

# « Iterated Forward/Backward Relational Infinitary Static Analysis »

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Course 16.399: “Abstract interpretation”

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Recalls on operational and collecting semantics



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Programs states (recall from lecture 5)

States  $\langle \ell, \rho \rangle \in \Sigma[P]$  record a program point  $\ell \in \text{in}_P[P]$  and an environment  $\rho \in \text{Env}[P]$  assigning values to variables:

$$\begin{aligned} \Sigma &\in \text{Prog} \mapsto \rho(\mathbb{V} \times \mathbb{R}), \\ \Sigma[P] &\stackrel{\text{def}}{=} \text{in}_P[P] \times \text{Env}[P]. \end{aligned} \quad (1)$$



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## Program transition relation (recall from lecture 5)

The small-step operational semantics of commands, sequences and programs  $C \in \text{Com} \cup \text{Seq} \cup \text{Prog}$  within a program  $P \in \text{Prog}$  involves transition judgements<sup>1</sup>

$$\langle \ell, \rho \rangle \Vdash [C] \Rightarrow \langle \ell', \rho' \rangle .$$

<sup>1</sup> Such judgements mean that if execution is at control point  $\ell \in \text{in}_P[C]$  in environment  $\rho \in \text{Env}[P]$  then the next computation step within command  $C$  leads to program control point  $\ell' \in \text{in}_P[C]$  in the new environment  $\rho' \in \text{Env}[P]$ .



## Transition system of a program (recall from lecture 5)

The transition system of a program  $P = S ; ;$  is

$$\langle \Sigma[P], \tau[P] \rangle$$

where  $\Sigma[P]$  is the set (1) of program states and  $\tau[C]$ ,  $C \in \text{Cmp}[P]$  is the transition relation for component  $C$  of program  $P$ , defined by

$$\tau[C] \stackrel{\text{def}}{=} \{ \langle \langle \ell, \rho \rangle, \langle \ell', \rho' \rangle \rangle \mid \langle \ell, \rho \rangle \Vdash [C] \Rightarrow \langle \ell', \rho' \rangle \} \quad (2)$$



## Initial States (recall from lecture 5)

Execution starts at the program entry point with all variables uninitialized:

$$\text{Entry}[P] \stackrel{\text{def}}{=} \{ \langle \text{at}_P[P], \lambda X \in \text{Var}[P]. \Omega_i \rangle \} . \quad (3)$$



## Final States (recall from lecture 5)

Execution ends without error when control reaches the program exit point

$$\text{Exit}[P] \stackrel{\text{def}}{=} \{ \text{after}_P[P] \} \times \text{Env}[P] .$$

When the evaluation of an arithmetic or boolean expression fails with a runtime error, the program execution is blocked so that no further transition is possible.



## Big-step operational semantics of a program (recall from lecture 5)

- The big-step operational semantics of a program  $P$  is

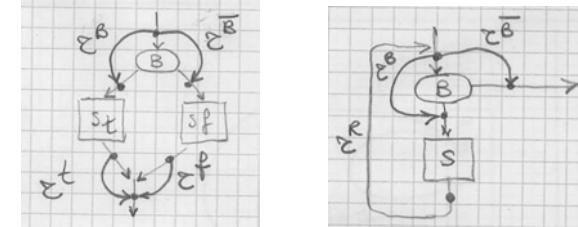
$$\langle \Sigma[P], t^*[P] \rangle$$

where  $t^*[P] \stackrel{\text{def}}{=} (t[P])^*$  is the reflexive transitive closure of the transition relation  $t[P]$

- Infinite executions are not considered with this semantics

where:

$$\begin{aligned}\tau^B &\stackrel{\text{def}}{=} \{ \langle \langle \text{at}_P[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}], \rho \rangle, \langle \text{at}_P[S_t], \rho \rangle \mid \rho \vdash B \Rightarrow \text{tt} \} \\ \tau^{\bar{B}} &\stackrel{\text{def}}{=} \{ \langle \langle \text{at}_P[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}], \rho \rangle, \langle \text{at}_P[S_f], \rho \rangle \mid \rho \vdash T(\neg B) \Rightarrow \text{tt} \} \\ \tau^t &\stackrel{\text{def}}{=} \{ \langle \langle \text{after}_P[S_t], \rho \rangle, \langle \text{after}_P[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}], \rho \rangle \mid \rho \in \text{Env}[P] \} \\ \tau^f &\stackrel{\text{def}}{=} \{ \langle \langle \text{after}_P[S_f], \rho \rangle, \langle \text{after}_P[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}], \rho \rangle \mid \rho \in \text{Env}[P] \}\end{aligned}$$



## Structural big-step operational semantics (recall from lecture 8)

$$\tau^*[skip] = 1_{\Sigma[P]} \cup \tau[skip] \quad (4)$$

$$\tau^*[X := A] = 1_{\Sigma[P]} \cup \tau[X := A]$$

$$\begin{aligned}\tau^*[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}] &= \quad (5) \\ &(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t) \cup \\ &(1_{\Sigma[P]} \cup \tau^{\bar{B}}) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)\end{aligned}$$

$$\begin{aligned}\tau^*[\text{while } B \text{ do } S \text{ od}] &= \quad (6) \\ &((1_{\Sigma[P]} \cup \tau^*[S] \circ \tau^R) \circ (\tau^B \circ \tau^*[S] \circ \tau^R)^*) \circ \\ &(1_{\Sigma[P]} \cup \tau^B \circ \tau^*[S] \cup \tau^{\bar{B}}) \cup \tau[S]^*\end{aligned}$$

where:

$$\begin{aligned}\tau^B &\stackrel{\text{def}}{=} \{ \langle \langle \text{at}_P[\text{while } B \text{ do } S \text{ od}], \rho \rangle, \langle \text{at}_P[S], \rho \rangle \mid \rho \vdash B \Rightarrow \text{tt} \} \\ \tau^{\bar{B}} &\stackrel{\text{def}}{=} \{ \langle \langle \text{at}_P[\text{while } B \text{ do } S \text{ od}], \rho \rangle, \langle \text{after}_P[\text{while } B \text{ do } S \text{ od}], \rho \rangle \mid \rho \vdash T(\neg B) \Rightarrow \text{tt} \} \\ \tau^R &\stackrel{\text{def}}{=} \{ \langle \langle \text{after}_P[S], \rho \rangle, \langle \text{at}_P[\text{while } B \text{ do } S \text{ od}], \rho \rangle \mid \rho \in \text{Env}[P] \}\end{aligned}$$

## Definition of the forward collecting semantics of boolean expressions (recall from lecture 8)

Recall the *collecting semantics*  $\text{Cbexp}[\![B]\!]R$  of a boolean expression  $B$  from course 8:

$$\begin{aligned}\text{Cbexp} &\in \text{Bexp} \mapsto \wp(\text{Env}\llbracket P \rrbracket) \xrightarrow{\sqcup} \wp(\text{Env}\llbracket P \rrbracket), \\ \text{Cbexp}[\![B]\!]R &\stackrel{\text{def}}{=} \{\rho \in R \mid \rho \vdash B \Rightarrow \text{tt}\}.\end{aligned}\quad (7)$$

such that:

$$\begin{aligned}\text{Cbexp}[\![B]\!]\left(\bigcup_{k \in S} R_k\right) &= \bigcup_{k \in S} (\text{Cbexp}[\![B]\!]R_k) \\ \text{Cbexp}[\![B]\!]\emptyset &= \emptyset.\end{aligned}$$



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## Structural specification of the forward collecting semantics of boolean expressions (recall from lecture 8)

$$\begin{aligned}\text{Cbexp}[\![\text{true}]\!]R &\stackrel{\text{def}}{=} R \\ \text{Cbexp}[\![\text{false}]\!]R &\stackrel{\text{def}}{=} \emptyset \\ \text{Cbexp}[\![A_1 \wedge A_2]\!]R &\stackrel{\text{def}}{=} \underline{\sqsubseteq}^C (\text{Faexp}[\![A_1]\!], \text{Faexp}[\![A_2]\!])R \\ \text{where } \underline{\sqsubseteq}^C (F, G)R &\stackrel{\text{def}}{=} \{\rho \in R \mid \exists v_1 \in F(\{\rho\}) \cap \mathbb{I} : \exists v_2 \in G(\{\rho\}) \cap \mathbb{I} : v_1 \sqsubseteq v_2 = \text{tt}\} \\ \text{Cbexp}[\![B_1 \wedge B_2]\!]R &\stackrel{\text{def}}{=} \text{Cbexp}[\![B_1]\!]R \cap \text{Cbexp}[\![B_2]\!]R \\ \text{Cbexp}[\![B_1 \vee B_2]\!]R &\stackrel{\text{def}}{=} \text{Cbexp}[\![B_1]\!]R \cup \text{Cbexp}[\![B_2]\!]R\end{aligned}$$



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## Backward collecting semantics of arithmetic expressions (recall)

The *backward/top-down collecting semantics*  $\text{Baexp}[\![A]\!](R)P$  of an arithmetic expression  $A$  defines the subset of possible environments  $R$  such that the arithmetic expression may evaluate, without producing a runtime error, to a value belonging to given set  $P$ :

$$\begin{aligned}\text{Baexp} &\in \text{Aexp} \mapsto \wp(\mathbb{R}) \xrightarrow{\sqcup} \wp(\mathbb{I}_\Omega) \xrightarrow{\sqcup} \wp(\mathbb{R}), \\ \text{Baexp}[\![A]\!](R)P &\stackrel{\text{def}}{=} \{\rho \in R \mid \exists i \in P \cap \mathbb{I} : \rho \vdash A \Rightarrow i\}.\end{aligned}\quad (8)$$

$\forall P \in \wp(\mathbb{R}) : \lambda R . \text{Baexp}[\![A]\!](R)P$  is a lower closure operator

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## Structural definition of the backward/bottom-up collecting semantics of arithmetic expressions

$$\text{Baexp}[\![n]\!](R)P = (\underline{n} \in P \cap \mathbb{I} ? R : \emptyset) \quad (9)$$

$$(10)$$

$$\text{Baexp}[\![X]\!](R)P = \{\rho \in R \mid \rho(X) \in P \cap \mathbb{I}\} \quad (11)$$

$$(12)$$

$$\text{Baexp}[\![?]\!](R)P = (\underline{P \cap \mathbb{I} = \emptyset} ? \emptyset : R) \quad (11)$$

$$\text{Baexp}[\![uA']\!](R)P = \text{Baexp}[\![A']\!](R)(\underline{u}^C(\text{Faexp}[\![A']\!]R, P)) \quad (12)$$

$$\text{where } \underline{u}^C(Q, P) \stackrel{\text{def}}{=} \{v \in Q \mid \underline{u}v \in P \cap \mathbb{I}\} \quad (9)$$

$$\text{Baexp}[\![A_1 \wedge A_2]\!](R)P = \underline{u}^C(\text{Faexp}[\![A_1]\!]R, \text{Faexp}[\![A_2]\!]R, P) \quad (13)$$

$$\text{let } \langle P_1, P_2 \rangle = \underline{b}^C(\text{Faexp}[\![A_1]\!]R, \text{Faexp}[\![A_2]\!]R, P) \text{ in}$$

$$\text{Baexp}[\![A_1]\!](R)P_1 \cap \text{Baexp}[\![A_2]\!](R)P_2 \quad (13)$$

$$\text{where } \underline{b}^C(P_1, P_2, P) \stackrel{\text{def}}{=} \{(v_1, v_2) \in P_1 \times P_2 \mid v_1 \wedge v_2 \in P \cap \mathbb{I}\}$$



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## Definition of the postcondition semantics of commands (recall from lecture 14)

The postcondition semantics of a command  $C \in \text{Com}$  (within a given program  $P$ ) specifies the strongest post-condition  $\text{FPcom}[C]R$  satisfied by environments resulting from the execution of the command  $C$  starting in any of the environments satisfying the precondition  $R$ , if and when this execution terminates.

$$\begin{aligned} \text{FPcom} &\in \text{Com} \mapsto \wp(\text{Env}[P]) \xrightarrow{\sqcup} \wp(\text{Env}[P]) \\ \text{FPcom}[C]R &\stackrel{\text{def}}{=} \{\rho' \mid \exists \rho \in R : \langle \text{at}_P[C], \rho \rangle, \langle \text{after}_P[C], \rho' \rangle \in \tau^*[C]\} \end{aligned} \quad (14)$$

The postcondition semantics of a command can be understood, up to an interpretation, as a predicate transformer.

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## Backward/precondition collecting semantics

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## Definition of the backward/precondition collecting semantics

- The *backward collecting semantics* of commands  $C$  is
 
$$\begin{aligned} \text{BPcom} &\in \text{Com} \mapsto \wp(\text{Env}[P]) \xrightarrow{\sqcup} \wp(\text{Env}[P]) \\ \text{BPcom}[C]R &\stackrel{\text{def}}{=} \{\rho \mid \exists \rho' \in R : \langle \text{at}_P[C], \rho \rangle, \langle \text{after}_P[C], \rho' \rangle \in \tau^*[C]\} \end{aligned} \quad (15)$$
- $\text{BPcom}[C]R$  is the weakest precondition for execution of  $P$  from entry point of command  $C$  to have the possibility to reach a final state in  $R$  on exit of the command
- The condition is necessary but not sufficient, because of non-determinism. So non-termination or termination in a state not in  $R$  is left opened



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## Structural specification of the backward collecting semantics

$$\begin{aligned} \text{BPcom}[\text{skip}]R &= R \\ \text{BPcom}[X := A]R &= \{\rho \mid \exists i \in \mathbb{I} : \rho \vdash A \Rightarrow i \wedge \rho[X := i] \in R\} \\ \text{BPcom}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]R &= \text{Cbexp}[B](\text{BPcom}[S_t]R) \cup \text{Cbexp}[T(\neg(B))](\text{BPcom}[S_f]R) \\ \text{BPcom}[\text{while } B \text{ do } S \text{ od}]R &= \text{Ifp}_{\emptyset}^{\subseteq} \lambda X . \text{Cbexp}[T(\neg(B))]R \cup \text{Cbexp}[B](\text{BPcom}[S]X) \\ \text{BPcom}[C ; S]R &= (\text{BPcom}[C] \circ \text{BPcom}[S])R \\ \text{BPcom}[S ; ;]R &= \text{BPcom}[S] \end{aligned}$$



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### Note

If we define:

$$\llbracket R \rrbracket_p = \mathcal{G}(\text{Env}[\llbracket P \rrbracket])$$

$$\llbracket c \rrbracket \in \mathcal{G}(\Sigma[\llbracket P \rrbracket] \times \Sigma[\llbracket P \rrbracket]) \rightarrow (\mathcal{P}(R) \rightarrow \mathcal{G}(R))$$

$$\llbracket c \rrbracket x = \lambda R. \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[c] \rrbracket, p \rangle, \langle \llbracket \text{after}_p[c] \rrbracket, p' \rangle \in x \}$$

then

$\text{Bcom}[\llbracket c \rrbracket]R = \llbracket c \rrbracket (\Sigma^*[\llbracket c \rrbracket])$  is an abstract interpretation of the big-step operational semantics  $t^*[\llbracket c \rrbracket]$

□



## Proof of correctness of the structural specification of the backward collecting semantics

PROOF.

We observe that  $\llbracket p \rrbracket[\llbracket c \rrbracket]$  is a complete join morphism:

$$\llbracket p \rrbracket[\llbracket c \rrbracket] \left( \bigcup_{i \in \Delta} x_i \right)$$

$$= \lambda R. \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[c] \rrbracket, p \rangle, \langle \llbracket \text{after}_p[c] \rrbracket, p' \rangle \in \bigcup_{i \in \Delta} x_i \}$$

$$= \lambda R. \bigcup_{i \in \Delta} \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[c] \rrbracket, p \rangle, \langle \llbracket \text{after}_p[c] \rrbracket, p' \rangle \in x_i \}$$

$$= \bigcup_{i \in \Delta} \llbracket p \rrbracket[\llbracket c \rrbracket](x_i)$$

so that this is the lower-adjoint of a Galois connection:

$$\langle \mathcal{G}(\Sigma[\llbracket P \rrbracket] \times \Sigma[\llbracket P \rrbracket]), \subseteq \rangle \xleftarrow{\llbracket \text{def}[\llbracket c \rrbracket] \rrbracket} \langle \mathcal{G}(R) \rightarrow \mathcal{G}(R), \subseteq \rangle$$

for the pointwise extension  $\subseteq$  of  $\subseteq$ .



We proceed by structural induction on the structure of programs.

