

第六次作业

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- 1 给出函数表
- | x | 1.05 | 1.10 | 1.15 | 1.20 |
|------|------|------|------|------|
| f(x) | 2.12 | 2.20 | 2.17 | 2.32 |
- 构造拉格朗日插值函数, 计算 $f(1.075)$ 和 $f(1.175)$ 的近似值。

直接套公式计算即可。其中乘法用 `product` 函数实现。已部分并行化。代码如下:

[1.f90](#)

```
1 function lagrange(x)
2     !works only on the given question.
3     implicit none
4     Real :: lagrange, x, ret
5     Integer :: length, i
6     Real, parameter :: xs(*) = (/1.05, 1.1, 1.15, 1.2/)
7     Real, parameter :: ys(*) = (/2.12, 2.2, 2.17, 2.32/)
8
9     ret = 0.
10    length = size(xs)
11    do i = 1, length
12        !$omp workshare
13        ret = ret + &
14            ys(i)*product(x-xs(1:i-1))*product(x-xs(i+1:length))/ &
15            product(xs(i)-xs(1:i-1))/product(xs(i)-xs(i+1:length))
16        !$omp end workshare
17    end do
18    lagrange = ret
19 end function lagrange
20
21 program main
22     implicit none
23     Real :: lagrange
24     write(*, *) 'f(1.075) = ', lagrange(1.075)
25     write(*, *) 'f(1.175) = ', lagrange(1.175)
26 end program
```

输出文件为[output.txt](#)。

2 IDL 编写拉格朗日插值，自己写/调包各一个，并比较。

买不起 IDL，支持正版。用 python 完成。

同上，直接套公式。为复用性，定义为类。代码如下：

[lagrange.py](#)

```

1  #!/usr/bin/python3
2  import numpy as np
3  import matplotlib.pyplot as plt
4
5  class Lagrange:
6      '''
7      This class works as a function once initialed.
8      '''
9
10     def __init__(self, xs, ys):
11         '''
12         __init__(self, xs, ys)
13
14         args:
15             xs, ys: points for interpolate.
16         '''
17         self.xs = xs.reshape(xs.size, 1)
18         self.ys = ys.reshape(ys.size, 1)
19
20     def __call__(self, x):
21         '''
22         __call__(self, x)
23
24         args:
25             x: a number or a ndarray.
26
27         returns:
28             pridiction of x, using lagrange interpolate.
29         '''
30         ret = 0
31         if isinstance(x, np.ndarray):
32             x = x.reshape(1, x.size)
33         else:
34             x = np.array(x).reshape(1, 1)

```

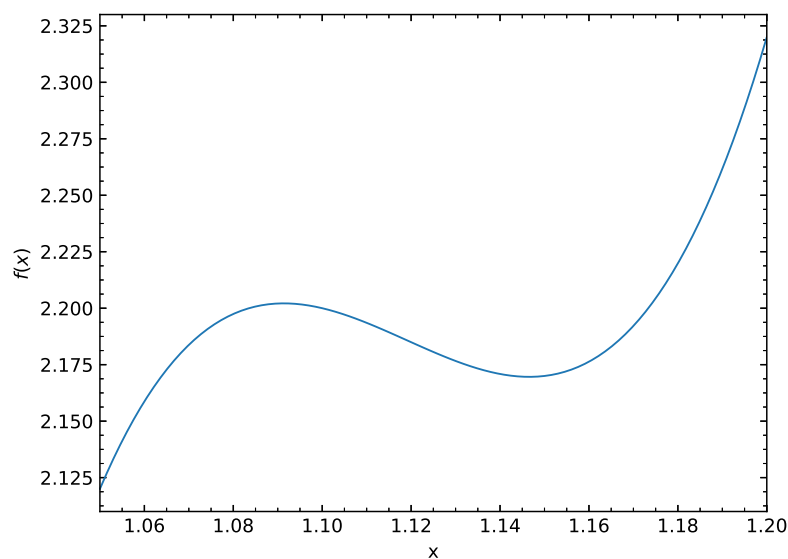
```

35         for i in range(len(xs)):
36             ret += self.ys[i][0]*np.product(x-self.xs[:i], axis=0)* \
37                 np.product(x-self.xs[i+1:], axis=0)/ \
38                 np.product(self.xs[i][0]-self.xs[:i,0])/ \
39                 np.product(self.xs[i][0]-self.xs[i+1:,0])
40         return ret
41
42 if __name__ == '__main__':
43     #Solve the question
44     import sys
45     xs = np.array([1.05, 1.1, 1.15, 1.2])
46     ys = np.array([2.12, 2.2, 2.17, 2.32])
47
48     f = Lagrange(xs, ys)
49     x = np.linspace(1.05, 1.2, 100)
50     y = f(x)
51     plt.plot(x, y, lw=1)
52     plt.minorticks_on()
53     plt.tick_params(which='both',
54                     direction='in',
55                     top=True,
56                     right=True)
57     plt.xlim(x.min(), x.max())
58     plt.xlabel(r' $x$ ')
59     plt.ylabel(r' $f(x)$ ')
60     if len(sys.argv) == 1:
61         plt.show()
62     else:
63         plt.savefig(sys.argv[1], format='eps')

