

# Modelling SDEs in biology

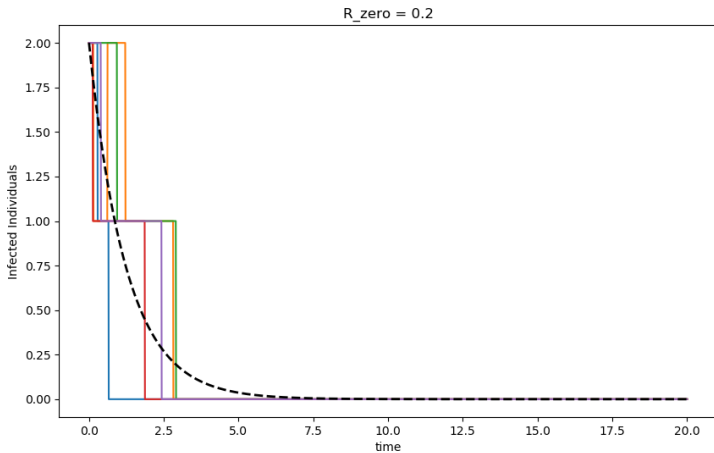
Formulation, Numerical Simulation and Analysis.

## Second day: Numerical methods for SDEs

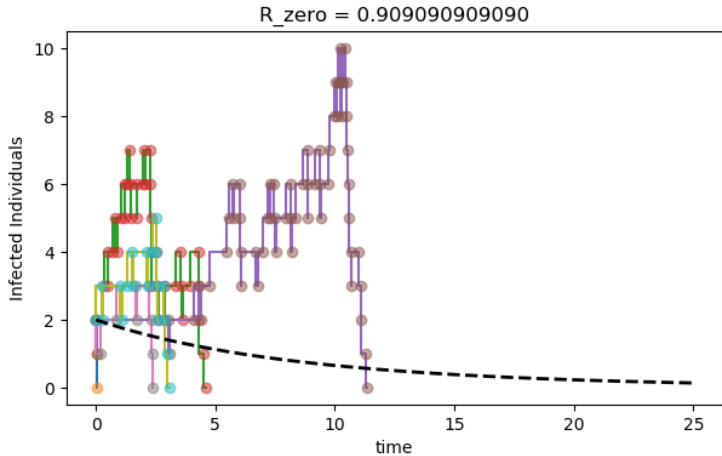
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Saúl Díaz Infante Velasco

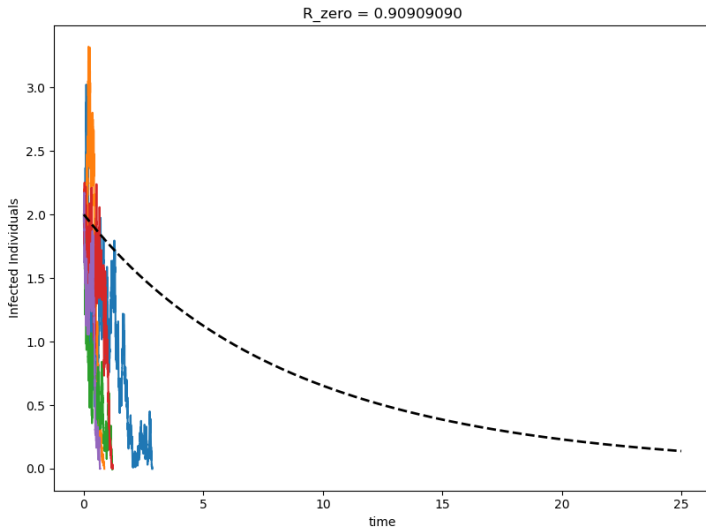
CONACYT-UNIVERSIDAD de SONORA, Cimat, Guanajuato Gto



```
1  if 0 < infected[delta_t_i] < N-1:
2      # Is there a birth?
3      birth_probability = beta * infected[delta_t_i] * (N -
4          infected[delta_t_i]) / N * delta_t
5      death_probability = (b + gamma) * infected[delta_t_i]
6          * delta_t
7      complement_probability = 1.0 - (birth_probability +
8          death_probability) * delta_t
9      if np.random.rand() <= birth_probability:
10         birth = True
11     if np.random.rand() <= death_probability:
12         death = True
13     transition = 1 * birth - 1 * death
14     infected[delta_t_i + 1] = infected[delta_t_i] +
        transition
15 # The evolution stops if we reach $0$ or $N$.
16 else:
17     infected[delta_t_i + 1] = infected[delta_t_i]
```



```
1 while (i[j] > 0 and t[j] < final_time):
2     u_1 = np.random.rand()
3     u_2 = np.random.rand()
4     den = (beta / N) * i[j] * s[j] + (b + gamma) * i[j]
5     infection_prob = (beta * s[j] / N) / (beta * s[j] / N +
6         b + gamma)
7     # exponential random time
8     t.append(t[j] - np.log(u_1) / den)
9     if u_1 <= infection_prob:
10         i.append(i[j] + 1)
11         s.append(s[j] - 1)
12     else:
13         i.append(i[j] - 1)
14         s.append(s[j] + 1)
15     j = j+1
```



```
1 for k in np.arange(num_of_realizations):
2     normal_sampler = np.zeros(array_size)
3     normal_sampler[1:] = np.sqrt(delta_t) * np.random.randn(
4         array_size - 1)
5     winner_inc = np.cumsum(normal_sampler)
6     infected[0] = infected_0
7     for i in np.arange(array_size - 1):
8         delta_w_i = winner_inc[i+1] - winner_inc[i]
9         euler_i = infected[i] + f(infected[i], 0) * delta_t \
10             + g(infected[i]) * delta_w_i
11         infected[i + 1] = euler_i
12     plt.plot(time, infected)
13 # odeint parameters
```