$\text{Bcom}[\llbracket \text{skip} \rrbracket]R$

$$\triangleq \llbracket p \rrbracket[\llbracket \text{skip} \rrbracket] (t^*[\llbracket \text{skip} \rrbracket])R$$

$$= \llbracket p \rrbracket[\llbracket \text{skip} \rrbracket] (\perp \Sigma[\llbracket P \rrbracket] \cup \Sigma[\llbracket \text{skip} \rrbracket])R$$

$$= \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[\llbracket \text{skip} \rrbracket], p \rangle, \langle \llbracket \text{after}_p[\llbracket \text{skip} \rrbracket], p' \rangle \in \perp \Sigma[\llbracket P \rrbracket] \cup \Sigma[\llbracket \text{skip} \rrbracket] \}$$

$$= \{ p \mid \exists p' \in R : p' = p \} \quad \text{since } \llbracket \text{def}_p[\llbracket \text{skip} \rrbracket] \neq \llbracket \text{after}_p[\llbracket \text{skip} \rrbracket] \text{ and def- } \Sigma[\llbracket \text{skip} \rrbracket]S$$

$$= R$$



$\text{Bcom}[\llbracket X := A \rrbracket]R$

$$\triangleq \llbracket p \rrbracket[\llbracket X := A \rrbracket] (t^*[\llbracket X := A \rrbracket])R$$

$$= \llbracket p \rrbracket[\llbracket X := A \rrbracket] (\perp \Sigma[\llbracket P \rrbracket] \cup \Sigma[\llbracket X := A \rrbracket])R$$

$$= \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[\llbracket X := A \rrbracket], p \rangle, \langle \llbracket \text{after}_p[\llbracket X := A \rrbracket], p' \rangle \in \perp \Sigma[\llbracket P \rrbracket] \cup \Sigma[\llbracket X := A \rrbracket] \}$$

$$= \{ p \mid \exists p' \in R : \langle \llbracket \text{def}_p[\llbracket X := A \rrbracket], p \rangle, \langle \llbracket \text{after}_p[\llbracket X := A \rrbracket], p' \rangle \in \langle \llbracket \text{def}_p[\llbracket X := A \rrbracket]p \rangle, \langle \llbracket \text{after}_p[\llbracket X := A \rrbracket]p[X \leftarrow i] \rangle \mid i \in \mathbb{I} \wedge p \vdash A \Rightarrow i \}$$

$$\quad \text{since } \llbracket \text{def}_p[\llbracket c \rrbracket] \neq \llbracket \text{after}_p[\llbracket c \rrbracket] \text{ and def- } \Sigma[\llbracket X := A \rrbracket]S$$

$$= \{ p \mid \exists p' \in R : \exists i \in \mathbb{I} : p' = p[X \leftarrow i] \wedge p \vdash A \Rightarrow i \}$$

$$= \{ p \mid \exists i \in \mathbb{I} : p \vdash A \Rightarrow i \wedge p[X \leftarrow i] \in R \}$$



■  $\text{B}\alpha\text{om}[\mathbf{C}]R$  where  $C = \text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}$

$$\triangleq \alpha_p[\mathbf{C}] (t^*[\mathbf{C}]) R$$

$$= \alpha_p[\mathbf{C}] ((1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_t] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^t)) \cup ((1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_f] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^f)) R$$

$$= \alpha_p[\mathbf{C}] ((1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_t] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^t)) R$$

$$\cup \alpha_p[\mathbf{C}] ((1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_f] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^f)) R$$

We handle the case of the true alternative, the false alternative being handled in the same way.



= ? We observe that  $\underline{\alpha}_p[\mathbf{C}] = p'$  is impossible since  $e' \in \text{inf}_p[\mathbf{S}_t]$  would imply  $\underline{\alpha}_p[\mathbf{C}] \in \text{inf}_p[\mathbf{S}_t]$  in contradiction with (3g)

i.e.  $\{\underline{\alpha}_p[\mathbf{C}], \text{after}_p[\mathbf{C}]\} \cap (\text{inf}_p[\mathbf{S}_t] \cup \text{inf}_p[\mathbf{S}_f]) = \emptyset$ ;

We observe that  $\underline{\text{after}}_p[\mathbf{C}] = C''$  is impossible for similar reasons. S

$$\{p \mid \exists p'' \in R : \exists p', p'' \in R : \exists e', e'' \in \text{inf}_p[\mathbf{C}] =$$

$$\langle \underline{\alpha}_p[\mathbf{C}], p \rangle, \langle e', p' \rangle \in \Sigma^B$$

$$\wedge \langle \langle e', p' \rangle, \langle e'', p'' \rangle \rangle \in \Sigma^*[\mathbf{S}_t]$$

$$\wedge \langle \langle e'', p'' \rangle, \langle \text{after}_p[\mathbf{C}], p''' \rangle \in \Sigma^t \}$$

= ? By def. of  $\Sigma^B$ ,  $p' = p$  and  $e' = \underline{\alpha}_p[\mathbf{S}_t]$ . By def. of  $\Sigma^t$ ,  $p'' = p''$  and  $e'' = \underline{\text{after}}_p[\mathbf{S}_t]$  S



$$\alpha_p[\mathbf{C}] ((1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_t] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^t)) R$$

$$= \{p \mid \exists p' \in R : \langle \underline{\alpha}_{\underline{p}}[\mathbf{C}], p \rangle, \langle \text{after}_{\underline{p}}[\mathbf{C}], p' \rangle \in (1_{\Sigma[\mathbf{P}]} \cup \Sigma^B) \circ t^*[\mathbf{S}_t] \circ (1_{\Sigma[\mathbf{P}]} \cup \Sigma^t)\} \quad ? \text{ by def. } \alpha[\mathbf{C}] S$$

$$= \{p \mid \exists p'' \in R : \exists p', p'' \in R : \exists e', e'' \in \text{inf}_p[\mathbf{C}] =$$

$$\langle \underline{\alpha}_p[\mathbf{C}], p \rangle, \langle e', p' \rangle \in (1_{\Sigma[\mathbf{P}]} \cup \Sigma^B)$$

$$\wedge \langle \langle e', p' \rangle, \langle e'', p'' \rangle \in \Sigma^*[\mathbf{S}_t]$$

$$\wedge \langle \langle e'', p'' \rangle, \langle \text{after}_p[\mathbf{C}], p''' \rangle \in (1_{\Sigma[\mathbf{P}]} \cup \Sigma^t)\}$$

? by def. of the composition  $\circ$  of relations S



$\models 2$  by def.  $\mathcal{C}^B$  and  $\mathcal{C}^S$

$$\begin{aligned} & \{ p \mid \exists p' \in R : p \vdash B \Rightarrow t \vdash \ll \text{at}_p[\text{st}], p \gg, \ll \text{after}_p[\text{se}], p' \gg \in \mathcal{C}^*[\text{se}] \} \\ & = \{ p \in \{ p \mid \exists p' \in R : \ll \text{at}_p[\text{st}], p \gg, \ll \text{after}_p[\text{se}], p' \gg \in \mathcal{C}^*[\text{se}] \} \\ & \quad \mid p \vdash B \Rightarrow t \vdash \} \\ & = \{ p \in \alpha_p[\text{st}] \mid (\mathcal{C}^*[\text{st}]) \wedge p \vdash B \Rightarrow t \vdash \} \\ & = \models 2 \text{ by def. } \mathcal{C}^{\text{exp}}[\text{S}] R S \\ & \mathcal{C}^{\text{exp}}[\text{B}] (\alpha_p[\text{st}] (\mathcal{C}^*[\text{st}]) R) \\ & = 2 \text{ by induction hypothesis} \\ & \mathcal{C}^{\text{exp}}[\text{B}] (\mathcal{B}_{\text{com}}[\text{st}] R) \end{aligned}$$

The false alternative is similar with  $S^F$  for  $st$  and  $T(\neg B)$  for  $B$ .



$\mathcal{B}_{\text{com}}[c] R$  where  $c = \text{while } B \text{ do } S \text{ od}$

$$\begin{aligned} & = \alpha_p[c] (t^*[c]) R \\ & = \alpha_p[c] (((1_{\mathcal{E}[p]} \cup t^*[S] \circ \mathcal{C}^R) \circ (\mathcal{C}^B \circ \mathcal{C}^*[\text{S}] \circ \mathcal{C}^R)^*) \\ & \quad \cup (\sum_{p'} \cup \mathcal{C}^B \circ t^*[S] \cup \mathcal{C}^{\bar{B}})) \cup \mathcal{C}^*[\text{S}] R \\ & = \{ p \mid \exists p'' \in R : \ll \text{at}_p[c], p \gg, \ll \text{after}_p[c], p' \gg \in \mathcal{C}^*[\text{S}] \} \\ & \quad \cup \{ p \mid \exists p'' \in R : \exists p', p'' \in R : \exists e', e'' \in \text{in}_p[c] = \\ & \quad \ll \text{at}_p[c], p \gg, \ll e', p' \gg \in (\sum_{p'} \cup t^*[S] \circ \mathcal{C}^R) \wedge \\ & \quad \ll e', p' \gg, \ll e'', p'' \gg \in (\mathcal{C}^B \circ \mathcal{C}^*[\text{S}] \circ \mathcal{C}^R)^* \wedge \\ & \quad \ll p', p'' \gg, \ll \text{after}_p[c], p'' \gg \in (\sum_{p'} \cup \mathcal{C}^B \circ t^*[S] \cup \mathcal{C}^{\bar{B}}) \} \end{aligned}$$



$\models 2$ . The first term is  $\emptyset$  since  $\{\text{at}_p[c], \text{after}_p[c]\} \cap \text{in}_p[S] = \emptyset$  by (56) and  $\langle \langle e_1, p_1 \rangle, \langle e_2, p_2 \rangle \rangle \in \mathcal{C}^*[\text{S}]$  implies  $e_1, e_2 \in \text{in}_p[\text{S}]$ .

For the second term,  $e' = \text{at}_p[c]$  since otherwise  $\exists e_1, p_1 :$   
 $\langle \langle \text{at}_p[c], p \rangle, \langle e_1, p_1 \rangle \rangle \in t^*[S] \circ \mathcal{C}^R$  which would  
imply  $\text{at}_p[c] \in \text{in}_p[S]$  in contradiction with (56).  
For the second term,  $\langle \langle e'', p'' \rangle, \langle \text{at}_{p''}[c], p'' \rangle \rangle \in \mathcal{I}_{\mathcal{E}[p]}$  is impossible since then  $\langle \langle e', p' \rangle, \langle \text{after}_p[c], p' \rangle \rangle \in (\mathcal{C}^B \circ \mathcal{C}^*[\text{S}] \circ \mathcal{C}^R)^n$ , with  $n \geq 0$  which it self is impossible since either  $n=0$  and  $e' = \text{after}_p[c]$  so  $e' = \text{at}_p[c] = \text{after}_p[c]$  in contradiction with (56) or  $n > 0$  and  $\exists e_1, p_1 : \langle \langle e_1, p_1 \rangle, \langle \text{after}_p[c], p_1 \rangle \rangle \in \mathcal{C}^R$  in contradiction with the definition of  $\mathcal{C}^R$  and (56).



$$\begin{aligned} & \{ p \mid \exists p'' \in R : \ll \text{at}_p[c], p \gg, \ll e', p'' \gg \in (\mathcal{C}^B \circ \mathcal{C}^*[\text{S}] \circ \mathcal{C}^R)^* \\ & \quad \wedge \ll e'', p'' \gg, \ll \text{at}_{p''}[c], p'' \gg \in \mathcal{C}^{\bar{B}} \} \end{aligned}$$

$\models 2$  by def.  $\mathcal{C}^{\bar{B}}$  so that  $e'' = \text{at}_p[c]$  and  $p'' = p'''$

$$\begin{aligned} & \{ p \mid \exists p' \in R : \ll \text{at}_p[c], p \gg, \ll \text{at}_p[c], p' \gg \in (\mathcal{C}^B \circ \mathcal{C}^*[\text{S}] \circ \mathcal{C}^R)^* \\ & \quad \wedge p' \vdash T(\neg B) \Rightarrow t \vdash \} \end{aligned}$$



$$\begin{aligned}
 &= \{ p \mid \exists p' \in \{ p' \in R \mid p' \vdash T(\gamma B) \Rightarrow t \} : \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \\
 &\quad \langle \underline{\text{ab}}_p[\mathbb{C}], p' \rangle \in (\gamma^B \circ \gamma^S \circ \gamma^R)^* \} \\
 &= \text{def. } \mathcal{C}\text{bexp } S \\
 &\{ p \mid \exists p' \in \mathcal{C}\text{bexp } [T(\gamma B)]R : \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p' \rangle \in \\
 &\quad (\gamma^B \circ \gamma^S \circ \gamma^R)^* \} \\
 &= \alpha'((\gamma^B \circ \gamma^S \circ \gamma^R)^*)
 \end{aligned}$$

by defining ( $\beta$  for a given while command  $C$  and a given  $R \in \mathcal{R}$ ):

$$R = \mathcal{C}\text{bexp } [T(\gamma B)]R$$

$$\alpha'(t) \triangleq \{ p \mid \exists p' \in R : \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p' \rangle \in t \}$$

We have

$$\alpha'(\bigcup_{i \in \mathbb{N}} t_i) = \bigcup_{i \in \mathbb{N}} \alpha'(t_i)$$


$$\begin{aligned}
 &\bullet \alpha'(1) \\
 &= \{ p' \mid \exists p \in R : \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p' \rangle \in 1 \in \mathbb{Z} \} \\
 &= \{ p' \mid \exists p \in R : p' = p \} \\
 &= R \\
 &\alpha'(t \circ X) \\
 &= \{ p \mid \exists p' \in R : \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p' \rangle \in \gamma^B \circ \gamma^S \circ \gamma^R \circ X \} \\
 &= \text{def. composition } \circ S
 \end{aligned}$$


whence a Galois connection

$$\langle \mathfrak{P}(\Sigma[\mathbb{P}] \times \Sigma[\mathbb{P}]), \leq \rangle \xrightarrow[\alpha']{\cong} \langle \mathfrak{P}(R), \leq \rangle$$

such that

$$\begin{aligned}
 &\alpha'(t^*) \quad \text{where } t = (\gamma^B \circ \gamma^S \circ \gamma^R) \\
 &= \alpha'(\text{eff } \Delta X \cdot 1 \cup t \circ X) \\
 &= \text{eff } F'
 \end{aligned}$$

where  $\alpha'(1 \cup t \circ X) = F'(\alpha'(X))$ .

i.e.  $\alpha'(1) \cup \alpha'(t \circ X) = F'(\alpha'(X))$

since  $\alpha'$  is a complete join morphism.



$$\begin{aligned}
 &\{ p \mid \exists p''' \in R : \exists p', p'', p''' \in R = \exists e', e'', e''' \in \underline{\text{ab}}_p[\mathbb{C}] = \\
 &\quad \langle \underline{\text{ab}}_p[\mathbb{C}], p \rangle, \langle e', p' \rangle \in \gamma^B \\
 &\quad \wedge \langle e', p' \rangle, \langle e'', p'' \rangle \in \gamma^S \\
 &\quad \wedge \langle e'', p'' \rangle, \langle e'''', p''' \rangle \in \gamma^R \\
 &\quad \wedge \langle e''', p''' \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p''' \rangle \in X \} \\
 &= \text{def. of } \gamma^B, \text{ we have } e' = \underline{\text{ab}}_p[\mathbb{S}], p' = p \text{ and by} \\
 &\text{definition of } \gamma^e, \text{ we have } e'' = \underline{\text{after}}_p[\mathbb{S}], p'' = p''' \text{ and} \\
 &\quad e''' = \underline{\text{after}}_p[\mathbb{C}] \\
 &\{ p \mid \exists p''' \in R : \exists p'' \in R = p + B \Rightarrow t \\
 &\quad \wedge \langle \underline{\text{ab}}_p[\mathbb{S}], p \rangle, \langle \underline{\text{after}}_p[\mathbb{S}], p'' \rangle \in \gamma^S \\
 &\quad \wedge \langle \underline{\text{after}}_p[\mathbb{S}], p'' \rangle, \langle \underline{\text{ab}}_p[\mathbb{C}], p''' \rangle \in X \}
 \end{aligned}$$


$= \{ p \in \{ p \mid \exists p'' \in R : \exists p'' \in R : \langle \text{cat}_p[S], p \rangle, \langle \text{after}_p[S], p'' \rangle \in t^*[S] \wedge \langle \text{after}_p[S], p'' \rangle, \langle \text{cat}_p[C], p''' \rangle \in X \} \}$   
 $\quad \text{pt } B \Rightarrow t$

$= 2$  by def of  $\text{Cbeop}_S$

$\text{Cbeop}[B] (\{ p \mid \exists p' \in R : \langle \text{after}_p[S], p \rangle, \langle \text{cat}_p[C], p' \rangle \in X \} : \langle \text{cat}_p[S], p \rangle, \langle \text{after}_p[S], p' \rangle \in t^*[S])$

