

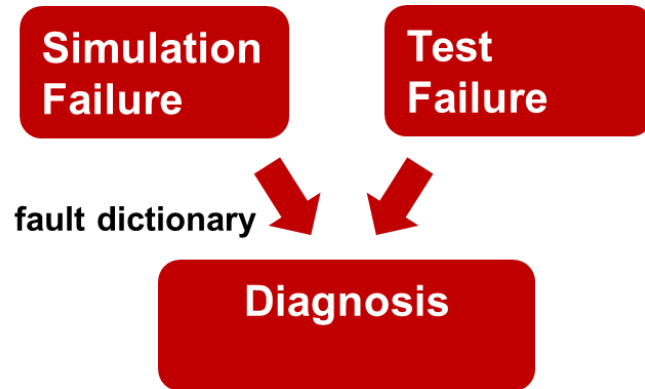
# Diagnosis

- Introduction
- Logic Diagnosis
  - ◆ SSF diagnosis
    - \* Static Cause-effect diagnosis
    - \* Dynamic Cause-effect diagnosis
    - \* Effect-cause diagnosis
      - Path Tracing: CPT, STAR
      - Pruning
      - Ranking
  - ◆ Unmodeled / multiple fault diagnosis
- Scan Chain Diagnosis
- Failure Analysis
- Conclusions

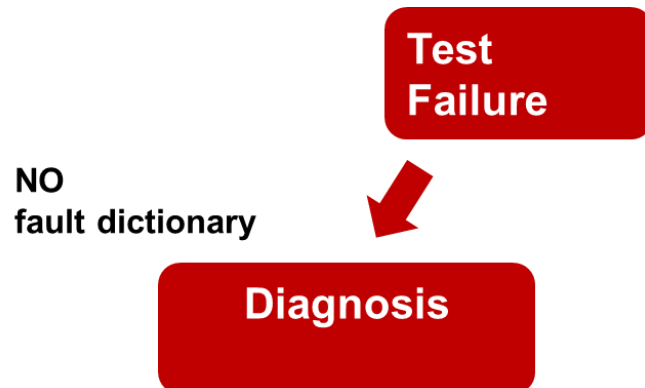


# Review

## cause-effect diagnosis



## effect-cause diagnosis



# Typical Effect-Cause Diagnosis Flow

test patterns, ckt

test failures

**Path-Tracing**

CPT, STAR

*candidate* faults

**Pruning**

Set operation, Layout, Timing ...

*suspect* faults

**Ranking**

Fault Simulation

*ranked suspect* faults

\* This flow can be  
modified in different  
diagnosis tools

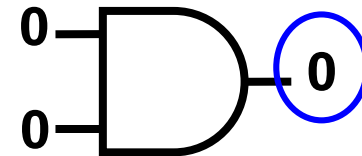
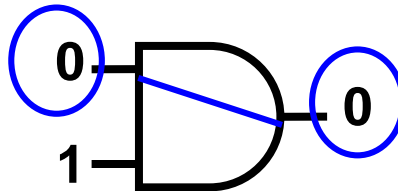
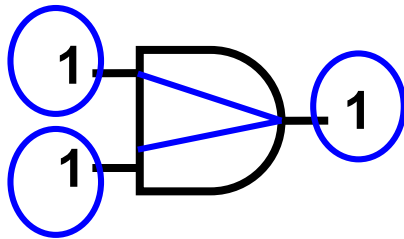
# Diagnosis

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# Review: Critical Path (see CH 5)

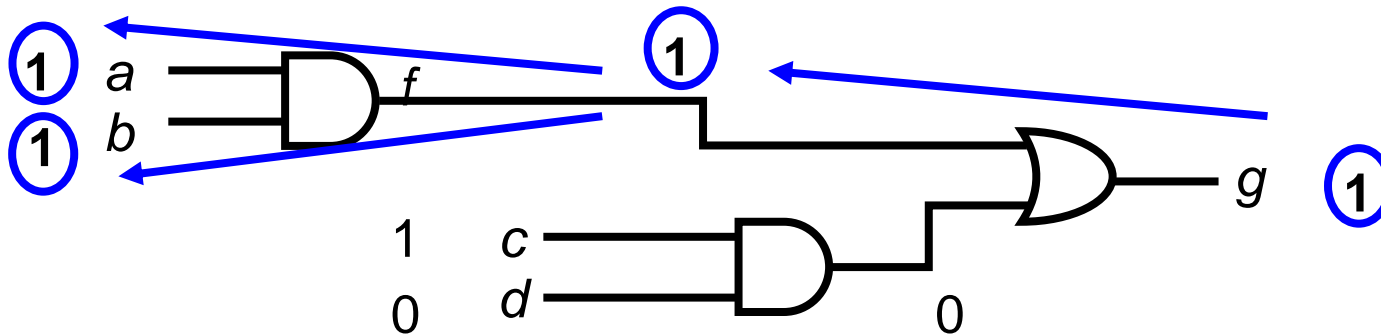
- $x$  is **Critical Signal**
  - ♦  $x$ 's value change causes some primary output values to change
- Example: when gate output is critical
  - ♦ (1) If **all gate inputs are non-controlling**, they are all critical
  - ♦ (2) If **only one gate input is controlling**, it is critical
  - ♦ (3) Otherwise, no input is critical



critical signals are circled

# Review: Critical Path Tracing (see CH 5)

- CPT : trace critical signals from output
- CPT is simple in **fanout-free cone (FFC)**
  - ♦ **Linear time** algorithm. **No fault simulation** needed
- Example: Critical signals: ***a, b, f, g.***

