

October 1, 2023

## 1 It is a Non Linear Problem

```
[ ]: using JuMP
import Ipopt
```

```
[ ]: model = Model(Ipopt.Optimizer) # Using Non Linear solver
```

```
A JuMP Model
Feasibility problem with:
Variables: 0
Model mode: AUTOMATIC
CachingOptimizer state: EMPTY_OPTIMIZER
Solver name: Ipopt
```

```
[ ]: @variable(model, l, lower_bound = 0)
```

$$l$$

```
[ ]: @variable(model, b, lower_bound = 0)
```

$$b$$

```
[ ]: @variable(model, h, lower_bound = 0)
```

$$h$$

```
[ ]: corner_waste_cost = 4 * h^2
```

$$4h^2$$

```
[ ]: welding_cost = 2 * h
```

$$2h$$

```
[ ]: @constraint(model, l + 2 * h == 22)
```

$$l + 2h = 22$$

```
[ ]: @constraint(model, b + 2 * h == 17)
```

$$b + 2h = 17$$

```
[ ]: total_profit = @NLexpression(model, 8* l * b * h - corner_waste_cost -
    ↪welding_cost)
```

```
subexpression[1]: (8.0 * l * b * h - h * h * 4.0) - 2.0 * h
```

```
[ ]: @NLobjective(model, Max, total_profit)
```

```
[ ]: @show model
```

```
model = A JuMP Model
Maximization problem with:
Variables: 3
Objective function type: Nonlinear
`AffExpr`-in-`MathOptInterface.EqualTo{Float64}`: 2 constraints
`VariableRef`-in-`MathOptInterface.GreaterThan{Float64}`: 3 constraints
Model mode: AUTOMATIC
CachingOptimizer state: EMPTY_OPTIMIZER
Solver name: Ipopt
Names registered in the model: b, h, l

A JuMP Model
Maximization problem with:
Variables: 3
Objective function type: Nonlinear
`AffExpr`-in-`MathOptInterface.EqualTo{Float64}`: 2 constraints
`VariableRef`-in-`MathOptInterface.GreaterThan{Float64}`: 3 constraints
Model mode: AUTOMATIC
CachingOptimizer state: EMPTY_OPTIMIZER
Solver name: Ipopt
Names registered in the model: b, h, l
```

```
[ ]: optimize!(model)
```

```
*****
This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).
For more information visit https://github.com/coin-or/Ipopt
*****
```

```
This is Ipopt version 3.14.13, running with linear solver MUMPS 5.6.1.
```

```

Number of nonzeros in equality constraint Jacobian...:      4
Number of nonzeros in inequality constraint Jacobian.:      0
Number of nonzeros in Lagrangian Hessian...:              6

```

```

Total number of variables...:      3
      variables with only lower bounds:      3
      variables with lower and upper bounds:    0
      variables with only upper bounds:      0
Total number of equality constraints...:      2
Total number of inequality constraints...:      0
      inequality constraints with only lower bounds:    0
      inequality constraints with lower and upper bounds: 0
      inequality constraints with only upper bounds:    0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	-2.0391979e-02	2.20e+01	1.13e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	-4.1810080e+00	1.99e+01	7.69e+01	-1.0	8.54e+00	-	1.17e-03	9.28e-02h	1
2	-2.6539272e+02	3.55e-15	3.76e+02	-1.0	7.64e+00	-	1.09e-02	1.00e+00h	1
3	1.1296492e+03	3.55e-15	2.55e+02	-1.0	2.89e+00	2.0	6.54e-01	1.00e+00f	1
4	3.5562631e+03	0.00e+00	6.87e+02	-1.0	1.04e+01	1.5	2.26e-01	1.00e+00f	1
5	4.1765848e+03	0.00e+00	4.06e+01	-1.0	2.25e+00	-	1.00e+00	1.00e+00f	1
6	4.1874980e+03	0.00e+00	9.96e-01	-1.0	3.53e-01	-	1.00e+00	1.00e+00f	1
7	4.1875048e+03	0.00e+00	6.64e-04	-1.7	9.11e-03	-	1.00e+00	1.00e+00f	1
8	4.1875048e+03	0.00e+00	1.78e-09	-3.8	5.85e-06	-	1.00e+00	1.00e+00f	1
9	4.1875048e+03	0.00e+00	1.85e-11	-5.7	2.88e-09	-	1.00e+00	1.00e+00f	1
iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
10	4.1875048e+03	0.00e+00	3.53e-13	-8.6	3.61e-11	-	1.00e+00	1.00e+00f	1

Number of Iterations...: 10

	(scaled)	(unscaled)
Objective...:	-4.1875047654921573e+03	4.1875047654921573e+03
Dual infeasibility...:	3.5295945402507846e-13	3.5295945402507846e-13
Constraint violation...:	0.0000000000000000e+00	0.0000000000000000e+00
Variable bound violation:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity...:	2.5059035703024915e-09	2.5059035703024915e-09
Overall NLP error...:	2.5059035703024915e-09	2.5059035703024915e-09

```

Number of objective function evaluations      = 11
Number of objective gradient evaluations      = 11
Number of equality constraint evaluations      = 11
Number of inequality constraint evaluations    = 0
Number of equality constraint Jacobian evaluations = 1
Number of inequality constraint Jacobian evaluations = 0
Number of Lagrangian Hessian evaluations     = 10
Total seconds in IPOPT                       = 1.358

```

EXIT: Optimal Solution Found.

```
[ ]: @show value.(l)
```

```
value.(l) = 15.742373793241692
```

```
15.742373793241692
```

```
[ ]: @show value.(b)
```

```
value.(b) = 10.742373793241692
```

```
10.742373793241692
```

```
[ ]: @show value.(h)
```

```
value.(h) = 3.1288131033791533
```

```
3.1288131033791533
```

```
[ ]: @show objective_value(model) # Max Profit
```

```
objective_value(model) = 4187.504765492157
```

```
4187.504765492157
```