

Optimizing the Performance of Computer Vision Application

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Introduction

Introduction:

- Computer vision is a field that enables machines to interpret and analyze visual data, allowing us to demonstrate various applications and optimizations through live demos.

Challenges:

- Performance is often limited by computational resources, processing speed, and accuracy, which can hinder real-time processing and effectiveness.

Research Focus:

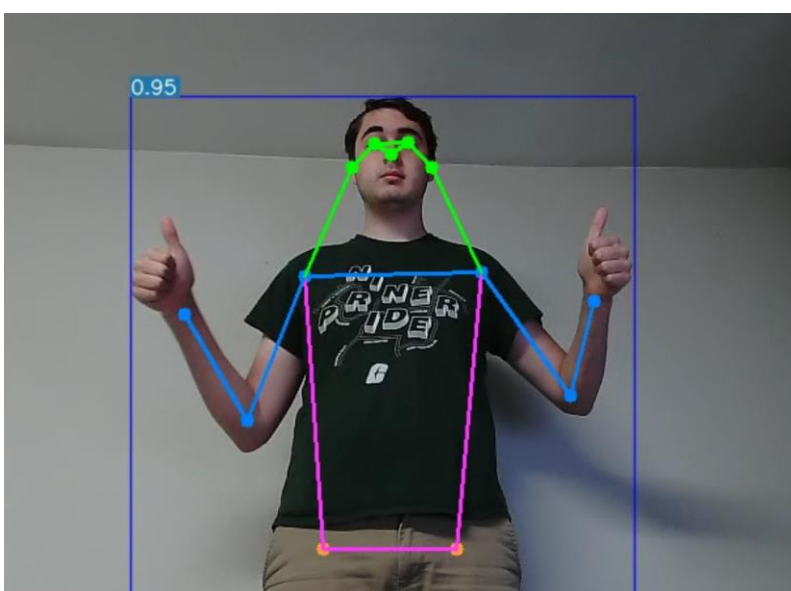
- Our research aims to optimize performance by improving algorithm efficiency and resource management, enhancing speed and accuracy.

How they work:

- Both computer vision applications follow the same structure of capturing a frame, processing it with a machine learning model, rendering it, and looping until completion.

Importance:

- Computer vision uses complex algorithms to help machines interpret and respond to visual data, making them increasingly important in everyday life.



Webcam output from application 1

Application 1: Position Estimation

Objective:

- To increase performance of a live webcam feed and make the application estimate position in real-time.

Challenges:

- Ensuring real-time image processing
- Providing accurate position estimations

Methods:

- Utilize modern hardware to do complex calculations faster.
- Use efficient and effective pretrained models

Application 2: Action Recognition

Objective:

- To identify and classify human actions from a live webcam feed in real-time and overlay the predictions.

Challenges:

- Ensuring real-time action recognition in a live demonstration
- Recognizing and processing multiple actions for display

Methods:

- Using a profiler to find bottlenecks in the code
- Using basic strategies to decouple the rendering and analysis sections.

Profiling

- A code profiler analyzes performance by measuring the execution time for each function.
- Profilers are used to identify inefficient parts of code.
- By utilizing a profiler, we were able to identify bottlenecks in our second application to optimize it for performance.

```
ncalls  tottime  pcall  ctime  pcall  filename:lineno(function)
1859   3.861   0.894   3.861   0.894 {built-in method torch.tensor}
76    2.667   0.035   2.667   0.035 {method 'cpu' of 'torch._C.TensorBase' objects}
76    0.983   0.013   0.983   0.013 {method 'cuda' of 'torch._C.TensorBase' objects}
348    0.961   0.003   0.961   0.003 {method 'uniform_' of 'torch._C.TensorBase' objects}
7    0.665   0.665  12.864  12.864 Main.py:38(webcam_inference)
76    0.666   0.003   0.666   0.003 {__init__}
6527   0.472   0.000   0.472   0.000 {built-in method torch.conv2d}
71    0.338   0.338   0.338   0.338 {method 'release' of 'cv2.VideoCapture' objects}
5923   0.202   0.000   0.202   0.000 {built-in method torch._C._nn_linear}
992    0.233   0.000   0.204   0.000 C:\Users\cbroh\Anaconda3\envs\exp_action_rec\lib\site-packages\torch\serialization.py:1372(load_tensor)
2012   0.210   0.000   0.218   0.000 {method 'to' of 'torch._C.TensorBase' objects}
1688   0.209   0.000   0.443   0.000 C:\Users\cbroh\OneDrive\Desktop\online_action_recognition-master\timesform
r\models\v1t.py:78(forward)
634    0.120   0.000   0.120   0.000 {built-in method torch.where}
107    0.123   0.001   0.123   0.001 {built-in method torch._ops.torchvision.nms}
4949   0.097   0.000   0.097   0.000 {built-in method torch.batch_norm}
14040   0.009   0.000   0.009   0.000 {method 'reshape' of 'torch._C.TensorBase' objects}
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r\models\v1t.py:115(forward)
41    0.003   0.001   0.003   0.001 {method 'normal_' of 'torch._C.TensorBase' objects}
1787121  0.000   0.000   6.572   0.013 C:\Users\cbroh\Anaconda3\envs\exp_action_rec\lib\site-packages\torch\nn\modules\module.py:1530(call_impl)
```