$= 2 \text{ after}[S] - \text{at}[C] \text{ and def. } \alpha'$

$\text{Cbeop}[B] (\{ p \mid \exists p' \in \alpha'(x) : \langle \text{at}_p[S], p \rangle, \langle \text{after}_p[S], p' \rangle \in t^*[S] \})$

$= 2 \text{ def. } \alpha_p[S]$

$\text{Cbeop}[B] (\alpha_p[S] (t^*[S]) (\alpha'(x)))$



$= 2$  structural induction hypothesis  
 $\text{Cbeop}[B] (\text{Bcom}[S] (\alpha'(x)))$

$\Rightarrow F'(x) = \text{Cbeop}[T(B)]R \cup \text{Cbeop}[B](\text{Bcom}[S]x)$

and  $\text{Bcom}[C]R = \frac{\text{P}}{\text{P}} \stackrel{?}{=} F'$

$= \text{Bcom}[C; S]R$   
 $= \text{at}[C; S] (t^*[C; S])R$   
 $= \text{at}[C; S] (t^*[C] \circ t^*[S])R$   
 $= \{ p \mid \exists p' \in R : \langle \text{at}_p[C; S], p \rangle, \langle \text{at}_{t^*p}[C; S], p' \rangle \in t^*[C] \circ t^*[S] \}$   
 $= \{ p \mid \exists p' \in R : \langle \text{at}_p[C], p \rangle, \langle \text{at}_{t^*p}[S], p' \rangle \in t^*[C] \circ t^*[S] \}$   
 $\quad 2 \text{ by } (S7) S$   
 $= \{ p \mid \exists p'' \in R, p' \in R, p'' \in \text{in}_p[C; S] : \langle \text{at}_p[C], p \rangle, \langle p', p' \rangle \in t^*[C]$   
 $\quad \langle p', p'' \rangle, \langle \text{at}_{t^*p}[S], p'' \rangle \in t^*[S] \}$



$= 2$  since  $e' \in \text{in}_p[C]$  and  $e' \in \text{in}_p[S]$ , we must have  
 $e' = \text{after}_p[C] = \text{at}_p[S] \}$

$\{ p \mid \exists p'' \in R : \langle \text{at}_p[C], p \rangle, \langle \text{at}_{t^*p}[C], p' \rangle \in t^*[C] \wedge \langle \text{at}_p[S], p'' \rangle, \langle \text{at}_{t^*p}[S], p'' \rangle \in t^*[S] \}$

$= \{ p \mid \exists p' \in R \mid \exists p'' \in R : \langle \text{at}_p[S], p' \rangle, \langle \text{after}_p[S], p'' \rangle \in t^*[S] \} : \langle \text{at}_p[C], p \rangle, \langle \text{after}_p[C], p' \rangle \in t^*[C] \}$

$= \text{Bam}[C] (\{ p' \mid \exists p'' \in R : \langle \text{at}_p[S], p' \rangle, \langle \text{after}_p[S], p'' \rangle \in t^*[S] \})$

$= \text{Bam}[C] (\text{Bam}[S]R)$

$= (\text{Bam}[C] \circ \text{Bam}[S])(R)$



$\sqsubseteq_{\text{Com}}[C];;R$   
 $= \{ p \mid \exists p' \in R : \langle \text{cate}_p[\mathbb{P}], p \rangle, \langle \text{cate}_{p'}[\mathbb{P}], p' \rangle \in t^*[C];;R \}$   
 $= \{ p \mid \exists p' \in R : \langle \text{cate}_p[C], p \rangle, \langle \text{cate}_{p'}[C], p' \rangle \in t^*[C] \}$   
 $= \text{GCom}[C]R$

□

□



## Definition of the backward/precondition collecting semantics

- The abstract backward/precondition semantics

$\text{Abcom}[C]R$  of command  $C$  in abstract environment  $R$  satisfies:

$$\text{Abcom}[C]R \stackrel{\cdot}{\sqsubseteq} \alpha(\text{BPcom}[C](\gamma(R)))$$



## Backward/precondition relational abstract semantics



Note : this is the case when

$$\langle (\wp(R_p) \rightarrow \wp(R_p)), \stackrel{\delta}{\subseteq} \rangle \stackrel{\alpha}{\leftrightarrow} \langle L, \sqsubseteq \rangle.$$

where  $R_p = \wp(\text{Env}[\mathbb{P}])$ . In absence of best approximation one would use a concretization function only where the soundness condition  $\alpha \circ f \circ \gamma \sqsubseteq F^\#$  becomes  $F \circ \gamma \sqsubseteq \gamma \circ F^\#$  for all concrete/abstract operations  $F/F^\#$

□



## Structural specification of the backward collecting semantics

$\text{Abcom}[\text{skip}]R = R$

$\text{Abcom}[X := A]R \sqsupseteq \alpha(\{\rho \mid \exists i \in I : \rho \vdash A \Rightarrow i \wedge \rho[X := i] \in \gamma(R)\})$

$\text{Abcom}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]R =$

$\text{Abexp}[B](\text{Abcom}[S_t]R) \sqcup \text{Abexp}[T(\neg(B))](\text{Abcom}[S_f]R)$

$\text{Abcom}[\text{while } B \text{ do } S \text{ od}]R =$

$\text{Ifp}_\emptyset^\subseteq \lambda X. \text{Abexp}[T(\neg(B))]R \sqcup \text{Abexp}[B](\text{Abcom}[S]X)$

$\text{Abcom}[C ; S]R = (\text{Abcom}[C] \circ \text{Abcom}[S])R$

$\text{Abcom}[S ; ;]R = \text{Abcom}[S]$



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PROOF.

The soundness condition is:

$$\alpha \circ \text{Bcom}[c] \circ \gamma \leq \text{Abcom}[c]$$

for Galois connections, or more generally

$$\text{Bcom}[c] \circ \gamma \leq \text{Abcom}[c] \circ \gamma$$

in absence of best approximant and use of a concretization function only.

The proof is by structural induction on commands.



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- $\alpha \circ \text{Bcom}[\text{skip}] \circ \gamma$

$$= \alpha \circ \gamma$$

$$\leq 1$$

$$\triangleq \text{Abcom}$$

In case of concretization only we have

$$\text{Bcom}[\text{skip}] \circ \gamma \leq \alpha \circ \text{Atom}[\text{skip}]$$

$$\Rightarrow 1 \circ \gamma \leq \gamma \circ 1 \quad \{ \text{where } 1 \text{ is identity} \}$$

$$\Rightarrow \text{true}$$

- for the assignment the soundness follows directly from its definition and that of Bcom.



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- for the test  $c = \text{if } \text{Bexp} \text{ then } L_{C_1} \text{ else } L_{C_2} \text{ fi}$

$$(\alpha \circ \text{Bcom}[c] \circ \gamma)R$$

$$= \alpha(\text{Abexp}[\text{Bexp}](\text{Bcom}[L_{C_1}] \gamma(R)))$$

$$\cup \text{Abexp}[T(\neg \text{Bexp})](\text{Bcom}[L_{C_2}] \gamma(R))$$

$$= ? \quad \text{To do is extensive, Abexp[B] is monotonic and } \alpha \text{ is a complete join morphism}$$


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$$\begin{aligned}
& \alpha(\text{eberp}[\text{Bexp}]\{\delta(\alpha(\text{Bcom}[LC_1]\delta(R)))\}) \\
\sqsubseteq & \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]\{\delta(\alpha(\text{Bcom}[LC_2]\delta(R)))\}) \\
\equiv & \text{induction hypothesis, } \alpha, \text{eberp}[B], \delta \text{ monotone} \quad S \\
& \alpha(\text{eberp}[\text{Bexp}]\{\delta(\text{Abcom}[LC_1]R)\}) \\
\sqsubseteq & \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]\{\delta(\text{Abcom}[LC_2]R)\}) \\
\equiv & \text{induction hypothesis, } \alpha \circ \text{eberp}[B] \circ \delta \in \text{eberp}^\#[\text{B}] \text{ hypothesis} \\
& \text{eberp}^*[\text{Bexp}](\text{Abcom}[LC_1]R) \\
\sqsubseteq & \text{eberp}^\#[\text{T}(\neg\text{Bexp})](\text{Abcom}[LC_2]R) \\
\triangleq & \text{Abcom}[C]R.
\end{aligned}$$



$$\begin{aligned}
& \leq 2 \quad \delta \text{ is monotone} \Rightarrow \delta(X) \cup \delta(Y) = \delta(X \sqcup Y) \\
& \text{where } \sqcup \text{ is the abstract join} \quad S \\
& \delta(\text{eberp}^\#[\text{Bexp}](\text{Abcom}[LC_1]R)) \sqcup \\
& \quad \text{eberp}^\#[\text{T}(\neg\text{Bexp})](\text{Abcom}[LC_2]R)) \\
& = \delta(\text{Abcom}[C]R).
\end{aligned}$$



$$\begin{aligned}
& \text{In case of a } \delta\text{-based abstract interpretation, we} \\
& \text{would have} \\
& \quad \text{eberp}[\text{Bexp}](\text{Bcom}[LC_1](\delta(R))) \\
& \quad \text{eberp}[\text{T}(\neg\text{Bexp})](\text{Bcom}[LC_2](\delta(R))) \\
\equiv & \text{eberp}[B] \text{ is monotone and induction hypothesis} \\
& \quad \text{eberp}[\text{Bexp}](\delta(\text{Abcom}[LC_1]R)) \\
& \quad \text{eberp}[\text{T}(\neg\text{Bexp})](\delta(\text{Abcom}[LC_2]R)) \\
\sqsubseteq & \text{eberp}[B] \circ \delta \in \delta \circ \text{eberp}^\#[\text{B}] \quad S \\
& \quad \delta(\text{eberp}^\#[\text{Bexp}](\text{Abcom}[LC_1]R)) \\
& \quad \delta(\text{eberp}^\#[\text{T}(\neg\text{Bexp})](\text{Abcom}[LC_2]R))
\end{aligned}$$



$$\begin{aligned}
& \text{For the while loop } C = \text{while } \text{Bexp} \text{ do } LC \text{ od, we} \\
& \text{have:} \\
& \quad \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]\delta(R) \cup \text{eberp}[\text{Bexp}](\text{Bcom}[LC]X)) \\
& = \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]R) \\
& \quad \sqcup \alpha(\text{eberp}[\text{Bexp}](\text{Bcom}[LC]X)) \\
& \quad \text{since } \alpha \text{ is a complete join morphism} \quad S \\
\equiv & \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]\delta(R)) \sqcup \\
& \quad \alpha(\text{eberp}[\text{Bexp}]\delta(\alpha(\text{Bcom}[LC]X))) \\
& \quad \text{since } \delta \circ \alpha \text{ is extensive and } \text{eberp}[\text{Bexp}] \text{ is monotone} \quad S \\
\equiv & \alpha(\text{eberp}[\text{T}(\neg\text{Bexp})]\delta(R)) \sqcup \\
& \quad \alpha(\text{eberp}[\text{Bexp}]\delta(\text{Abcom}[LC](\alpha(X)))) \\
& \quad \text{by induction hypothesis and monotony} \\
\equiv & \text{eberp}^\#[\text{T}(\neg\text{Bexp})]R \sqcup \text{eberp}^\#[\text{Bexp}](\text{Abcom}[LC](\alpha(X)))
\end{aligned}$$



so by the hypothesis approximation, therefore we conclude that

$$\begin{aligned} & \alpha(\text{Bcom}[\text{while } \text{Bexp do LCod}]) \circ(R) \\ &= \alpha(\text{loop}_{\#}^{\infty} \sqcup x. \text{Bexp}[T(\neg \text{Bexp})] \circ(R) \cup \\ & \quad \text{Bexp}[\text{Bexp}] (\text{Bcom}[LC] x)) \\ &\equiv \text{loop}_{\#}^{\infty} \sqcup x. \text{Bexp}^{\#}[T(\neg \text{Bexp})] R \cup \\ & \quad \text{Bexp}^{\#}[\text{Bexp}] (\text{Abcom}[LC] x) \end{aligned}$$

The case of a  $\times$ -based abstraction is similar. We have:

$$\begin{aligned} & \text{Bexp}[T(\neg \text{Bexp})] \circ(R) \cup \text{Bexp}[\text{Bexp}] (\text{Bcom}[LC] \circ(x)) \\ &\leq \{ \text{Bexp}[B] \text{ is monotone, hypothesis on } \text{Bexp}^{\#} \text{ and induction hypothesis} \} \end{aligned}$$



Then we have  $F \circ \gamma \leq \gamma \circ F^{\#}$  which implies

$$\begin{aligned} & \text{loop}_{\#}^{\infty} F \leq \gamma(\text{loop}_{\#}^{\infty} F^{\#}) \text{ since by transfinite induction} \\ & \perp \leq \gamma(\perp), \text{ if } x^{\delta} \leq \gamma(x^{\#}) \text{ then } F(x^{\delta}) \leq F \circ \gamma(x^{\#}) \\ & \leq \gamma \circ F^{\#}(x^{\#}) \Rightarrow x^{\#} \leq \gamma(x^{\#}) \text{ for transfinite ordinals,} \\ & \forall x^{\beta} \leq \gamma(x^{\#}) \text{ for all } \beta \leq \lambda, \text{ then } x^{\#} = \bigcup_{\beta < \lambda} x^{\beta} \leq \\ & \bigcup_{\beta < \lambda} \gamma(x^{\beta}) \leq \gamma(\bigcup_{\beta < \lambda} x^{\beta}) \text{ since } x \text{ is monotonic whence} \\ & x^{\#} \leq \gamma(x^{\#}). \text{ So } \text{loop}_{\#}^{\infty} F = x^{\#} = x^{\max(\epsilon, \epsilon')} = x^{\# \max(\epsilon, \epsilon')} = \\ & x^{\epsilon'} = \text{loop}_{\#}^{\infty} F. \text{ We conclude that} \end{aligned}$$

$$\begin{aligned} & \text{Bcom}[\text{while } \text{Bexp do LCod}] \circ(R) \\ &= \text{loop}_{\#}^{\infty} \sqcup x. \text{Bexp}[T(\neg \text{Bexp})] \circ(R) \cup \text{Bexp}[\text{Bexp}] (\text{Bcom}[LC] x) \\ &\equiv \gamma(\text{loop}_{\#}^{\infty} \sqcup x. \text{Bexp}^{\#}[T(\neg \text{Bexp})] R \cup \text{Bexp}^{\#}[\text{Bexp}] (\text{Abcom}[LC] x)). \end{aligned}$$



$$\begin{aligned} & \gamma(\text{Bexp}^{\#}[\text{Bexp}] e) \cup \text{Bexp}[\text{Bexp}] (\gamma(\text{Abcom}[LC] x)) \\ &\leq \{ \text{we use once again the hypothesis on } \text{Bexp}^{\#} \text{ such that } \text{Bexp}[\text{B}] = \gamma \leq \gamma \circ \text{Bexp}^{\#}[\text{B}] \} \\ & \gamma(\text{Bexp}^{\#}[\text{Bexp}] R) \cup \gamma(\text{Bexp}^{\#}[\text{B}] (\text{Abcom}[LC] x)) \\ &\leq \{ \gamma \text{ is monotone so } x \leq x \vee y \text{ implies } \gamma(x) \leq \gamma(x \vee y) \text{ similarly } \gamma(y) \leq \gamma(x \vee y) \text{ whence } \gamma(x) \cup \gamma(y) \leq \gamma(x \vee y) \} \\ & \gamma(\text{Bexp}^{\#}[\text{Bexp}] R \cup \text{Bexp}^{\#}[\text{B}] (\text{Abcom}[LC] x)) \end{aligned}$$



- We have
- $\text{do Bcom}[\text{Com}; LC] \circ \gamma$
- $= \text{do Bcom}[\text{Com}] \circ \text{Bcom}[LC] \circ \gamma$
- $\leq \{ \text{do is extensive, and Bcom}[\text{Com}] \text{ are monotonic} \}$
- $\text{do Bcom}[\text{Com}] \circ \gamma \circ \text{do Bcom}[LC] \circ \gamma$
- $\leq \{ \text{induction hypothesis and monotony} \}$



$$\alpha \circ \text{BCom}[\text{Com}] \circ \gamma \circ \text{AbCom}[\text{LC}_0] \circ \gamma$$

$\subseteq$  2 conclude by positive

$$\text{AbCom}[\text{Com}] \circ \text{AbCom}[\text{LC}_0].$$

In the case of a  $\gamma$ -based abstraction, we have similarly,

$$\text{BCom}[\text{Com} ; \text{LC}_0](\gamma(x))$$

$$= \text{BCom}[\text{Com}](\text{BCom}[\text{LC}_0](\gamma(x)))$$

$\subseteq$  2 monotony and ind. hyp.

$$\text{BCom}[\text{Com}](\gamma(\text{AbCom}[\text{LC}_0]x))$$

$\subseteq$  2 ind. hyp.

$$\gamma(\text{AbCom}[\text{Com}] \circ \text{AbCom}[\text{LC}_0](x))$$

$$= \gamma(\text{AbCom}[\text{Com} ; \text{LC}_0]x).$$



- Note 1 : The proof of the  $\gamma$ -based abstract implies that of a Galois connection-based abstraction since  $F \circ Y \subseteq \gamma \circ F^\#$  implies  $\alpha \circ F \circ \gamma \subseteq \alpha \circ \gamma \circ F^\# \subseteq F^\#$  (monotony,  $\gamma$  is reductive)

- Note 2 : We have never used the hypothesis that  $\text{AbCom}[\text{B}]$  is monotonic so that the proof can be easily generalized to the widening / narrowing case.