# Table of contents

- 1 **HW**
- 2 **LM**
- 3 **Explicit schemes**
- 4 **Brownian Motion**
- 5 **Weak vs Strong**
- 6 **Convergence and stability**



Let,  $I_t = i$ . Denote by  $T_i$  the interevent time.  $H_i(t)\mathbb{P}[T_i > t]$ .

$$\begin{aligned}H_i(t + \Delta t) &= H_i(t)p_{ii}(\Delta t) \\&= H_i(t)(1 - (b(i) + d(i))\Delta t + o(\Delta t)) \\ \frac{H_i(t + \Delta t) - H_i(t)}{\Delta t} &= -(b(i) + d(i))H_i(t) + o(\Delta t)\end{aligned}$$

Thus

$$\frac{dH_i(t)}{dt} = -(b(i) + d(i))H_i(t)$$

which have solution  $H_i(t) = \exp(-(b(i) + d(i))t)$

Let  $F_i(t) = \mathbb{P}[T_i \leq t] = 1 - \exp(-(b(i) + d(i))t)$

Then using a uniform r.v.  $u \sim [0, 1]$

$$\begin{aligned}\mathbb{P}[F_i^{-1}(u) \leq t] &= \mathbb{P}[F_i(F_i^{-1}(u)) \leq F_i(t)] \\ &= \mathbb{P}[u \leq F_i(t)] \\ &= F_i(t).\end{aligned}$$

Therefore

$$T_i = F_i^{-1}(u) = -\frac{\log(u)}{b(i) + d(i)}$$

SDE

$$dx(t) = \underbrace{f(x(t), t)dt}_{\text{deriva}} + \underbrace{g(x(t), t)dB(t)}_{\text{difusión}},$$

$$f: \mathbb{R}^d \times [0, T] \rightarrow \mathbb{R}^d, \quad g: \mathbb{R}^d \times [0, T] \rightarrow \mathbb{R}^{d \times m}$$
$$B(t) = (B_1(t), \dots, B_m(t))^T, \quad (\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$$

SDE

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SDE

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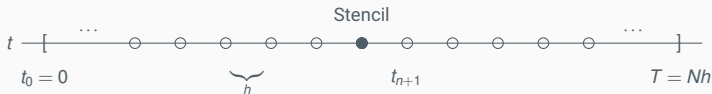
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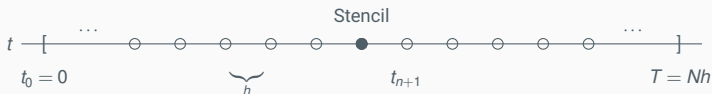


$$x(t_{n+1}) = x(t_n) + \int_{t_n}^{t_{n+1}} f(x(s), s) ds + \int_{t_n}^{t_{n+1}} g(x(s), s) dB(s)$$

# Construction idea

SDE

$$x(t) = x_0 + \int_0^t f(x(s), s) ds + \int_0^t g(x(s), s) dB(s)$$

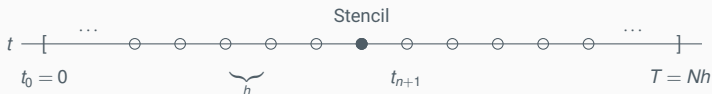


$$x(t_{n+1}) = x(t_n) + \underbrace{\int_{t_n}^{t_{n+1}} f(x(s), s) ds}_{\approx \text{det}} + \underbrace{\int_{t_n}^{t_{n+1}} g(x(s), s) dB(s)}_{\approx}$$

