

$$1 \text{ m} = 10^{-3} \text{ km}$$

Page

Prove the relation b/w newton and dyne

$$1 \text{ N} = 10^5 \text{ dyne}$$

$$1 \text{ dyne} = 10^{-5} \text{ N}$$

$$1 \text{ N} = 1 \text{ kg} \times 1 \text{ m/s}^2$$

$$1 \text{ kg} \times 100 \text{ cm/s}^2$$

$$1 \text{ N} = 1000 \times 100 \times 9.8 \text{ cm/s}^2$$

$$1 \text{ N} = 10^5 \text{ g cm/s}^2$$

Relation b/w Tesla and Gauss

$$1 \text{ T} = \frac{1 \text{ N}}{1 \text{ m}} = \frac{10^5 \text{ dyne}}{10^4 \text{ Bi} \times 10 \text{ cm}} = 10^4 \text{ G}$$

Relation b/w Neper and decibel

$$1 \text{ neper} = 8.68 \text{ dB}$$

Practical file format

L.H.S (white page)

Aim

Apparatus

Formula Used

Diagram

Observations

Calculations

Result

R.H.S (Pen side)

Aim

Apparatus

Theory / Principle

Procedure

Result

Precautions

Learning outcomes

Group B

Exp  $\Rightarrow$  AP = attenuation & propagation losses  
in optical fibre

$$1 \text{ n} = 8.68$$

$$V_1 = \frac{31}{17} \times 10^3$$

$$V_2 = \frac{17}{17} \times 10^3$$

$$l_1 = l_2 = 1m$$

$$\frac{31}{17} = e^{-2\alpha}$$

$$1.82 = e^{-2\alpha}$$

$$\frac{V_1}{V_2} = e^{-\alpha(l_1 + l_2)}$$

$$0.26 = -2\alpha$$

$$\alpha = -0.13$$

classmate

Date \_\_\_\_\_

Page \_\_\_\_\_

Ph 121 Modern & Computational Physics  
Book = Engineering Physics by H-K Malik

Unit - 1  $\Rightarrow$  Electro dynamics

$\hookrightarrow$  Physical Qty

**CURL, Gradient, Divergence**

Unit - 2  $\Rightarrow$  Lasers

$\hookrightarrow$  What is a laser

$\hookrightarrow$  Laser principle

$\hookrightarrow$  Types of lasers

Unit  $\Rightarrow$  3 Optical fibres

Unit - 4  $\Rightarrow$  Magnetic Materials

Unit - 5  $\Rightarrow$  Superconductivity

Unit - 6  $\Rightarrow$  Quantum Mechanics

Any quantity which we can measure is a physical quantity. Eg  $\rightarrow$  temp, length

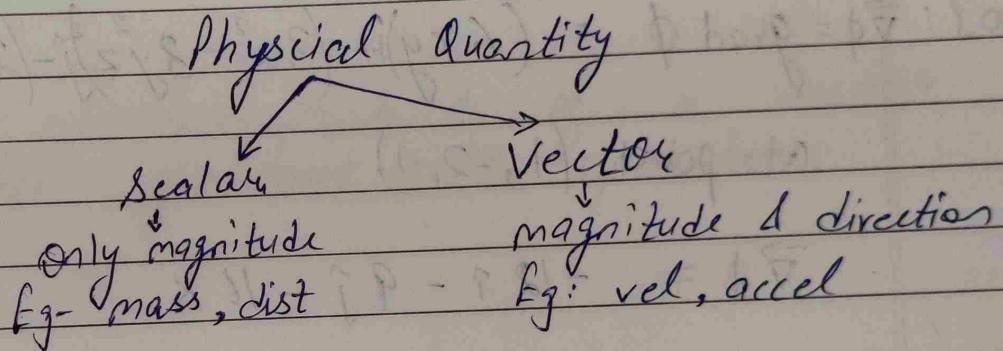
Physical Quantity

Scalar      vector

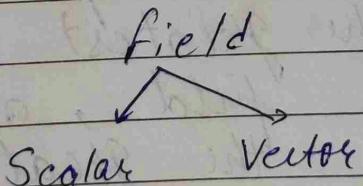
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# ELECTRODYNAMICS

Physical Quantity: Any quantity which we can measure is a physical quantity.  
Eg - temp, length



Field: If a physical quantity varies from point to point it becomes a field



Dell operator: It is a vector differential operator

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$$

It is also known as nable

\*  $\vec{\nabla} \phi = \text{grad } \phi$ , where  $\phi$  is a scalar function

$$\text{grad } \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} = \vec{\nabla} \phi$$

When del operator acts upon a function it becomes gradient. Gradient of  $\phi$  is a vector quantity

Ques: If  $\phi(x, y, z) = 3x^2y - y^3z^2$ , calculate the gradient of  $\phi$  at the point  $(1, -2, -1)$

Sol:  $\vec{\nabla} \phi = \text{grad } \phi = (6xy)\hat{i} + (3x^2 - 3y^2z^2)\hat{j} - (2y^3z)\hat{k}$  using partial diff  
at point  $(1, -2, -1)$

$$\vec{\nabla} \phi = -12\hat{i} - 9\hat{j} - 16\hat{k}$$

### Gradient of Scalar Fields

The gradient of a scalar field is a vector field, which points in the direction of the greatest rate of increase of the scalar field, and whose magnitude is the greatest rate of change

$$|\vec{\nabla} \phi| = \sqrt{(-12)^2 + (-9)^2 + (-16)^2}$$

Ques:  $\phi = x^3 + y^3 + z^3 - 3xyz$ , find  $\vec{\nabla} \phi$  &  $|\vec{\nabla} \phi|$  at  $(1, -1, 2)$

