## EE5904/ME5404 Neural Networks: Homework #2 XU NUO, A0313771H

## Q1. Rosenbrock's Valley Problem

Consider the Rosenbrock's Valley function:

$$f(x, y) = (1 - x)^2 + 100(y - x^2)^2$$

a). Show that it has a global minimum at (x, y) = (1,1) where f(x, y) = 0.

Now suppose the starting point is randomly initialized in the open interval (-1,1) for x and y, find the global minimum using:

b). Steepest (Gradient) descent method

$$w(k+1) = w(k) - \eta g(k)$$

with learning rate  $\eta = 0.001$ . Here the weight vector refers to the two-dimensional vector [x, y]. Record the number of iterations when f(x, y) converges to (or very close to) 0 and plot out the trajectory of (x, y) in the 2-dimensional space. Also plot out the function value as it approaches the global minimum. What would happen if a larger learning rate, say  $\eta = 1.0$ , is used?

c). Newton's method (as discussed on page 13 in the slides of lecture Four)

$$\Delta w(n) = -H^{-1}(n)g(n)$$

Record the number of iterations when f(x,y) converges to (or very close to) 0 and plot out the trajectory of (x,y) in the 2-dimensional space. Also plot out the function value as it approaches the global minimum.

#### A1.

a). First, let the first-order partial derivatives of f(x, y) with respect to x and y be 0 respectively.

$$\frac{\partial f(x,y)}{\partial x} = 400x^3 - 400xy + 2x - 2 = 0 \tag{1}$$

$$\frac{\partial f(x,y)}{\partial y} = 200y - 200x^2 = 0$$
 (2)

(x,y) that conform to the above two equations are all candidate extreme points of the function. From (2) we can get  $y = x^2$ . Substituting  $y = x^2$  into (1) gives us (x,y) = (1,1). Therefore (1,1) is the only extreme point of the function. The sum of two square terms constitutes the function so obviously  $f(x,y) \ge 0$ .  $f(x,y) \ge f(1,1) = 0$  shows that it has a global minimum at (x,y) = (1,1) where f(x,y) = 0.

b). I randomly initialize x and y in a strictly open interval of (-1,1) and define the Rosenbrock function and its partial derivative. The learning rate is set to 0.001 and the number of iterations is 100000. The threshold is set to 0.001. When the L2 norm of the gradient is less than the threshold, the function is considered to have basically converged and reached the global minimum. The code is shown below:

```
# Import necessary libraries
import matplotlib.pyplot as plt
import numpy as np
import random

# Starting point randomly initialized in the open interval (-1,1)
while True:
    x_init = random.uniform(-1, 1)
```

```
y_init = random.uniform(-1, 1)
   if (x init != -1 and x init != 1) or (y init != -1 and y init != 1):
       break
# Define Rosenbrock function
def rosenbrock(x, y):
   return (1-x) ** 2 + 100 * (y - x ** 2) **2
# Define the derivative function of Rosenbrock
def rosenbrock_gradient(x, y):
   dfx = 400 * x ** 3 - 400 * x * y + 2 * x - 2
   dfy = 200 * y - 200 * x ** 2
   return np.array([dfx, dfy])
# Define hyperparameters
xy_trajectory = []
function_values = []
learning_rate = 0.001
epochs = 100000
threshold = 0.001
x update = x init
y_update = y_init
# Find the minimum value of the rosenbrock function by steepest gradient descent method
for i in range(epochs):
   xy_trajectory.append((x_update, y_update))
   function_values.append(rosenbrock(x_update,y_update))
   grad = rosenbrock_gradient(x_update, y_update)
   x_update -= learning_rate * grad[0]
   y_update -= learning_rate * grad[1]
   # If the L2 norm of the gradient is less thant the predetermined threshold
   # The function is considered to have basically converged
   if np.linalg.norm(grad) < threshold:</pre>
       print(f"Converged at epoch {i+1}")
       break
print(f"Final (x, y): ({x_update:.6f}, {y_update:.6f})")
print(f"Function value at final point: {rosenbrock(x_update, y_update):.6f}")
# Extract x and y values of each interation separately
x_vals, y_vals = zip(*xy_trajectory)
# Plot the trajectory of (x,y)
```

