## **Input:** $t_0, t_f, x_0, h, \text{tol}, \lambda_f$ Output: $x^*, u^*, \lambda$ **procedure** FORWARD BACKWARD SWEEP $(g, \lambda_{\text{function}}, u, x_0, \lambda_f, h, n_{max})$ while $\epsilon > \text{tol do}$ $u_{\text{old}} \leftarrow u$ $x_{\text{old}} \leftarrow x$ $x \leftarrow \text{RUNGE} \text{ KUTTA FORWARD}(q, u, x_0, h)$ $\lambda_{\text{old}} \leftarrow \lambda$ $\lambda \leftarrow \text{RUNGE} \quad \text{KUTTA} \quad \text{BACKWARD}(\lambda_{\text{function}}, x, \lambda_f, h)$

 $u_1 \leftarrow \text{OPTIMALITY} \quad \text{CONDITION}(u, x, \lambda)$  $u \leftarrow \alpha u_1 + (1 - \alpha)u_{old}, \qquad \alpha \in [0, 1]$  $\epsilon_u \leftarrow \frac{||u - u_{\text{old}}||}{||u||}$ 

 $\epsilon_x \leftarrow \frac{||x - x_{\text{old}}||}{||x||}$ 

Algorithm 2 Forward Backward Sweep

▷ relative error

 $\epsilon_{\lambda} \leftarrow \frac{||\lambda - \lambda_{\mathrm{old}}||}{||\lambda||}$ 

 $\epsilon \leftarrow \max\left\{\epsilon_u, \epsilon_r, \epsilon_\lambda\right\}$ 

end while

return  $x^*, u^*, \lambda$ ▷ Optimal pair end procedure