Sol:  $\vec{\nabla} \phi = (3x^2 - 3yz)\hat{i} + (3y^2 - 3xz)\hat{j} + (3z^2 - 3xy)\hat{k}$

at point  $(1, -1, 2)$

$$\vec{v}\phi = (3+6)\hat{i} + (3-6)\hat{j} + (12+3)\hat{k}$$

$$\vec{v}\phi = 9\hat{i} - 3\hat{j} + 15\hat{k}$$

$$|\vec{v}\phi| = \sqrt{3(9+1+25)} = 3\sqrt{35}$$

## Divergence

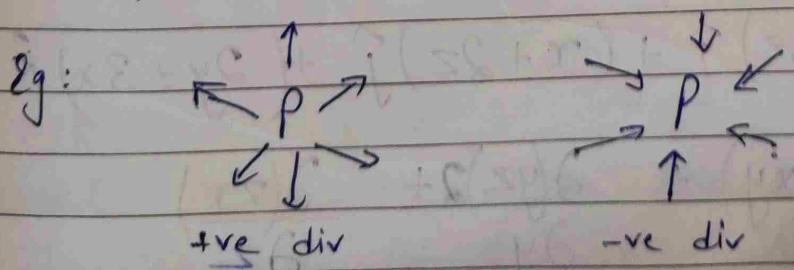
It is the scalar product of a vector field with gradient del operator

$$\text{div } \vec{F} = \vec{v} \cdot \vec{F}$$

$$= \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k})$$

$$= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

geometrical interpretation: It is a measure of how much a vector  $\vec{F}$  spreads out (diverges) from the point in question



$P$  = electric field

Note: If Divergence of vector field is zero then it is also termed as Solenoidal Field

Divergence is an operator that measures the magnitude of a vector field's source or sink at a given point.

The divergence of a vector field is a scalar and at a point it is defined as the amount of flux diverging from a unit volume element per second around that point.

Ques: Calculate divergence & del operator

$$(a) \vec{v}_1 = x^2 \hat{i} + 3xz^2 \hat{j} - 2xz \hat{k}$$

$$\vec{\nabla} = (2x + 3z^2 - 2z) \hat{i} + (6x - 2x) \hat{k}$$

$$\begin{aligned} \text{div } \vec{v}_1 &= 2x^3 + 3x^2 z^2 - 2x^2 z + 6x^3 - 2x^3 \cancel{\frac{\partial(x^2)}{\partial x}} + \cancel{\frac{\partial(3z^2)}{\partial y}} \\ &= 6x^3 + 3x^2 z^2 - 2x^2 z = 2x + 0 - 2x = 0 \end{aligned}$$

$$(b) \vec{v}_2 = xy \hat{i} + 2yz \hat{j} + 3zx \hat{k}$$

$$\vec{\nabla} = (y + 3z) \hat{i} + (x + 2z) \hat{j} + (2y + 3x) \hat{k}$$

$$\begin{aligned} \text{div } \vec{v}_2 &= \frac{\partial(xy)}{\partial x} + \frac{\partial(yz)}{\partial y} + \frac{\partial(zx)}{\partial z} \\ &= y + 2z + x \end{aligned}$$

$$= y + 2z + x \quad \text{Ans} = 4$$

Ques.

$$\phi = 2x^3y \frac{z}{z^2} \text{ find } \operatorname{div}(\operatorname{grad} \phi)$$

Sol:

$$\operatorname{grad} \phi = (6x^2yz^2)\hat{i} + (4z^2x^3)\hat{j} + (4x^3yz^2)\hat{k}$$

$$\operatorname{div}(\operatorname{grad} \phi) = 6yz^2 + 4x^3z^2 + 4x^3y^2$$

$$= 12xyz^2 + 4x^3y^2$$

### Curl Of Vector Field

$$\vec{\nabla} = \frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}$$

$$\vec{A} = A_1\hat{i} + A_2\hat{j} + A_3\hat{k}$$

$$\operatorname{curl} \vec{A} = \vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$= \hat{i} \left( \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - \hat{j} \left( \frac{\partial A_3}{\partial x} + \frac{\partial A_1}{\partial z} \right) + \hat{k} \left( \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

Curl measures the tendency to rotate around a point. It shows a vector field's rate of rotation i.e. the direction of axis of rotation & the magnitude of rotation.

Note:  $\text{grad } \phi = \text{vector}$

$\text{div } \vec{A} = \text{scalar}$

$\text{curl } \vec{A} = \text{vector}$

When  $\text{curl } = 0$  then that field is called irrotational field or curl-free, or non-curl or conservative field

Ques.  $\vec{F} = (x+3y)\hat{i} + (y-3z)\hat{j} + (x-2z)\hat{k}$ . Prove  $F$  is solenoidal

$$\text{Sol: } \text{div } \vec{F} = \frac{\partial(x+3y)}{\partial x} + \frac{\partial(y-3z)}{\partial y} + \frac{\partial(x-2z)}{\partial z}$$

$$= 1 + 3 - 0 + 1 + 0 - 2 = 0$$

Thus  $F$  is solenoidal

Ques. Prove  $\vec{F} = (x^2+xy^2)\hat{i} + (y^2+x^2y)\hat{j}$  is irrotational

$$\text{Sol: } \text{curl} = \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2+xy^2 & y^2+x^2y & 0 \end{vmatrix}$$

$$= \hat{i} \left( -\frac{\partial(y^2+x^2y)}{\partial z} \right) - \hat{j} \left( -\frac{\partial(x^2+xy^2)}{\partial z} \right) + \hat{k} \left( \frac{\partial(y^2+x^2y)}{\partial x} - \frac{\partial(x^2+xy^2)}{\partial y} \right)$$

$$\approx 0 + 0 + (2xy - 2xy) = 0$$

Thus  $F$  is irrotational

Ques:

$$\vec{A} = x^2y \hat{i} - 2xz \hat{j} + 2yz \hat{k}$$

Find  $\text{curl } \text{curl } \vec{A}$

Sol:

$$\begin{aligned}\text{curl } \vec{A} &= \hat{i} \left( -2x - \frac{\partial}{\partial z} \right) \hat{j} (0 - 0) + \hat{k} (x^2 - 2z) \\ &= (-2x - \cancel{\frac{\partial}{\partial z}}) \hat{i} + (x^2 - 2z) \hat{k}\end{aligned}$$

$$\begin{aligned}\text{curl} (\text{curl } \vec{A}) &= \hat{i} (0) - \hat{j} (-2) - (2x \cdot 0) + \hat{k} (0) \\ &= (-2x - 4) \hat{j} + (2x + 2) \hat{j}\end{aligned}$$

### Maxwell's Equations

### Gauss Divergence Theorem

The integral of a derivative (divergence) over a region (volume) is equal to the value of the function at the boundaries (surface)

$$\boxed{\int \left( \nabla \cdot \vec{F} \right) dV = \oint_S \vec{F} \cdot d\vec{S}}$$

3D to 2D

It is also known as fundamental theorem for divergence

It is used to convert volume integral into surface integral

$$\begin{aligned}&+ \hat{k} \left( \frac{\partial y^2}{\partial z} + \frac{\partial z^2}{\partial y} \right) \\ &- \hat{x} \left( \frac{\partial z^2}{\partial x} + \frac{\partial x^2}{\partial z} \right) \\ &\frac{\partial x^2}{\partial y} + \frac{\partial y^2}{\partial x}\end{aligned}$$

## Fundamental Theorem for curl

OR

## Stokes Theorem

The integral of a derivative (curl) over a region (a patch of surface) is equal to the value of the function at the boundary (perimeter of the patch)

$$\iint_S (\vec{\nabla} \times \vec{F}) \cdot d\vec{S} = \oint_C \vec{F} \cdot d\vec{l}$$

2D to 2D

## Equation of Continuity

OR

## Conservation of Charge

The total current flowing out of some volume must be equal to the rate of decrease of the charge within that volume, if the charge is neither being created nor lost.

$$I = \frac{dq}{dt} = \frac{d}{dt} \iint_S \rho dV - (i)$$

( $\rho$  = charge density)

$$I = \oint_C \vec{J} \cdot d\vec{l} = \frac{dq}{dt} - (ii)$$

( $J$  = current density)

from (i) & (ii)

$$\oint_s \vec{J} \cdot d\vec{s} = -\frac{d}{dt} \int_V \rho dV = -\frac{dq}{dt} \quad \text{--- (iii)}$$

Note: -ve sign indicates the decrease of charge in volume  $V$

From gauss divergence theorem (apply on (iii))

$$\oint_s \vec{J} \cdot d\vec{s} = \int_V (\nabla \cdot \vec{J}) dV = \text{--- (iv)}$$

from (iii) & (iv)

$$\int_V (\nabla \cdot \vec{J}) dV = -\frac{d}{dt} \int_V \rho dV = -\int_V \frac{d\rho}{dt} dV \quad \text{--- (v)}$$

$$\boxed{\text{div} \cdot \vec{J} = \nabla \cdot \vec{J} = -\frac{d\rho}{dt}} \rightarrow \text{equation of continuity}$$

$$\text{Also } \text{div } \vec{J} + \frac{d\rho}{dt} = 0$$

$$\boxed{\nabla \cdot \vec{J} + \frac{d\rho}{dt} = 0}$$

At steady state

$$\frac{d\rho}{dt} = 0$$

$$\boxed{\nabla \cdot \vec{J} = 0}$$

as charge density remain constant

## Maxwell's Equations

### I Gauss's Law of Electricity

It states that the total electric flux through the closed surface is equal to  $(1/\epsilon_0)$  times the total charge enclosed by the surface.

$$\phi = \oint \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \sum q = \frac{1}{\epsilon_0} Q$$

Suppose that charge  $q$  is distributed over a volume  $V$ . Let  $\rho$  be the volume charge density

$$\text{Total charge } q = \iiint \rho dV$$

Gauss law

$$\phi = \oint \vec{E} \cdot d\vec{s} = \frac{1}{\epsilon_0} \iiint \rho dV$$

Acc. to gauss div theorem

$$\oint \vec{E} \cdot d\vec{s} = \iiint (\nabla \cdot \vec{E}) dV$$

$$\iiint (\nabla \cdot \vec{E}) dV = \frac{1}{\epsilon_0} \iiint \rho dV$$

$$\boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

Also

displacement vector

Differential form of Gauss's Law for electricity

$$\vec{D} = \epsilon_0 \vec{E}$$

$$\nabla \cdot \vec{D} = \rho$$

Significance (i) It is time independent equations  
or steady state equation

(ii) It gives the relationship b/w electric flux & charge density

(iii) It shows charge acts as source or sink for electric lines of force.

## II Maxwell's Second Equation

Total magnetic flux in closed surface is zero

$$\oint \vec{B} \cdot d\vec{s} = 0$$

Acc. to Gauss div

$$\oint \vec{B} \cdot d\vec{s} = \int \nabla \cdot \vec{B} dV = 0$$

$$\nabla \cdot \vec{B} = 0$$

This is analogue of Gauss' law in magnetism

Significance : (i) It shows that magnetic monopole does not exist

(ii) There is no source or sink for the magnetic lines of force

(iii) It is time independent differential equation.