# Construction idea

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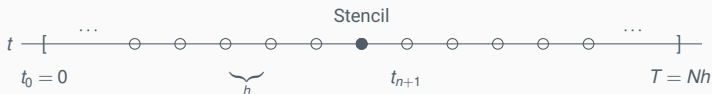
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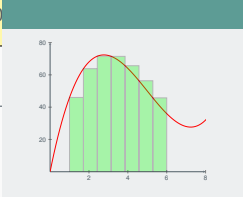
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 $\Delta B_n = B_{t_{n+1}} - B_{t_n}$

SDE

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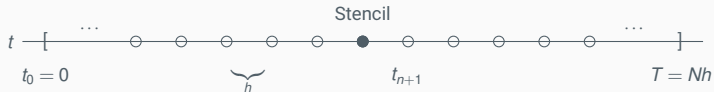
$\Delta B_n = B_{t_{n+1}} - B_{t_n}$

$$X_0 = x_0, \quad X_n \approx x(t_n), \quad n = 1 \dots, N-1$$

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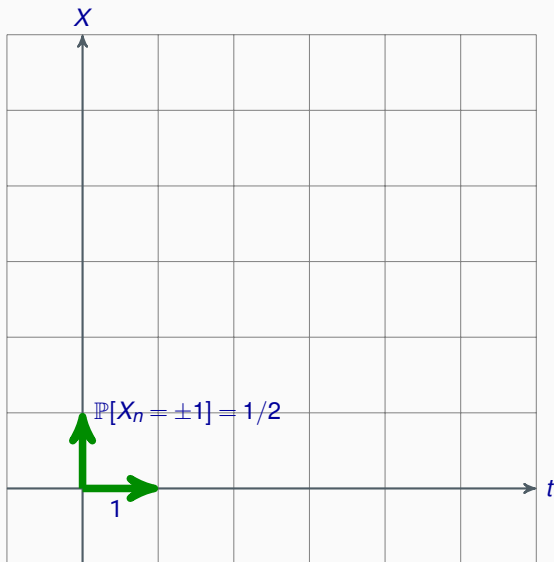


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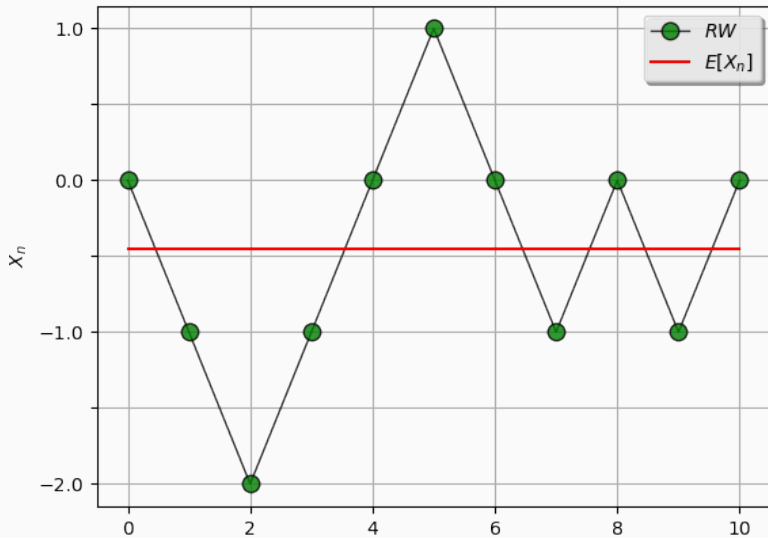
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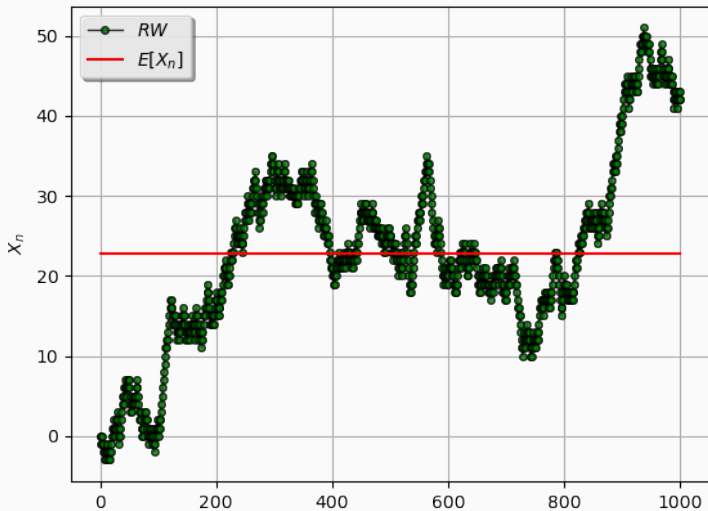
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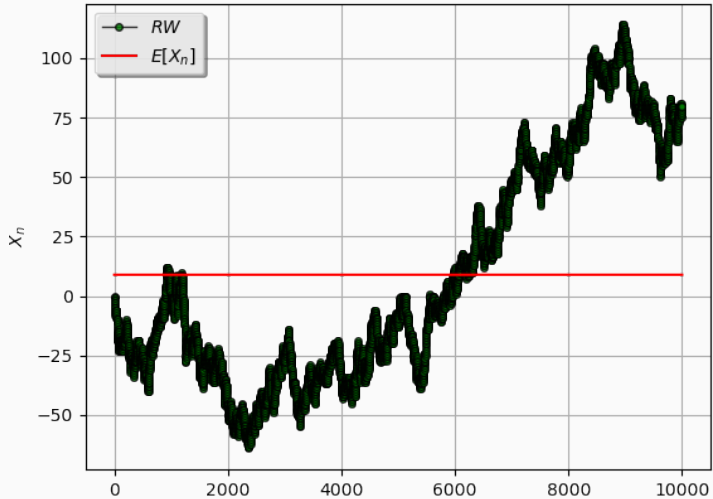
$$X_{n+1} = X_n + f(X_n)h + g(X_n) \underbrace{\Delta B_n}_{\approx}$$