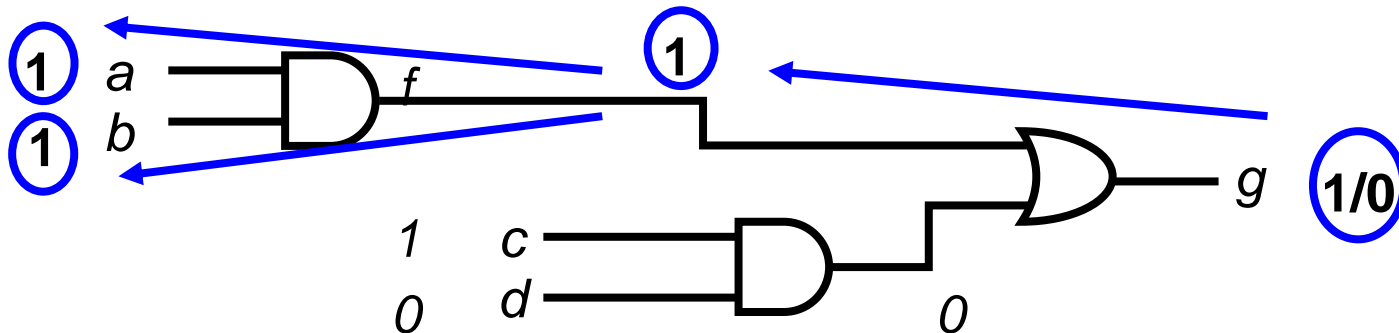


CPT (*O*) /\**O* is a node\*/

1. **foreach** gate input *g* of *O*
2.   **if** (*g* is critical signal) **then**
3.     CPT (*g*) ;
4.   **else return**;

# CPT for Diagnosis

- CPT from failing output
  - ♦ Critical signals are **candidate fault sites**
  - ♦ Stuck values are opposite to their good logic values
- Example: CPT from failing output  $g$ 
  - ♦ 4 candidate faults:  $g$  SA0,  $f$  SA0,  $a$  SA0,  $b$  SA0



## THEOREM:

Assume there is only one SSF in FFC.

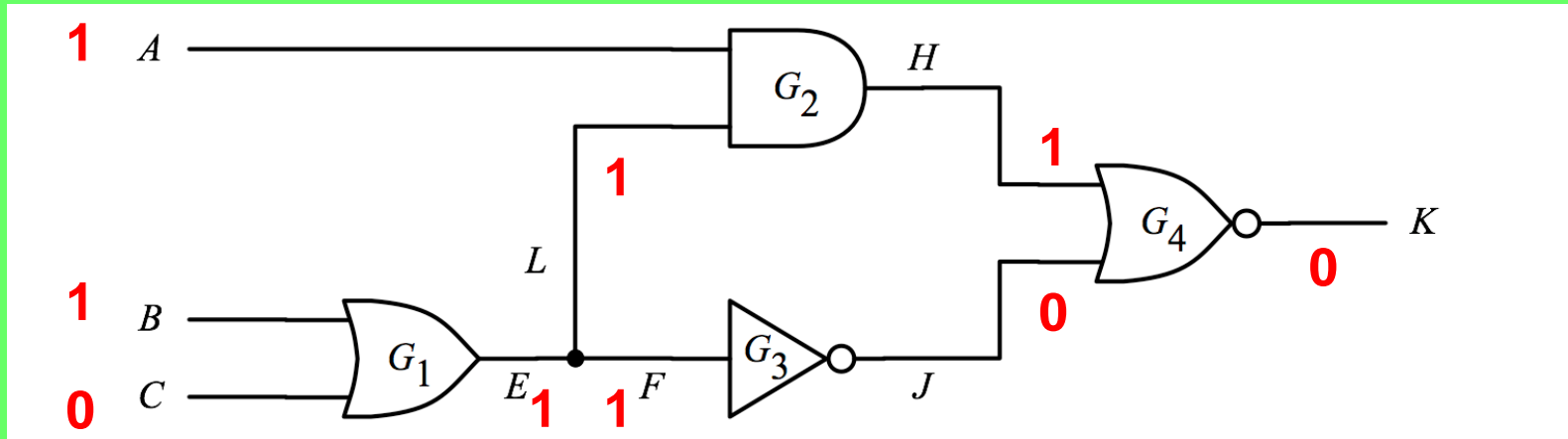
The fault must be one of candidate faults using CPT.

# Quiz

Q: Suppose a CUT fails this test pattern.

(1) Use CPT to find candidate faults. (2) How do you know fanout stem  $E$  is critical or not?

A:

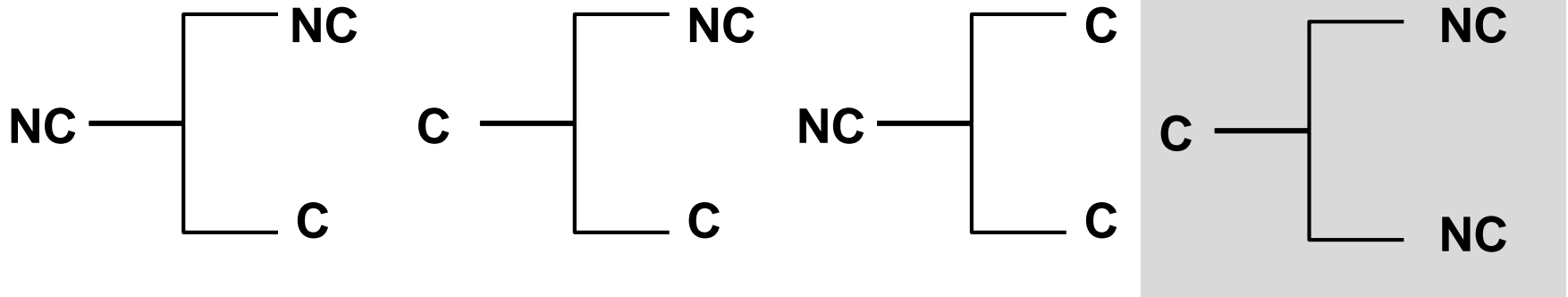


**CPT Cannot Decide Criticality of Fanout Stem**

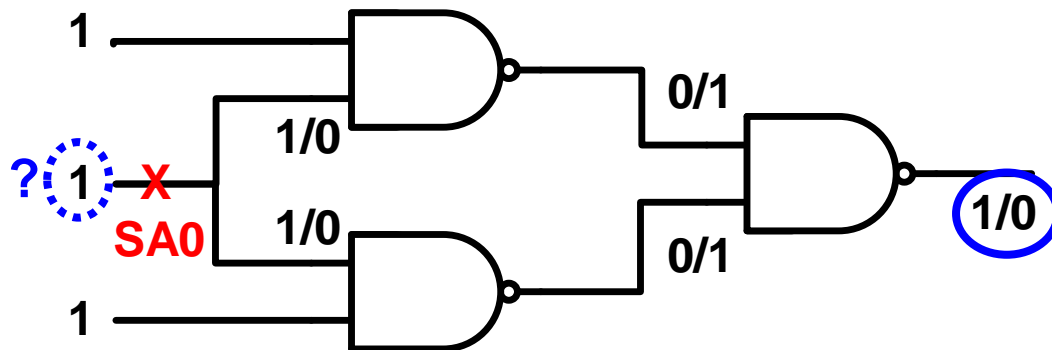


# Four Cases for Fanout

- All four cases are possible



- Case 4 example: *multiple path sensitization*
  - ♦ No branch is critical but stem is critical. How to trace?



**Case 4 Very Bad for Diagnosis**

# Diagnosis

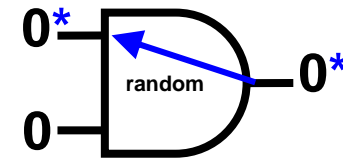
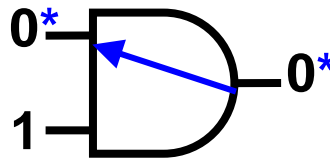
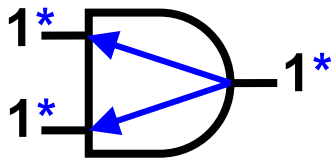
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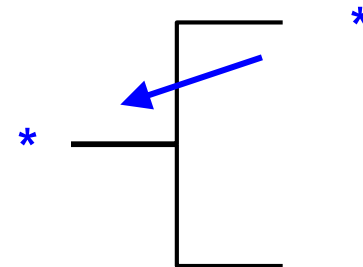
**STAR Can Handle Fanouts**

# STAR Tracing [Akers 90]

- A **starred signal** means that it **can be a candidate fault site**
- When a gate output is starred
  - ♦ (1) If all gate inputs are non-controlling, they are all starred
  - ♦ (2) If only one gate input is controlling, it is starred
  - ♦ (3) **Otherwise, randomly select one** to be starred

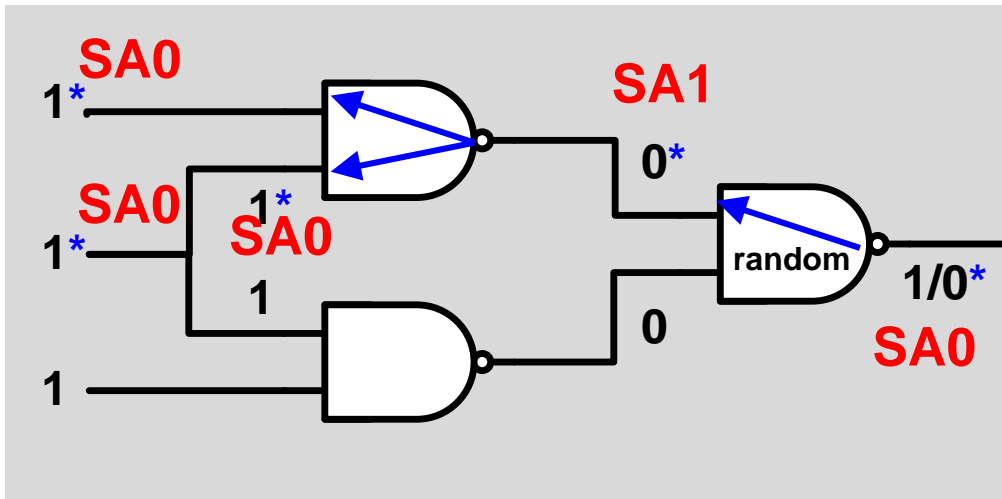


- When **any fanout branch** is starred, its fanout stem is starred
  - ♦ otherwise, fanout stem is NOT starred



# STAR Tracing for Diagnosis

- Run StarTracing() from each failing output
  - ♦ Starred signals are candidate fault sites
  - ♦ Stuck-at values are opposite to its good logic value
- Example: 5 candidate faults

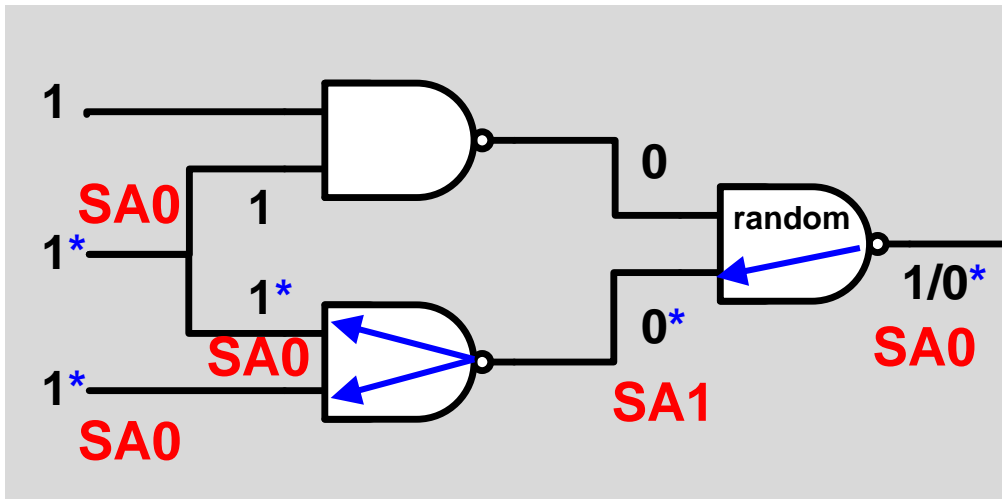


StarTracing (*O*)