III

### Maxwell's Third Equation OR Faraday's Law of Electromagnetic Induction

(iii)

It states that EMF is induced in a circuit, if there is a change in the magnetic flux linked through the circuit & if the circuit is closed, an induced current begins to flow.

$$\text{EMF} = -\frac{d\phi}{dt}$$

Acc. to Faraday's Law  $\text{EMF} = -\frac{d\phi}{dt}$

$$\phi_{(t)} = \int_S \vec{B} \cdot d\vec{s} \quad \text{--- magnetic flux}$$

$$\text{EMF}_{\text{total}} = \oint_L \vec{E} \cdot d\vec{L}$$

$$\oint_L \vec{E} \cdot d\vec{L} = \int_S \vec{\nabla} \times \vec{E} \cdot d\vec{S} \quad (\text{Stokes theorem})$$

$$\int_S \vec{\nabla} \times \vec{E} \cdot d\vec{S} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{S} = \int_S -\frac{dB}{dt} \cdot d\vec{S}$$

$$\vec{\nabla} \times \vec{E} = -\frac{dB(t)}{dt}$$

diff of Maxwell 3rd eq

Significance: (i) It relates the space variation of electric field with time variation of magnetic field

(ii) It is time dependent differential equation

IV

(iii) It proves that the electric field can be generated by change in magnetic field

#### IV Amperc's Circuital Law

The line integral of magnetic field  $\vec{B}$  around any closed loop is equal to  $\mu_0$  times the net current  $I$  flowing through the area enclosed by the loop

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

where  $\mu_0$  = permeability of free space

$$\vec{H} = \frac{\vec{B}}{\mu_0}$$

From Amperc's Law

$$\oint \vec{H} \cdot d\vec{l} = I$$

and also,

$$\oint \vec{H} \cdot d\vec{l} = \oint (\vec{\nabla} \times \vec{H}) \cdot d\vec{s} \quad (\text{from Stokes theorem})$$

and

$$I = \oint \vec{J} \cdot d\vec{l}, \quad \vec{J} = \int_S \rho d\vec{n}$$

$$\oint (\vec{\nabla} \times \vec{H}) \cdot d\vec{s} = \oint \vec{J} \cdot d\vec{l}$$

$$\boxed{\vec{\nabla} \times \vec{H} = \vec{J}}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\vec{\nabla} \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = \vec{\nabla} \cdot \vec{J} \quad [\vec{\nabla} \cdot \vec{J} = 0 \text{ div of } \vec{J} \text{ is always zero}]$$

$$\vec{\nabla} \cdot \vec{J} = 0$$

But from eq of continuity  $\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$

so Maxwell realised that the definition of total current density is incomplete & suggested to add another term

$$\vec{\nabla} \times \vec{H} = \vec{J} + \vec{J}^d$$

taking div both sides

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = \vec{\nabla} \cdot (\vec{J} + \vec{J}^d)$$

$$\text{As } \vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = 0$$

$$\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot \vec{J}^d = 0$$

$$\vec{\nabla} \cdot \vec{J}^d = -\vec{\nabla} \cdot \vec{J} = \frac{\partial \rho}{\partial t}$$

$$\vec{\nabla} \cdot \vec{J}^d = \frac{\partial \rho}{\partial t}$$

Acc to gauss Law of electrostat

$$\vec{\nabla} \cdot \vec{D} = \rho$$

$$\vec{\nabla} \cdot \vec{J}^d = \frac{\partial}{\partial t} \vec{\nabla} \cdot \vec{D} = \vec{\nabla} \cdot \frac{\partial \vec{D}}{\partial t}$$

$$\Rightarrow \vec{J} = \frac{\partial \vec{D}}{\partial t} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

modified form of Ampere's Circuital law

$$\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{B}}{\partial t} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

- Significance:
- (i) time dependent
  - (ii) relates the space variation of magnetic field with time variation of electric field
  - (iii) proves that magnetic field can be generated by changing electric field.

integral form:  $\int \vec{H} \cdot d\vec{l} = \int \left[ \vec{J} + \frac{\partial \vec{D}}{\partial t} \right] \cdot d\vec{s}$

Propagation of Electromagnetic Wave in free space

Here  $\rho = 0$  &  $J = 0$

$$\vec{\nabla} \cdot \vec{E} = 0 \quad (i)$$

$$\vec{\nabla} \cdot \vec{H} = 0 \quad (ii)$$

$$\vec{\nabla} \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t} = -\frac{\partial \vec{B}}{\partial t} \quad (iii)$$

$$\vec{B} = \mu_0 \vec{H}$$

$$\vec{\nabla} \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \frac{\partial \vec{B}}{\partial t} \quad (iv)$$

taking curl of eq 3 on both sides

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = -\mu_0 \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{H})$$

$$[\text{LHS} = \vec{A} \times (\vec{B} \times \vec{C}) = A(\vec{B} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})]$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{E}) - \vec{E}(\vec{\nabla} \cdot \vec{\nabla})$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = -\vec{\nabla} \cdot \vec{E}$$

$$\vec{\nabla} \cdot \vec{E} = -\mu_0 \frac{\partial}{\partial t} (\vec{\nabla} \times \vec{H})$$

from eq (4)

$$\vec{\nabla} \cdot \vec{E} = -\mu_0 \epsilon_0 \frac{\partial}{\partial t} \left( \frac{\partial F}{\partial t} \right)$$

$$\vec{\nabla} \cdot \vec{E} = -\mu_0 \epsilon_0 \left( \frac{\partial^2 \vec{E}}{\partial t^2} \right)$$

$$\vec{\nabla} \cdot \vec{E} + \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$\vec{\nabla} \cdot \vec{E} + \frac{1}{V^2} \frac{\partial^2 F}{\partial t^2} = 0 \quad \left[ V = \frac{1}{\sqrt{\mu_0 \epsilon_0}}, \frac{1}{V^2} = \mu_0 \epsilon_0 \right]$$

$$(V = 4\pi \times 10^{-7} \quad \epsilon_0 = 8.85 \times 10^{-12})$$

$$\Rightarrow \vec{\nabla} \cdot \vec{E} + \mu_0 \epsilon_0 \frac{\partial^2 \vec{H}}{\partial t^2} = 0$$