- Finally  $\alpha \circ \text{BCom}[\text{LC}_0;j] \circ \gamma = \alpha \circ \text{BCom}[\text{LC}_0] \circ \gamma \subseteq \text{AbCom}[\text{LC}_0;j] = \text{AbCom}[\text{LC}_0;j]$ . Similarly,  
 $\text{BCom}[\text{LC}_0;j](\gamma(x)) = \text{BCom}[\text{LC}_0]\gamma(x) \subseteq \gamma(\text{AbCom}[\text{LC}_0]x)$  by induction hypothesis.  
 $= \gamma(\text{AbCom}[\text{LC}_0;j]x)$ .

□

□

Generic backward/precondition linear relational analyzer



## Linear syntax

We just have to add a function at mapping linearized commands to their entry point:

```

1 (* linear_Syntax.mli *)
2 open Abstract_Syntax
3 (* A linear arithmetic expression a1.x1+...+an.xn+b, where n is the *)
4 (* number of program variables, is represented by a vector:      *)
5 (* LINEAR_AEXP a1 ... an b. A non-linear arithmetic expression is  *)
6 (* represented by RANDOM_AEXP.          *)
7 type laexp =
8   | RANDOM_AEXP           (* random expression      *)
9   | LINEAR_AEXP of int array (* linear expression    *)
10 and lbexp =
11   | LTRUE | LFALSE        (* constant boolean expression *)
12   | RANDOM_BEXP          (* random boolean expression *)
13   | LAND of lbexp list (* boolean conjunction      *)

```

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```

31 (* LINEAR_AEXP a1 ... an b. A non-linear arithmetic expression is  *)
32 (* represented by RANDOM_AEXP.          *)
33 type laexp =
34   | RANDOM_AEXP           (* random expression      *)
35   | LINEAR_AEXP of int array (* linear expression    *)
36 and lbexp =
37   | LTRUE | LFALSE        (* constant boolean expression *)
38   | RANDOM_BEXP          (* random boolean expression *)
39   | LAND of lbexp list (* boolean conjunction      *)
40   | LOR of lbexp list (* boolean disjunction      *)
41   | LGE of int array   (* LGE a1 ... an b is a1.x1+...+an.xn >= b *)
42   | LEQ of int array   (* LEQ a1 ... an b is a1.x1+...+an.xn = b *)
43 and label = Abstract_Syntax.label
44 and lcom =
45   | LSKIP of label * label
46   | LASSIGN of label * variable * laexp * label
47   | LSEQ of label * (lcom list) * label
48   | LIF of label * lbexp * lbexp * lcom * lcom * label

```



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```

14  | LOR of lbexp list (* boolean disjunction      *)
15  | LGE of int array  (* LGE a1 ... an b is a1.x1+...+an.xn >= b *)
16  | LEQ of int array  (* LEQ a1 ... an b is a1.x1+...+an.xn = b *)
17 and label = Abstract_Syntax.label
18 and lcom =
19   | LSKIP of label * label
20   | LASSIGN of label * variable * laexp * label
21   | LSEQ of label * (lcom list) * label
22   | LIF of label * lbexp * lbexp * lcom * lcom * label
23   | LWHILE of label * lbexp * lbexp * lcom * label
24 val at : lcom -> label          (* command entry label      *)
25 val after : lcom -> label        (* command exit label      *)
26 val incom : label -> lcom -> bool (* label in command      *)
27 (* linear_Syntax.mli *)
28 open Abstract_Syntax
29 (* A linear arithmetic expression a1.x1+...+an.xn+b, where n is the *)
30 (* number of program variables, is represented by a vector:      *)

```

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```

49   | LWHILE of label * lbexp * lbexp * lcom * label
50 (* linearized command entry label *)
51 let at c = match c with
52   | LSKIP (l,m)           -> l
53   | LASSIGN (l,x,a,m)     -> l
54   | LSEQ (l,s,m)          -> l
55   | LIF (l,b,nb,st,sf,m) -> l
56   | LWHILE (l,b,nb,s,m)   -> l
57 (* linearized command exit label *)
58 let after c = match c with
59   | LSKIP (l,m)           -> m
60   | LASSIGN (l,x,a,m)     -> m
61   | LSEQ (l,s,m)          -> m
62   | LIF (l,b,nb,st,sf,m) -> m
63   | LWHILE (l,b,nb,s,m)   -> m
64 (* label in command      *)
65 let rec incom l c = match c with
66   | LSKIP (11,12)          -> (l=11) or (l=12)

```



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```

67  | LASSIGN (l1,x,a,l2)    -> (l=11) or (l=12)
68  | LSEQ (l1,s,l2)         -> (l=11) or (l=12) or (inseq l s)
69  | LIF (l1,b,nb,st,sf,l2) -> (l=11) or (l=12) or (incom l st)
70                                or (incom l sf)
71  | LWHILE (l1,b,nb,s,l2)  -> (l=11) or (l=12) or (incom l s)
72 and inseq l s = match s with
73  | [] -> false
74  | h::t -> (incom l h) or (inseq l t)

```



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```

87 let rec bcom c r l =
88   match c with
89   | (LSKIP (l', l'')) ->
90     if (l = l') then r
91     else if (l = l'') then r
92     else (raise (Error "SKIP incoherence"))
93   | (LASSIGN (l',x,a,l'')) ->
94     if (l = l') then b_ASSIGN x a r
95     else if (l = l'') then r
96     else (raise (Error "ASSIGN incoherence"))
97   | (LSEQ (l', s, l'')) ->
98     (bcomseq s r l)
99   | (LIF (l', b, nb, t, f, l'')) ->
100    (if (l = l') then
101      (join (a_bexp b (bcom t r (at t))) (a_bexp nb (bcom f r (at f)))
102    else if (incom l t) then
103      (bcom t r l)
104    else if (incom l f) then

```



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## backward relational abstract interpretation of commands

```

75 (* bcom.mli *)
76 open Linear_Syntax
77 open Aenv
78 (* backward abstract interpretation of commands *)
79 val bcom : lcom -> Aenv.t -> label -> Aenv.t

80 (* bcom.ml *)
81 open Linear_Syntax
82 open Aenv
83 open Abexp
84 open Fixpoint
85 (* backward abstract semantics of commands *)
86 exception Error of string

```



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```

105          (bcom f r l)
106        else if (l = l'') then
107          r
108        else (raise (Error "IF incoherence"))
109   | (LWHILE (l', b, nb, c', l'')) ->
110     let f x = (join (a_bexp b (bcom c' x (at c')))) (a_bexp nb r))
111     in let i = lfp (bot ()) leq widen narrow f in
112       (if (l = l') then i
113        else if (incom l c') then (bcom c' i l)
114        else if (l = l'') then r
115        else (raise (Error "WHILE incoherence")))
116   and bcomseq s r l = match s with
117   | []  -> raise (Error "empty SEQ incoherence")
118   | [c] -> if (incom l c) then (bcom c r l)
119             else (raise (Error "SEQ incoherence"))
120   | h::t -> if (incom l h) then (bcom h (bcomseq t r (at (List.hd t)))) l
121             else (bcomseq t r l)

```



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## The generic backward/precondition linear relational static analyzer

```
122 (* main.ml = main-bw.ml *)
123 open Program_To_Abstract_Syntax
124 open Labels
125 open Pretty_Print
126 open Lpretty_Print
127 open Abstract_To_Linear_Syntax
128 open Linear_Syntax
129 open Aenv
130 open Acom
131 open Bcom
132 let _ =
133   let arg = if (Array.length Sys.argv) = 1 then ""
134             else Sys.argv.(1) in
```



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## Polyhedral backward/precondition analysis



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```
135 Random.self_init ();
136 let p = (abstract_syntax_of_program arg) in
137   (print_string "** Program:\n";
138    pretty_print p;
139    let p' = (linearize_com p) in
140      print_string "** Linearized program:\n";
141      lpretty_print p';
142      init ();
143      print_string "** Postcondition:\n";
144      print (top ());
145      print_string "** Precondition:\n";
146      print (bcom p' (top ()) (at p'));
147      quit ())
```



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## The polyhedral abstract environment for backward static analysis

- We just have to add the definition of b\_ASSIGN to handle backward assignments:

```
148 (* aenv.mli *)
149 open Linear_Syntax
150 open Array
151 open Variables
152 (* set of environments *)
153 type t
154 (* relational library initialization *)
155 val init : unit -> unit
156 (* relational library exit *)
157 val quit : unit -> unit
158 (* infimum *)
```



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```

159 val bot : unit -> t
160 (* check for infimum *)
161 val is_bot : t -> bool
162 (* uninitalization *)
163 val initerr : unit -> t
164 (* supremum *)
165 val top : unit -> t
166 (* least upper bound *)
167 val join : t -> t -> t
168 (* greatest lower bound *)
169 val meet : t -> t -> t
170 (* approximation ordering *)
171 val leq : t -> t -> bool
172 (* equality *)
173 val eq : t -> t -> bool
174 (* printing *)
175 val print : t -> unit
176 (* forward collecting semantics of assignment *)
```



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```

194 open Variables
195 type lattice = BOT | TOP
196 type t =
197   NULL of lattice (* in absence of any variable, dimension = 0 *)
198 | POLY of Poly.t (* must be of dimension > 0 *)
199 exception PolyError of string
200 (* relational library initialization *)
201 let maxdims = 10000
202 let maxrows = 100
203 let init () = (Polka.initialize false maxdims maxrows;
204                 Polka.strict := false)
205 (* relational library exit (* print statistics *) *)
206 let quit () = Polka.finalize ()
207 (* infimum *)
208 let bot () = match (number_of_variables ()) with
209   | 0 -> NULL BOT
210   | n -> if (n < 0) then
211             raise (PolyError "negative number of variables (bot)")
```



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```

177 (* f_ASSIGN x f r = {e[x <- i] | e in r /\ i in f({e}) cap I } *)
178 val f_ASSIGN : variable -> laexp -> t -> t
179 (* backward collecting semantics of assignment *)
180 (* b_ASSIGN x f r = {e | exists i in f({e}) cap I: e[x <- i] in r } *)
181 val b_ASSIGN : variable -> laexp -> t -> t
182 (* collecting semantics of boolean expressions *)
183 (* f_LGE a r = {e in r | a0.v0+...+an-1.vn-1 >= an } *)
184 val f_LGE : (int array) -> t -> t
185 (* f_LEQ a r = {e in r | a0.v0+...+an-1.vn-1 = an } *)
186 val f_LEQ : (int array) -> t -> t
187 (* convergence acceleration *)
188 (* widening *)
189 val widen : t -> t -> t
190 (* narrowing *)
191 val narrow : t -> t -> t
192 (* aenv.ml *)
193 open Linear_Syntax
```



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```

212 else if (n > maxdims) then
213   raise (PolyError "too many variables (bot)")
214 else
215   POLY (Poly.empty n) (* 1 <= n <= polka_maxcolumns-polka_dec *)
216 (* check for infimum *)
217 let is_bot r = match r with
218   | NULL BOT -> true
219   | NULL TOP -> false
220   | POLY p -> (Poly.is_equal p (Poly.empty (number_of_variables ())))
221 (* uninitalization *)
222 let initerr () = match (number_of_variables ()) with
223   | 0 -> NULL TOP
224   | n -> if (n < 0) then
225             raise (PolyError "negative number of variables (initerr)")
226   else if (n > maxdims) then
227             raise (PolyError "too many variables (initerr)")
228   else
229     POLY (Poly.universe n)
```



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```

230 (* supremum *)
231 let top () = match (number_of_variables ()) with
232 | 0 -> NULL TOP
233 | n -> if (n < 0) then
234     raise (PolyError "negative number of variables (top)")
235 else if (n > maxdims) then
236     raise (PolyError "too many variables (top)")
237 else
238     POLY (Poly.universe n)
239 (* least upper bound *)
240 let ljoin l1 l2 = match (l1, l2) with
241 | BOT, _ -> l2
242 | _, BOT -> l1
243 | _, _ -> TOP
244 let join r1 r2 = match (r1, r2) with
245 | NULL l1, NULL l2 -> (NULL (ljoin l1 l2))
246 | POLY p1, POLY p2 -> (POLY (Poly.union p1 p2))
247 | _, _ -> raise (PolyError "join")

```



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```

266 (* equality *)
267 let eq r1 r2 = match (r1, r2) with
268 | NULL l1, NULL l2 -> (l1 = l2)
269 | POLY p1, POLY p2 -> (Poly.is_equal p1 p2)
270 | _, _ -> raise (PolyError "eq")
271 (* printing *)
272 let print r = match r with
273 | NULL BOT -> (print_string "{ _|_ }\n")
274 | NULL TOP -> (print_string "{ T }\n")
275 | POLY p ->
276     (Poly.minimize p; (* to get the constraints and generators of p *)
277      Poly.print_constraints string_of_variable Format.std_formatter p;
278      Format.pp_print_newline Format.std_formatter ())
279 (* convert a0.v0+...+an-1.vn-1+an where n = (number_of_variables ()) int
280 (* vector [1,an,a0,...,an-1].
281 let vector_of_lin_expr a =
282     let v = Vector.make ((number_of_variables ()) + 2) in
283         (Vector.set v 0 1;

```



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```

248 (* greatest lower bound *)
249 let lmeet l1 l2 = match (l1, l2) with
250 | TOP, _ -> l2
251 | _, TOP -> l1
252 | _, _ -> BOT
253 let meet r1 r2 = match (r1, r2) with
254 | NULL l1, NULL l2 -> (NULL (lmeet l1 l2))
255 | POLY p1, POLY p2 -> (POLY (Poly.inter p1 p2))
256 | _, _ -> raise (PolyError "meet")
257 (* approximation ordering *)
258 let lleq l1 l2 = match (l1, l2) with
259 | BOT, _ -> true
260 | _, TOP -> true
261 | TOP, BOT -> false
262 let leq r1 r2 = match (r1, r2) with
263 | NULL l1, NULL l2 -> (lleq l1 l2)
264 | POLY p1, POLY p2 -> (Poly.is_included_in p1 p2)
265 | _, _ -> raise (PolyError "leq")

```



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```

284 Vector.set v 1 (a.(number_of_variables ()));
285 for i = 0 to ((number_of_variables ()) - 1) do
286     Vector.set v (i+2) a.(i)
287 done;
288 (*
289 Vector._print v;
290 Vector.print_constraint string_of_variable Format.std_formatter v;
291 Format.pp_print_newline Format.std_formatter ();
292 *)
293 v)
294 (* f_ASSIGN x f r = {e[x <- i] | e in r /\ i in f({e}) cap I } *)
295 let f_ASSIGN x f r =
296     match r with
297     | NULL _ -> r
298     | POLY p -> (match f with
299     | RANDOM_AEXP ->
300         let d = [|{ Polka.pos = x; Polka.nbdims = 1 }|] in
301             (POLY (Poly.add_dims_and_embed_multi (Poly.del_dims_multi p) d)))

```



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```

302 | LINEAR_AEXP a ->
303   (POLY (Poly.assign_var p x (vector_of_lin_expr a)))
304 (* b_ASSIGN x f r = {e | exists i in f({e}) cap I: e[x <- i] in r } *)
305 let b_ASSIGN x f r =
306   match r with
307   | NULL _ -> r
308   | POLY p -> POLY (match f with
309   | RANDOM_AEXP ->
310     let d = [|{ Polka.pos = x; Polka.nbdims = 1 }|] in
311       (Poly.add_dims_and_embed_multi (Poly.del_dims_multi p d) d)
312   | LINEAR_AEXP a ->
313     (Poly.minimize p; (* <- to get around a bug of Polka 2.0.2 *)
314      (* in substitute_var *)
315      Poly.substitute_var p x (vector_of_lin_expr a)))
316 (* f_LGE a r = {e in r | a0.v0+...+an-1.vn-1+an >= 0} *)
317 let f_LGE a r =
318   match r with
319   | NULL _ -> r

