

Problems on Subspaces and Linear Operators

1. Suppose $T \in \mathcal{L}(V)$ and U is a subspace of V . a) Prove that $U \subseteq \text{null } T$, then U is invariant under T . b) Prove that if $\text{range } T \subseteq U$, then U is invariant under T . **Solution:** a) Suppose $u \in U \subseteq \text{null } T$: Then $T(u) = 0$, but $0 \in U$. b) Suppose $u \in U$. If $U \supseteq \text{range } T$, then because $T(u) \in \text{range } T \subseteq U$, we have $T(u) \in U$.

2. Suppose that $T \in \mathcal{L}(V)$ and V_1, \dots, V_m are subspaces of V invariant under T . Prove that $V_1 + \dots + V_m$ is invariant under T . **Solution:** Suppose $u \in V_1 + \dots + V_m$: Then $u = v_1 + \dots + v_m$ with $v_k \in V_k$ and so

$$T(u) = T(v_1 + \dots + v_m) = T(v_1) + \dots + T(v_m)$$

but $T(v_k) \in V_k$ because they are invariant, and therefore $T(u) \in V_1 + \dots + V_m$, and $V_1 + \dots + V_m$ is invariant.

3. Suppose $T \in \mathcal{L}(V)$. Prove that the intersection of every collection of subspaces of V invariant under T is invariant under T . **Solution:** Suppose $u \in \bigcap_{i \in I} V_i$ with V_i invariant under T , then $Tu \in \bigcap_{i \in I} \text{range}(T|_{V_i})$. Because V_i is invariant under T : $\text{range}(T|_{V_i}) \subseteq V_i$ for all $i \in I$ and so

$$Tu \in \bigcap_{i \in I} V_i$$

4. Prove or give a counterexample: If V is finite-dimensional and U is a subspace of V that is invariant under every operator on V , then $U = \{0\}$ or $U = V$. **Solution:** Suppose there exist a subspace U that is invariant under T for all $T \in \mathcal{L}(V)$ but $U \neq \{0\}$ and $U \neq V$. Then there exists a $u \in U$ with $u \neq 0$ and a $v \in V \setminus U$. Then there exists an operator T with $T(u) = v$ and $T(w) = 0$ for the other basis vectors $\{u, w_1, \dots, w_{m-1}\}$ of V , and $m = \dim V$. This operator is well defined, but U is of course not invariant to this T , in contradiction to our hypothesis. Therefore no such subspace exists.

5. Suppose $T \in \mathcal{L}(\mathbb{R}^2)$ is defined by $T(x, y) = (-3y, x)$. Find the eigenvalues of T . **Solution:**

$$\begin{aligned} (-3y, x) &= \lambda(x, y) \implies -3y = \lambda x \text{ and } x = \lambda y \\ &\implies -3y = \lambda(\lambda y) = \lambda^2 y \implies -3 = \lambda^2 \end{aligned}$$

This operator has no real eigenvalues.

6. Define $T \in \mathcal{L}(\mathbb{F}^2)$ by $T(w, z) = (z, w)$. Find all eigenvalues and eigenvectors of T . **Solution:**

$$\begin{aligned} (z, w) &= \lambda(w, z) : z = \lambda w, w = \lambda z \\ z &= \lambda^2 z, 1 = \lambda^2 \implies \lambda_1 = 1 \end{aligned}$$

For $\lambda = 1$: $(z, w) = 1 \cdot (w, z) \implies z = w$ and $w = z \implies v_1 = (x, x)$ For $\lambda = -1$: $(z, w) = -1 \cdot (w, z) \implies z = -w$ and $w = -z \implies v_2 = (-x, x)$

7. Define $T \in \mathbb{F}^3$ by $T(z_1, z_2, z_3) = (2z_2, 0, 5z_3)$. Find all eigenvalues and eigenvectors of T . **Solution:**

$$2z_2 = \lambda z_1, \quad 0 = \lambda z_2, \quad 5z_3 = \lambda z_3 \implies \lambda_1 = 5$$

For $\lambda = 5$: $(2z_2, 0, 5z_3) = 5(z_1, z_2, z_3) \implies v_1 = (0, 0, x)$ and

(Incomplete line in original: likely leads to $\lambda_2 = 0$ and $\lambda_3 = 2$ or similar, based on the equations $2z_2 = \lambda z_1, 0 = \lambda z_2$. If $\lambda = 0$, then $2z_2 = 0 \implies z_2 = 0$. z_1 is free. $v_2 = (x, 0, 0)$. If $\lambda = 2$, then $2z_2 = 2z_1 \implies z_2 = z_1$. $0 = 2z_2$ implies $z_2 = 0$ and $z_1 = 0$. $v_3 = (0, 0, z_3)$ which gives $\lambda = 5$ again. Let's assume the missing part corresponds to $\lambda = 0$ and $\lambda = 2$).

Recommended Reading

- **Linear algebra problem book** by Paul R. Halmos (Match: 0.77)
- **Linear Algebra Done Right** by Sheldon Axler (Match: 0.74)
- **Linear Algebra** by Seymour Lipschutz (Match: 0.73)