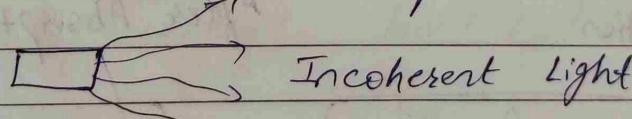
# LASERS

LASER stands for Light Amplification by Stimulated Emission of Radiation

Laser is a very intense, concentrated, highly parallel and monochromatic beam of light

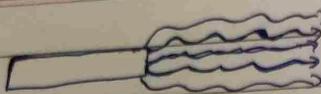
Coherence is very important property of laser

Incoherent Light: Incoherent light is due to spontaneous and random emission of photons which are not in phase with each other.



Cohherent Light: Coherent light is uniform in frequency, amplitude, certainty and constant initial phase difference

It is obtained due to stimulated emission of photons from the atoms jumping from meta stable state to lower energy state



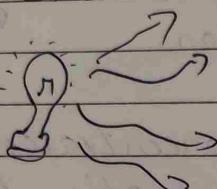
Coherent light

Incoherent

Many Wavelengths

Multidirectional

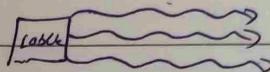
Incoherent

Laser Light

Monochromatic

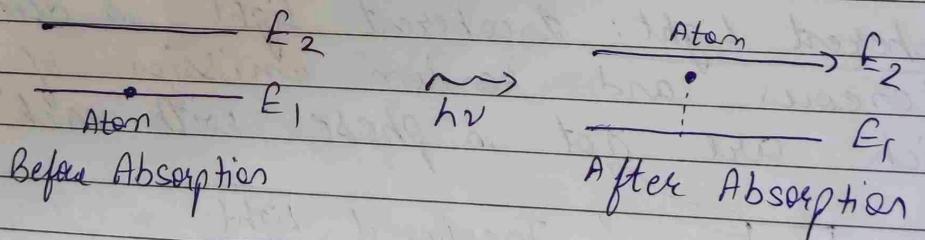
Directional

Coherent



## Various Atomic Interactions Related to LASER

### a) Induced Absorption / Absorption of Radiation



$$V = \frac{E_2 - E_1}{h}$$

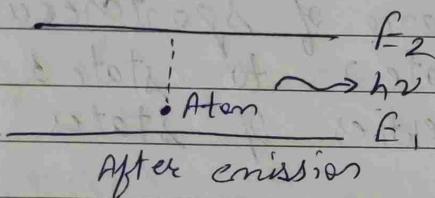
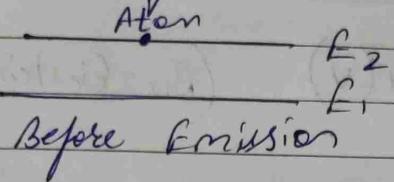
(h = Planck's constant)  
(h =  $6.626 \times 10^{-34} \text{ Js}$ )

### b) Spontaneous Emission

An excited atom can stay in the higher energy state only for the time of  $10^{-8} \text{ sec}$ . After this time, it returns back to lower energy state by emitting a photon of energy  $h\nu = E_2 - E_1$ .

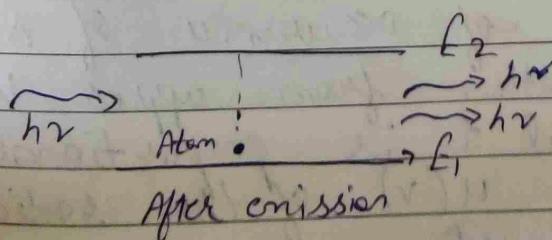
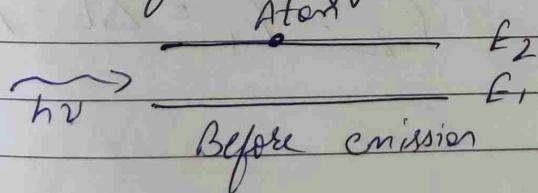


During spontaneous emission photons are randomly emitted and hence they will not be in phase with each other. Therefore light is incoherent.



### c) Stimulated Emission / Induced Emission

When photon of suitable size (energy) is showered on an excited atom in the higher energy state, the atom falls back to the ground state by emitting a photon of energy  $h\nu = E_2 - E_1$ .



It results in appearance of one additional photon. Light is coherent as photons emitted are in phase.

### Absorption of Radiation

The prob. of occurrence of this absorption from state 1 to state 2 is  $\propto$  to the energy density  $u(v)$  of the radiation

$$P_{12} = B_{12} u(v) \quad (B_{12} = \text{Einstein Coefficient})$$

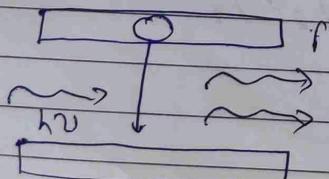
### Spontaneous Emission

The prob. of occurrence of spontaneous emission transition from state 2 to state 1 depends only on the properties of states 2 & 1 is given by

$$P'_{21} = A_{21}$$

$A_{21}$  = Proportionality Constant  
 $B$  = Einstein coefficient of spontaneous emission of radiation