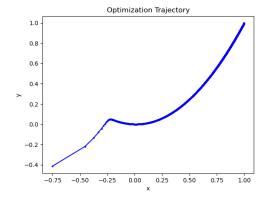
```
plt.figure()
plt.plot(x_vals, y_vals, marker = "o", linestyle = "-", color = "b", markersize = 2)
plt.xlabel("x")
plt.ylabel("y")
plt.title("Optimization Trajectory")
plt.show(block = False)

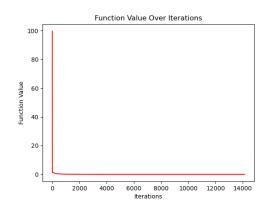
# Plot the function value
plt.figure()
plt.plot(range(len(function_values)), function_values, color = "r")
plt.xlabel("Iterations")
plt.ylabel("Function Value")
plt.title("Function Value Over Iterations")
plt.show()
```

```
Converged at epoch 14141

Final (x, y): (0.998884, 0.997764)

Function value at final point: 0.000001
```





The function converged at epoch 14141 at (0.998884, 0.997764) when threshold is set to 0.001. The function value at this point is 0.000001. We can basically determine that the global minimum point of Rosenbrock function is at (1,1) and the function value is 0.

When the learning rate is too high, such as when it is adjusted to 1, the program will prompt error messages as shown below:

```
RuntimeWarning: overflow encountered in scalar power
RuntimeWarning: overflow encountered in scalar multiply
RuntimeWarning: invalid value encountered in scalar subtract
Final (x, y): (nan, nan)
Function value at final point: nan
```

This issue arises because the Rosenbrock function exhibits steep gradient variations. When combined with an excessively large learning rate, the values of x and y extreme updates over multiple iterations, leading to numerical instability. As a result, the values exceed the floating-point range, causing overflow and gradient

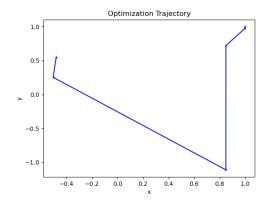
explosion, rather than gradually converging to the optimal solution.

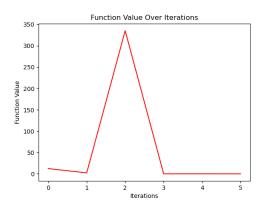
c). The code for finding the global minimum using Newton's method is as follows:

```
# Import necessary libraries
import matplotlib.pyplot as plt
import numpy as np
import random
# Starting point randomly initialized in the open interval (-1,1)
   x_init = random.uniform(-1, 1)
   y_init = random.uniform(-1, 1)
   if (x_init != -1 and x_init != 1) or (y_init != -1 and y_init != 1):
       break
# Define Rosenbrock function
def rosenbrock(x, y):
   return (1-x) ** 2 + 100 * (y - x ** 2) **2
# Define the derivative function of Rosenbrock
def rosenbrock_gradient(x, y):
   dfx = 400 * x ** 3 - 400 * x * y + 2 * x - 2
   dfy = 200 * y - 200 * x ** 2
   return np.array([dfx, dfy])
# Define the Hessian Matrix for Rosenbrock
def rosenbrock_hessian(x, y):
   f_xx = 1200 * x ** 2 - 400 * y + 2
   f_xy = -400 * x
   f_yx = -400 * x
   f_yy = 200
   return np.array([[f_xx, f_xy],
                   [f_yx, f_yy]])
# Define hyperparameters
xy_trajectory = []
function_values = []
epochs = 100
threshold = 0.001
x_update = x_init
y_update = y_init
# Find the minimum value of the rosenbrock function by Newton's Method
```

```
for i in range(epochs):
   xy_trajectory.append((x_update, y_update))
   function_values.append(rosenbrock(x_update,y_update))
   grad = rosenbrock_gradient(x_update, y_update)
   hessian = rosenbrock_hessian(x_update, y_update)
   delta_w = np.linalg.inv(hessian) @ grad
   x_update -= delta_w[0]
   y_update -= delta_w[1]
   # If the L2 norm of the gradient is less thant the predetermined threshold
   # The function is considered to have basically converged
   if np.linalg.norm(grad) < threshold:</pre>
       print(f"Converged at epoch {i+1}")
       break
print(f"Final (x, y): ({x update:.6f}, {y update:.6f})")
print(f"Function value at final point: {rosenbrock(x_update, y_update):.6f}")
# Extract x and y values of each interation separately
x_vals, y_vals = zip(*xy_trajectory)
# Plot the trajectory of (x,y)
plt.figure()
plt.plot(x_vals, y_vals, marker = "o", linestyle = "-", color = "b", markersize = 2)
plt.xlabel("x")
plt.ylabel("y")
plt.title("Optimization Trajectory")
plt.show(block = False)
# Plot the function value
plt.figure()
plt.plot(range(len(function_values)), function_values, color = "r")
plt.xlabel("Iterations")
plt.ylabel("Function Value")
plt.title("Function Value Over Iterations")
plt.show()
Converged at epoch 6
Final (x, y): (1.000000, 1.000000)
```