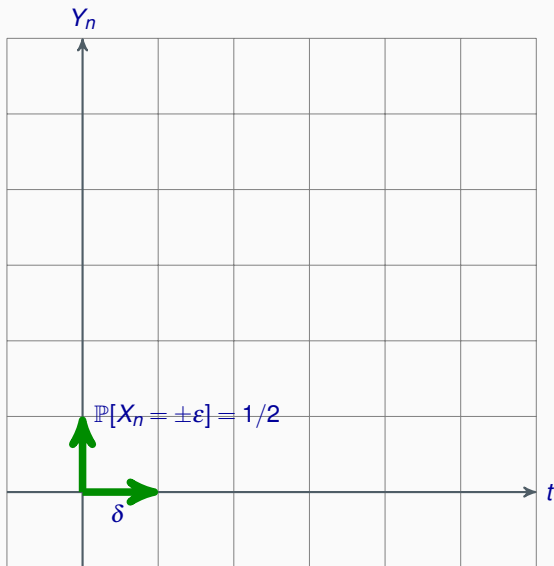














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Let  $\lambda \in \mathbb{R}$  fixed. Compute

► característica  $\lim_{\delta,\varepsilon \rightarrow 0} \mathbb{E} \left[ e^{i\lambda Y_{\delta,\varepsilon}(t)} \right].$

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$$t = n\delta,$$

$$\begin{aligned} \mathbb{E} \left[ e^{i\lambda Y_{\delta,\varepsilon}(t)} \right] &= \prod_{j=1}^n \mathbb{E} \left[ e^{i\lambda X_j} \right] \\ &= \left( \mathbb{E} \left[ e^{i\lambda X_j} \right] \right)^n \\ &= \left( \frac{1}{2} e^{i\lambda \varepsilon} + \frac{1}{2} e^{-i\lambda \varepsilon} \right)^n \\ &= (\cos(\lambda \varepsilon))^n \\ &= (\cos(\lambda \varepsilon))^{\frac{t}{\delta}}. \end{aligned}$$

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$$t = n\delta, \quad u = (\cos(\lambda\varepsilon))^{\frac{1}{\delta}} \quad \ln(u) = \frac{1}{\delta} \ln(\cos(\lambda\varepsilon))$$

For  $x, \varepsilon$  small!  $\ln(1+x) \approx x$

$$\cos(\lambda\varepsilon) \approx \underbrace{1 - \frac{1}{2}\lambda^2\varepsilon^2}_{1+x}.$$

Then

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$$t = n\delta, \quad u = (\cos(\lambda\varepsilon))^{\frac{1}{\delta}}$$

$$u \approx e^{-\frac{1}{2\delta}\lambda^2\varepsilon^2}$$

$$\mathbb{E}\left[e^{i\lambda Y_{\delta,\varepsilon}(t)}\right] \approx e^{-\frac{1}{2\delta}t\lambda^2\varepsilon^2}.$$

$$\varepsilon^2 = \delta$$

$$\lim_{\delta \rightarrow 0} \mathbb{E}\left[e^{i\lambda Y_{\delta,\sqrt{\delta}}(t)}\right] = e^{-\frac{1}{2}t\lambda^2}, \quad \lambda \in \mathbb{R}.$$

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$$t = n\delta, \quad u = (\cos(\lambda \varepsilon))^{\frac{1}{\delta}}$$

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$$\mathbb{E} \left[ e^{i\lambda Y_{\delta, \varepsilon}(t)} \right] \approx e^{-\frac{1}{2\delta} t \lambda^2 \varepsilon^2}.$$

$$\varepsilon^2 = \delta$$

$$\lim_{\delta \rightarrow 0} \mathbb{E} \left[ e^{i\lambda Y_{\delta, \sqrt{\delta}}(t)} \right] = e^{-\frac{1}{2} t \lambda^2}, \quad \lambda \in \mathbb{R}.$$

$$\therefore B(t) \stackrel{\mathcal{D}}{=} \lim_{\delta \rightarrow 0} Y_{\delta, \sqrt{\delta}}(t)$$