### Stimulated Emission



$$E_2 - E_1 = \Delta E = h\nu$$

The probability of occurrence of stimulated emission transition from upper level 2 to lower level 1 is proportional to the energy density  $u(v)$  of the radiation & is expressed as

$$P''_{21} = B_{21} u(v)$$

where  $B_{21}$  = Einstein coefficient of stimulated emission of radiation

## Relation b/w Einstein's Coefficients

Let  $N_1$  &  $N_2$  = no. of atoms at any instant in state 1 & 2. The probability of absorption for no. of atoms from state 1 to 2 per unit time is

$$N_1 P_{12} = N_1 B_{12} u(v)$$

Total prob. of transition for no. of atoms from state 2 to 1, either by spontaneous or by stimulated emission per unit time is

$$= N_2 (P'_{21} + P''_{21}) J = N_2 A_{21} + N_2 B_{21} u(v)$$

$$= N_2 P_{21} = N_2 [A_{21} + B_{21} u(v)]$$

In thermal equilibrium at temp T, the absorption probabilities are equal

$$(N_1 P_{12} = N_2 P_{21})$$

$$N_1 B_{12} u(v) = N_2 A_{21} + N_2 B_{21} u(v)$$

$$N_1 B_{12} u(v) - N_2 B_{21} u(v) = N_2 A_{21}$$

$$u(v) = \frac{N_2 A_{21}}{N_1 B_{12} - N_2 B_{21}}$$

$$u(v) = \frac{A_{21}}{B_{21} \left( \frac{N_1}{N_2} \frac{B_{12}}{B_{21}} - 1 \right)}$$

But acc. to Einstein

$$B_{12} = B_2$$

$$u(v) = \frac{A_{21}}{B_{21}} \frac{1}{\left(\frac{N_1}{N_2} - 1\right)}$$

Acc. to Boltzmann law, the distribution of atoms among the energy states  $E_1$  &  $E_2$  at the thermal equilibrium at temp  $T$  is

$$\frac{N_1}{N_2} = \frac{e^{-E_1/KT}}{e^{-E_2/KT}} = e^{\frac{(E_2-E_1)/KT}{(h\nu)/KT}}$$

(where  $K$  = Boltzmann constant)

$$u(v) = \frac{A_{21}}{B_{21}} \frac{1}{\left(e^{\frac{hv}{KT}} - 1\right)}$$

Planck's radiation formula yields energy density of radiation

$$u(v) = \frac{8\pi hv^3}{c^3} \frac{1}{\left(e^{\frac{hv}{KT}} - 1\right)}$$

Relation b/w Einstein coefficients A & B

$$\frac{A_{21}}{B_{21}} = \frac{8\pi hv^3}{c^3}$$

$$\frac{B_{21}}{A_{21}} = \left( \frac{c^3}{8\pi h} \right) \frac{1}{v^3}$$

That is  $B_{21}/A_{21}$  is inversely  $\propto$  to freq of the resonant radiation. Therefore the higher the freq smaller the value of  $B_{21}$ . That is, it is comparatively difficult to obtain the stimulated emission at higher frequencies.

Ques: Calculate the relative population of  $N_2$  atoms in sodium lamp in first & ground state at temp  $350^\circ C$ .  $\lambda = 590 nm$

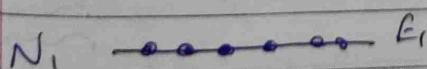
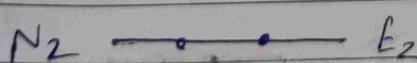
$$\text{Sol: } \frac{N_1}{N_2} = e^{\frac{(hv)KT}{\lambda KT}} = e^{\frac{hc}{\lambda K}} = e^{\frac{6.626 \times 10^{-34} \times 341.8}{1.38 \times 10^{-23} \times 590 \times 10^{-9} \times 623}}$$

### Population Inversion & Pumping

Acc. to Boltzmann the ratio of atoms in energy states 2 & 1 at temp  $T$  is given by

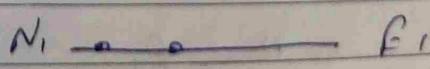
$$\frac{N_2}{N_1} = e^{\frac{-E_2/KT}{-E_1/KT}} = e^{\frac{-(E_2 - E_1)/KT}{}}$$

for population inversion:  $(N_2 \gg N_1)$  i.e.