Function value at final point: 0.000000





The function converged at epoch 6 at (1,1) when threshold is set to 0.001. The function value at this point is 0. Using Newton's method to find the global minimum point requires defining the Hessian matrix of the Rosenbrock function and multiplying its inverse matrix with the matrix composed of gradients to obtain the updated values of x and y. The Hessian matrix can automatically adjust the direction and step size, so there will be no oscillation and no need for a learning rate. And because the first-order and second-order derivatives are used at the same time, the convergence speed is quadratic, and the error is reduced by the square of each iteration, so the function converges extremely quickly, but the need to calculate the second-order derivative also increases the amount of calculation for each step.

#### **Q2.** Function Approximation

Consider using MLP to approximate the following function:

$$y = 1.2\sin(\pi x) - \cos(2.4\pi x)$$
 for  $x \in [-1.6, 1.6]$ 

The training set is generated by dividing the domain [-1.6,1.6] using a uniform step length 0.05, while the test set is constructed by dividing the domain [-1.6,1.6] using a uniform step length 0.01. You may use the MATLAB deep learning toolbox to implement a MLP (see the Appendix for guidance) and do the following experiments:

a): Use the sequential mode with BP algorithm and experiment with the following different structures of the MLP: 1-n-1 (where n = 1, 2, ..., 10, 20, 50, 100). For each architecture plot out the outputs of the MLP for the test samples after training and compare them to the desired outputs. Try to determine whether it is under-fitting, proper fitting or over-fitting. Identify the minimal number of hidden neurons from the experiments, and check if the result is consistent with the guideline given in the lecture slides. Compute the outputs of the MLP when x = -3 and +3, and see if the MLP can make reasonable predictions outside of the domain of the input limited by the training set.

- b). Use the batch mode with trainlm algorithm to repeat the above procedure.
- c). Use the batch mode with trainbr algorithm to repeat the above procedure.

## A2.

a). I created a 1-n-1 MLP using *feedforward* function in MATLAB. For the parameters, I chose *traingd* for the most common gradient descent backpropagation, *mse* as the loss function, 0.01 as the learning rate, and trained the model for 500 epochs. The training was done in a sample-by-sample sequential mode, training one sample at a time and updating the MLP using *adapt* function. The code is shown below:

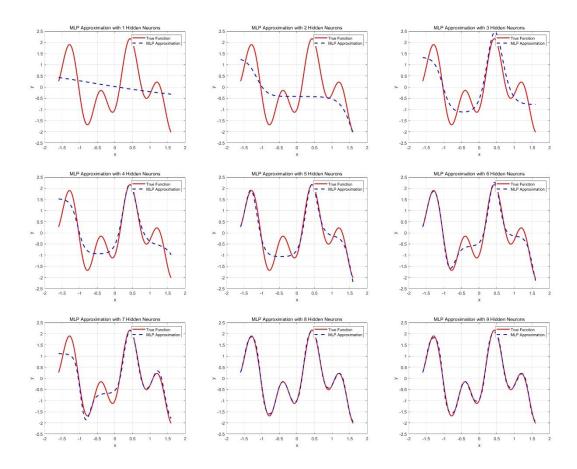
```
clear;
close all;
% Generate data for training and testing
x_{train} = -1.6 : 0.05 : 1.6;
y_train = 1.2 * sin(pi * x_train) - cos(2.4 * pi * x_train);
x_{test} = -1.6 : 0.01 : 1.6;
y_{test} = 1.2 * sin(pi * x_{test}) - cos(2.4 * pi * x_{test});
% The number of hidden neurons
hidden_neurons = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 20, 50, 100];
% Epochs set to 500 for training
epochs = 500;
for i = 1:length(hidden_neurons)
   % Convert from numeric arrays to cell arrays
   % Used by the adapt function for sequential mode training.
   x_cell = num2cell(x_train, 1);
   y_cell = num2cell(y_train, 1);
   n = hidden_neurons(i); % One hidden layer with n neurons
   net = feedforwardnet(n); % Define an MLP with n hidden neurons and SISO
   net.trainFcn = 'traingd'; % Regular gradient descent BP as training function
   net.performFcn = 'mse'; % Mean Square Error as performance function
   net.trainParam.lr = 0.01; % Learning rate set to 0.01
   net.trainParam.epochs = epochs; % Epochs set to 500
   % Sequential mode training
   for j = 1:epochs
       idx = randperm(length(x_train)); % Shuffle the order of training data to improve
generalization ability
       net = adapt(net, x_cell(:,idx), y_cell(:,idx)); % Sample by sample training
   end
   % Using the trained MLP to predict the test set
   y_pred = net(x_test);
   % Plot the original function and the function inferred by the MLP
   figure;
   plot(x_test, y_test, 'r', 'LineWidth', 2);
   hold on;
   plot(x_test, y_pred, 'b--', 'LineWidth', 2);
```

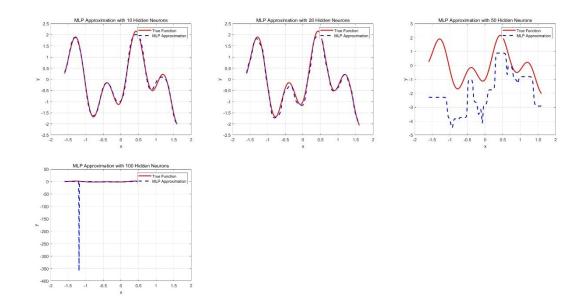
```
legend('True Function', 'MLP Approximation');
xlabel('x');
ylabel('y');
title(['MLP Approximation with ', num2str(n), ' Hidden Neurons']);
grid on;

% Preidictions out of the training set
x_extra = [-3, 3];
y_extra_pred = net(x_extra);

disp(['Hidden Neurons: ', num2str(n)]);
disp('Ground truth for x=-3: 0.8090')
disp(['MLP Prediction for x=-3: ', num2str(y_extra_pred(1))]);
disp('Ground truth for x=3: 0.8090')
disp(['MLP Prediction for x=3: ', num2str(y_extra_pred(2))]);
disp('------');
end
```

When the number of hidden layer neurons is different, the degree of MLP's fitting of the original function is shown in the following figures:

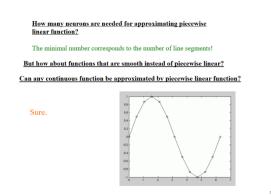




By observing the degree of fit of the original function and the MLP approximated function in the figures, we can decide whether the model is under-fitting, proper-fitting, or over-fitting:

| Degree of Fit            | Under-fitting |   |   |   |   |   | Proper-fitting |    |     |   |   |    |    |
|--------------------------|---------------|---|---|---|---|---|----------------|----|-----|---|---|----|----|
| Number of Hidden Neurons | 1             | 2 | 3 | 4 | 5 | 6 | 7              | 50 | 100 | 8 | 9 | 10 | 20 |

From the table, we can see that the minimum number of hidden layer neurons required for proper-fitting is 8. The result is consistent with the guideline given in the lecture slide as shown below:



Sequential mode updates parameters sample by sample, which makes convergence difficult, especially when n=50 or n=100 which far exceeds the data complexity. The impact of each sample's gradient update on the weight may be amplified. In addition, as can be seen from the figures, the predicted model does not overlap too much with the original function, so I think that n=50 and n=100 make the model underfit rather than overfit.