## Theorem

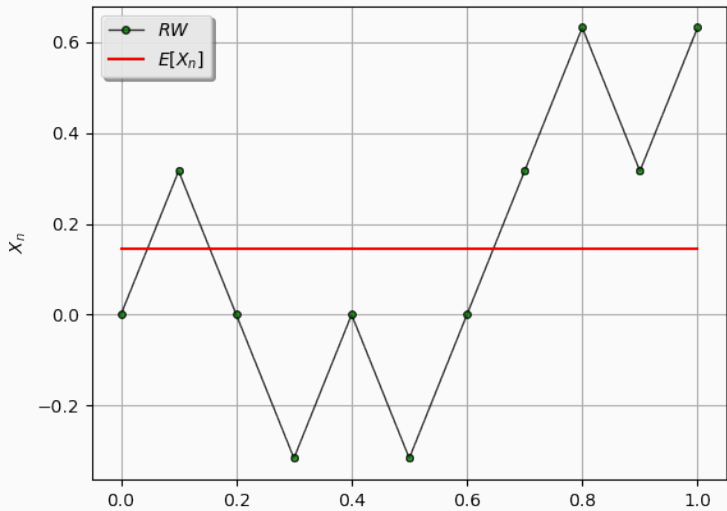
Let  $Y_{\delta,\varepsilon}(t)$  a random walk starting at 0, with jumps  $\varepsilon$ ,  $-\varepsilon$ , of equal probability at  $\delta, 2\delta, 3\delta, \dots$ . Assume  $\varepsilon^2 = \delta$ . Then for each  $t \geq 0$ , the limit

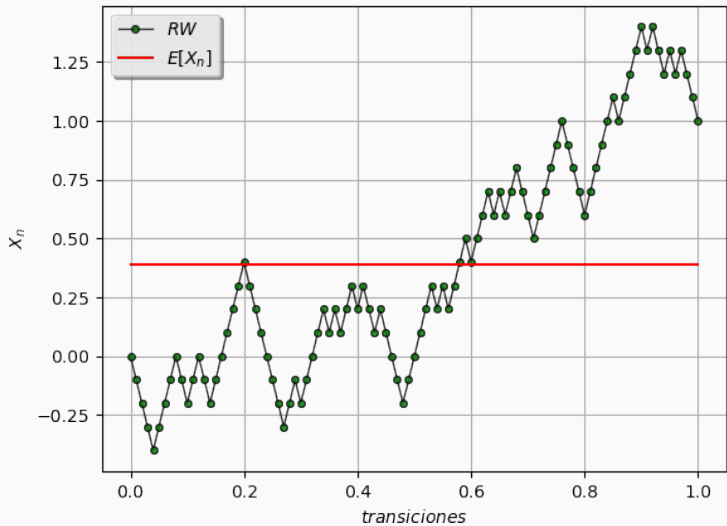
$$B(t) = \lim_{\delta \rightarrow 0} Y_{\delta, \sqrt{\delta}}(t),$$

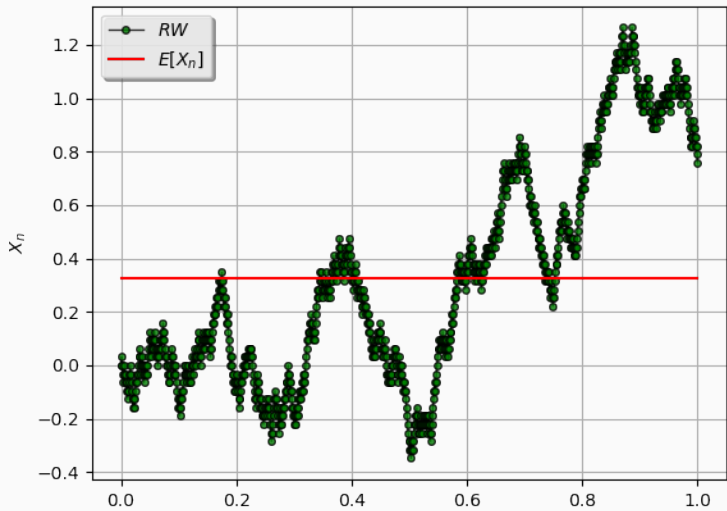
exist in distribution,

$$\mathbb{E} \left[ e^{i\lambda B(t)} \right] = e^{-\frac{1}{2} t \lambda^2}, \quad \lambda \in \mathbb{R}.$$

```
1 N = 10
2 T = 1.0
3 delta = T/np.float(N)
4 eps = 1.0/np.sqrt(np.float(N))
5 t = np.linspace(0,T,N+1)
6 b = np.random.binomial(1,.5, N) # bernulli 0,1
7 omega = 2.0 * b - 1           # bernulli -1,1
8 Xn = eps * (omega.cumsum())   # bernulli -h,h
9 Xn = np.concatenate(([0], Xn))
```





