

st125333_Assignment1_DLCV

August 19, 2025

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[1]: !python --version
```

Python 3.12.4

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[2]: import sys
      print(sys.executable)
```

C:\Users\satna\miniconda3\envs\myConda\python.exe

```
[3]: import torch
      print(torch.version.cuda)
      print(torch.cuda.is_available())
```

12.6
False

```
[4]: !nvidia-smi
```

'nvidia-smi' is not recognized as an internal or external command,
operable program or batch file.

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[7]: from ultralytics import YOLO
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[8]: image_files = [f"{i}.jpg" for i in range(1, 6)]
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[9]: modelv8n = YOLO("yolov8n.pt")
      results = modelv8n(image_files)
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0: 640x640 1 car, 1 airplane, 1 umbrella, 2 kites, 1 cup, 165.1ms
1: 640x640 1 car, 1 cow, 1 umbrella, 2 kites, 1 cup, 1 chair, 1 potted plant, 1
vase, 165.1ms
2: 640x640 3 persons, 1 tv, 1 cell phone, 165.1ms
3: 640x640 4 cups, 1 bowl, 1 banana, 1 clock, 165.1ms
4: 640x640 1 bowl, 1 sandwich, 3 oranges, 1 carrot, 1 dining table, 165.1ms
Speed: 6.4ms preprocess, 165.1ms inference, 5.1ms postprocess per image at shape
(1, 3, 640, 640)

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[10]: for idx, result in enumerate(results):
        boxes = result.boxes # Boxes object for bounding box outputs
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masks = result.masks # Masks object for segmentation masks outputs
keypoints = result.keypoints # Keypoints object for pose outputs
probs = result.probs # Probs object for classification outputs
obb = result.obb # Oriented boxes object for OBB outputs
result.show() # display to screen
result.save(filename=f"outputs/result_v8n_{idx}.jpg") # save to disk

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[11]: modelv12n = YOLO("yolo12n.pt")
      results = modelv12n(image_files)

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0: 640x640 1 car, 1 kite, 1 cup, 1 apple, 185.7ms
1: 640x640 1 car, 2 horses, 1 umbrella, 1 cup, 185.7ms
2: 640x640 2 persons, 1 tv, 1 cell phone, 185.7ms
3: 640x640 2 cups, 3 bowls, 1 dining table, 185.7ms
4: 640x640 7 oranges, 2 dining tables, 185.7ms
Speed: 5.7ms preprocess, 185.7ms inference, 1.9ms postprocess per image at shape
(1, 3, 640, 640)

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[12]: for idx, result in enumerate(results):
      boxes = result.boxes # Boxes object for bounding box outputs
      masks = result.masks # Masks object for segmentation masks outputs
      keypoints = result.keypoints # Keypoints object for pose outputs
      probs = result.probs # Probs object for classification outputs
      obb = result.obb # Oriented boxes object for OBB outputs
      result.show() # display to screen
      result.save(filename=f"outputs/result_v12n_{idx}.jpg") # save to disk

```

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