```



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## Examples of backward polyhedral static analysis

```

Generic-FW-BW-REL-Abstract-Interpreter % ./a.out
x := 1;
while (x > 0) do
  x := x + 10000000
od;;
...
** Postcondition:
{1>=0}
** Precondition:
empty(1)

```

- The only way for the program execution to exit the loop is to *never start it* (because of arithmetic overflow when  $\mathbb{I}$  is unbounded or non-termination if  $\mathbb{N} \subseteq \mathbb{I}$ )



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```

320 | POLY p -> POLY (Poly.add_constraint p (vector_of_lin_expr a))
321 (* f_LEQ a r = {e in r | a0.v0+...+an-1.vn-1+an = 0} *)
322 let minus = Array.map (fun x -> (- x))
323 let f_LEQ a r = meet (f_LGE a r) (f_LGE (minus a) r)
324 (* widening *)
325 let widen r1 r2 = match (r1, r2) with
326   | NULL l1, NULL l2 -> (NULL (ljoin l1 l2))
327   | POLY p1, POLY p2 -> (POLY (Poly.widening p1 p2))
328   | _, _ -> raise (PolyError "widen")
329 (* narrowing *)
330 (* let narrow a b = a (* does not ensure termination *) *)
331 let narrow a b = b (* less precise but does ensure termination *)

```



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The precondition/postcondition collecting semantics



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## Definition of the forward/backward semantics

- We assume that a transition system  $\langle \Sigma, \tau, I, F \rangle$  is given such that
  - $\Sigma$  is a set of states
  - $\tau \in \wp(\Sigma \times \Sigma)$  is the transition relation between a state and its potential successors
  - $I \subseteq \Sigma$  is the set of initial states
  - $F \subseteq \Sigma$  is the set of final states



- The backward or precondition semantics is the set of states from which the final states  $F$  may be potentially reached

$$\begin{aligned} \text{pre}[\tau^*]F \\ = \{s \in \Sigma \mid \exists s' \in F : \tau^*(s, s')\} \\ \subseteq \text{lfp}_\emptyset \mathcal{B} \end{aligned}$$

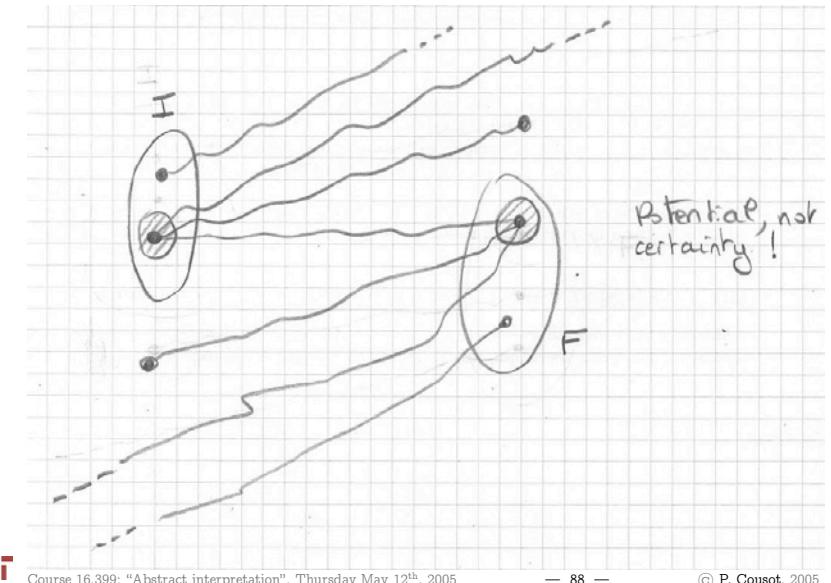
where  $\mathcal{B}(X) = F \cup \text{pre}[t]X$   
and  $\text{pre}[t]X = \{s \in \Sigma \mid \exists s' \in X : t(s, s')\}$



- The forward or postcondition semantics is the set of states which are reachable from the initial states  $I$

$$\begin{aligned} \text{post}[\tau^*]I \\ = \{s' \in \Sigma \mid \exists s \in I : \tau^*(s, s')\} \\ \subseteq \text{lfp}_\emptyset \mathcal{F} \end{aligned}$$

where  $\mathcal{F}(X) = I \cup \text{post}[t]X$   
and  $\text{post}[t]X = \{s' \in \Sigma \mid \exists s \in X : t(s, s')\}$



- The forward/backward or precondition/postcondition semantics is the pair

$$\langle I \cap \text{pre}[\tau^*]F, \text{post}[\tau^*]I \cap F \rangle$$

- In the concrete, there is nothing new
- However, in the abstract, we can do much better than separate overapproximations of  $\text{pre}[\tau^*]F$  and  $\text{post}[\tau^*]I$



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```
Generic-FW-BW-REL-Abstract-Interpreter % make bw
Backward analysis
Generic-FW-BW-REL-Abstract-Interpreter % make pol
Polyhedral analysis
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example48.sil
** Postcondition:
{1>=0}
** Precondition:
{X+2Y=2}
Generic-FW-BW-REL-Abstract-Interpreter % make iter
Iterated forward/backward analysis
Generic-FW-BW-REL-Abstract-Interpreter % make pol
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example48.sil
** Precondition:
{X+2Y=2}
** Postcondition:
{X+Y=5}
```



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## Example of abstract forward/backward semantics

```
Generic-FW-BW-REL-Abstract-Interpreter % cat ../Examples/example48.sil
% example48.sil %
X := X + Y + 3;
while (X + Y <> 5) do
  skip
od;;
Generic-FW-REL-Abstract-Interpreter % make pol
Polyhedral analysis
Generic-FW-REL-Abstract-Interpreter % ./a.out ../Examples/example48.sil
...
** Precondition:
{1>=0}
** Postcondition:
{X+Y=5}
```



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## Properties of the forward/backward collecting semantics

**THEOREM.**  $\langle I \cap \text{pre}[\tau^*]F, F \cap \text{post}[\tau^*]I \rangle =$   
 $\text{gfp}^{\subseteq_2} \lambda \langle X, Y \rangle . \langle I, F \rangle \cap_2 \langle X \cap \text{pre}[\tau^*]Y, Y \cap \text{post}[\tau^*]X \rangle$  ■

**PROOF.** We prove that  $\langle I \cap \text{pre}[\tau^*]F, F \cap \text{post}[\tau^*]I \rangle$  is a fixpoint of  
 $\lambda \langle X, Y \rangle . \langle I, F \rangle \cap_2 \langle X \cap \text{pre}[\tau^*]Y, Y \cap \text{post}[\tau^*]X \rangle$   
componentwise. For the first component, we have

$$\begin{aligned} & I \cap (I \cap \text{pre}[\tau^*]F) \cap \text{pre}[\tau^*](F \cap \text{post}[\tau^*]I) \\ & \quad \{ \text{def. pre} \} \\ & = I \cap \text{pre}[\tau^*]F \cap \{ s \mid \exists s_2 : \tau^*(s, s_2) \wedge s_2 \in F \wedge s_2 \in \text{post}[\tau^*]I \} \\ & \quad \{ \text{def. post} \} \\ & = I \cap \text{pre}[\tau^*]F \cap \{ s \mid \exists s_2 : \tau^*(s, s_2) \wedge s_2 \in F \wedge \exists s_3 : s_3 \in I \wedge \tau^*(s_3, s_2) \} \end{aligned}$$



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$\{ \text{def. pre} \}$   
 $= I \cap \{s \mid \exists s_1 : s_1 \in F \wedge \tau^*(s, s_A) \wedge \exists s_2 : \tau^*(s, s_2) \wedge s_2 \in F \wedge \exists s_3 : s_3 \in I \wedge \tau^*(s_3, s_2)\}$   
 (simplifying with  $s_1 = s_2$  and  $s_3 = s$ )  
 $= I \cap \{s \mid \exists s_2 : \tau^*(s, s_2) \wedge s_2 \in F\}$   
 $\quad \{ \text{def. pre} \}$   
 $= I \cap \text{pre}[\tau^*]F$

for  $I, F$  and  $\tau$ .

To show that  $\langle I \cap \text{pre}[\tau^*]F, F \cap \text{post}[\tau^*]I \rangle$  is the greatest fixpoint of  $\lambda \langle X, Y \rangle \cdot \langle I, F \rangle \sqcap_2 \langle X \cap \text{pre}[\tau^*]Y, Y \cap \text{post}[\tau^*]X \rangle$  we let  $\langle X, Y \rangle$  be any such fixpoint. We have:  $X = I \cap X \cap \text{pre}[\tau^*]Y$  so  $X \subseteq I \cap \text{pre}[\tau^*]Y$ . Moreover  $Y = F \cap Y \cap \text{post}[\tau^*]X$  implies  $Y \subseteq F$  so by monotony  $X \subseteq I \cap \text{pre}[\tau^*]F$ . Similarly,  $Y \subseteq F \cap \text{post}[\tau^*]F$ .  $\square$



## Pre/postcondition abstract semantics

- We are given an abstraction  $\langle \wp(\Sigma), \subseteq \rangle \xrightleftharpoons[\alpha]{\gamma} \langle L, \sqsubseteq \rangle$
  - We want to compute an overapproximation of:
- $$\begin{aligned} & \langle \alpha(I \cap \text{pre}[\tau^*]F), \alpha(F \cap \text{post}[\tau^*]I) \rangle \\ &= \langle \alpha(I \cap \text{lfp } \lambda Z \cdot F \cup \text{pre}[\tau]Z), \alpha(F \cap \text{lfp } \lambda Z \cdot I \cup \text{post}[\tau]Z) \rangle \end{aligned}$$

- One solution is to overapproximate

$$\begin{aligned} & \langle \alpha(I) \sqcap \text{lfp } \lambda Z \cdot \alpha(F) \sqcup \alpha(\text{pre}[\tau](\gamma(Z))), \\ & \quad \alpha(F) \sqcap \text{lfp } \lambda Z \cdot \alpha(I) \sqcup \alpha(\text{post}[\tau]\gamma(Z)) \rangle \end{aligned}$$



## The precondition/postcondition abstract semantics and its implementation



- A better solution is to use the greatest fixpoint characterization and to overapproximate:

$$\begin{aligned} & \alpha_2(\text{gfp}^{\sqsubseteq_2} \lambda \langle X, Y \rangle \cdot \langle I, F \rangle \sqcap_2 \\ & \quad \langle X \cap \text{pre}[\tau^*]Y, Y \cap \text{post}[\tau^*]X \rangle) \\ & \quad \text{fixpoint overapproximation} \\ & \sqsubseteq_2 \text{gfp}^{\sqsubseteq_2} \lambda \langle X, Y \rangle \cdot \langle \alpha(I), \alpha(F) \rangle \sqcap_2 \\ & \quad \langle \alpha(\gamma(X) \cap \text{pre}[\tau^*]\gamma(Y)), \alpha(\gamma(Y) \cap \text{post}[\tau^*]\gamma(X)) \rangle \\ & \quad \text{fixpoint definition of pre}[\tau^*] \text{ and post}[\tau^*] \\ &= \text{gfp}^{\sqsubseteq_2} \lambda \langle X, Y \rangle \cdot \langle \alpha(I), \alpha(F) \rangle \sqcap_2 \\ & \quad \langle \alpha(\gamma(X) \cap \text{lfp } \lambda Z \cdot \gamma(Y) \cup \text{pre}[\tau]Z), \\ & \quad \alpha(\gamma(Y) \cap \text{lfp } \lambda Z \cdot \gamma(X) \cup \text{post}[\tau]Z) \rangle \end{aligned}$$



$\{\alpha \text{ monotone}\}$   
 $\sqsubseteq_2 \text{gfp}^{\sqsubseteq_2} \lambda\langle X, Y \rangle . \langle \alpha(I), \alpha(F) \rangle \sqcap_2$   
 $\langle \alpha(\gamma(X)) \sqcap \text{lfp } \lambda Z . \alpha(\gamma(Y)) \sqcup \alpha(\text{pre}[\tau](\gamma(Z))),$   
 $\alpha(\gamma(Y)) \sqcap \lambda Z . \alpha(\gamma(X)) \sqcup \alpha(\text{post}[\tau]\gamma(Z)) \rangle$   
 $\{\alpha \circ \gamma \text{ reductive and monotony}\}$   
 $\sqsubseteq_2 \text{gfp}^{\sqsubseteq_2} \lambda\langle X, Y \rangle . \langle \alpha(I), \alpha(F) \rangle \sqcap_2$   
 $\langle X \sqcap \text{lfp } \lambda Z . Y \sqcup \alpha(\text{pre}[\tau](\gamma(Z))),$   
 $Y \sqcap \lambda Z . X \sqcup \alpha(\text{post}[\tau]\gamma(Z)) \rangle$

## Pre/postcondition static analysis

Assuming  $\alpha(I) \sqsubseteq I^\sharp$ ,  $\alpha(F) \sqsubseteq F^\sharp$ ,  $\alpha \circ \text{pre}[\tau] \circ \gamma \dot{\sqsubseteq} B^\sharp$ ,  $\alpha \circ \text{post}[\tau] \circ \gamma \dot{\sqsubseteq} F^\sharp$ , and using chaotic iterations, the algorithm is

$$\begin{aligned} X^0 &= I^\sharp \\ Y^0 &= F^\sharp \\ \dots & \\ X^{n+1} &= X^n \sqcap \text{lfp } \lambda Z . Y^n \sqcup B^\sharp(Z) \\ Y^{n+1} &= Y^n \sqcap \text{lfp } \lambda Z . X^{n+1} \sqcup F^\sharp(Z) \\ \dots & \end{aligned}$$

Convergence may have to be enforced via a narrowing.

## Implementation of the pre/postcondition static analysis

In the implementation the initial precondition is that variables are uninitialized and the postcondition is `tt`, that is  $\top$  is both cases.

```
332 (* main.ml = main-iter-fw-bw.ml *)
333 open Program_To_Abstract_Syntax
334 open Labels
335 open Pretty_Print
336 open Lpretty_Print
337 open Abstract_To_Linear_Syntax
338 open Linear_Syntax
339 open Aenv
340 open Acom
341 open Bcom
```

```
342 let _ =
343   let narrowing_limit = 100 in
344   let arg = if (Array.length Sys.argv) = 1 then ""
345           else Sys.argv.(1) in
346   Random.self_init ();
347   let p = (abstract_syntax_of_program arg) in
348   (print_string "** Program:\n";
349    pretty_print p;
350    let p' = (linearize_com p) in
351    print_string "** Linearized program:\n";
352    lpretty_print p';
353    init ();
354    let rec iterate pre n =
355      (print_string "** Precondition:\n";
356      print pre;
357      let post = (acom p' pre (after p')) in
358      (print_string "** Postcondition:\n";
359      print post;
```

```

360   let pre' = (bcom p' post (at p')) in
361     (if (Aenv.eq pre pre') then
362       (print_string "stable precondition after ";
363        print_int n;print_string " iteration(s).\n")
364     else if (n < narrowing_limit) then
365       (print_string "unstable precondition after ";
366        print_int n;print_string " iteration(s).\n";
367        iterate pre' (n+1))
368     else
369       (print_string "stable stopped "; print_int n;
370        print_string " iterations (narrowing).\n")))
371   in iterate (initerr ()) 1;
372   quit ()

```



```

** Program:
0:
  x := y;
1:
  z := ((2 * x) + 1);
2:
  while ((y < 0) | (0 < y)) do
    3:
      skip
    4:
      od { (y = 0) }
5:

```



## Examples of pre/postcondition static analysis

In the examples, we enforce a postcondition  $B$  as:

while  $\neg B$  do skip od

which, since termination is enforced by the backward analysis, requires  $B$  to hold just before the loop.

```

Generic-FW-BW-REL-Abstract-Interpreter % make iter
Iterated forward/backward analysis
Generic-FW-BW-REL-Abstract-Interpreter % make pol
...
Polyhedral analysis
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example49.sil

```



```

** Linearized program:
0:
  x := 1.y + 0.x + 0.z + 0;
1:
  z := 0.y + 2.x + 0.z + 1;
2:
  while (-1.y + 0.x + 0.z + -1 >= 0 | 1.y + 0.x + 0.z + -1 >= 0) do
    3:
      skip
    4:
      od { -1.y + 0.x + 0.z + 0 = 0 }
5:

```



```

** Precondition:
{1>=0}
** Postcondition:
{z=1,x=0,y=0}
unstable precondition after 1 iteration(s).

** Precondition:
{y=0}
** Postcondition:
{z=1,x=0,y=0}
stable precondition after 2 iteration(s).
Generic-FW-BW-REL-Abstract-Interpreter %

```

### Comments on this example:

- The initial precondition  $\{1>=0\}$  is  $\top$  whence states no hypothesis on the input data



- The forward analysis provides the first postcondition stating that on termination  $y=0$  whence  $z=1$  and  $x=0$
- Since  $y$  is not modified in the program, the next backward analysis provides the second precondition that we must have  $y=0$  initially
- The last forward iteration shows that the fixpoint is reached



The following program is proved to never terminate:

```

Generic-FW-BW-REL-Abstract-Interpreter % ./a.out
x := 1;
while (x > 0) do
    x := x + 1000000
od;;
** Precondition:
{1>=0}
** Postcondition:
empty(1)
unstable precondition after 1 iteration(s).
** Precondition:
empty(1)
** Postcondition:
empty(1)
stable precondition after 2 iteration(s).