Output of profiler from application 2

Results

Performance Improvements:

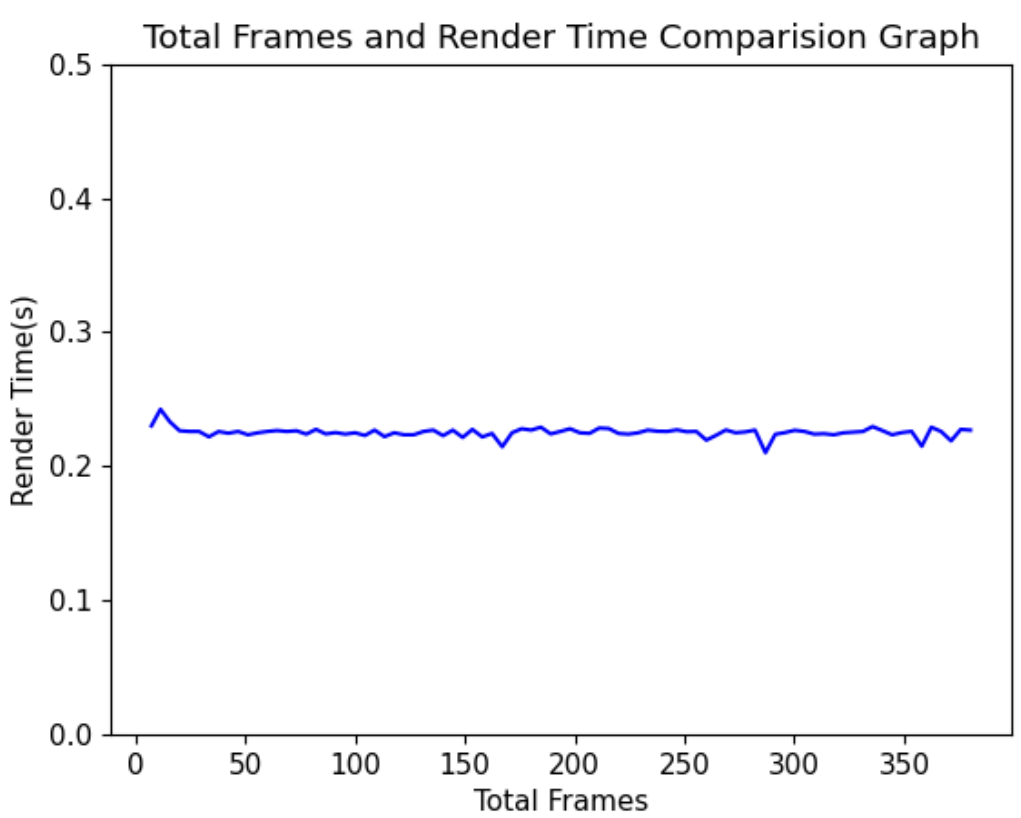
- Overall gain with significant increase in frames per second (FPS) for both applications after code modifications.

