

# Sathurshan Arulmohan

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## Skills

**Programming Languages:** MATLAB, Simulink, Java, Python, Bash, C, C++, C#

**Technical Skills/Tools:** Git, Linux, ROS, Technical Writing, Software Testing, OOP, NLP, CAD, Verilog, Arduino

**Other:** Fluent English, Moderate French, Microsoft Office (Word, PowerPoint, Excel), G Driver's License

## Education

**McMaster University** | *Bachelor of Engineering: Software Engineering Co-op*

*Sept. 2021 - April 2025*

- Software Testing, Signals and Systems, Software Design I-III, Requirements and Security, Concurrent Systems

## Experiences

### McMaster Engineering EcoCAR EV Challenge

#### Path Planning Lead

*Aug. 2023 - Present*

- Managed a team of 15 members to simultaneously develop **Cooperative Adaptive Cruise Control**, **Lane Centering**, and **Automatic Parking** features with validation of up to 80% against ground truth
- Collaborated with leads, professors, and engineers to strategize seamless integration of entire architecture

#### Software Developer

*Sept. 2021 – July 2023*

- Led a team of 7 members to design simulation scenarios and **data flow plans** for all the team's autonomous features, which helped the team achieve 1<sup>st</sup> place out of 13 teams in technical deliverables
- Integrated **sensor fusion**, **track-level clustering**, and **road segmentation** algorithms for perception pipeline
- Developed code in MATLAB to create **boundary boxes** at any orientation and determine relative positions and speeds of objects with under 2.5% error

### McMaster University, Faculty of Engineering

#### Engineering 1P13 Teaching Assistant

*Sep. 2022 - Present*

- Mentored up to 125 first-year engineering students in engineering design fundamentals
- Educated students in code development in Python to develop their critical thinking and technical skills

### McSCert

#### Software Research Assistant II

*May 2023 – Present*

- Developed **object detection** and **tracking** algorithms, which provided a 1.65x enhancement over the original implementation for an RC vehicle equipped with a camera and LiDAR
- Researched and analyzed various road topologies to improve vehicle throughput and fuel consumption by 5%
- Implemented **concurrent pipelines** to run experiments and perform analytics on **computer clusters**, resulting in a 24-fold reduction in processing time

#### Software Research Assistant I

*May 2022 – Aug. 2022*

- Developed an automated pipeline to compare, analyze, and visualize the accuracy of existing **NLP** tools' annotations, which allowed the team to run 4 times more experiments
- Improved CRF's (NLP tool) performance to annotate user stories with up to 90% accuracy
- **Co-authored** [published paper](#) on research findings

## Projects

### Urbanism: Island City Generator

*Jan. 2023 – Apr. 2023*

- Designed a [Java program](#) using **OOP** to generate sustainable island cities utilizing 12% less resources

### DBSCAN Track Fusion Implementation

*Oct. 2022 – Nov. 2022*

- Implemented a [DBSCAN algorithm](#) in MATLAB with up to 85% validity for **fusing track level data**

## Awards

- **CAE Scholarships in Computing and Software Engineering:** McMaster University, \$3,400 scholarship
- **Provost's Honour Roll Medal 2022:** McMaster University, Faculty of Engineering
- **Schulich Leader 2021:** The Schulich Foundation, \$100,000 scholarship