1. **foreach** gate input *g* of *O*
2.   **if** (*g* is starred) **then**
3.       StarTracing (*g*) ;
4.   **else return**;

# Another STAR Tracing

- STAR tracing can be performed **multiple times** for a pattern
  - ♦ Each time can result in **different** candidate faults
- Example: 5 (different) candidate faults
  - ♦ Fanout stem is still one of candidates



StarTracing ( $O$ )

1. **foreach** gate input  $g$  of  $O$
2.   **if** ( $g$  is starred) **then**
3.     StarTracing ( $g$ ) ;
4.   **else return**;

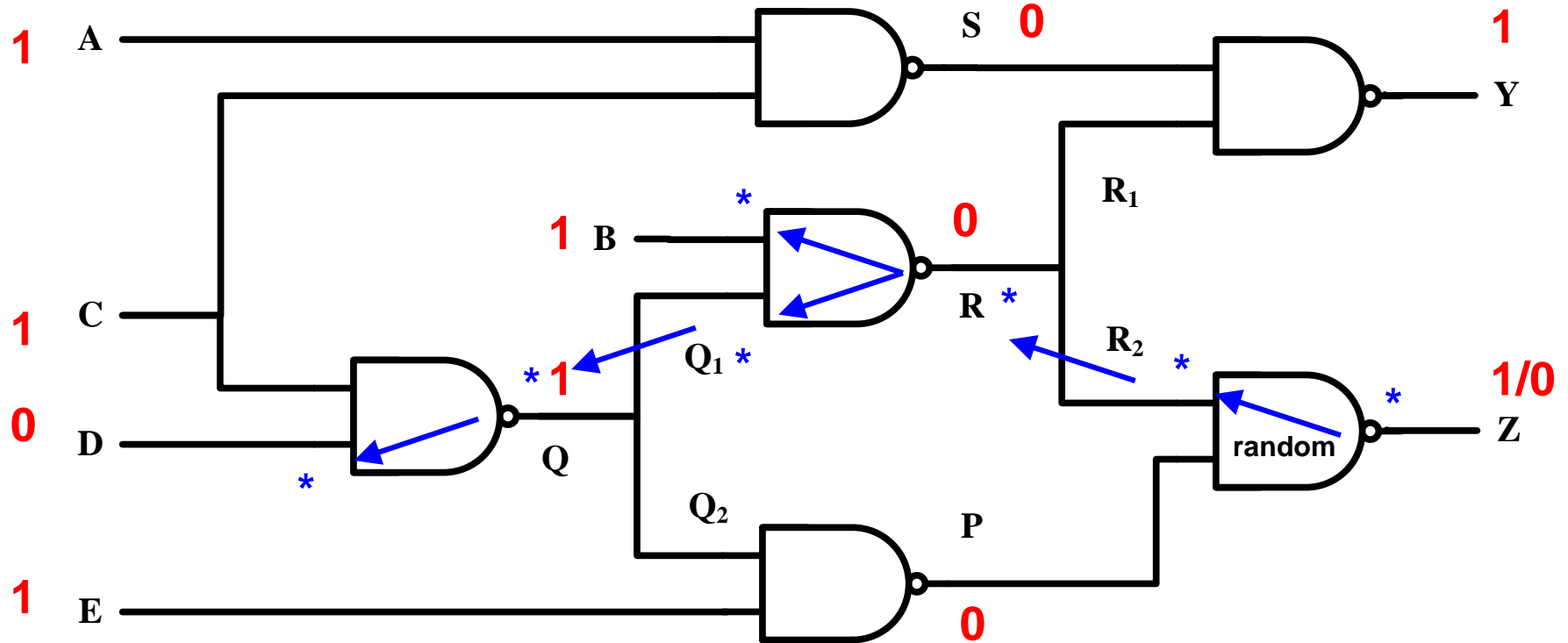
**THEOREM:** (to be proved in FFT)

Assume there is only one SSF in CUT. The fault must be one of candidate faults using STAR Tracing.

# STAR Tracing Example (pattern 1/2)

- Example: STAR Tracing from failing output Z

- 7 candidate faults: Z SA0, R<sub>2</sub> SA1, R SA1, Q<sub>1</sub> SA0, Q SA0, B SA0, D SA1

