# **TARUN LAHROD**

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### **EXPERIENCE**

#### **BVPIEEE**

math Dec 2017 - Present

- HKN Infra executive (Post)
- Computer Society- Chapter representative (Post)
- Conducted a certified Android Development workshop series for 20+ students.

### **FERVOUR X - 10th Edition**

## 8th Mar 2018

New Delhi, India

- Fervour X Annual Techno-Managerial fest of BVPIEEE.
- Volunteered for managing the event Line Following Challenge.

#### **WIEHACK - BVPIEEE**

## 2nd - 3rd Oct 2018

New Delhi.India

• In organizing team of WIEHACK - An All Women Hackathon

#### **INNOVICON**

# 2nd Feb 2019 - 3rd Feb 2019♥ New Delhi, India

- An Artificial Intelligence theme based conference organized by BVPIEEE, IEEE student branch of BVCOE, New Delhi, India.
- In organizing team of INNOVICON.

### **CERTIFICATIONS**

- Completed Robotics and Arduino development series by Robotics and Automation Society (RAS) BVPIEEE.
- Completed Android development series under BVPIEEE.
- Participated in IEEEXtreme 2018 24 Hour Programming competition.

### **ACHIEVEMENTS**

- Qualified upto Qualifier level in Texas Instrumentation IICDC 2018
- 1st prize winner at Rajasthan Hackathon 5.0 Digifest, Bikaner 2018
- Ranked in top 10 in INSPIRE AWARDS 2015 State Level.
- Qualifier in INSPIRE AWARDS 2015 National Level.

### SKILLS

C, C++, Python, Java HTML5, CSS, JS, PHP Machine learning, Deep Learning Tensorflow, Pytorch, RDBMS, Linux



### **EDUCATION**

**Bachelor of Technology** 

Bharati Vidyapeeth's College of Engineering, New Delhi

Aug 2017 - Present

Computer Science And Engineering

**CBSE Board (XII)** 

Kendriya Vidyalaya Paschim Vihar

**⊞** 2017

• 76.2%

CBSE Board (X)

Kendriya Vidyalaya Paschim Vihar

**2015** 

• 8.8 CGPA

### **HONORS & AWARDS**

Digifest Bikaner



Received 1st Prize at Rajasthan Hackathon 5.0, funded 15 lacs for project.

## **PROJECTS**

### **Robotic Snake**

- Developed a Snake-Bot that can prove to be useful for surveillance.
- Has applications in disaster management scenerio.
- Integrated computer vision applications.
- Boards used: Arduino Mega and Raspberry Pi 3

#### Atmega 2560 based path planning bot

- Path planning implementing Dijkstra algorithm
- Autonomous bot with arm to uplift and hold objects of comparable size.
- Made for eYantra 2018 competition.

#### Lift

- Constructed a lift like mechanism.
- Can lift weight upto 4 Kg.
- Arduino development based project.

# **SOFTWARES**

Android Studio, Arduino IDE, Visual Studio, V-REP, Jupyter Notebook, Processing 3, Brackets.

# **HOBBIES**

Anime fan (Otaku) - Stein's Gate and Your lie in April being the favourite, Musical instrument - Guitar (Intermediate), Sports - Badminton and Swimming