## **RL-Course**

Saúl Díaz Infante, David González Sánchez 2024-05-30

## Table of contents

Preface						
Outline						
1	The	Dynamic Programming Algorithm	6			
	1.1	Introduction	6			
	1.2	The Basic Problem	6			
	1.3	The Dynamic Programming Algorithm	6			
	1.4	State Augmentation and Other Reformulations	6			
	1.5	Some Mathematical Issues	6			
	1.6	Dynamic Programming and Minimax Control	6			
	1.7	Notes, Sources, and Exercises	6			
2	Dynamic Programming 7					
	2.1	Policy Evaluation (Prediction)	7			
	2.2	Policy Improvement	7			
	2.3	Policy Iteration	7			
	2.4	Value Iteration	7			
	2.5	Asynchronous Dynamic Programming	7			
	2.6	Generalized Policy Iteration	7			
	2.7	Efficiency of Dynamic Programming	7			
	2.8	Summary	7			
3	Арр	lications	8			
	3.1	Recycling Robot	8			
	3.2	A robot with randomly moves in a grid world	8			
4	Finite Markov Decision Processes					
	4.1	The Agent–Environment Interface	9			
	4.2	Goals and Rewards	9			
	4.3	Returns and Episodes	9			
	4.4	Unified Notation for Episodic and Continuing Tasks	9			
	4.5	Policies and Value Functions	9			
	4.6	Optimal Policies and Optimal Value Functions	9			
	4.7	Optimality and Approximation	9			
	1 2	Summary	0			

5	Finit	te Markov Decision Processes	10		
	5.1	The Agent–Environment Interface	10		
	5.2	Goals and Rewards	10		
	5.3	Returns and Episodes	10		
	5.4	Unified Notation for Episodic and Continuing Tasks	10		
	5.5	Policies and Value Functions	10		
	5.6	Optimal Policies and Optimal Value Functions	10		
	5.7	Optimality and Approximation	10		
	5.8	Summary	10		
6	Dynamic Programming				
	6.1	Policy Evaluation (Prediction)	11		
	6.2	Policy Improvement	11		
	6.3	Policy Iteration			
	6.4	Value Iteration	11		
	6.5	Asynchronous Dynamic Programming	11		
	6.6	Generalized Policy Iteration	11		
	6.7	Efficiency of Dynamic Programming	11		
	6.8	Summary	11		
Re	References				

## **Preface**

This notes are based in the course from Berstekas for the MIT see all lectures and other resources for complete the understanding.

### **Outline**

The texbook for chapter one is the Bertsekas' book (Bertsekas 2005). Chapter 2 and 3 are adapted from Suttons' book (Ch.3,Ch.4 Sutton and Barto 2018). For application and broad conection with more Matchine Learning Applications we refer to (Brunton and Kutz 2019). Also we recomend for a handbook of algorithms (Szepesvári [2022] \copyright 2022). For applications with implemented code we follows the books (Bilgin 2020).

### 1 The Dynamic Programming Algorithm

- 1.1 Introduction
- 1.2 The Basic Problem
- 1.3 The Dynamic Programming Algorithm
- 1.4 State Augmentation and Other Reformulations
- 1.5 Some Mathematical Issues
- 1.6 Dynamic Programming and Minimax Control
- 1.7 Notes, Sources, and Exercises

## 2 Dynamic Programming

- 2.1 Policy Evaluation (Prediction)
- 2.2 Policy Improvement
- 2.3 Policy Iteration
- 2.4 Value Iteration
- 2.5 Asynchronous Dynamic Programming
- 2.6 Generalized Policy Iteration
- 2.7 Efficiency of Dynamic Programming
- 2.8 Summary

# 3 Applications

- 3.1 Recycling Robot
- 3.2 A robot with randomly moves in a grid world.

#### 4 Finite Markov Decision Processes

- 4.1 The Agent–Environment Interface
- 4.2 Goals and Rewards
- 4.3 Returns and Episodes
- 4.4 Unified Notation for Episodic and Continuing Tasks
- 4.5 Policies and Value Functions
- 4.6 Optimal Policies and Optimal Value Functions
- 4.7 Optimality and Approximation
- 4.8 Summary

#### 5 Finite Markov Decision Processes

- 5.1 The Agent–Environment Interface
- 5.2 Goals and Rewards
- 5.3 Returns and Episodes
- 5.4 Unified Notation for Episodic and Continuing Tasks
- 5.5 Policies and Value Functions
- 5.6 Optimal Policies and Optimal Value Functions
- 5.7 Optimality and Approximation
- 5.8 Summary

## **6 Dynamic Programming**

- **6.1 Policy Evaluation (Prediction)**
- **6.2 Policy Improvement**
- **6.3 Policy Iteration**
- **6.4 Value Iteration**
- 6.5 Asynchronous Dynamic Programming
- 6.6 Generalized Policy Iteration
- 6.7 Efficiency of Dynamic Programming
- 6.8 Summary

#### References

- Bertsekas, Dimitri P. 2005. *Dynamic Programming and Optimal Control. Vol. I.* Third. Athena Scientific, Belmont, MA.
- Bilgin, E. 2020. Mastering Reinforcement Learning with Python: Build Next-Generation, Self-Learning Models Using Reinforcement Learning Techniques and Best Practices. Packt Publishing. https://books.google.com.mx/books?id=s0MQEAAAQBAJ.
- Brunton, Steven L., and J. Nathan Kutz. 2019. *Data-Driven Science and Engineering*. Cambridge University Press, Cambridge. https://doi.org/10.1017/9781108380690.
- Sutton, Richard S., and Andrew G. Barto. 2018. Reinforcement Learning: An Introduction. Second. Adaptive Computation and Machine Learning. MIT Press, Cambridge, MA.
- Szepesvári, Csaba. [2022] \copyright 2022. Algorithms for Reinforcement Learning. Vol. 9. Synthesis Lectures on Artificial Intelligence and Machine Learning. Springer, Cham. https://doi.org/10.1007/978-3-031-01551-9.