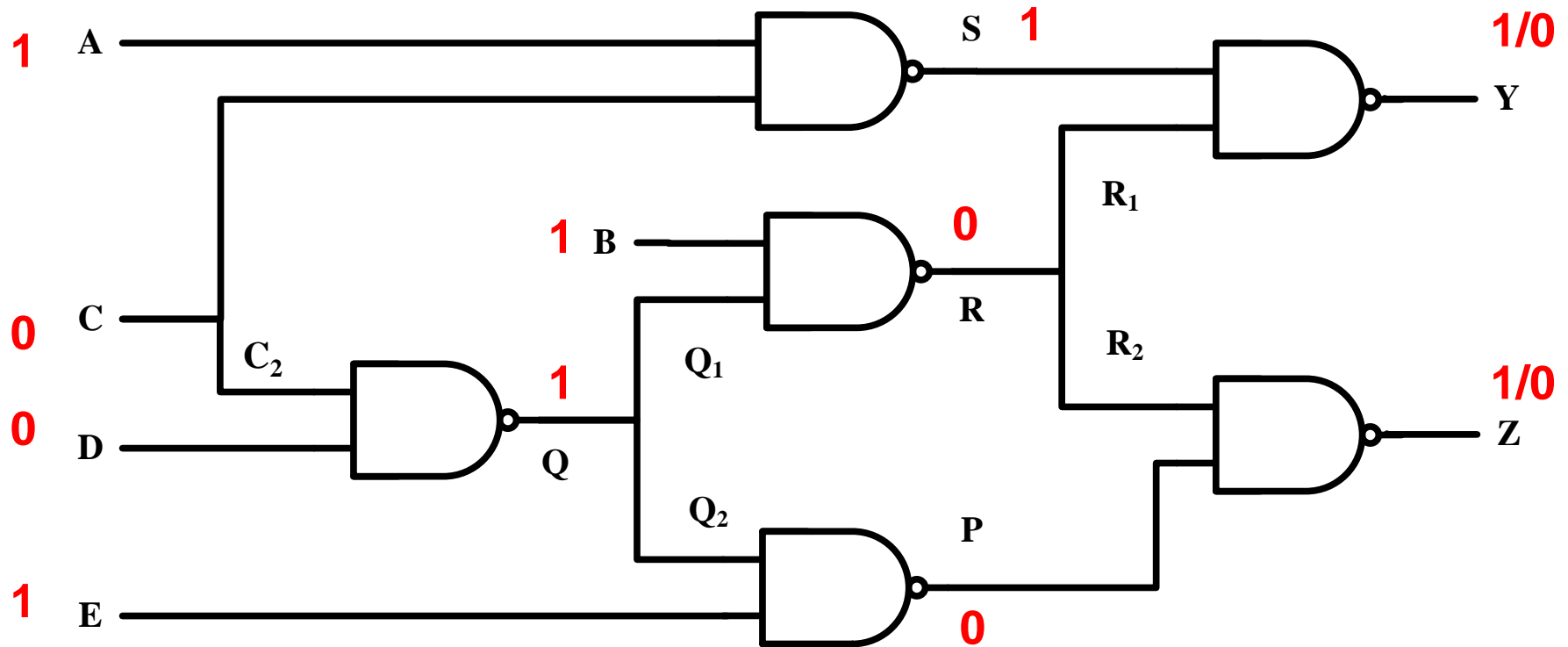


# STAR Tracing Example (pattern 2/2)

Q: Apply another pattern. Y and Z are failing outputs.

(1) Which signals are starred? (2) What are candidate faults?

(Suppose we randomly select P and C)



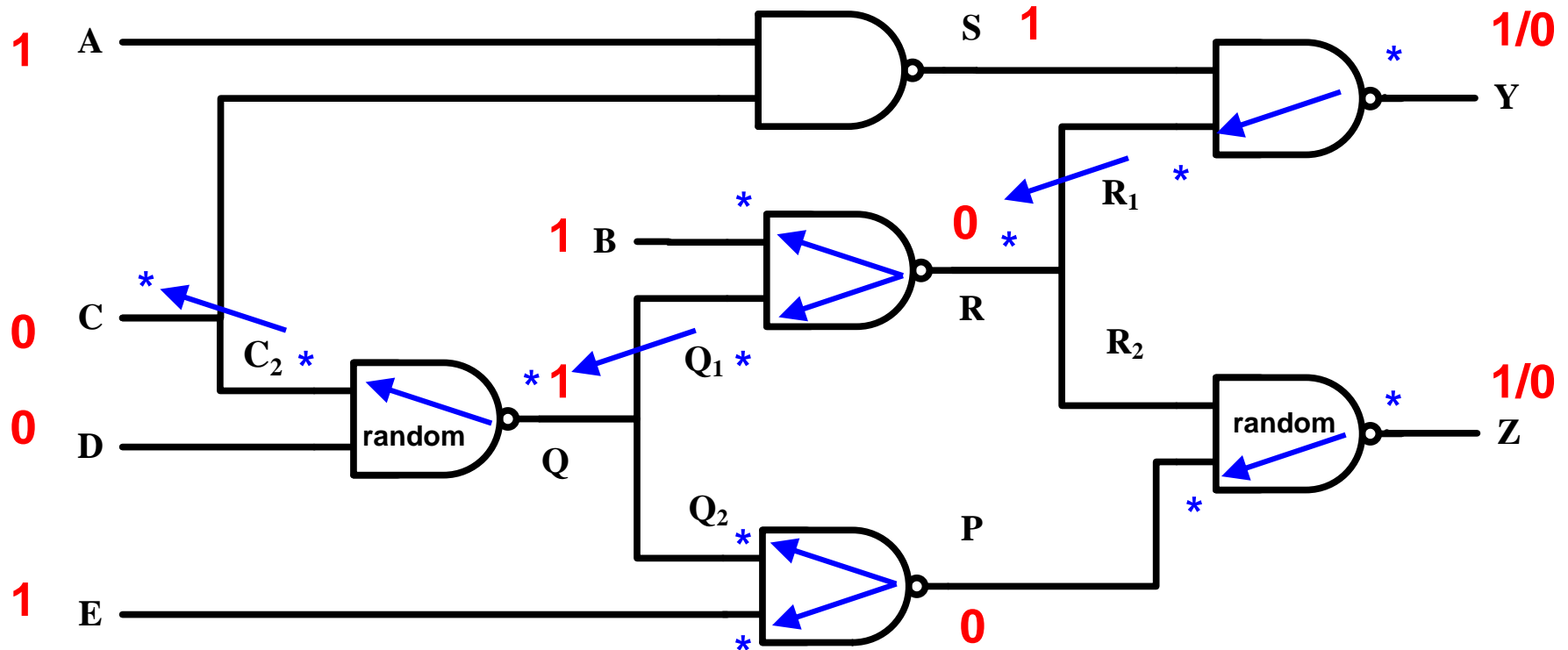
# ANSWER

Q: Apply another pattern. Y and Z are failing outputs.

(1) Which signals are starred? 12

(2) What are candidate faults?

