

Drone Survey Management System

☐ Overview

This project focuses on the mission management and reporting aspects of drone operations, providing a comprehensive solution for:

- **Mission Planning:** Define survey areas, flight paths, and data collection parameters
- **Fleet Management:** Monitor drone inventory and real-time status across organizations
- **Mission Monitoring:** Track real-time flight progress with map visualization
- **Survey Analytics:** Generate comprehensive reports and analytics

Note: Live video feeds, actual data collection (images/videos), and map/model generation are outside the project scope.

☐ Key Features

☐ Mission Planning and Configuration

- Define survey areas and flight paths
- Configure flight altitudes, waypoints, and routes
- Set data collection parameters (frequency, sensors)
- Support for advanced survey patterns (crosshatch, perimeter)
- Mission-specific parameter configuration (altitude, overlap percentage)

☐ Fleet Visualization and Management Dashboard

- Organization-wide drone inventory display
- Real-time drone status monitoring (available, in-mission)
- Battery levels and vital statistics tracking
- Fleet coordination across multiple sites

☐ Real-time Mission Monitoring Interface

- Interactive map visualization of drone flight paths

- Mission progress tracking (% complete, ETA)
- Live mission status updates (starting, in progress, completed, aborted)
- Mission control actions (pause, resume, abort)

□ Survey Reporting and Analytics Portal

- Comprehensive survey summaries
- Individual flight statistics (duration, distance, coverage)
- Organization-wide survey analytics
- Historical mission data and trends

Project Structure

```
drone-survey-management-system
├── src
│   ├── main.py          # Entry point for the application
│   ├── database.py      # Database management and operations
│   ├── models.py        # Data models for drones and missions
│   ├── schemas.py       # Pydantic schemas for data validation
│   ├── enums.py         # Enumerations for statuses and patterns
│   ├── utils.py         # Utility functions
│   └── __init__.py      # Package initialization
├── tests
│   ├── test_api.py      # Unit tests for API endpoints
│   ├── test_database.py # Tests for database operations
│   ├── test_models.py   # Tests for data models
│   ├── test_enums.py    # Tests for enumerations
│   ├── test_error_handling.py # Tests for error handling
│   ├── test_mission_simulation.py # Tests for mission simulation
│   ├── test_websocket.py # Tests for WebSocket functionality
│   ├── test_performance.py # Performance tests
│   └── test_integration.py # Integration tests
├── requirements.txt      # Project dependencies
└── README.md            # Project documentation
```

Installation

1. Clone the repository:

```
git clone https://github.com/Sathvik-Malgikar/drone-survey-management-system.git
```

2. Install the required dependencies:

```
pip install -r requirements.txt
```

Usage

To run the application, execute the following command:

```
uvicorn src.main:app --reload
```

This will start the FastAPI server, and you can access the API at `http://localhost:8000`.

Testing

To run the tests, use the following command:

```
pytest
```

This will execute all the tests in the `tests` directory.

Contributing

Contributions are welcome! Please submit a pull request or open an issue for any enhancements or bug fixes.

License

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