When the number of neurons in the hidden layer is different, the predicted output of MLP when x=-3 and x=3 are as follows:

Hidden Neurons: 1

```
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.51851
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.19595
-----
Hidden Neurons: 2
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 1.2323
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -4.1242
Hidden Neurons: 3
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 1.7472
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.89462
Hidden Neurons: 4
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.80332
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.41676
______
Hidden Neurons: 5
Ground truth for x=-3:0.8090
MLP Prediction for x=-3: -0.30949
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -3.8367
Hidden Neurons: 6
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.38681
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -3.096
_____
Hidden Neurons: 7
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.28911
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.0517
_____
Hidden Neurons: 8
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.72655
```

```
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.1348
_____
Hidden Neurons: 9
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.049021
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.0468
_____
Hidden Neurons: 10
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 2.5793
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -1.975
Hidden Neurons: 20
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.0059098
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.3874
_____
Hidden Neurons: 50
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -45.4695
Ground truth for x=3:0.8090
MLP Prediction for x=3: 129.9262
Hidden Neurons: 100
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 2458.2731
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -1113.6718
-----
```

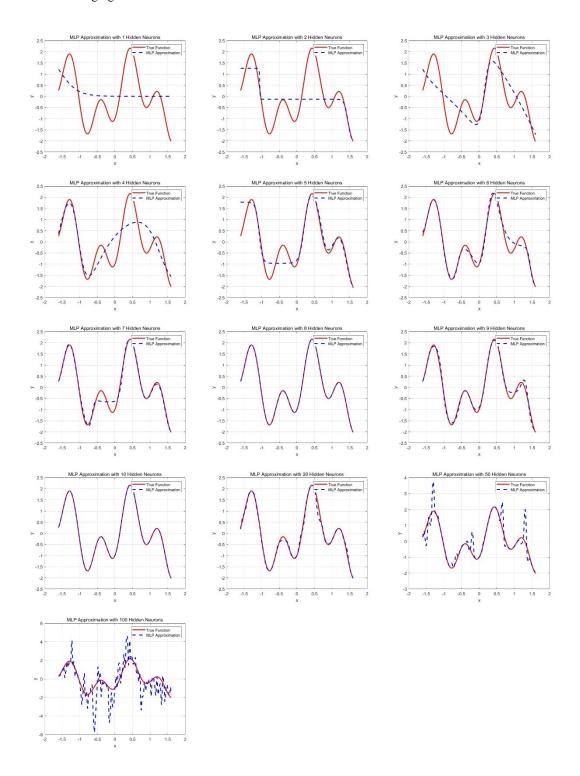
From the output of the program, we can see that the model cannot make reasonable predictions outside the domain of the input limited by the training set. This is because the model prefers linear predictions outside the range of the training set and makes poor predictions for nonlinear transformations.

b). The code for training the MLP with trainlm using the batch mode is shown below:

```
clc;
clear;
close all;
```

```
% Generate data for training and testing
x train = -1.6 : 0.05 : 1.6;
y_train = 1.2 * sin(pi * x_train) - cos(2.4 * pi * x_train);
x_{test} = -1.6 : 0.01 : 1.6;
y_{test} = 1.2 * sin(pi * x_{test}) - cos(2.4 * pi * x_{test});
% The number of hidden neurons
hidden_neurons = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 20, 50, 100];
for i = 1:length(hidden_neurons)
   n = hidden_neurons(i); % One hidden layer with n neurons
   net = feedforwardnet(n); % Define an MLP with n hidden neurons and SISO
   net.trainFcn = 'trainlm'; % Levenberg-Marquardt BP as training function, no learning
rate involved
   net.performFcn = 'mse'; % Mean Square Error as performance function
   % Train the MLP
   net = train(net, x_train, y_train); % Default epochs set to 1000 and use batch mode
   % Using the trained MLP to predict the test set
   y_pred = net(x_test);
   % Plot the original function and the function inferred by the MLP
   figure;
   plot(x_test, y_test, 'r', 'LineWidth', 2);
   plot(x_test, y_pred, 'b--', 'LineWidth', 2);
   legend('True Function', 'MLP Approximation');
   xlabel('x');
   ylabel('y');
   title(['MLP Approximation with ', num2str(n), ' Hidden Neurons']);
   grid on;
   % Preidictions out of the training set
   x_{extra} = [-3, 3];
   y_extra_pred = net(x_extra);
   disp(['Hidden Neurons: ', num2str(n)]);
   disp('Ground truth for x=-3: 0.8090')
   disp(['MLP Prediction for x=-3: ', num2str(y_extra_pred(1))]);
   disp('Ground truth for x=3: 0.8090')
   disp(['MLP Prediction for x=3: ', num2str(y_extra_pred(2))]);
```