Y SA0, Z SA0, R<sub>1</sub> SA1, R SA1, P SA1, B SA0, Q<sub>1</sub> SA0, Q<sub>2</sub> SA0, Q SA0, C<sub>2</sub> SA1, C SA1, E SA0





# Diagnosis

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# Typical Effect-Cause Diagnosis Flow

test patterns, ckt

test failures

**Path-Tracing**

CPT, STAR

candidate faults

**Pruning**

Set operation, Layout, Timing ...

suspect faults

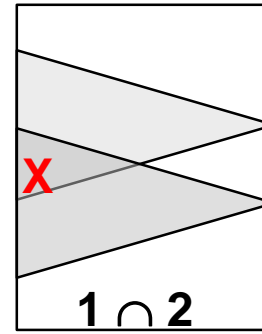
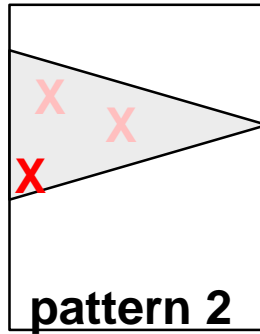
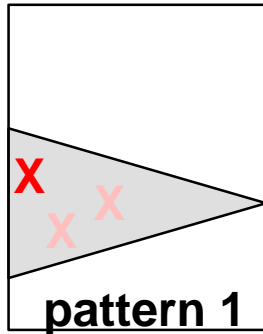
**Ranking**

Fault Simulation

ranked suspect faults

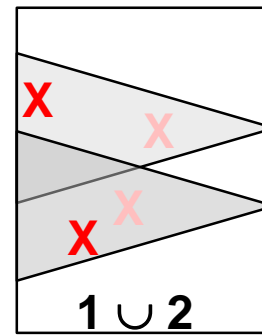
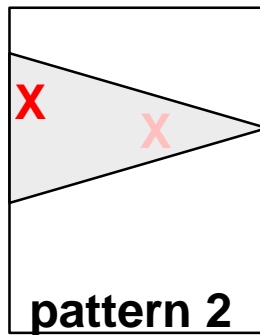
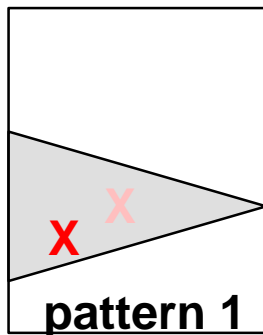
# Single Fault / Multiple Faults (\*not in exam)

- Single fault : take **intersection** of candidate faults
  - ♦ guaranteed to be correct



**X true fault**  
X false fault

- Multiple fault: take **union** of candidate faults
  - ♦ may be incorrect : can miss some true faults (Why? FFT)



# Example (Cont'd)

- After pattern 1

- 7 candidate faults:

Z SA0, R<sub>2</sub> SA1, R SA1, Q<sub>1</sub> SA0, Q SA0, B SA0, D SA1

- After pattern 2

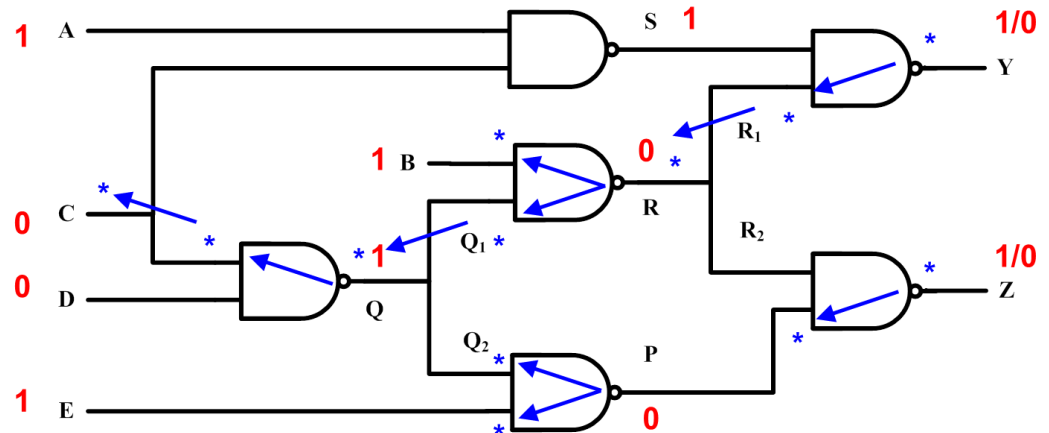
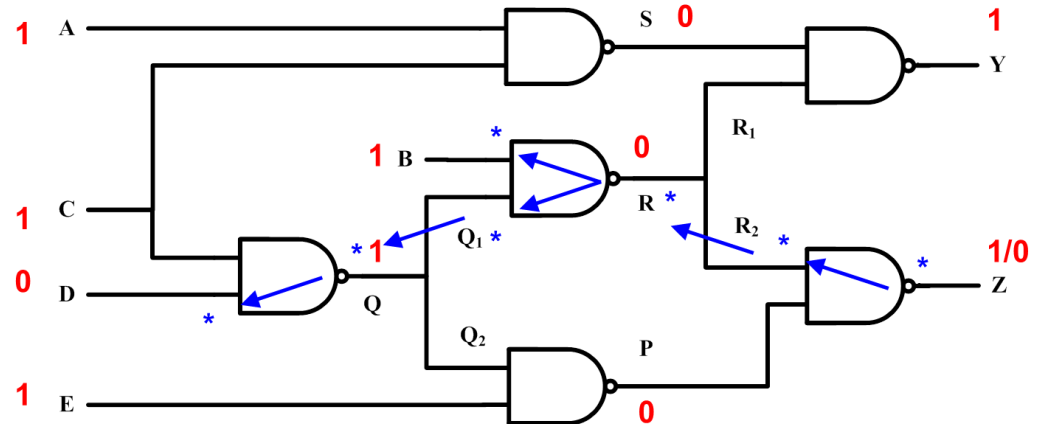
- 12 candidate faults:

Y SA0, Z SA0, R<sub>1</sub> SA1, R SA1, P SA1, B SA0, Q<sub>1</sub> SA0, Q<sub>2</sub> SA0, Q SA0, C<sub>2</sub> SA1, C SA1, E SA0

- After Intersection

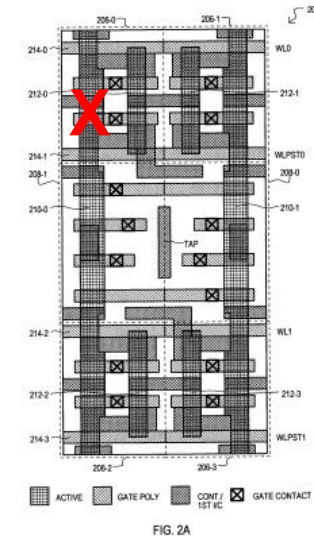
- 5 suspect faults

Z SA0, R SA1, Q<sub>1</sub> SA0, Q SA0, B SA0

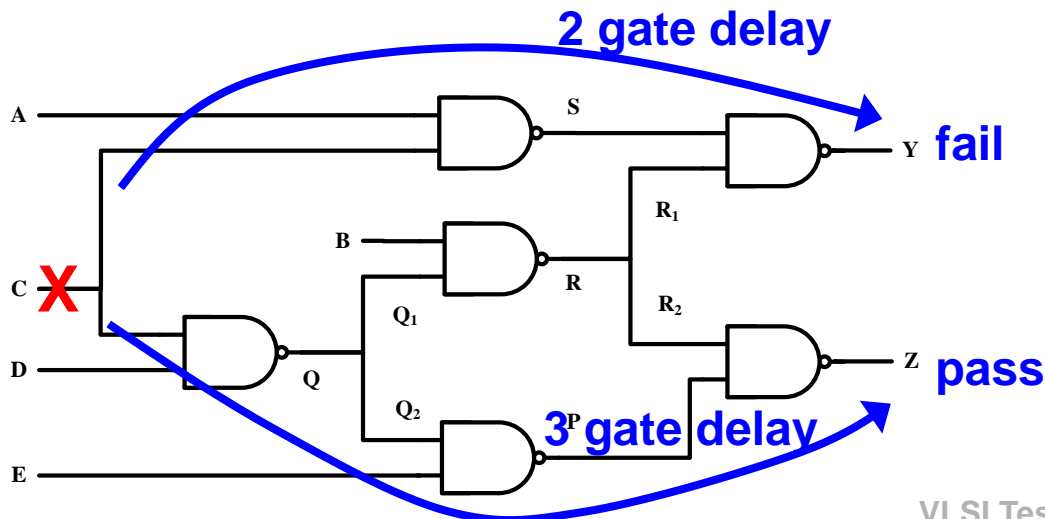


# Other Pruning Techniques (\* not in exam)

- **Layout information** for bridging fault diagnosis
  - ♦ **Bridging pairs** must be neighbors on layout
  - ♦ If two faults are physically far from each other
    - \* They can be pruned
- **Timing information** for delay fault diagnosis
  - ♦ If a fault fails short path but pass longer path
    - \* It can be pruned



X



# Diagnosis

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# Typical Effect-Cause Diagnosis Flow

test patterns, ckt

test failures

**Path-Tracing**

CPT, STAR

candidate faults

**Pruning**

Set operation, Layout, Timing ...

suspect faults

**Ranking**

Fault Simulation

ranked suspect faults

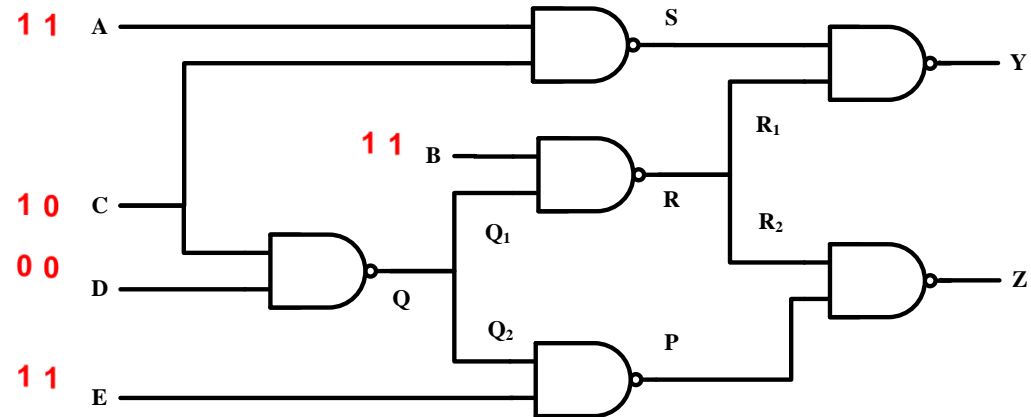
# Ranking

- Fault simulate 5 suspect faults

- Z SA0, R SA1, Q<sub>1</sub> SA0, Q SA0, B SA0

- Q SA0 is ranked #1**

$$Diagnosis\ Score = \frac{TFSF}{TFSP + \alpha \cdot TPSF + TFSF} \times 100\%$$



	faults	pattern1		pattern2		Diagnosis score			
		Y	Z	Y	Z	TFSF	TPSF	TFSP	score
1	Z SA0		X		X	2		1	0.67
2	R SA1			X		1		2	0.33
3	Q <sub>1</sub> SA0		X	X		2		1	0.67
4	Q SA0		X	X	X	3			1.00
5	B SA0			X		1		2	0.33
	Test Failure		X	X	X				

