Scientific Computing, Spring 2002 (http://www.math.nyu.edu/faculty/goodman/teaching/SciComp2002/)

Sample final

- 1. For each statement, answer true or false and explain your reasoning in a sentence or two. If a statement is false, the best way to explain that is by giving a counterexample.
 - a. There is a function, f(x) that we wish to compute numerically. We know that for x values around 10^{-3} , f is about 10^{5} and f' is about 10^{10} . This function is too ill conditioned to compute in single precision.
 - **b.** The function from part a is too ill conditioned to be computed in double precision.
 - c. If we apply Newton's method to finding the minimum of the function $f(x, y, z) = x^4 + x^2y^2 + (x 2 * z)^4$, we will get local quadratic convergence. Note that the minimum occurs at x = y = z = 0.
 - **d.** I have a random variable X with density $f(x) = \frac{1}{Z}e^{-x^4}$ and I do not know Z. There is a way to sample the X population without first computing Z.
 - **e.** For X as in part d, it is possible to compute Z to high accuracy by a simple quadrature method.
 - **f.** Monte Carlo would be the best (fastest, easiest to code, most accurate) way to compute $E[X^2]$, where X is as in part d.
- 2. Give a simple way to get a fourth order finite difference approximation to

$$\frac{\partial^2 f}{\partial x \partial y}(x, y)$$

using the same step size, h, in x and y. You need not give the precise coefficients, but you should explain how a code to do it would work. Your method should not use more than 25 evaluations of the function f.

3. Suppose the vectors in R^2 , $\begin{pmatrix} x_n \\ y_n \end{pmatrix}$, satisfy the relations

$$\begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} = \begin{pmatrix} 2 & 4 \\ 3 & 5 \end{pmatrix} \begin{pmatrix} x_n \\ y_n \end{pmatrix} + \begin{pmatrix} y_{n-1} \\ 6x_{n-1} \end{pmatrix} .$$

Find a 4×4 matrix whose eigenvalues determine whether the numbers x_n or y_n remain bounded as $n \to \infty$.

4. We create a piecewise linear interpolation for a smooth function f(x) interpolating at the grid points $x_k = k * \Delta x$.

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- **a.** How does the error depend on Δx ?
- **b.** Describe an adaptive strategy that chooses Δx in a systematic way to achieve an error less than ϵ . Assume that you have a procedure that computes the error for a given Δx .
- 5. You have a function f(x) (which is really n functions of n variables $(f_1(x_1, \ldots, x_n), \ldots, f_n(x))$, and a solver that finds $x \in R^n$ with f(x) = c for $c = (c_1, \ldots, c_n)$. You have a procedure that evaluates f(x) accurately for any x but you did not write the solver and do not know how well it works. You run the solver in single and double precision for a certain c and get answers that differ by 15%. You do not know whether the solver is at fault or the problem of finding x from c is ill conditioned. What could you do to find out?
- **6.** We have the following first pass code with the important lines numbered.

```
#define N
            12345
#define MAX 100
int main () {
    double a[N], b[N];
    double sum = 0;
    for ( int i = 0; i < N; i++)
                                              // 1
       a[i] = 1/(1 + double(i));
                                              // 2
                // double a[i] if i is even
       if (i % 2) a[i] *= 2;
                                              // 3
       sum += a[sqrt(i)];
                                              // 4
    b[0] = 0;
    int n = (int) sum;
    if (n > N) n = N;
              i = 1; i < n-1; i++) {
                                              // 5
       b[i] = (b[i-1] + a[i+1]) / b[i-1];
                                              // 6
       if ( i * b[i] > MAX ) break; }
                                              // 7
    cout << "Reached i = " << i << end;</pre>
   return 0; //Nothing can possibly go wrong here.
```

- a. The intermediate representation of the loop in lines 5-6 contains an invariant expression, an arithmetic calculation whose operands and answer do not change during the loop. What is it?
- **b.** Does the array element reference pattern in line 4 very bad for cache performance?
- **c.** Which of the conditionals is worse for pipeline performance with branch prediction, line 3 or line 7? Explain.

- **d.** We are considering rewriting the loop 1-4 to eliminate the conditional in line 3. Would the cache performance get worse? Would the rewrite result in the code becoming slower?
- **e.** Can we combine the two loops into one loop to improve cache performance? Would this make the code faster?

Some topics not tested here but possible for the final: IEEE arithmetic, numerical linear algebra, LU factorization, conditioning. Monte Carlo sampling methods and error bars, ...