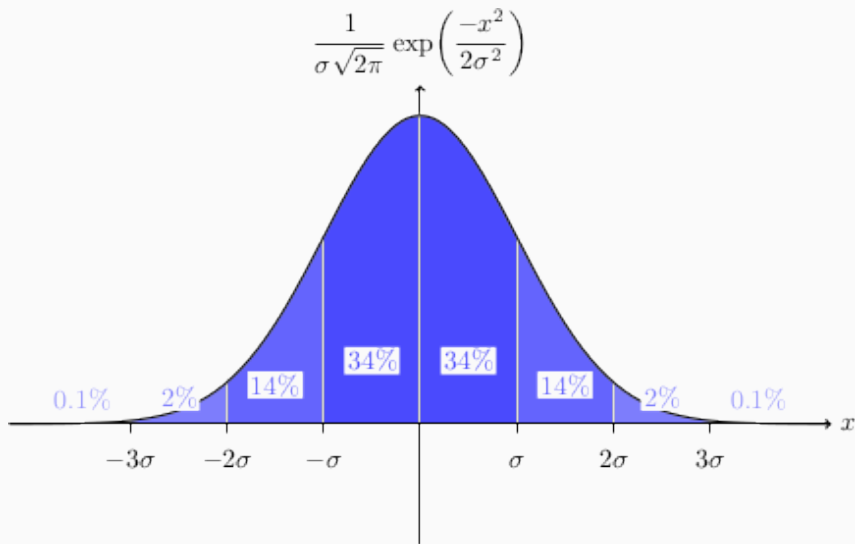


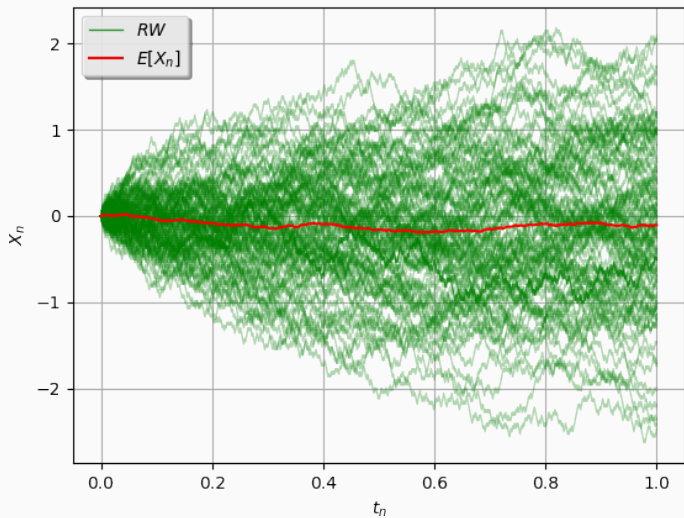
### Construcción

$$\varepsilon^2 = \delta$$

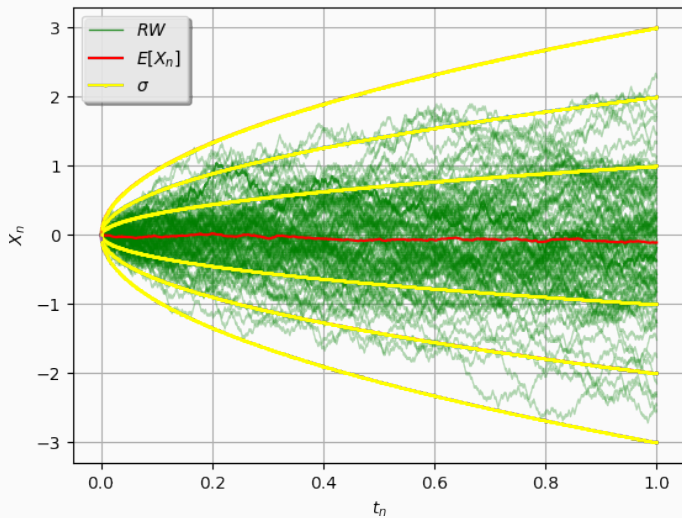
$$Y_{\delta,\varepsilon}(t) \xrightarrow[\delta,\varepsilon \rightarrow 0]{\mathcal{D}} B(t) \quad \forall t \geq 0$$

$$\mathbb{E} \left[ e^{i\lambda B(t)} \right] \xrightarrow[\delta,\varepsilon \rightarrow 0]{} e^{-\frac{1}{2}t\lambda^2}, \quad \lambda \in \mathbb{R}.$$