```



```

Generic-FW-BW-REL-Abstract-Interpreter % cat ../Examples/example45.sil
% example45.sil %
X := X + Y;
while (X + Y <> 0) do
    skip
od;;
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example45.sil
** Precondition:
{1>=0}
** Postcondition:
{X+Y=0}
unstable precondition after 1 iteration(s).
** Precondition:
{X+2Y=0}
** Postcondition:
{X+Y=0}
stable precondition after 2 iteration(s).

```



```

Generic-FW-BW-REL-Abstract-Interpreter % cat ../Examples/example46.sil
% example46.sil %
X := Y;
while (X + Y + Z <> 0) do
  skip
od;;
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example46.sil
** Precondition:
{1>=0}
** Postcondition:
{2Y+Z=0,Y=X}
unstable precondition after 1 iteration(s).
** Precondition:
{2Y+Z=0}
** Postcondition:
{2Y+Z=0,Y=X}
stable precondition after 2 iteration(s).

```



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## The forward/backward reachability collecting semantics



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```

Generic-FW-BW-REL-Abstract-Interpreter % cat ../Examples/example47.sil
% example47.sil %
X := Y;
while (X + Y + Z > 0) do
  skip
od;;
Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ../Examples/example47.sil
** Precondition:
{1>=0}
** Postcondition:
{Y=X,2Y+Z<=0}
unstable precondition after 1 iteration(s).
** Precondition:
{2Y+Z<=0}
** Postcondition:
{Y=X,2Y+Z<=0}
stable precondition after 2 iteration(s).

```



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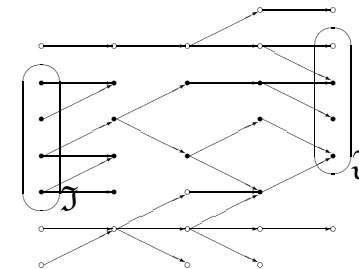
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## The forward reachability collecting semantics

- The forward reachability semantics

$$\text{post}[\tau^*]I = \text{lfp}^\subseteq \lambda X . I \cup \text{post}[\tau]X$$

is the set of descendants of the initial states  $I$  by transitions  $\tau$



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Recall the following fixpoint characterization of the forward reachability collecting semantics:

**THEOREM.**  $\mathfrak{D} = \text{post}[\tau^*]\mathfrak{I} = \text{lfp } F[\mathbb{P}]$  where  $F[\mathbb{P}] \in \langle \wp(S), \cup \mapsto \langle \wp(S), \cup \rangle$  is defined by  $F[\mathbb{P}]X = \mathfrak{I} \cup \text{post}[\tau X]$ . ■

**PROOF.** Observe that  $\wp(\mathfrak{S} \times \mathfrak{S})(\subseteq, \emptyset, \mathfrak{S} \times \mathfrak{S}, \cup, \cap)$  and  $\wp(\mathfrak{S})(\subseteq, \emptyset, \mathfrak{S}, \cup, \cap)$  are complete lattices. Define  $\alpha \in \wp(\mathfrak{S} \times \mathfrak{S}) \rightarrow \wp(\mathfrak{S})$  by  $\alpha(X) = \text{post}[X]\mathfrak{I}$ . It is a complete  $\cup$ -morphism so that there exists  $\gamma$  such that  $\wp(\mathfrak{S} \times \mathfrak{S})(\subseteq) \xleftarrow{\gamma} \wp(\mathfrak{S})(\subseteq)$ . We have  $\tau^* = \text{lfp } T = \bigcup_{n \in \mathbb{N}} T^n(\emptyset)$  where  $T(X) = 1 \cup X \circ \tau$ ,  $1 = \alpha(\emptyset)$  and  $F[\mathbb{P}] \in \langle \wp(S), \cup \mapsto \langle \wp(S), \cup \rangle$  is such that for all  $X \in \wp(\mathfrak{S} \times \mathfrak{S})$ , we have  $\alpha \circ T(X) = \text{post}[T(X)]\mathfrak{I} = \{s \mid \exists s' \in \mathfrak{I} : \langle s', s \rangle \in T(X)\} = \{s \mid \exists s' \in \mathfrak{I} : \langle s', s \rangle \in 1 \cup X \circ \tau = \{s \mid \exists s' \in \mathfrak{I} : \langle s', s \rangle \in 1 \vee (\langle s', s \rangle \in X \circ \tau) = \{s \mid \exists s' \in \mathfrak{I} : (s' = s) \vee (\langle s', s \rangle \in X \circ \tau) = \mathfrak{I} \cup \{s \mid \exists s' \in \mathfrak{I} : \langle s', s \rangle \in X \circ \tau = \mathfrak{I} \cup \{s \mid \exists s' \in \mathfrak{I} : \exists s'' \in \mathfrak{S} : \langle s', s'' \rangle \in X \wedge s'' \tau\} = \mathfrak{I} \cup \{s \mid \exists s'' \in \{s'' \mid \exists s' \in \mathfrak{I} : \langle s', s'' \rangle \in X \wedge s'' \tau\} = \mathfrak{I} \cup \{s \mid \exists s'' \in \text{post}[X]\mathfrak{I} : s'' \tau\} = \mathfrak{I} \cup \text{post}[\tau](\text{post}[X]\mathfrak{I}) = F[\mathbb{P}](\text{post}[X]\mathfrak{I}) = F[\mathbb{P}] \circ \alpha(X)$ . By the fixpoint transfer theorem, we have  $\text{lfp } T = \text{lfp } F[\mathbb{P}]$  so that  $\mathfrak{D} = \text{post}[\tau^*]\mathfrak{I} = \alpha(\tau^*) = \alpha(\text{lfp } T) = \text{lfp } F[\mathbb{P}]$ . □

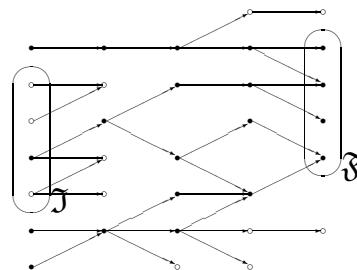
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## The backward reachability collecting semantics

– The backward reachability semantics

$$\text{pre}[\tau^*]F = \text{lfp } \subseteq \lambda Y . F \cup \text{pre}[\tau]Y$$

is the set of potential descendants of the final states  $F$  by transitions  $\tau$



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## The forward/backward reachability collecting semantics

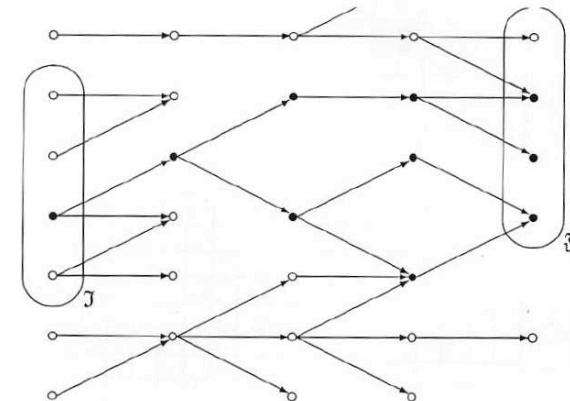
- We are interested in the forward/backward collecting semantics which is defined as  $\text{post}[\tau^*]I \cap \text{pre}[\tau^*]F$  that is the intersection of two fixpoints  $\text{lfp } \subseteq \lambda X . I \cup \text{post}[\tau]X \cap \lambda Y . F \cup \text{pre}[\tau]Y$
- We look for a more precise analysis than the mere intersection of the independent overapproximations of  $\text{lfp } \subseteq \lambda X . I \cup \text{post}[\tau]X$  and  $\text{lfp } \subseteq \lambda Y . F \cup \text{pre}[\tau]Y$



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Descendant states (●) of the initial states (○) which are ascendant states of the final states (✗).



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## Properties of the forward/backward collecting semantics

**THEOREM.** For all transition systems  $\langle \Sigma, I, F, \tau \rangle$  where  $\mathcal{F}(X) \stackrel{\text{def}}{=} I \cup \text{post}[\tau]X$ ,  $\mathcal{B}(X) \stackrel{\text{def}}{=} I \cup \text{pre}[\tau]X$ , and  $X \subseteq \Sigma$ , we have:

$$(\text{pre}[\tau]X) \cap \text{lfp } \mathcal{F} \subseteq \text{pre}[\tau](X \cap \text{lfp } \mathcal{F}) \quad (16)$$

$$(\text{post}[\tau]X) \cap \text{lfp } \mathcal{B}[\llbracket P \rrbracket] \subseteq \text{post}[\tau](X \cap \text{lfp } \mathcal{B}) \quad (17)$$

$$\text{lfp } \mathcal{F} \cap \text{lfp } \mathcal{B} \quad (18)$$

$$= \text{lfp } \lambda X . (\text{lfp } \mathcal{F} \cap \mathcal{B}(X)) \quad (19)$$

$$= \text{lfp } \lambda X . (\text{lfp } \mathcal{B} \cap \mathcal{F}(X)) \quad (20)$$

$$= \text{lfp } \lambda X . (\text{lfp } \mathcal{F} \cap \text{lfp } \mathcal{B} \cap \mathcal{B}(X)) \quad (21)$$

$$= \text{lfp } \lambda X . (\text{lfp } \mathcal{F} \cap \text{lfp } \mathcal{B} \cap \mathcal{F}(X)) \quad (22)$$

■



## The forward/backward reachability abstract semantics

**PROOF.** — To prove (16), observe that the theorem on page 113 implies that  $(\text{pre}[\tau]X) \cap \text{lfp } \mathcal{F} = \{s \mid \exists s' \in X : s \tau s'\} \cap \{s \mid \exists s'' \in I : s'' \tau^* s\} \subseteq \{s \mid \exists s' \in X : \exists s'' \in I : s'' \tau^* s' \wedge s \tau s'\}$  since  $s'' \tau^* s$  and  $s \tau s'$  imply  $s'' \tau^* s'$ . This is precisely  $\text{pre}[\tau](X \cap \text{post}[\tau^*]I) = \text{pre}[\tau](X \cap \text{lfp } \mathcal{F})$ . The proof of (17) is similar to that of (16).

— To prove (19), let  $X^n, n \in \mathbb{N}$  and  $Y^n, n \in \mathbb{N}$  be the iteration sequences starting from the infimum  $\emptyset$  for  $\mathcal{B}$  and  $\lambda X . (\text{lfp } \mathcal{F} \cap \mathcal{B}[\llbracket P \rrbracket]X)$  respectively. We have  $\text{lfp } \mathcal{F} \cap X^0 = \emptyset = Y^0$ . Assume that  $\text{lfp } \mathcal{F} \cap X^n \subseteq Y^n$  by induction hypothesis. Then  $\text{lfp } \mathcal{F} \cap X^{n+1} = \text{lfp } \mathcal{F} \cap \mathcal{B}(X^n) = \text{lfp } \mathcal{F} \cap (\text{pre}[\tau]X^n \cup F) = \text{lfp } \mathcal{F} \cap ((\text{pre}[\tau]X^n \cap \text{lfp } \mathcal{F}) \cup F)$ , which, by (16), is included in  $\text{lfp } \mathcal{F} \cap (\text{pre}[\tau](X^n \cap \text{lfp } \mathcal{F}) \cup F)$  which, by induction hypothesis and monotony, is included in  $\text{lfp } \mathcal{F} \cap (\text{pre}[\tau](Y^n) \cup F) = \text{lfp } \mathcal{F} \cap \mathcal{B}Y^n = Y^{n+1}$ . It follows that  $\text{lfp } \mathcal{F} \cap \text{lfp } \mathcal{B} = (\cup_{n \in \mathbb{N}} X^n) \cap \text{lfp } \mathcal{F} = \cup_{n \in \mathbb{N}} (X^n \cap \text{lfp } \mathcal{F}) \subseteq \cup_{n \in \mathbb{N}} Y^n = \text{lfp } \lambda X . (\text{lfp } \mathcal{F} \cap \mathcal{B}(X))$ . But  $\text{lfp}$  is monotone so that  $\text{lfp } \lambda X . (\text{lfp } \mathcal{F} \cap \mathcal{B}(X)) \subseteq \text{lfp } \lambda X . (\text{lfp } \mathcal{F}) \cap \text{lfp } \lambda X . (\mathcal{B}(X)) = \text{lfp } \mathcal{F} \cap \text{lfp } \mathcal{B}$ . Equality follows by antisymmetry. The proofs of (20) to (22) are similar. □



Let us recall the following fixpoint approximation result:

**THEOREM.** If  $P(\preceq, f, t, \wedge, \vee)$  is a complete lattice,  $F$ ,  $\bar{F} \in P(\preceq) \xrightarrow{m} P(\preceq)$ , and  $F \preceq \bar{F}$ , then  $\text{lfp } F \preceq \text{lfp } \bar{F}$ . ■

**PROOF.** We have  $F(\text{lfp } \bar{F}) \preceq \bar{F}(\text{lfp } \bar{F}) = \text{lfp } \bar{F}$  whence  $\text{lfp } F \preceq \text{lfp } \bar{F}$  since  $\text{lfp } F = \bigwedge \{X \mid F(X) \preceq X\}$  by Tarski's fixpoint theorem. □

as well as fixpoint abstraction:

**THEOREM.** If  $P(\preceq, f, t, \wedge, \vee)$  and  $P^\#(\preceq^\#, f^\#, t^\#, \wedge^\#, \vee^\#)$  are complete lattices,  $P(\preceq) \xrightleftharpoons[\alpha]{\gamma} P^\#(\preceq^\#)$  and  $F \in P(\preceq) \xrightarrow{m} P(\preceq)$ , then  $\alpha(\text{lfp } F) \preceq^\# \text{lfp } \alpha \circ F \circ \gamma$ . ■



PROOF. By Tarski's fixpoint theorem, the least fixpoints exist. So let  $p^\# = \text{lfp } \alpha \circ F \circ \gamma$ . We have  $\alpha \circ F \circ \gamma(p^\#) = p^\#$  whence  $F \circ \gamma(p^\#) \preceq p^\#$  by def. Galois connection. It follows that  $\gamma(p^\#)$  is a postfixpoint of  $F$  whence  $\text{lfp } F \preceq \gamma(p^\#)$  by Tarski's fixpoint theorem or equivalently  $\alpha(\text{lfp } F) \preceq^\# p^\# = \text{lfp } \alpha \circ F \circ \gamma$ .  $\square$

- In order to approximate  $\text{lfp } F \wedge \text{lfp } B$  from above using abstract interpretations  $F^\#$  of  $F$  and  $B^\#$  of  $B$ , we can use the abstract upper approximation  $\text{lfp } F^\# \wedge^\# \text{lfp } B^\#$ .
- However, a better approximation suggested in [2] can be obtained as the limit of the decreasing chain



$$\begin{aligned} \dot{X}^0 &= \text{lfp } F^\# \\ \dot{X}^{2n+1} &= \text{lfp } \lambda X . \dot{X}^{2n} \wedge^\# F^\#(X) \\ \dot{X}^{2n+2} &= \text{lfp } \lambda X . \dot{X}^{2n+1} \wedge^\# B^\#(X) \end{aligned}$$

for all  $n \in \mathbb{N}$ .

- Observe that by theorem on page 117 there is no improvement when considering the exact collecting semantics.
- However, when considering approximations of the collecting semantics, not all information can be collected in one pass and iteration can lead definite improvement



- If the abstract lattice does not satisfy the descending chain condition then [2] also suggests to use a narrowing operator  $\Delta$  to enforce convergence of the downward iteration  $\dot{X}^k, k \in \mathbb{N}$ .
- The same way a widening/narrowing approach can be used to enforce convergence of the iterates for  $\lambda X . \dot{X}^{2n} \wedge^\# F^\#(X)$  and  $\lambda X . \dot{X}^{2n+1} \wedge^\# B^\#(X)$ .
- The correctness of this approach follows from the following result on fixpoint meet approximation:



**THEOREM.** If  $P(\preceq, f, t, \wedge, \vee)$  and  $P^\#(\preceq^\#, f^\#, t^\#, \wedge^\#, \vee^\#)$  are complete lattices,  $P(\preceq) \xrightleftharpoons[\gamma]{\alpha} P^\#(\preceq^\#)$ ,  $F \in P(\preceq) \xrightarrow{m} P(\preceq)$  and  $B \in P(\preceq) \xrightarrow{m} P(\preceq)$  satisfy hypotheses (21) and (22) of theorem ,  $F^\# \in P^\#(\preceq^\#) \xrightarrow{m} P^\#(\preceq^\#)$ ,  $B^\# \in P^\#(\preceq^\#) \xrightarrow{m} P^\#(\preceq^\#)$ ,  $\alpha \circ F \circ \gamma \preceq^\# F^\#$ ,  $\alpha \circ B \circ \gamma \preceq^\# B^\#$ ,  $\dot{X}^0$  is  $\text{lfp } F^\#$  or  $\text{lfp } B^\#$  and for all  $n \in \mathbb{N}$ ,  $\dot{X}^{2n+1} = \text{lfp } \lambda X . (\dot{X}^{2n} \wedge^\# B^\#(X))$  and  $\dot{X}^{2n+2} = \text{lfp } \lambda X . (\dot{X}^{2n+1} \wedge^\# F^\#(X))$  then  $\forall k \in \mathbb{N} : \alpha(\text{lfp } F \wedge \text{lfp } B) \preceq^\# \dot{X}^{k+1} \preceq^\# \dot{X}^k$ . ■

**PROOF.** Observe that by the fixpoint property,  $\dot{X}^{2n+1} = \dot{X}^{2n} \wedge^\# B^\#(\dot{X}^{2n+1})$  and  $\dot{X}^{2n+2} = \dot{X}^{2n+1} \wedge^\# F^\#(\dot{X}^{2n+2})$ , hence  $\dot{X}^{2n} \preceq^\# \dot{X}^{2n+1} \preceq^\# \dot{X}^{2n+2}$  since  $\wedge^\#$  is the greatest lower bound for  $\preceq^\#$  so that  $\dot{X}^k, k \in \mathbb{N}$  is a decreasing chain.



We have  $\alpha(\text{lfp } F \wedge \text{lfp } B) \preceq^\# \alpha(\text{lfp } F)$  since  $\alpha$  is monotone and  $\alpha(\text{lfp } F) \preceq^\# \text{lfp } F^\#$  by theorems on pages 120 and 120, thus proving the proposition for  $k = 0$ . Let us observe that  $\alpha \circ F \circ \gamma \preceq^\# F^\#$  implies  $F \circ \gamma \preceq \gamma \circ F^\#$  by def. Galois connection so that in particular for an argument of the form  $\alpha(X)$ ,  $F \circ \gamma \circ \alpha \preceq \gamma \circ F^\# \circ \alpha$ .  $\gamma \circ \alpha$  is extensive so that by monotony and transitivity  $F \preceq \gamma \circ F^\# \circ \alpha$ . Assume now by induction hypothesis that  $\alpha(\text{lfp } F \wedge \text{lfp } B) \preceq^\# \dot{X}^{2n}$ , whence  $\text{lfp } F \wedge \text{lfp } B \preceq^\# \gamma(\dot{X}^{2n})$  by def. Galois connection. Since  $F \preceq \gamma \circ F^\# \circ \alpha$ , it follows that  $\lambda X \cdot \text{lfp } F \wedge \text{lfp } B \wedge F(X) \preceq^\# \lambda X \cdot \gamma(\dot{X}^{2n}) \wedge \gamma \circ F^\# \circ \alpha(X) = \lambda X \cdot \gamma(\dot{X}^{2n} \wedge F^\# \circ \alpha(X))$  since  $\gamma$  is a complete meet morphism. Now by hypothesis (21) of theorem, we have  $\text{lfp } F \wedge \text{lfp } B = \text{lfp } \lambda X \cdot (\text{lfp } F \wedge \text{lfp } B \wedge F(X)) \preceq^\# \text{lfp } \lambda X \cdot \gamma(\dot{X}^{2n} \wedge F^\# \circ \alpha(X))$  by theorem on page 120. Let  $G$  be  $\lambda X \cdot \dot{X}^{2n} \wedge F^\#(X)$ .  $\alpha \circ \gamma$  is reductive so that by monotony  $G \circ \alpha \circ \gamma \preceq^\# G$  and  $\alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\# G \circ \alpha \circ \gamma$ , whence, by transitivity,  $\alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\# G$ . By the theorem on page 120 we have  $\alpha(\text{lfp } \gamma \circ G \circ \alpha) \preceq^\# \text{lfp } \alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\# \text{lfp } G$  by theorem on page 120. Hence,  $\text{lfp } \lambda X \cdot \gamma(\dot{X}^{2n} \wedge F^\# \circ \alpha(X)) \preceq \gamma(\text{lfp } \lambda X \cdot \dot{X}^{2n} \wedge F^\#(X))$  so that by transitivity we conclude that  $\alpha(\text{lfp } F \wedge \text{lfp } B) \preceq^\# \dot{X}^{2n+1}$ . The proof that  $\alpha(\text{lfp } F \wedge \text{lfp } B) \preceq^\# \dot{X}^{2n+2}$  is similar using hypothesis (22) of theorem.  $\square$



