

Attention is All You Sign: Sign Language Translation with Transformers

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Abstract. This paper improves the translation system in Sign Language Translation (SLT) by using Transformers. We report a wide range of experimental results for various Transformer setups and introduce a novel end-to-end SLT system combining **Spatial-Temporal Multi-Cue (STMC)** and **Transformer networks**. Our methodology improves on the current state-of-the-art by over 5 and 7 BLEU respectively on **ground truth (GT) glosses and predicted glosses of the PHOENIX-Weather 2014T dataset**. On the ASLG-PC12 corpus, we report an improvement of over **16 BLEU**. Our findings also reveal that end-to-end translation with predicted glosses outperforms translation on GT glosses. This shows the potential for further improvement in SLT by either jointly training the SLR and translation systems or by revising the **gloss annotation scheme**.

1 Introduction

In SLT, a tokenization system first generates glosses from sign language videos. Then, a translation system translates the recognized glosses into spoken language. Recent efforts work on the first step, but there has been none improving the translation system. This paper aims to fill this research gap by leveraging recent success in Neural Machine Translation (NMT), namely Transformers.

The contributions of this paper can be summarized as: (i) The first successful application of Transformers to SLT achieving state-of-the-art results; (ii) A novel STMC-Transformer model for end-to-end translation surpassing GT glosses translation contrary to previous assumptions; (iii) The first usage of weight tying, transfer learning, and ensemble learning in SLT.

2 Related Work

2.1 Sign Language Translation

[4] jointly use a 2D-CNN model to extract gloss-level features from video frames, and a sequence-to-sequence (seq2seq) model for German SLT. Subsequent works

^{*}Work carried out while at École Polytechnique. The Titan X Pascal used for this research was donated by the NVIDIA Corporation.

all focus on improving tokenization rather than translation. A contemporaneous paper [5] jointly trains Transformers for both tokenization and translation. [8] estimate human keypoints to extract glosses, then use seq2seq models for Korean SLT. [1] use seq2seq models to translate ASL glosses [10].

2.2 Neural Machine Translation

Neural Machine Translation (NMT) employs neural networks for text translation. Recent methods typically use seq2seq models with an encoder and decoder.

Earlier approaches use recurrent [11] for the encoder and decoder. Recent works use attention mechanisms [2, 9] that calculates context-dependent alignment scores between encoder and decoder hidden states. [12] introduces the Transformer, a seq2seq model relying on self-attention instead of recurrence.

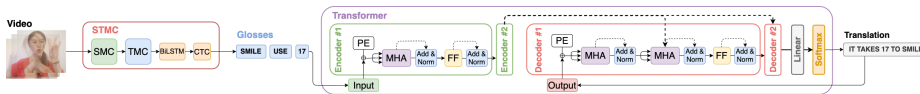


Fig. 1: STMC-Transformer network for end-to-end SLT

3 Model architecture

3.1 Spatial-Temporal Multi-Cue (STMC) Network

We use the STMC network [13] for tokenization. A spatial multi-cue (SMC) module decomposes the input video into spatial features of multiple visual cues. Then, a temporal multi-cue (TMC) module calculates temporal correlations within and between cues at different time steps. Obtained features are analyzed by Bi-directional Long Short-Term Memory (BiLSTM) [11] and Connectionist Temporal Classification (CTC) [7] units for sequence learning and inference.

3.2 Transformer

For translation, we train a two-layered Transformer [12] to maximize the log-likelihood $\sum_{(x_i, y_i) \in D} \log P(y_i | x_i, \theta)$, where D contains gloss-text pairs.

4 Datasets

PHOENIX-Weather 2014T [4] is extracted from weather forecast airings of the German tv station PHOENIX. **ASLG-PC12** [10] is constructed from English data of Project Gutenberg that has been transformed into ASL glosses following a rule-based approach. We make our data and code publicly available¹.

¹<https://github.com/kayoyin/transformer-slt>

5 Experiments and Discussions

We organize our experiments into two groups: (i) Gloss2Text in which we translate GT gloss annotations to simulate perfect tokenization; (ii) Sign2Gloss2Text where we perform end-to-end translation with the STMC-Transformer.