When the number of hidden layer neurons is different, the degree of MLP's fitting of the original function is shown in the following figures:



By observing the degree of fit of the original function and the MLP approximated function in the figures, we can decide whether the model is under-fitting, proper-fitting, or over-fitting:

| Degree of Fit            | Under-fitting |   |   |   |   |   |   | Proper-fitting |   |    |    | Over-fitting |     |
|--------------------------|---------------|---|---|---|---|---|---|----------------|---|----|----|--------------|-----|
| Number of Hidden Neurons | 1             | 2 | 3 | 4 | 5 | 6 | 7 | 8              | 9 | 10 | 20 | 50           | 100 |

From the table, we can see that the minimum number of hidden layer neurons required for proper-fitting is still 8.

When the number of neurons in the hidden layer is different, the predicted output of MLP when x=-3 and x=3 are as follows:

```
Hidden Neurons: 1
Ground truth for x=-3:0.8090
MLP Prediction for x=-3: 2.2583
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 0.0025707
Hidden Neurons: 2
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 1.26
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.0644
______
Hidden Neurons: 3
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 19.4167
Ground truth for x=3:0.8090
MLP Prediction for x=3: -7.4566
Hidden Neurons: 4
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -11.0854
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -1.9794
Hidden Neurons: 5
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 1.7841
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.4057
Hidden Neurons: 6
Ground truth for x=-3:0.8090
MLP Prediction for x=-3: 0.19935
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.0201
```

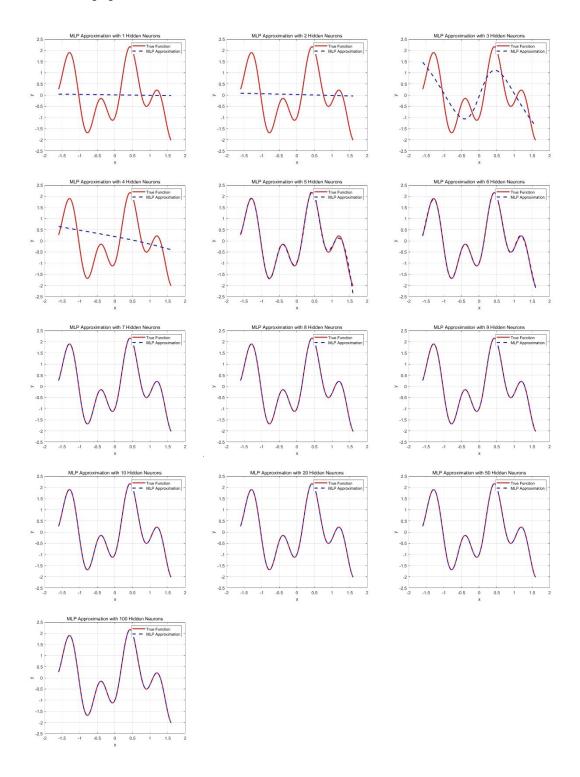
```
Hidden Neurons: 7
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.12433
Ground truth for x=3:0.8090
MLP Prediction for x=3: -2.2871
Hidden Neurons: 8
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.27241
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.3679
_____
Hidden Neurons: 9
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.017797
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.0174
Hidden Neurons: 10
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.37373
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.3309
Hidden Neurons: 20
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.51566
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.113
_____
Hidden Neurons: 50
Ground truth for x=-3:0.8090
MLP Prediction for x=-3: -0.083564
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 0.4076
_____
Hidden Neurons: 100
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.21512
Ground truth for x=3:0.8090
MLP Prediction for x=3: -2.2767
-----
```

From the output of the program, we can see that the model still cannot make reasonable predictions outside the

domain of the input limited by the training set.

c). Because the code only needs to change the backpropagation algorithm from *trainlm* to *trainbr*, the code is not shown for brevity.