Normal State  
Thermal equilibrium condition

$$N_1 \gg N_2$$

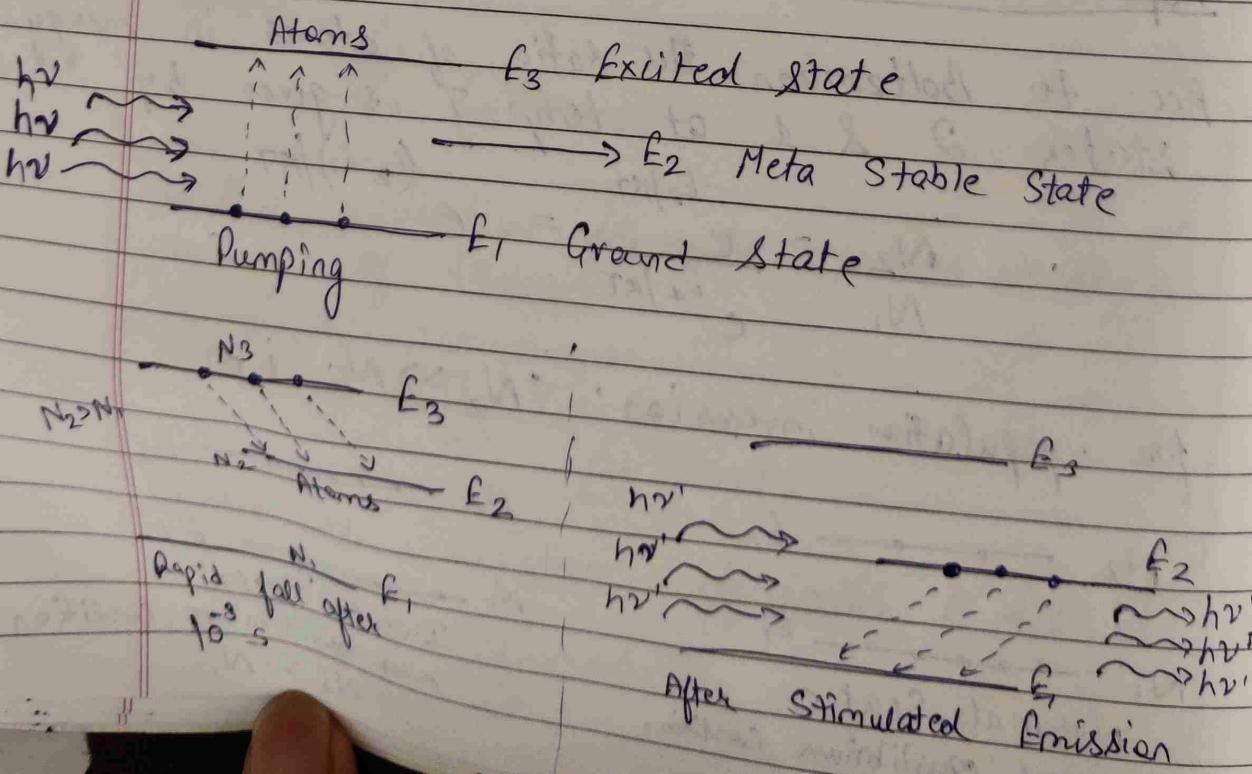
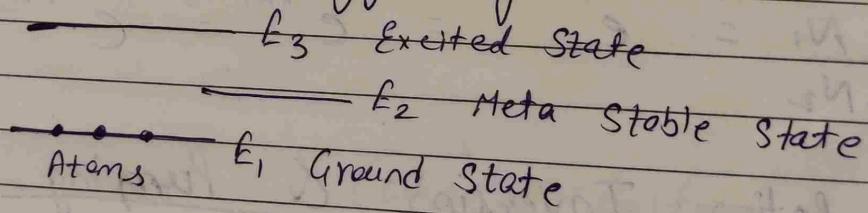


Inverted State  
Non equilibrium condition  
 $N_2 \gg N_1$

The process of making population of atoms in the higher energy state more than that in the lower energy state is known as 'population inversion'.

The method by which a population inversion is achieved is called 'pumping'. In this process atoms are raised to an excited state by injecting into system photon of frequency different from the stimulating frequency.

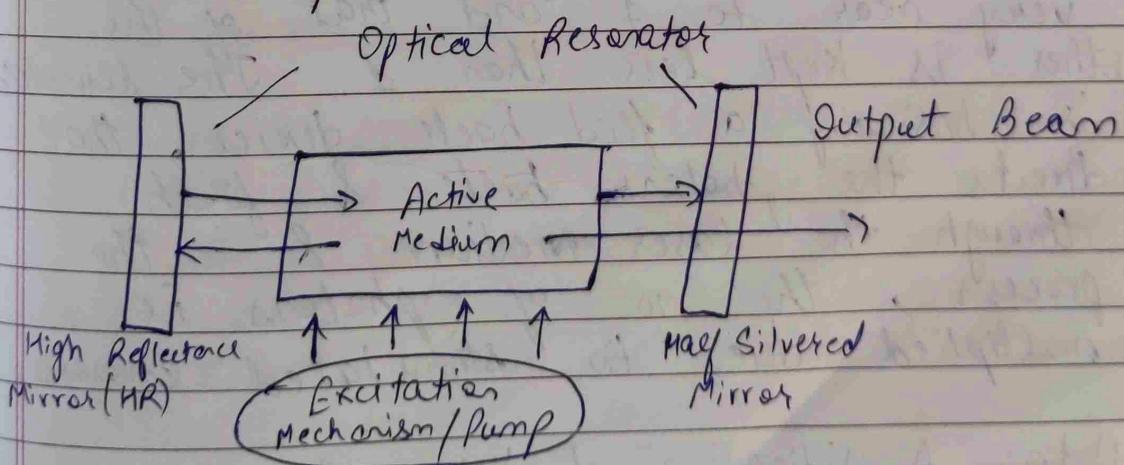
Population inversion can be explained by three level energy diagram.



## Types of Pumping.

- 1) Electrical Pumping: Atoms can be excited by e impact in sufficiently intense gaseous discharge. It is suited to gas & semiconductor lasers.
- 2) Optical Pumping: Atoms are excited by powerful lamp or a light source whose light populates excited states by photon absorption. Suitable to solid state or liquid lasers.
- 3) Chemical Pumping: Here inversion is achieved from an exothermic chemical reaction. It usually applies to material in gas phase & it generally requires highly reactive & often explosive gas mixtures.

## Laser Components



- 1) Pump: (i) It is an external source which supplies energy to obtain population inversion. The pump can be optical, electrical or thermal. In Ruby Laser we use optical pumping & in He-Ne laser electric discharge pumping.

(ii) The lifetime of metastable energy state is to must be very large as compared to normal lifetime of the excited atom in any other energy state.

2) The Laser Medium: It is the material in which laser action is made to take place. It may be solid, liquid or gas. The very imp characteristic requirement for the medium is that inversion should be possible in it.

Note: Ruby Laser output is at 694.3 nm  
He-Ne Laser = 632.8 nm

3) The Resonator: It consists of a pair of plane or spherical mirrors having common principal axis. The reflection coefficient of one of the mirrors is very near to 1 and that of the other is kept less than 1. The resonator is basically a feed-back device, that directs the photons back & forth through the laser medium & in the process, the no. of photons is multiplied due to stimulated emission.