#2

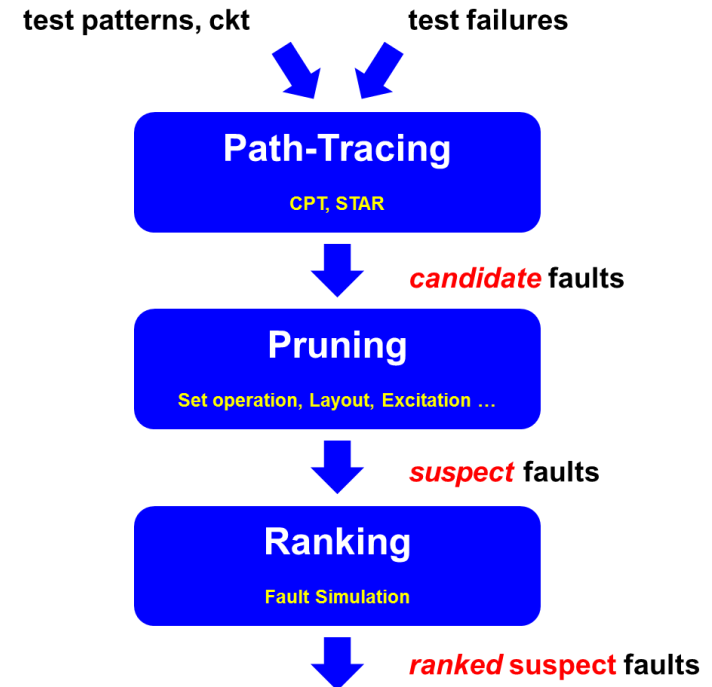
#2

#1



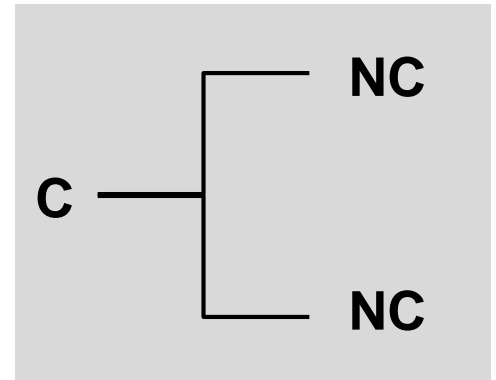
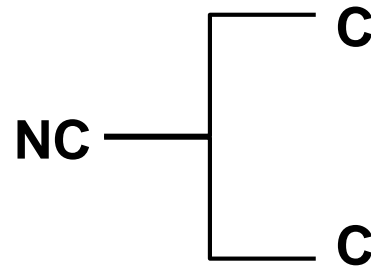
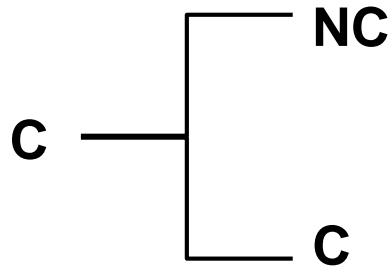
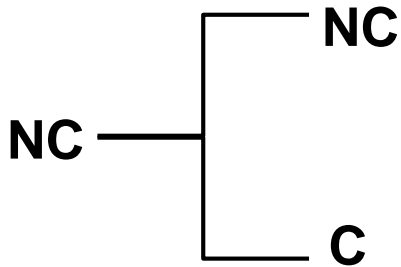
# Summary

- Effect-Cause Diagnosis
  - ◆ No dictionary is needed
  - ◆ Most effective diagnosis nowadays
- Typical flow
  - ◆ Path tracing, Pruning, Ranking
- STAR tracing
  - ◆ Fast. No fault simulation needed.
  - ◆ Guaranteed correct if SSF
    - \* Multiple path sensitization is OK



# FFT #1

- Q: All four cases are possible
  - ♦ Please give examples for cases 1, 2, 3
  - ♦ Can we handle them by STAR tracing?

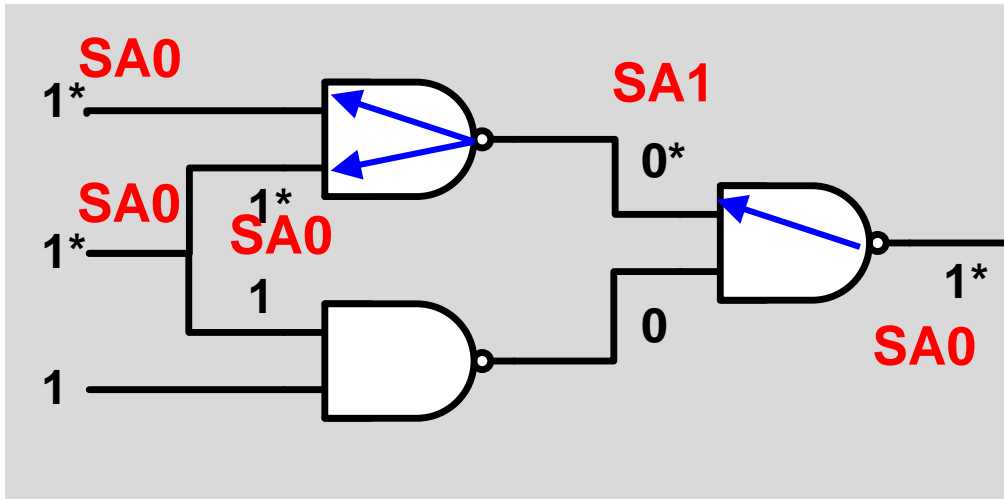


# FFT #2

- Please prove the theorem

## THEOREM:

Assume there is only one SSF in CUT. The fault must be one of candidate faults using STAR Tracing.



StarTracing ( $O$ )

1. **foreach** gate input  $g$  of  $O$
2.   **if** ( $g$  is starred) **then**
3.     StarTracing ( $g$ ) ;
4.   **else return;**

# FFT #3

- Multiple fault: take **union** of candidate faults
  - ♦ may be incorrect
    - \* can miss some true suspect faults
- Q: Why we cannot guarantee to find all multiple faults using STAR tracing?