When the number of hidden layer neurons is different, the degree of MLP's fitting of the original function is shown in the following figures:



By observing the degree of fit of the original function and the MLP approximated function in the figures, we can

decide whether the model is under-fitting, proper-fitting, or over-fitting:

| Degree of Fit            |   | Under- | Proper-fitting |   |   |   |   |   |   |    |    |    |     |
|--------------------------|---|--------|----------------|---|---|---|---|---|---|----|----|----|-----|
| Number of Hidden Neurons | 1 | 2      | 3              | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 20 | 50 | 100 |

From the table, we can see that the minimum number of hidden layer neurons required for proper-fitting is 5. I think it is because the Bayesian regularization property of the *trainbr* algorithm enables it to automatically adjust the complexity of the network, thereby achieving good fitting results even with fewer hidden neurons. It's worth noting that n=50 and n=100 still make the MLP properly fit the function. It's because *trainbr* uses Bayesian Regularization, it automatically adjusts the number of effective parameters of the network, so even if n is large, not all neurons are involved in fitting. Besides, it balances MSE and the weight size. They all contribute to avoiding overfitting.

When the number of neurons in the hidden layer is different, the predicted output of MLP when x=-3 and x=3 are as follows:

```
Hidden Neurons: 1
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.069324
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.049812
______
Hidden Neurons: 2
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.13897
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -0.095833
Hidden Neurons: 3
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 2.8727
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.8366
Hidden Neurons: 4
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 1.0464
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -1.0065
-----
Hidden Neurons: 5
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 8.3082
Ground truth for x=3: 0.8090
```

```
MLP Prediction for x=3: -16.2028
Hidden Neurons: 6
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -3.2189
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -4.1539
-----
Hidden Neurons: 7
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -13.006
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 12.7703
_____
Hidden Neurons: 8
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 0.28064
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 3.2699
-----
Hidden Neurons: 9
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: 2.1551
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -2.4152
_____
Hidden Neurons: 10
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.38695
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 5.0142
_____
Hidden Neurons: 20
Ground truth for x=-3:0.8090
MLP Prediction for x=-3: 0.51077
Ground truth for x=3: 0.8090
MLP Prediction for x=3: 2.4324
Hidden Neurons: 50
Ground truth for x=-3: 0.8090
MLP Prediction for x=-3: -0.0039936
Ground truth for x=3: 0.8090
MLP Prediction for x=3: -1.9679
```

```
Hidden Neurons: 100

Ground truth for x=-3: 0.8090

MLP Prediction for x=-3: -0.28667

Ground truth for x=3: 0.8090

MLP Prediction for x=3: -1.2572
```

From the output of the program, we can see that the model still cannot make reasonable predictions outside the domain of the input limited by the training set.

### Q3. Image Classification (Mod (71,3) = 2 (deer vs. ship))

Multi-layer perceptron (MLP) can be used to solve real-world pattern recognition problems. In this assignment, MLP will be designed to handle a binary classification task, i.e. animals vs. man-made objects. Specifically, students are divided into 3 groups based on matric numbers and each group is assigned with different dataset as illustrated in the following Table.

| Group ID | Animals with label 1 | Man-Made objects with label 0 |
|----------|----------------------|-------------------------------|
| 0        |                      |                               |
|          | cat                  | airplane                      |
| 1        | 490                  |                               |
|          | dog                  | automobile                    |
| 2        | STORY.               | E                             |
|          | deer                 | ship                          |

You may download the zipped dataset (e.g. group\_0.zip) from CANVAS. After unzipping, you will find two folders respectively, one of which is named by an animal and the other of which is named by a man-made object. You should use "0" as the label of man-made objects during training and "1" for animals. In each folder, there are 500 images indexing from 000 to 499. The training set you used should consists of images in each folder indexing from 000 to 449, so there are totally 900 images for training. The remaining images in each folder indexing from 450 to 499 are used as the test set, so there should be totally 100 images in the test set.