```

{1} i:=n;
{2} L:
{3}   si i>0 alors
{4}     j:=0;
{5}   M:
{6}   si j>i alors
{7}     i:=i-1;
{8}   sllera L,
{9}   finsi;
{10}  j:=j+1;
{11}  sllera M;
{12}  finsi;

```

- The analysis in [2] is not structural but equational and so the forward system of equations is:



## Example

- Let us consider the original example given in [2], with interval analysis, so that a widening/narrowing is required:

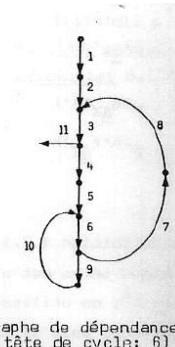
$$\begin{aligned}
 P^1 &\equiv \text{lfp}(\bar{F}(\bar{\phi})) \\
 P^2 &= P^1 \Delta x^2 \\
 \dots \\
 P^{2k+1} &= P^{2k} \Delta x^{2k+1} \\
 P^{2k+2} &= P^{2k+1} \Delta x^{2k+2}
 \end{aligned}
 \quad \text{ou } x^2 \equiv \text{lfp}(\lambda x. P^1 \cap \bar{B}(\bar{\Psi})(x))$$

$$\begin{aligned}
 \dots \\
 \text{ou } x^{2k+1} &\equiv \text{lfp}(\lambda x. P^{2k} \cap \bar{F}(\bar{\phi})(x)) \\
 \text{ou } x^{2k+2} &\equiv \text{lfp}(\lambda x. P^{2k+1} \cap \bar{B}(\bar{\phi})(x))
 \end{aligned}$$

- We illustrate on bubble sort [Z. Manna, 1974, p. 191]



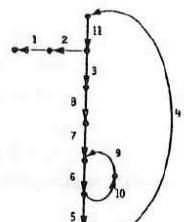
$$\begin{cases}
 P_1 = \bar{\phi} \\
 P_2 = P_1(i+n) \\
 P_3 = P_2 \sqcup P_8 \\
 P_4 = P_3(i + i \neq 0) \\
 P_5 = P_4(j + [0,0]) \\
 P_6 = P_5 \sqcup P_{10} \\
 P_7 = P_6(i + i \sqcap j, j + i \sqcap j) \\
 P_8 = P_7(i + i - 1) \\
 P_9 = P_6(i + i \neq j, j + i \neq j) \\
 P_{10} = P_9(j + j + 1) \\
 P_{11} = P_3(i + i \sqcap [0,0])
 \end{cases}$$



- The backward system of equations is:



$$\left\{ \begin{array}{l} P_1 = P_2 (i + [-\infty, +\infty], n + 1) \\ P_2 = P_3 \\ P_3 = P_{11} \cup P_4 \\ P_4 = P_5 (j + [-\infty, +\infty]) \\ P_5 = P_6 \\ P_6 = P_7 \cup P_9 \\ P_7 = P_8 (i + i + 1) \\ P_8 = P_3 \\ P_9 = P_{10} (j + j - 1) \\ P_{10} = P_6 \\ P_{11} = \overline{\Psi} \end{array} \right.$$



Graphe de dépendance  
(tête de cycle: 6)

- The considered program specification is:

$$\begin{aligned}\overline{\phi} &= \{(i=1), (j=1), (n=[-\infty, +\infty])\} \\ \overline{\Psi} &= \{(i=[-\infty, +\infty]), (j=[-\infty, +\infty]), (n=[-\infty, +\infty])\}\end{aligned}$$



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Since  $i$  is decremented by 1 in the loop which ends with  $i = 0$ ,  $i$  must necessarily be positive on loop entry, so  $n$  must be initially positive

- The third iteration is:

$$P^3 = P^2 \Delta X^3 \quad \text{où } X^3 \models \text{lfp}(\lambda X. P^2 \sqcap \overline{B}(\overline{\Psi})(X))$$

1	2	3	4	5	6	7	8	9	10	11
$i$	$\perp$	$[0, +\infty] [0, +\infty] [1, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [0, 0]$	$j$	$\perp$	$[1, +\infty] [1, +\infty] [0, 0] [0, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [1, +\infty]$	$n$	$[0, +\infty] [0, +\infty]$			

This propagates forward the information on  $n$

- The next iteration shows that a fixpoint is reached



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- The first forward iteration is:

$$P^1 \models \text{lfp}(\overline{F}(\overline{\phi}))$$

$$\begin{array}{cccccccccccc} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 \\ i & \perp & [-\infty, +\infty] [-\infty, +\infty] [-\infty, +\infty] [-\infty, +\infty] [0, +\infty] [-1, +\infty] [-\infty, +\infty] [-\infty, +\infty] [0, 0] \\ j & \perp & \perp & [0, +\infty] [0, +\infty] [0, 0] [0, +\infty] \\ n & [-\infty, +\infty] \end{array}$$

It is discovered that  $j$  being initialized to 0 and incremented, it should be positive.

- The second iteration is:

$$P^2 = P^1 \Delta X^2 \quad \text{où } X^2 \models \text{lfp}(\lambda X. P^1 \sqcap \overline{B}(\overline{\Psi})(X))$$

$$\begin{array}{cccccccccccc} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 \\ i & \perp & [0, +\infty] [0, +\infty] [1, +\infty] [1, +\infty] [1, +\infty] [0, +\infty] [1, +\infty] [1, +\infty] [0, 0] \\ j & \perp & \perp & [0, +\infty] \\ n & [0, +\infty] [-\infty, +\infty] \end{array}$$



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- The analysis proves that if  $n$  is initially negative then the program execution either terminates by an error or does not terminate

- By propagating forward the invariants, one determines where execution tests have to be placed
- With polyhedral analysis, the result is the following:

```
Generic-FW-BW-REL-Abstract-Interpreter % cat ./Examples/example30.sil
i := n;
while (i <> 1) do
  j := 0;
  while(j <> i) do
    j := j + 1
  od;
  i := i - 1
od;;
```



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```

Generic-FW-BW-REL-Abstract-Interpreter % ./a.out ..//Examples/example30.sil
** Precondition:
{i>=0}
** Postcondition:
{i=1,n>=1}
unstable precondition after 1 iteration(s).
** Precondition:
{n>=1}
** Postcondition:
{i=1,n>=1}
stable precondition after 2 iteration(s).

```



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## Optimality

**Lemma 1** Let  $P^b(\sqsubseteq^b, \sqcup^b, \top^b, \sqcap^b, \sqsupseteq^b)$  and  $P^\sharp(\sqsubseteq^\sharp, \sqcup^\sharp, \top^\sharp, \sqcap^\sharp, \sqsupseteq^\sharp)$  be complete lattices with a Galois connection  $P^b \xrightarrow[\alpha]{\gamma} P^\sharp$ ,  $F^b \in P^b \rightarrow P^b$  and  $B^b \in P^b \rightarrow P^b$  be two monotonic functions, and let

$$L^b = \text{gfp } \lambda Z. (Z \sqcap^b F^b(Z) \sqcap^b B^b(Z))$$

If  $F^\sharp \in P^\sharp \rightarrow P^\sharp$  and  $B^\sharp \in P^\sharp \rightarrow P^\sharp$  are monotonic and satisfy  $\alpha \circ F^b \circ \gamma \sqsubseteq^\sharp F^\sharp$  and  $\alpha \circ B^b \circ \gamma \sqsubseteq^\sharp B^\sharp$ , then the sequence  $(X_n)_{n \in N}$  defined by  $X_0 = \top^\sharp$ ,  $X_{2n+1} = X_{2n} \sqcap^\sharp F^\sharp(X_{2n})$ , and  $X_{2n+2} = X_{2n+1} \sqcap^\sharp B^\sharp(X_{2n+1})$ ,  $\forall n \geq 0$  is such that:

$$\forall n \geq 0, \alpha(L^b) \sqsubseteq^\sharp X_{n+1} \sqsubseteq^\sharp X_n$$

The optimality of this approach has been proved in [1]: it has been shown that  $L^b = \text{gfp } \lambda Z. (Z \sqcap^\sharp F^\sharp(Z) \sqcap^\sharp B^\sharp(Z))$  is the greatest lower bound of the set  $E^\sharp$  defined inductively as:

- $\top^\sharp \in E^\sharp$
- If  $Z$  is in  $E^\sharp$  then so are  $F^\sharp(Z)$  and  $B^\sharp(Z)$ .
- If  $Z_1$  and  $Z_2$  are in  $E^\sharp$  then so are  $Z_1 \sqcap^\sharp Z_2$  and  $Z_1 \sqcup^\sharp Z_2$ .

Therefore,  $L^\sharp$  is the best upper approximation of  $\alpha(L^b)$  that can be obtained using  $F^\sharp$  and  $B^\sharp$ .



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## Standard backward-forward combination

The standard backward-forward combination [4] derives from an application of this lemma to the particular case of backward and forward collecting semantics:

$F^b$ ,  $B^b$ ,  $F^\sharp$  and  $B^\sharp$  are instantiated as follows:

$$F^b = \lambda Y. \text{lgfp}_1 \lambda X. (Y \sqcap^b f^b(X))$$

$$B^b = \lambda Y. \text{lgfp}_2 \lambda X. (Y \sqcap^b b^b(X))$$

$$F^\sharp = \lambda Y. \text{lgfp}_1 \lambda X. (Y \sqcap^\sharp f^\sharp(X))$$

$$B^\sharp = \lambda Y. \text{lgfp}_2 \lambda X. (Y \sqcap^\sharp b^\sharp(X))$$

where lgfp means either lfp or gfp, and  $f^b, b^b \in P^b \rightarrow P^b$ ,  $f^\sharp, b^\sharp \in P^\sharp \rightarrow P^\sharp$  are monotonic. When  $\alpha \circ f^b \circ \gamma \sqsubseteq^\sharp f^\sharp$  and  $\alpha \circ b^b \circ \gamma \sqsubseteq^\sharp b^\sharp$ , the conditions of Lemma 1 are satisfied [7].



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Now, let  $P^b = \wp(\Sigma)$ ,  $\Sigma$  a set of states<sup>3</sup>, and  $\tau \in \wp(\Sigma \times \Sigma)$  a transition relation. As usual, we define  $\text{pre}$ ,  $\widetilde{\text{pre}}$ ,  $\text{post}$ ,  $\widetilde{\text{post}}$  as:

$$\text{post}(X) = \{s' \mid \exists s : \langle s, s' \rangle \in \tau \wedge s \in X\}$$

$$\widetilde{\text{post}}(X) = \{s' \mid \forall s : \langle s, s' \rangle \in \tau \Rightarrow s \in X\}$$

$$\text{pre}(X) = \{s \mid \exists s' : \langle s, s' \rangle \in \tau \wedge s' \in X\}$$

$$\widetilde{\text{pre}}(X) = \{s \mid \forall s' : \langle s, s' \rangle \in \tau \Rightarrow s' \in X\}$$

Given  $\mathcal{I}, \mathcal{F} \subseteq \Sigma$ , sets of initial and final states,  $f^b = \lambda X. (\mathcal{I} \cup \text{post}(X))$  and  $b^b = \lambda X. (\mathcal{F} \cup \text{pre}(X))$  (and  $\text{lgfp}_1 = \text{lgfp}_2 = \text{lfp}$ ), we have [4]:

$$L^b = F^b(\top^b) \sqcap^b B^b(\top^b) = \text{lfp } f^b \cap \text{lfp } b^b \quad (1)$$

By computing  $\gamma(L^\sharp)$ <sup>4</sup>, we obtain a good upper approximation of  $F^b(\Sigma) \cap B^b(\Sigma)$  (at least equal to  $\gamma(F^\sharp(\top^\sharp) \sqcap^\sharp B^\sharp(\top^\sharp))$ ).