## Definition

Brownian motion  $B$  is the unique process that satisfies

- (i)  $B(0) = 0$  c.s.
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# Weak vs Strong

given

$$dx(t) = f(x(t))dt + g(x(t))dB(t),$$

$$x(0) = x_0, \quad t \in [0, T]$$

Weak

$$X_{n+1} = X_n + f(X_n)h + g(X_n) \underbrace{\Delta B_n}_{\approx \sqrt{h}\epsilon_n}$$

$$\mathbb{P}[\epsilon_n = \pm 1] = 1/2$$

strong

$$X_{n+1} = X_n + f(X_n)h + g(X_n) \underbrace{\Delta B_n}_{\approx \sqrt{h}\epsilon_n}$$

$$\epsilon_n \sim N(0, 1)$$



# Some representative schemes

## $\theta$ -Euler Maruyama

$$Y_{k+1} = Y_k + h(1 - \theta)f(Y_k) + \theta f(Y_{k+1}) + g(Y_k)\Delta W_k, \\ \theta \in [0, 1].$$

- **Implicit:**

- $\theta$ -BEM
- FBEM

- **Explicit:**

- Tamed EM
- Truncated
- Sabanis



Xuerong Mao and Lukasz Szpruch.

**Strong convergence and stability of implicit numerical methods for stochastic differential equations with non-globally lipschitz continuous coefficients.**

*Journal of Computational and Applied Mathematics*,  
238:14–28, January 2013.

# Some representative schemes

## Forward-Backward Euler Maruyama

$$Y_k = Y_{k-1} + h(1 - \theta)f(Y_{k-1}) + \theta f(Y_k) + g(Y_{k-1})\Delta W_{k-1}$$

$$\widehat{Y}_{k+1} = \widehat{Y}_k + hf(Y_k) + g(Y_k)\Delta W_k, \quad \theta \in [0, 1].$$

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# Some representative schemes

## Tamed Euler Maruyama

$$Y_{k+1} = Y_k + \frac{hf(Y_k)}{1 + h\|f(Y_k)\|} + g(Y_k)\Delta W_k$$

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Martin Hutzenthaler, Arnulf Jentzen, and Peter E. Kloeden.

**Strong convergence of an explicit numerical method for sdes with nonglobally lipschitz continuous coefficients.**

*The Annals of Applied Probability*, 22(4):1611–1641, August 2012.

# Some representative schemes

## Truncated Euler Maruyama

- **Implicite:**

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$$Y_{k+1} = Y_k + f_{\Delta}(Y_k)h + g_{\Delta}(Y_k)\Delta_k,$$

$$f_{\Delta}(x) := \left( |x| \wedge \mu^{-1}(h(\Delta)) \frac{x}{|x|} \right),$$

$$g_{\Delta}(x) := \left( |x| \wedge \mu^{-1}(h(\Delta)) \frac{x}{|x|} \right)$$



Xuerong Mao.

**The truncated euler-maruyama method for stochastic differential equations.**

*Journal of Computational and Applied Mathematics*, 290:370 – 384, 2015.

# Some representative schemes

## Euler Maruyama with varying coefficients

$$Y_{k+1} = Y_k + \frac{hf(Y_k) + g(Y_k)\Delta W_k}{1 + k^{-\alpha}(\|f(Y_k)\| + \|g(Y_k)\|)}, \quad \alpha \in (0, 1/2]$$

- **Implicite:**
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Sotirios Sabanis.

**Euler approximations with varying coefficients : the case of superlinearly growing diffusion coefficients.**

To appear in Annals of Applied Probability, 2015.

- Julia: juliadiffeq
- Python:
  - StochPy
  - sdeint
  - Py3DE
- R:
  - sde
  - sde.sim.R
- MATLAB: SDE Models

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad Y_0 = y_0.$$

(EDE)

# Common hypothesis

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad Y_0 = y_0.$$

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$$f: \mathbb{R}^d \rightarrow \mathbb{R}^d,$$
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$$\begin{aligned} f: \mathbb{R}^d &\rightarrow \mathbb{R}^d, \\ f &= (f^{(1)}, \dots, f^{(d)}), \end{aligned}$$

## Difusion

$$\begin{aligned} g: \mathbb{R}^d &\rightarrow \mathbb{R}^{d \times m}, \\ g &= \left( g^{(i,j)} \right)_{\substack{i \in \{1, \dots, d\} \\ j \in \{1, \dots, m\}}} \\ W &= (W^{(1)}, \dots, W^{(m)}) \end{aligned}$$

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(EU-1) Local Lipschitz

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$\Rightarrow \exists! y(t)$



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(SDE)

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(SDE)

Higham D. J., Mao X. and Stuart A. M. (2002).

Methods for nonlinear stochastic

:1041–1063.