5.1 Gloss2Text (G2T)

	BLEU-1	BLEU-2	BLEU-3	BLEU-4	ROUGE-L	METEOR		BLEU-1	BLEU-2	BLEU-3	BLEU-4	ROUGE-L	METEOR
Raw data	11.88	5.05	2.41	1.36	22.81	12.12	Raw data	54.19	39.26	28.44	20.63	75.59	61.65
RNN Seq2seq [4]	44.13	31.47	23.89	19.26	45.45	–	Preprocessed data	68.82	56.36	46.53	38.37	83.28	79.06
Transformer [5]	48.90	36.88	29.45	24.54	–	–	Seq2seq [1]	86.7	79.5	73.2	65.9	–	–
Transformer	47.69	35.52	28.17	23.32	46.58	44.85	Transformer	92.98	89.09	85.63	82.41	95.87	96.46
Transformer Ens.	48.40	36.90	29.70	24.90	48.51	46.24	Transformer Ens.	92.88	89.22	85.95	82.87	96.22	96.60

(a) PHEONIX-WEATHER 2014T

(b) ASLG-PC12

Table 1: G2T results

We find that smaller models are better suited for our data of limited size, and larger batch size gives better performance. On ASLG-PC12, transfer learning using English fastText [3] vectors improves performance, while weight-tying the decoder gives the best BLEU-4, likely as it provides regularization. In Table 1, our Transformer Ensemble improves the state-of-the-art on PHOENIX-Weather 2014T and ASLG-PC12 by 5 and 17 BLEU-4 respectively. [5] uses a similar architecture to our single Transformer and obtains comparable results.

5.2 German Sign2Gloss2Text (S2G2T)

Model	Dev Set						Test Set					
	BLEU-1	BLEU-2	BLEU-3	BLEU-4	ROUGE-L	METEOR	BLEU-1	BLEU-2	BLEU-3	BLEU-4	ROUGE-L	METEOR
RNN G2T [4]	44.40	31.93	24.61	20.16	46.02	–	44.13	31.47	23.89	19.26	45.45	–
RNN S2G2T [4]	42.88	30.30	23.03	18.40	44.14	–	43.29	30.39	22.82	18.13	43.80	–
Transformer G2T	48.85	36.62	29.23	24.38	49.01	46.96	48.40	36.90	29.70	24.90	48.51	46.24
Transformer S2G2T [5]	47.73	34.82	27.11	22.11	–	–	48.47	35.35	27.57	22.45	–	–
STMC-Bahdanau RNN	45.89	32.24	24.93	20.52	44.46	43.48	47.53	33.82	26.07	21.54	45.50	44.87
STMC-Luong RNN	45.61	32.54	26.33	21.00	46.19	44.93	47.08	33.93	26.31	21.75	45.66	44.84
STMC-Transformer	48.27	35.20	27.47	22.47	46.31	44.95	48.73	36.53	29.03	24.00	46.77	45.78
STMC-Transformer Ens.	50.31	37.60	29.81	24.68	48.70	47.45	50.63	38.36	30.58	25.40	48.78	47.60

Table 2: SLT performance using STMC for CSLR.

Recurrent sequence-to-sequence networks We first train seq2seq models with Gated Recurrent Units [6] and Luong [9] or Bahdanau [2] attention. Surprisingly, these outperform previous recurrent models that translate GT glosses.

Transformer We train Transformer models with the same architecture as in G2T. Parameter search yields an initial learning rate 1 with 3,000 warm-up steps and beam size 4. Finally, we use our 8 best models in ensemble decoding.

STMC-Transformer also outperforms Transformers that translate GT glosses. While STMC performs imperfect CSLR, its gloss predictions may be better processed by the Transformer. Again, glosses are merely a simplified intermediate representation of the actual sign language, so it is not entirely unexpected that translating GT glosses does not give the best performance. Moreover, Transformers outperform recurrent networks in this setup as well and STMC-Transformer improves the state-of-the-art for video-to-text translation by 7 BLEU-4.

6 Conclusions and Future Work

In this paper, we proposed Transformers for SLT, notably the STMC-Transformer. Our experiments using different setups demonstrate how Transformers obtain better SLT performance than previous RNN-based networks. We also achieve new state-of-the-art results on different translation tasks on various datasets.

We especially obtained better performance by using a STMC network for tokenization instead of translating GT glosses. As future work, we suggest either training a CSLR model to output glosses easily usable by an NMT model, or design a novel gloss annotation scheme that optimizes translation.

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