```

输出图片:

[lagrange.eps](#)



调用 `scipy.interpolate.interp1d` 完成，代码如下：

[scipy-interpolate.py](#)

```

1 import sys
2 import numpy as np
3 from scipy.interpolate import interp1d
4 import matplotlib.pyplot as plt
5
6 xs = np.array([1.05, 1.1, 1.15, 1.2])
7 ys = np.array([2.12, 2.2, 2.17, 2.32])
8
9 #call function
10 f = interp1d(xs, ys, kind=xs.size-1)
11
12 x = np.linspace(1.05, 1.2, 100)
13 y = f(x)
14 plt.plot(x, y, lw=1)
15 plt.minorticks_on()
16 plt.tick_params(which='both',
17                 direction='in',
18                 top=True,
19                 right=True)
20 plt.xlim(x.min(), x.max())
21 plt.xlabel(r' $x$ ')
22 plt.ylabel(r' $f(x)$ ')
23 if len(sys.argv) == 1:
24     plt.show()

```

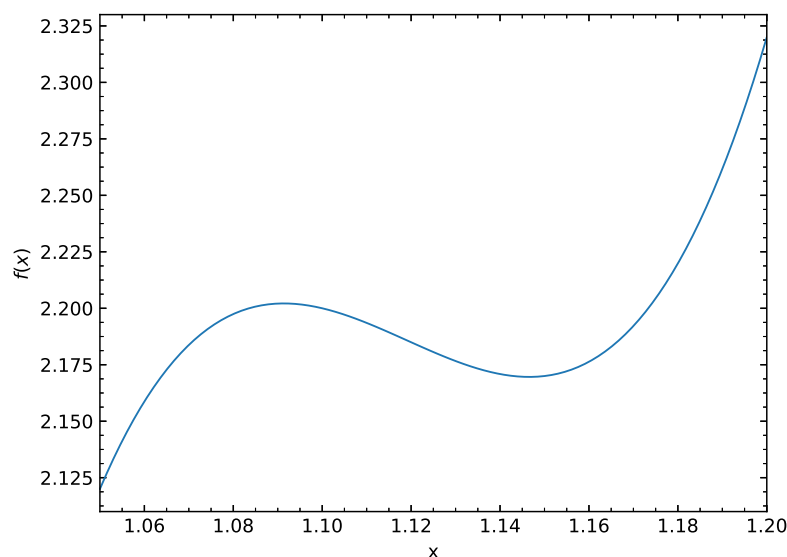
```

25 else:
26     plt.savefig(sys.argv[1], format='eps')

```

输出图片:

[scipy-interpolate.eps](#)



结果一样（为什么不呢？）。

3 求高次多项式的全部实根。

考虑用矩阵实现。由于 n 阶方阵有 n 个特征值，可构造方阵，使其特征值为 n 次方程的 n 个根。考虑如下矩阵：

$$M = \begin{pmatrix} 0 & 0 & \cdots & -p_0 \\ 1 & 0 & \cdots & -p_1 \\ \vdots & \ddots & & \vdots \\ 0 & \cdots & 1 & -p_{n-1} \end{pmatrix}$$

式中， p_i 为多项式中 x^i 项系数。容易算出， M 的特征多项式为：

$$p_0 + p_1\lambda + p_2\lambda^2 + \cdots + p_{n-1}\lambda^{n-1} + \lambda^n$$

所以 M 的特征值即为多项式方程的解。

例程中使用 QR 方法求解特征值，算法参考自[维基百科](#)。经过足够的迭代后，矩阵 $R \times Q$ 对角线上的元素即为矩阵的实特征值，如果该元素下方即左方元素为零的话。而其所有复特征值将在结果中表现为对角线附近 2×2 的方阵的特征值。参考<http://people.inf.ethz.ch/arbenz/ewp/Lnotes/chapter4.pdf>