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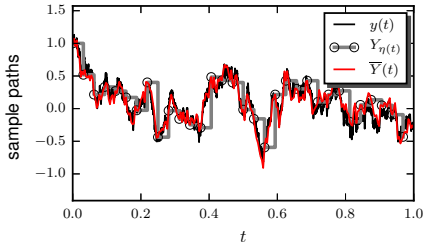
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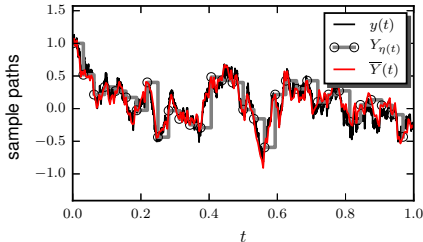
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## Theorem

EM converge

$$\lim_{h \rightarrow 0} \mathbb{E} \left[ \sup_{0 \leq t \leq T} |\bar{Y}(t) - y(t)|^2 \right] = 0.$$



Kloeden, P. E. and Platen, E. (1991).  
***Numerical Solution of Stochastic Differential Equations.***  
Applications of Mathematics. Springer-Verlag.

# consistency

EDE

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad Y_0 = y_0$$

(EDE)

Let  $Y^h$  a one step  
max  $h$ .

$$\varepsilon(h) = \mathbb{E}(|y(T) - Y^h(T)|)$$

## Definition

$Y^h$  at times  $(\tau)_h = \{\tau_n : n = 0, 1, \dots\}$  is **strong consistent**, si  $\exists C = C(h) \geq 0, \quad h_0$  s.t.  
 $\forall Y_n^h, n = 1, 2, \dots, N, \quad h \in (0, h_0)$

- $\lim_{h \downarrow 0} C(h) = 0$

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# consistency

EDE

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad Y_0 = y_0$$

(EDE)

Let  $Y^h$  a one step  
max  $h$ .

$$\varepsilon(h) = \mathbb{E}(|y(T) - Y^h(T)|)$$

## Definition

$Y^h$  at times  $(\tau)_h = \{\tau_n : n = 0, 1, \dots\}$  is **strong consistent**, si  $\exists C = C(h) \geq 0, \quad h_0$  s.t.  
 $\forall Y_n^h, n = 1, 2, \dots, N, \quad h \in (0, h_0)$

- $\lim_{h \downarrow 0} C(h) = 0$

- $\mathbb{E} \left( \left| \mathbb{E} \left( \frac{Y_{n+1}^h - Y_n^h}{h} \middle| \mathcal{F}_{\tau_n} \right) - f(Y_n^h) \right|^2 \right) \leq C(h).$

- $\mathbb{E} \left( \left| \frac{1}{h} Y_{n+1}^h - Y_n^h - \mathbb{E} \left( \frac{Y_{n+1}^h - Y_n^h}{h} \middle| \mathcal{F}_{\tau_n} \right) - g(Y_n^h) \Delta W_n \right|^2 \right) \leq C(h).$

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$Y^h$  a scheme with  
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## Definition

$Y^h$  is strong convergent to  $y$  if at final time  $T$

$$\lim_{h \downarrow 0} \mathbb{E}(|y(T) - Y^h(T)|) = 0$$

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad y_0 = y(0)$$

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### Definition (convergence order)

$Y^h$  is strong convergent with order  $\gamma$ , if  $\exists C$  independent from  $h$  y  $h_0$  s.t.

$$\varepsilon(h) = \mathbb{E}(|y(T) - Y(T)|) \leq Ch^\gamma \quad \forall h \in (0, h_0).$$

SDE

$$dy(t) = f(y(t))dt + g(y(t))dW_t, \quad y_0 = y(0)$$

## Theorem

*Consistency implies convergence*

<https://github.com/SaulDiazInfante/Modelling-Simulation-with-SDE>

[Mao and Szpruch, 2013]

## Theorem

$(EU-1)-(EU-3) \Rightarrow \exists! \{y(t)\}_{t \geq 0}, \forall y(0) = y_0 \in \mathbb{R}^d$ .  
Further  $0 < T < \infty$ ,

- $\mathbb{E}[y(T)] < (|y_0|^2 + 2\alpha T) \exp(2\beta T)$ ,
- $\tau_n := \inf\{t \geq 0 : |y(t)| > n\}, n \in \mathbb{N}$ ,
- $\mathbb{E}[|y(t)|^p] \leq 2^{\frac{p-2}{2}} (1 + \mathbb{E}[|y_0|^p]) e^{Cpt}$ .

◀ Extension



Mao, X. and Szpruch, L. (2013).  
**Strong convergence and stability of implicit numerical methods for stochastic differential equations with non-globally lipschitz continuous coefficients.**  
*Journal of Computational and Applied Mathematics*, 238:14–28.

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