $U(\Delta t)=e^{-i\tilde{H}\Delta t}$. So, $\psi_{i,j}^{n+1}=U(\Delta t)\psi_{i,j}^{n}$ and $\psi_{i,j}^{n-1}=U^{-1}(\Delta t)\psi_{i,j}^{n}$ where $U^{-1}(\Delta t)=e^{i\tilde{H}\Delta t}$

$$\psi^{\mathit{n}+1} = \psi^{\mathit{n}-1} + \left[e^{-i\tilde{H}\Delta t} - e^{i\tilde{H}\Delta t} \right] \psi^{\mathit{n}}$$

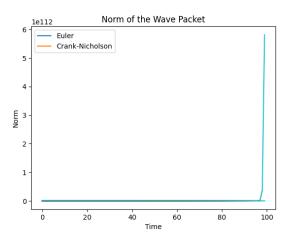
$$\frac{\partial^2 \psi}{\partial \mathbf{x}^2} \simeq -\frac{1}{2} \left[\psi_{i+1,j}^{\mathit{n}} + \psi_{i-1,j}^{\mathit{n}} - 2 \psi_{i,j}^{\mathit{n}} \right]$$



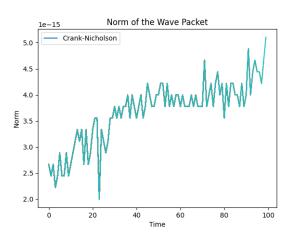
Finite difference algorithm

$$\begin{aligned} & \psi_{i,j}^{n+1} = \\ & \psi_{i,j}^{n-1} - 2i \left[\left(4\alpha + \frac{1}{2} \Delta t V_{i,j} \right) \psi_{i,j}^{n} - \alpha \left(\psi_{i+1,j}^{n} + \psi_{i-1,j}^{n} + \psi_{i,j+1}^{n} + \psi_{i,j-1}^{n} \right) \right] \\ & \text{where } \alpha = \Delta t / 2 (\Delta x)^{2} \end{aligned}$$

Euler algorithm



Euler algorithm



Conclusions

- Crank Nicholson matrix size scales quadratically unlike the 1D case.
- Not a tridiagonal matrix.
- Tried to save it as a sparse matrix but no considerable improvement.
- Finite difference method sidesteps matrix operations entirely.
- Finite difference misnomer?