在实验中，存在部分使得 QR 算法不收敛的情况，此时该算法将给出错误的结果。这种情况很少见。算法思路参考自[numpy](#)源码。

求解代码如下：

[util.f90](#)

```

1 module util
2     implicit none
3     contains
4         subroutine QR(a, q, r, n)
5             !q and r will be QR decomposition of a.
6             !a, q, and r should be n*n array
7
8             Real*8 :: a(:, :), q(:, :), r(:, :)
9             Integer :: n, i
10            Real*8, allocatable :: e(:, :), u(:), v(:, :), h(:, :)
11            Real*8 :: alpha
12
13            allocate(e(n, n))
14            allocate(u(n))
15            allocate(v(n, 1))
16            allocate(h(n, n))
17
18            e = 0
19            forall (i = 1:n)
20                e(i, i) = 1
21            end forall
22            r(:, :) = a
23            q(:, :) = e
24
25
26            do i = 1, n-1
27                u = 0
28                v = 0
29                h(:, :) = e
30                alpha = sqrt(sum(r(i:, i)**2))
31                u(i:) = r(i:, i) - e(i:, i)*alpha
32                v(i:, 1) = u(i:) / sqrt(sum(u(i:)**2))
33                h(i:, i:) = e(i:, i:) - 2*matmul(v(i:, :), transpose(v(i:, :)))
34                r(:, :) = matmul(h, r)
35                q(:, :) = matmul(q, transpose(h))
36            end do
37            r(:, :) = matmul(transpose(q), a)
38
39            deallocate(e)
40            deallocate(u)
41            deallocate(v)

```

```

42         deallocate(h)
43
44     end subroutine QR
45
46     subroutine eigen(a, x, n, e, max_step)
47         !eigen(a, x, n[, e=1e-5, max_step=2000])
48         !x will be a's eigenvalues.
49         !a should be shaped n*n, x's size should be n
50
51         Real*8 :: a(:, :), eo
52         Real*8 :: x(:)
53         Real*8, optional :: e
54         Integer, optional :: max_step
55         Integer :: n, i, max_stepo, j, num
56         Real*8 :: error
57         Real*8, allocatable :: q(:, :), r(:, :), a_t(:, :)
58         Logical, allocatable :: mask(:, :)
59         Logical :: flag
60
61         eo = 1e-5
62         max_stepo = 2000
63         if (present(e)) eo = e
64         if (present(max_step)) max_stepo = max_step
65
66         allocate(q(n, n))
67         allocate(r(n, n))
68         allocate(a_t(n, n))
69         allocate(mask(n, n))
70
71         mask = .false.
72         forall (i = 2:n)
73             forall (j = 1:i-1)
74                 mask(i, j) = .true.
75             end forall
76         end forall
77
78         a_t(:, :) = a
79
80         do i = 1, max_stepo
81             error = maxval(abs(a_t), mask=mask)
82             if (error < eo) then

```

```

83         goto 100
84     end if
85     call QR(a_t, q, r, n)
86     a_t(:, :) = matmul(r, q)
87 end do
88 100 continue
89 num = 0
90 do i = 1, n
91     flag = .true.
92     do j = 1, i-1
93         if (a_t(i, j) > eo) flag = .false.
94     end do
95     do j = i+1, n
96         if (a_t(j, i) > eo) flag = .false.
97     end do
98     if (flag) then
99         num = num + 1
100        x(num) = a_t(i, i)
101    end if
102 end do
103 n = num
104
105 deallocate(q)
106 deallocate(r)
107 deallocate(a_t)
108 deallocate(mask)
109
110 end subroutine eigen
111
112 subroutine solve(p, x, n)
113     !p(1) + p(2) * x + ... + p(n+1) * x**n
114
115     Real*8 :: p(:)
116     Real*8 :: x(:)
117     Integer :: n, i
118     Real*8, allocatable :: m(:, :)
119
120     allocate(m(n, n))
121
122     m = 0
123     forall (i = 1:n-1)

```



```

124         m(i+1, i) = 1
125     end forall
126     m(:, n) = -p(:n)/p(n+1)
127
128     call eigen(m, x, n)
129
130     deallocate(m)
131
132 end subroutine solve
133
134 end module util

```

测试代码如下:

[test.f90](#)

```

1 program main
2     use util
3     !There are still bugs in this program.
4     !Some times QR-algorithm is not convergent, and this program gives wrong answer
5     !i.e. p = (/ -1, 1, -1, 1/), x = 1 is a root, but can't be given here.
6     Real*8, allocatable :: p(:)
7     Real*8, allocatable :: x(:)
8     Integer :: n, i
9
10    write(0, *) 'Input order of the polynomial'
11    read(*, *) n
12    allocate(p(n+1))
13    allocate(x(n))
14
15    write(0, *) 'Input coefficients p(i)'
16    write(0, *) 'format: p(1) + p(2) * x + ... + p(n+1) * x^n'
17    read(*, *) p
18
19    call solve(p, x, n)
20    write(*, *) 'real roots are:'
21    do i = 1, n
22        write(*, *) x(i)
23    end do
24
25 end program main

```

测试输入文件为[input.txt](#), 输出文件为[output.txt](#), 输入提示保存为[err.txt](#)。

4 用四阶龙格-库塔格式求解初值问题

$$\frac{dy}{dx} = y^2 \cos x$$

$$y(0) = 1$$

$$0 \leq x \leq 0.8$$

直接套用公式求解即可。代码如下：

[runge-kutta.f90](#)

```

1 module runge_kutta
2     implicit none
3     contains
4         subroutine RK4_step(f, y0, n, x, dx, yout)
5             !Run one step of 4-order RK.
6             Real :: y0(n), yout(n), x, dx
7             Real, allocatable :: k1(:), k2(:), k3(:), k4(:)
8             Integer :: n, i, j
9             Real, external :: f
10
11             allocate(k1(n))
12             allocate(k2(n))
13             allocate(k3(n))
14             allocate(k4(n))
15
16             k1 = f(x, y0)
17             k2 = f(x + dx/2., y0 + k1*dx/2.)
18             k3 = f(x + dx/2., y0 + k2*dx/2.)
19             k4 = f(x + dx, y0 + dx*k3)
20
21             yout = y0 + dx/6*(k1 + 2*k2 + 2*k3 + k4)
22
23             deallocate(k1)
24             deallocate(k2)
25             deallocate(k3)
26             deallocate(k4)
27         end subroutine RK4_step
28
29         subroutine RK4(f, y0, n, x, dx, steps, yout)
30             !yout here is array of outputs in each step.
31             Real :: y0(n), yout(steps, n), x, dx
32             Integer :: n, steps, i

```

```

33         Real, external :: f
34
35         call RK4_step(f, y0, n, x, dx, yout(1, :))
36         do i = 2, steps
37             call RK4_step(f, yout(i-1, :), n, x+(i-1)*dx, dx, yout(i, :))
38         end do
39     end subroutine RK4
40 end module runge_kutta

```

测试代码如下:

[test.f90](#)

```

1 function f(t, y)
2     !dy/dt = f(t, y)
3     Real :: f
4     f = y**2 * cos(t)
5 end function f
6
7 program main
8     use runge_kutta
9     implicit none
10    Real :: y0(1) = (/1/), xr(2) = (/0., 0.8/)
11    Real, allocatable :: x(:), yout(:, :)
12    Integer :: n = 100, i !steps to run
13    Real, external :: f
14
15    allocate(x(n))
16    allocate(yout(n, 1))
17    forall (i = 1:n)
18        x(i) = xr(1) + (xr(2) - xr(1))/(n-1)*i
19    end forall
20
21    call RK4(f, y0, 1, xr(1), (xr(2)-xr(1))/(n-1), n, yout)
22
23    open(10, file='res.dat', form='unformatted')
24    write(10) x
25    write(10) yout
26    close(10)
27 end program

```

输出文件为[res.dat](#)。

画图代码如下:

[plot.py](#)

```
1 import numpy as np
2 from scipy.io import FortranFile
3 import matplotlib.pyplot as plt
4
5 f = FortranFile('res.dat', 'r')
6
7 x = f.read_reals(dtype=np.float32)
8 y = f.read_reals(dtype=np.float32)
9
10 plt.plot(x, y)
11 #plot more beautiful
12 plt.xlabel('x')
13 plt.ylabel('y')
14 plt.xlim(x.min(), x.max())
15 plt.minorticks_on()
16 plt.tick_params(which='both',
17                 top=True,
18                 right=True,
19                 direction='in')
20 plt.savefig('res.eps', format='eps')
21 f.close()
```

图像:

[res.eps](#)