Note: Amplification of light: In pumping the atoms are made to fall from meta stable state to lower energy & photons are emitted by stimulated emission. The photons reflected to back & forth in the active medium to excite the other atoms.

Thus a large no. of photons are emitted simultaneously which possess the same energy, phase & direction. This process is called amplification of light.

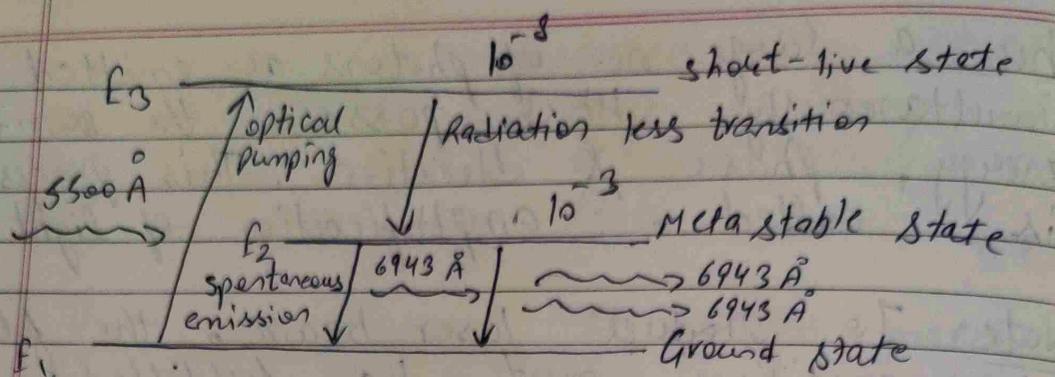
Note: To produce laser beam, the following two conditions must be fulfilled.

- 1) The meta-stable state should all the time have larger no. of atoms than the no. of atoms in lower energy state.
- 2) The photons emitted due to stimulated emission should stimulate other atoms to multiply the photons in the active medium.

Note: Four-level system lasers are best.

### Ruby Laser

The first laser was created in 1961 by T. Maiman. It is solid state laser. He used a rod of ruby as active (lasing) medium. It is a three level laser. It has chromium ions. Ruby rod is taken in form of cylindrical rod of about 4cm in length & 1cm in diameter. The end faces of ruby rod are silvered so that they form the optical resonator. Chromium atoms play the active role for laser action. Ruby laser uses optical pumping. The wavelength of laser is  $6943\text{ \AA}$ .



Features: Its output lies in visible spectrum.

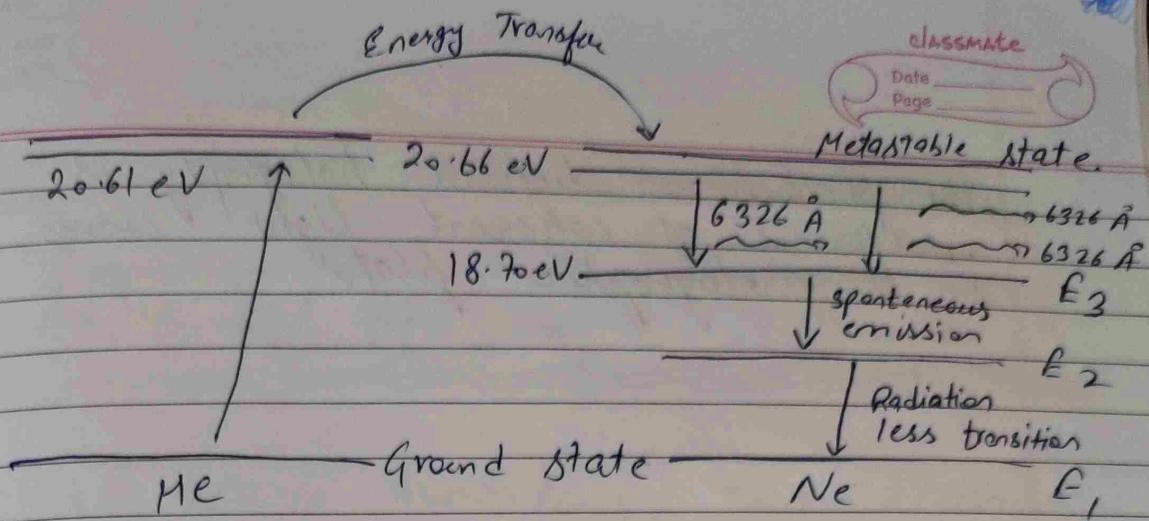
Light from Xeon flash lamp is pumping agent, Poor efficiency and it operates in pulsed mode.

#### Drawbacks

- 1) Pulsed or spiky output
- 2) Large fraction of pumped energy is lost as heat
- 3) Requires bulky cooling system

#### He-Ne Laser

- It was built in 1961 by Ali Javan
- A He-Ne laser is a type of small gas laser
- It's a four-level system
- The most common method of exciting gas medium is by passing an electric discharge through the gases
- Laser medium is mixture of Helium & Neon gases in ratio 10:1
- Ne atom play active role here and the purpose of He atoms is to provide energy to Ne atoms through collision & w



features : It lies in visible spectrum

- Low efficiency & low power output
- Operates in continuous mode

### Applications of Lasers

- In Communications
- Industrial Applications
- Medical Application
- Military Application
- In Computers
- In thermonuclear fission
- Entertainment
- Holography - The method of producing 3-dimensional image of an object. In holography both the phase and amplitude of the light waves are recorded in the film whereas in photography only amplitude is recorded.

The recorded hologram has no resemblance to the original object. It has it in a coded form of information of the object. The image is reproduced by a process called reconstruction.

The phenomenon behind holography is interference of coherent light waves on a photographic plate