Application 1:

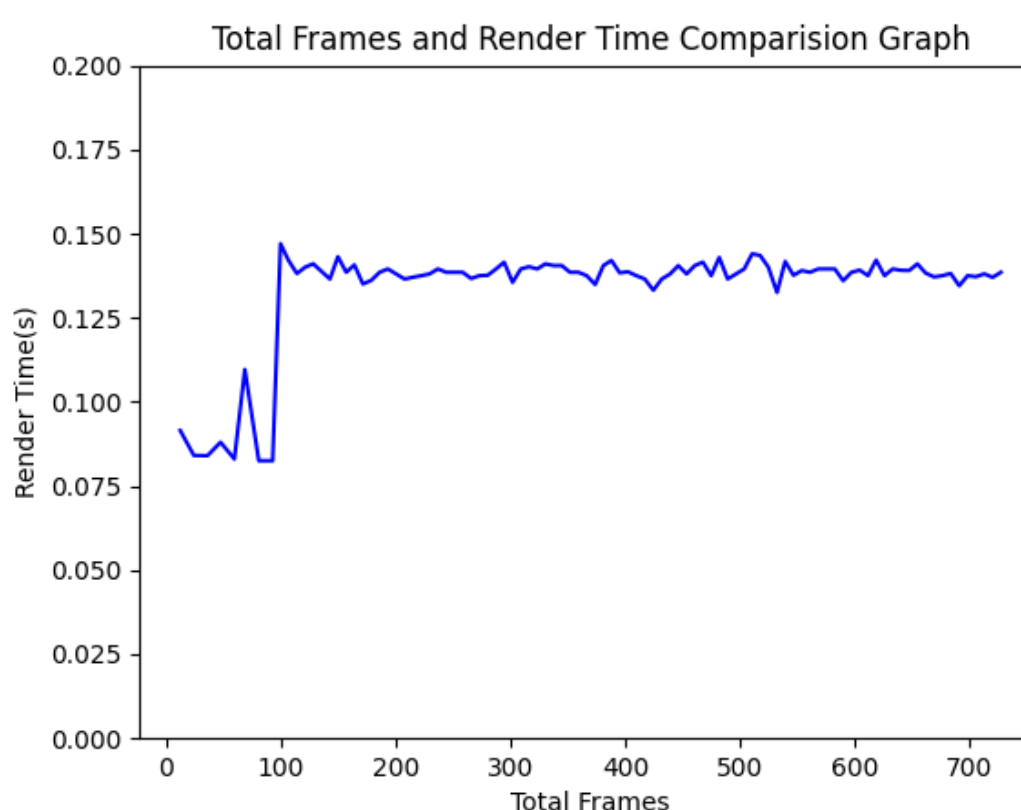
- Utilizing a GPU for video rendering, frame rate improved by 10 times its original value.

Application 2:

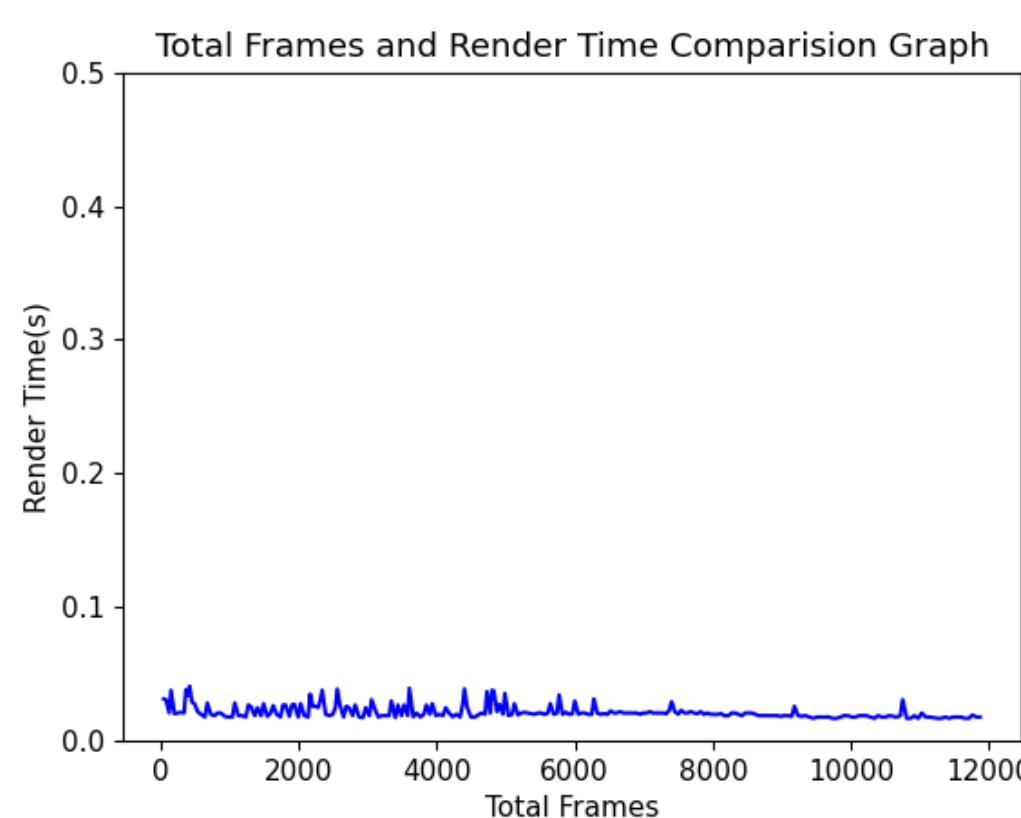
- Large predictions are processed every few frames instead of every frame to maintain real-time look and accuracy.