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## The ASTRÉE static analyzer



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ASTRÉE: A Sound, Automatic, Specializable,  
Domain-Aware, Parametric, Modular, Efficient and  
Precise Static Program Analyzer

[www.astree.ens.fr](http://www.astree.ens.fr)

### – C programs:

#### - with

- pointers (including on functions), structures and arrays
- floating point computations
- tests, loops and function calls
- limited branching (forward goto, break, continue)



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#### – without

- union
- dynamic memory allocation
- recursive function calls
- backward branching
- conflict side effects
- C libraries

– **Application Domain:** safety critical embedded real-time synchronous software for non-linear control of very complex control/command systems.



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## Concrete Operational Semantics

- International **norm of C** (ISO/IEC 9899:1999)
- *restricted by implementation-specific behaviors* depending upon the machine and compiler (e.g. representation and size of integers, IEEE 754-1985 norm for floats and doubles)
- *restricted by user-defined programming guidelines* (such as no modular arithmetic for signed integers, even though this might be the hardware choice)
- *restricted by program specific user requirements* (e.g. assert)



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## Abstract Semantics

- Trace-based refinement of the **reachable states** for the concrete operational semantics
- **Volatile environment** is specified by a *trusted* configuration file.



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## Example application

- Primary flight control software of the A340/A380 fly-by-wire system



- C program, automatically generated from a proprietary high-level specification (à la Simulink/SCADE)
- A340 family: 132,000 lines, **75,000 LOCs** after pre-processing, **10,000 global variables**, over **21,000** after expansion of small arrays
- A380: × 3



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## Implicit Specification: Absence of Runtime Errors

- No violation of the **norm of C** (e.g. array index out of bounds)
- **No implementation-specific undefined behaviors** (e.g. maximum short integer is 32767)
- **No violation of the programming guidelines** (e.g. static variables cannot be assumed to be initialized to 0)
- **No violation of the programmer assertions** (must all be statically verified).



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## The Class of Considered Periodic Synchronous Programs

- ```
declare volatile input, state and output variables;
initialize state and output variables;
loop forever
    - read volatile input variables,
    - compute output and state variables,
    - write to volatile output variables;
    wait_for_clock ();
end loop
```
- **Requirements:** the only interrupts are **clock ticks**;
  - **Execution time of loop body less than a clock tick [1]**.

---

### Reference

[1] C. Ferdinand, R. Heckmann, M. Langenbach, F. Martin, M. Schmidt, H. Theiling, S. Thesing, and R. Wilhelm. Reliable and precise WCET determination for a real-life processor. *ESOP (2001)*, LNCS 2211, 469–485.



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## Characteristics of the ASTRÉE Analyzer

**Static:** compile time analysis ( $\neq$  run time analysis Rational Purify, Parasoft Insure++)

**Program Analyzer:** analyzes programs not micromodels of programs ( $\neq$  PROMELA in SPIN or Alloy in the Alloy Analyzer)

**Automatic:** no end-user intervention needed ( $\neq$  ESC Java, ESC Java 2)

**Sound:** covers the whole state space ( $\neq$  MAGIC, CBMC) so never omit potential errors ( $\neq$  UNO, CMC from coverity.com) or sort most probable ones ( $\neq$  Splint)



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## Characteristics of the ASTRÉE Analyzer (Cont'd)

**Multiabstraction:** uses many numerical/symbolic abstract domains ( $\neq$  symbolic constraints in Bane or the canonical abstraction of TVLA)

**Infinitary:** all abstractions use infinite abstract domains with widening/narrowing ( $\neq$  model checking based analyzers such as VeriSoft, Bandera, Java PathFinder)

**Efficient:** always terminate ( $\neq$  counterexample-driven automatic abstraction refinement BLAST, SLAM)



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## Characteristics of the ASTRÉE Analyzer (Cont'd)

**Specializable:** can easily incorporate new abstractions (and reduction with already existing abstract domains) ( $\neq$  general-purpose analyzers PolySpace Verifier)

**Domain-Aware:** knows about control/command (e.g. digital filters) (as opposed to specialization to a mere programming style in C Global Surveyor)

**Parametric:** the precision/cost can be tailored to user needs by options and directives in the code



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## Characteristics of the ASTRÉE Analyzer (Cont'd)

**Automatic Parametrization:** the generation of parametric directives in the code can be programmed (to be specialized for a specific application domain)

**Modular:** an analyzer instance is built by selection of OCAML modules from a collection each implementing an abstract domain

**Precise:** very few or no false alarm when adapted to an application domain → it is a **VERIFIER!**



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## Example of Analysis Session

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Benchmarks (A340 Primary Flight Control Software)

- 132,000 lines, 75,000 LOCs after preprocessing
  - Comparative results (commercial software):  
4,200 (false?) alarms,  
3.5 days;
  - Our results, November 2003:  
0 alarms,  
40mn on 2.8 GHz PC,  
300 Megabytes  
→ A world première!

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(A380 Primary Flight Control Software)

- 350,000 lines
  - 0 alarms (mid-October 2004!),  
7h<sup>2</sup> on 2.8 GHz PC,  
1 Gigabyte

---

<sup>2</sup> We are still in a phase where we favour precision rather than computation costs, and this should go down. For example, the A340 analysis went up to 5 h, before being reduced by requiring less precision while still getting no false alarm.

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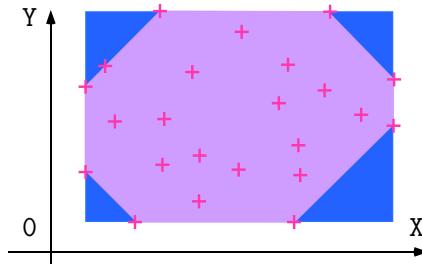
## Examples of Abstractions

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## General-Purpose Abstract Domains: Intervals and Octagons



Intervals:

$$\begin{cases} 1 \leq x \leq 9 \\ 1 \leq y \leq 20 \end{cases}$$

Octagons:

$$\begin{cases} 1 \leq x \leq 9 \\ x + y \leq 77 \\ 1 \leq y \leq 20 \\ x - y \leq 04 \end{cases}$$

**Difficulties:** many global variables, arrays (smashed or not), IEEE 754 floating-point arithmetic (in program and analyzer)



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## Floating-Point Computations

### Code Sample:

```
/* float-error.c */
int main () {
    float x, y, z, r;
    x = 1.000000019e+38;
    y = x + 1.0e21;
    z = x - 1.0e21;
    r = y - z;
    printf("%f\n", r);
} % gcc float-error.c
% ./a.out
0.000000
```

$$(x + a) - (x - a) \neq 2a$$

```
/* double-error.c */
int main () {
    double x; float y, z, r;
    /* x = ldexp(1.,50)+ldexp(1.,26); */
    x = 1125899973951487.0;
    y = x + 1;
    z = x - 1;
    r = y - z;
    printf("%f\n", r);
} % gcc double-error.c
% ./a.out
0.000000
```



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## Floating-Point Computations

### Code Sample:

```
/* float-error.c */
int main () {
    float x, y, z, r;
    x = 1.000000019e+38;
    y = x + 1.0e21;
    z = x - 1.0e21;
    r = y - z;
    printf("%f\n", r);
} % gcc float-error.c
% ./a.out
0.000000
```

$$(x + a) - (x - a) \neq 2a$$

```
/* double-error.c */
int main () {
    double x; float y, z, r;
    /* x = ldexp(1.,50)+ldexp(1.,26); */
    x = 1125899973951488.0;
    y = x + 1;
    z = x - 1;
    r = y - z;
    printf("%f\n", r);
} % gcc double-error.c
% ./a.out
134217728.000000
```



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## Symbolic abstract domain

- Interval analysis: if  $x \in [a, b]$ ,  $y \in [c, d]$  &  $a, c \geq 0$  then  $x - y \in [a - d, b - c]$  so if  $x \in [0, 100]$  then  $x - x \in [-100, 100]!!!$
- The symbolic abstract domain propagates the symbolic values of variables and performs simplifications;
- Must maintain the maximal possible rounding error for float computations (overestimated with intervals);

```
% cat -n x-x.c
1 void main () { int X, Y;
2     __ASTREE_known_fact(((0 <= X) && (X <= 100)));
3     Y = (X - X);
4     __ASTREE_log_vars((Y)); }
astree -exec-fn main -no-relational x-x.c
Call main@x-x.c:1:5-x-x.c:1:9:
<interval: Y in [-100, 100]>
astree -exec-fn main x-x.c
Call main@x-x.c:1:5-x-x.c:1:9:
<interval: Y in {}> <symbolic: Y = (X - i X)>
```



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## Clock Abstract Domain for Counters

### - Code Sample:

```
R = 0;
while (1) {
    if (I)
        { R = R+1; }
    else
        { R = 0; }
    T = (R>=n);
    wait_for_clock ();
}
```

- Output T is true iff the volatile input I has been true for the last n clock ticks.
- The clock ticks every s seconds for at most h hours, thus R is bounded.
- To prove that R cannot overflow, we must prove that R cannot exceed the elapsed clock ticks (impossible using only intervals).

### - Solution:

- We add a phantom variable `clock` in the concrete user semantics to track elapsed clock ticks.
- For each variable X, we abstract three intervals: `X`, `X+clock`, and `X-clock`.
- If `X+clock` or `X-clock` is bounded, so is X.



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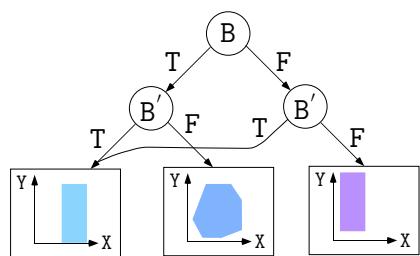
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## Boolean Relations for Boolean Control

### - Code Sample:

```
/* boolean.c */
typedef enum {F=0,T=1} BOOL;
BOOL B;
void main () {
    unsigned int X, Y;
    while (1) {
        ...
        B = (X == 0);
        ...
        if (!B) {
            Y = 1 / X;
        }
        ...
    }
}
```



The boolean relation abstract domain is parameterized by the height of the decision tree (an analyzer option) and the abstract domain at the leafs



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## Control Partitionning for Case Analysis

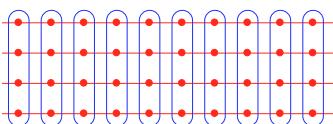
### - Code Sample:

```
/* trace_partitionning.c */
void main() {
    float t[5] = {-10.0, -10.0, 0.0, 10.0, 10.0};
    float c[4] = {0.0, 2.0, 2.0, 0.0};
    float d[4] = {-20.0, -20.0, 0.0, 20.0};
    float x, r;
    int i = 0;

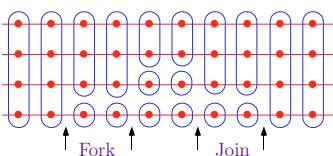
    ... found invariant -100 ≤ x ≤ 100 ...

    while ((i < 3) && (x >= t[i+1])) {
        i = i + 1;
    }
    r = (x - t[i]) * c[i] + d[i];
}
```

Control point partitionning:



Trace partitionning:



Delaying abstract unions in tests and loops is more precise for non-distributive abstract domains (and much less expensive than disjunctive completion).

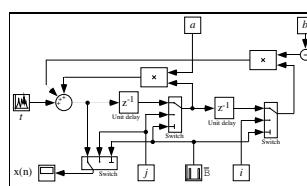


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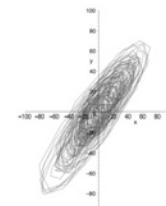
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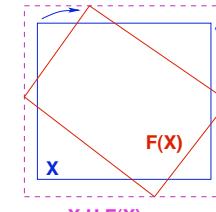
## 2<sup>d</sup> Order Digital Filter: Ellipsoid Abstract Domain for Filters



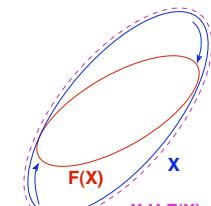
- Computes  $X_n = \begin{cases} \alpha X_{n-1} + \beta X_{n-2} + Y_n \\ I_n \end{cases}$
- The concrete computation is bounded, which must be proved in the abstract.
- There is no stable interval or octagon.
- The simplest stable surface is an ellipsoid.



execution trace



unstable interval



stable ellipsoid



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```

typedef enum {FALSE = 0, TRUE = 1} BOOLEAN;
BOOLEAN INIT; float P, X;
void filter () {
    static float E[2], S[2];
    if (INIT) { S[0] = X; P = X; E[0] = X; }
    else { P = (((0.5 * X) - (E[0] * 0.7)) + (E[1] * 0.4))
           + (S[0] * 1.5)) - (S[1] * 0.7); }
    E[1] = E[0]; E[0] = X; S[1] = S[0]; S[0] = P;
    /* S[0], S[1] in [-1327.02698354, 1327.02698354] */
}
void main () { X = 0.2 * X + 5; INIT = TRUE;
    while (1) {
        X = 0.9 * X + 35; /* simulated filter input */
        filter (); INIT = FALSE; }
}

```



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## Filter Example

## (Automatic) Parameterization

- All abstract domains of ASTRÉE are [parameterized](#), e.g.
  - variable packing for octagones and decision trees,
  - partition/merge program points,
  - loop unrollings,
  - thresholds in widenings, ...;
- End-users can either [parameterize by hand](#) (analyzer options, directives in the code), or
- choose the [automatic parameterization](#) (default options, directives for pattern-matched predefined program schemata).



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## Arithmetic-Geometric Progressions

```

% cat retro.c
typedef enum {FALSE=0, TRUE=1} BOOL;
BOOL FIRST;
volatile BOOL SWITCH;
volatile float E;
float P, X, A, B;

void dev()
{ X=E;
  if (FIRST) { P = X; }
  else
    { P = (P - (((2.0 * P) - A) - B)
           * 4.491048e-03); }
  B = A;
  if (SWITCH) {A = P;}
  else {A = X; }
}

void main()
{ FIRST = TRUE;
  while (TRUE) {
    dev();
    FIRST = FALSE;
    __ASTREE_wait_for_clock(); }

    % cat retro.config
    __ASTREE_volatile_input((E [-15.0, 15.0]));
    __ASTREE_volatile_input((SWITCH [0,1]));
    __ASTREE_max_clock((3600000));
    |P| <= (15. + 5.87747175411e-39
             / 1.19209290217e-07) * (1 +
             1.19209290217e-07)^clock -
             5.87747175411e-39 / 1.19209290217e-07
             <= 23.0393526881
}

```



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## The main loop invariant for the A340

A textual file over 4.5 Mb with

- 6,900 boolean interval assertions ( $x \in [0; 1]$ )
- 9,600 interval assertions ( $x \in [a; b]$ )
- 25,400 clock assertions ( $x+clk \in [a; b] \wedge x-clk \in [a; b]$ )
- 19,100 additive octagonal assertions ( $a \leq x + y \leq b$ )
- 19,200 subtractive octagonal assertions ( $a \leq x - y \leq b$ )
- 100 decision trees
- 60 ellipse invariants, etc ...

involving over 16,000 floating point constants (only 550 appearing in the program text)  $\times$  75,000 LOCs.



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## Possible origins of imprecision and how to fix it

In case of false alarm, the imprecision can come from:

- **Abstract transformers** (not best possible) → improve algorithm;
- **Automatized parametrization** (e.g. variable packing) → improve pattern-matched program schemata;
- **Iteration strategy** for fixpoints → fix widening<sup>3</sup>;
- **Inexpressivity** i.e. indispensable local inductive invariant are inexpressible in the abstract → add a **new abstract domain** to the reduced product (e.g. filters).

<sup>3</sup> This can be very hard since at the limit only a precise infinite iteration might be able to compute the proper abstract invariant. In that case, it might be better to design a more refined abstract domain.

## THE END

My MIT web site is <http://www.mit.edu/~cousot/>

The course web site is <http://web.mit.edu/afs/athena.mit.edu/course/16/16.399/www/>.



## Bibliography

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- [3] P. Cousot and R. Cousot. Abstract interpretation and application to logic programs. *Journal of Logic Programming*, 13(2–3):103–179, 1992.<sup>4</sup>
- [4] [www.astree.ens.fr/](http://www.astree.ens.fr/)

<sup>4</sup> The editor of JLP has mistakenly published the unreadable galley proof. For a correct version of this paper, see <http://www.ens.fr/~cousot>.