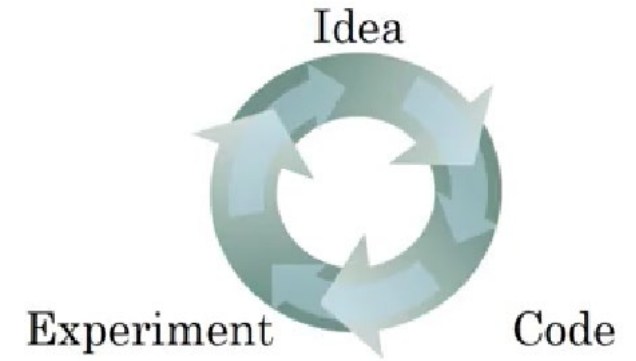




# STRUCTURING MACHINE LEARNING PROJECTS

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# ORTHOGONALIZATION



Orthogonalization: Tune the knobs of the system in a way to modify each element separately

Chain of assumption:

- Fit training set well on cost function
- Fit dev set well on cost function (**tuning**)
- Fit test set well on cost function
- Performs well in the real world

**PS:** Dev set and test set must come from the same distribution

❑ Old way of splitting data → train 60% test set 20% dev set 20%

❑ New way of splitting day → train 98% test set 1% dev set 1%

**PS:** If doing well on your metric + dev/test does not correspond to doing well on your application, change your metric and/or dev/test set

# HUMAN-LEVEL PERFORMANCE

## Avoidable bias: Human-level error – training error

- Train bigger model
- Train longer/better optimization algorithm (RMSprop, Momentum, Adam)
- NN architecture/hyperparameters search (RNN, CNN)

## Variance: Dev error – training error

- More data
- Regularization ( $L_2$ , Dropout, Data augmentation)
- NN architecture/hyperparameter search

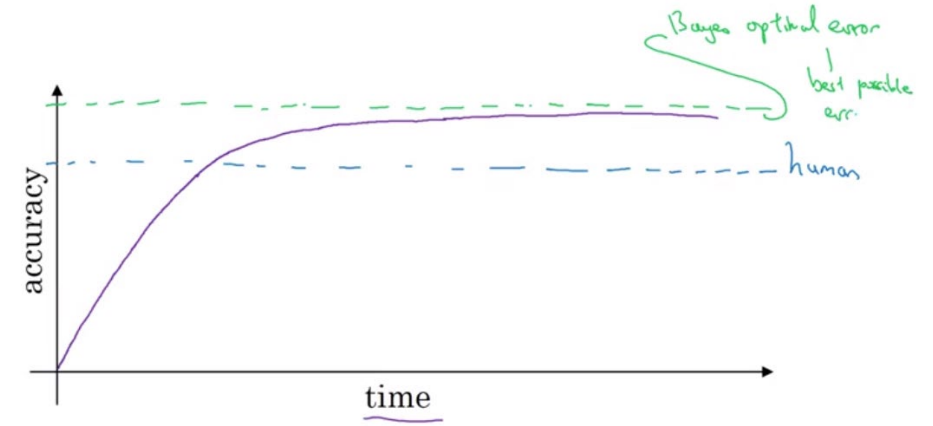
## Evaluation metrics:

- Harmonic mean: F Score:  $\frac{2}{\frac{1}{P} + \frac{1}{R}}$
- Average
- With bigger weights for 'big mistakes':  $\text{Error} = \frac{1}{\sum_i w^{(i)}} \sum_i w^{(i)} \text{cost}_i$ ;  $w^{(i)} = \begin{cases} 1, & \text{if } x^{(i)} \text{ is normal} \\ \text{Big weight}, & \text{if } x^{(i)} \text{ is 'big mistake'} \end{cases}$

Human-level error = Lowest human error (Closer to bias error)

**PS:** If training error < human-level error → We can't predict bias error

PS: Humans are good in natural perception cases: NLP, speech recognition, image recognition...



❑ Max metric → **Optimization** metric

❑ Good value corresponding to a threshold → **Satisfying** metric

# ERROR ANALYSIS

## Error analysis: Examine mistakes **manually**

- Get ~100 mislabeled dev set examples
- Count up how many for each category (add a category for incorrectly labeled examples)
  - Ceiling in performance: How well would working on a sub problem help you?

## Incorrectly labeled examples:

- **Random errors**: DL algorithms are quite robust to them
- **Systematic errors**: They are dangerous

## Guideline:

1. Set up dev/test set and metric
2. Build initial system quickly
3. Use bias/variance analysis and error analysis to prioritize next steps

## If training set and dev/test set from $\neq$ distributions:

- **Option 1**: Add new data to whole data  $\rightarrow$  Shuffle  $\rightarrow$  Divide data on train, dev and test
- **Option 2**: Add part of new data to training-dev set and the rest to dev and test
  - Training-dev set: Same distribution as training set, but not used for training

PS: Test error – Dev error = Degree of overfitting to the dev set

	General data	Specified data
Human-level	Human-level	
Error on examples trained on	Training error	
Error on examples not trained on	Training-dev error	Dev/Test error

**Avoidable bias**

**Variance**

**Data mismatch**

# OTHER NOTIONS

## Addressing data mismatch:

- Carry out manual error analysis to try to understand difference between training and dev/test sets
- Make training data more similar, or collect more data similar dev/test sets

Artificial data synthesis: Normal data set + Artificial effect = Synthesized data set → Create more data

**PS:** Be careful of overfitting to the 'artificial effect'

Transfer learning: Learned task A → Learn task B by modifying output layers

- Task A and task B must have the same input  $x$
- Task A have more data than task B
- Low level features from A could be helpful for learning B (similar features)

**Eg.** Image recognition → Radiology diagnosis, Speech recognition → Wakeword detection

Multi-task learning: Learn multiple tasks at the same time with the same input layers

- Training on a set of tasks could benefit from having shared lower-level features
- Amount of data you have for each task is quite similar usually
- Can train a big enough neural network to do well on all the tasks

End-to-end learning: Learn the function **mapping** from input to output **directly** (passing the intermediate steps)

- **Pros:** Let the data speak + Less hand-designing of components needed
- **Cons:** May need large amount of data + Excludes potentially useful hand-designed components

Traditional pipe line: Learn the  $\neq$  intermediate functions from input to output