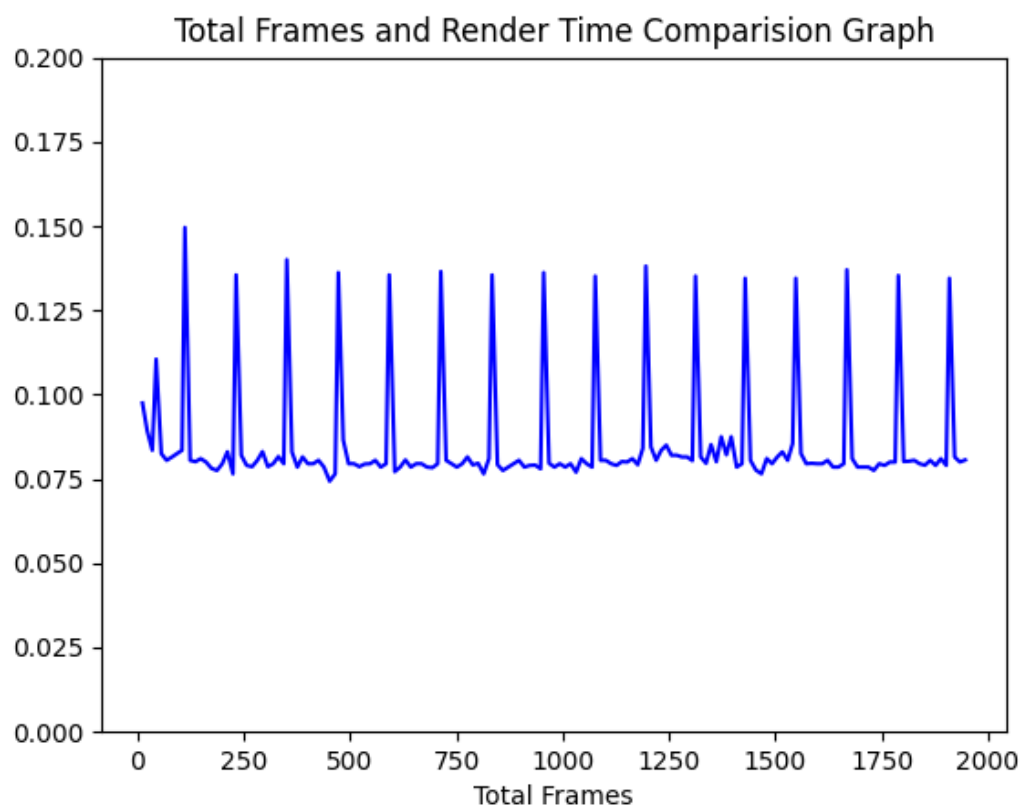
Average FPS: 4.296



Applications before optimizations



Average FPS: 444.470



Applications after optimizations

Conclusions

- Utilizing modern hardware for complex computations is key for real-time image processing.
- By leveraging modern hardware and efficient software, noticeable improvements in real-time performance have been observed on both applications.

Future Works

- Implementing threading in application 2 to further separate rendering from analysis.
- Making the applications compatible on different machines regardless of hardware limitations.