All the images are provided in RGB format with size 32\*32\*3. To simplify the problem, I recommend you transforming colorful images into grayscale, so that each image is in size of 32\*32. Besides, you can also reshape the matrix into a one-dimension vector with size 1024. (Hints: Two built-in functions rgb2gray and reshape would help; Please make full use of the official documentation, you can search all built-in functions from MATLAB official website.)

You are required to complete the following tasks:

a). Apply Rosenblatt's perceptron (single layer perceptron) to the dataset of your assigned group. After the training procedure, calculate the *classification accuracy* for *both* the training set and validation set, and evaluate the performance of the network.

- b). The global mean and variance of a dataset may influence the stability of training and the final performance of the model obtained. You can try to calculate the global mean and variance of the whole dataset, then *subtract* the mean value from each image and *divide* each image by the standard deviation. *Compare* the result with that in a) and *explain* it.
- c). Apply MLP to the dataset of your assigned group using *batch mode* training. After the training procedure, calculate the classification accuracy for both the training set and test set, and evaluate the performance of the network.
- d). Please determine whether your trained MLP in c) is overfitting. If so, please specify when (i.e. after which training epoch) it becomes overfitting. Try weights regularization and observe if it helps. (you may set the regularization strength by *performParam.regularization*)
- e). Apply MLP to the dataset of your assigned group using *sequential mode training*. After the training procedure, calculate the classification accuracy for both training set and test set, and evaluate the performance of the network. Compare the result to part c), and make your recommendation on the two approaches.
- f). Try to propose a scheme that you believe could help to improve the performance of your MLP and please explain the reason briefly.

#### A3.

a). In this part, I set the first 450 images of the two categories as training sets and the last 50 images as test sets, and concatenate them separately. After that, they are converted from 32\*32\*3 RGB images to 32\*32 grayscale images, and then flattened into 1024\*1 column vectors. Finally, the training set and test set are completely randomly shuffled to enhance the generalization ability of the model. The model consists of a single neuron and uses 0 and 1 as hard decision criteria. The number of training rounds is 2500, and the learning rate is 0.01. The code is shown below:

```
clc;
clear;
close all;
% Folder path
deer_folder = './deer';
ship_folder = './ship';
% Number of images per class for training
num train img = 450;
% Traverse all the pictures in the folder
deer_img = dir(fullfile(deer_folder, '*.jpg'));
ship_img = dir(fullfile(ship_folder, '*.jpg'));
% Create empty cell arrays to store the image paths of the training set and test set
deer_train = {};
ship_train = {};
deer_test = {};
ship_test = {};
```

```
% Separate training set and test set of the deer pictures
for i = 1 : length(deer_img)
   [~, name, ~] = fileparts(deer_img(i).name); % Extract file name
   num = str2double(name); % Convert a file name string to a number
   if num >= 0 && num < num_train_img % Training set</pre>
       deer_train{end + 1} = fullfile(deer_folder, deer_img(i).name);
   else % Test set
       deer test{end + 1} = fullfile(deer folder, deer img(i).name);
   end
end
% Separate training set and test set of the ship pictures
for i = 1 : length(ship_img)
   [~, name, ~] = fileparts(ship_img(i).name);
   num = str2double(name);
   if num >= 0 && num < num_train_img</pre>
       ship_train{end + 1} = fullfile(ship_folder, ship_img(i).name);
   else
       ship_test{end + 1} = fullfile(ship_folder, ship_img(i).name);
   end
end
% Merge the training and test sets separately and correspond to the correct labels
train_files = [deer_train, ship_train];
test_files = [deer_test, ship_test];
train_labels = [zeros(length(deer_train), 1); ones(length(ship_train), 1)];
test_labels = [zeros(length(deer_test), 1); ones(length(ship_test), 1)];
% Randomly shuffle the training set to improve generalization ability
temp_train = [train_files', num2cell(train_labels)];
temp_train = temp_train(randperm(size(temp_train, 1)), :);
train_files = temp_train(:, 1)';
train_labels = cell2mat(temp_train(:, 2));
% Randomly shuffle the test set
temp test = [test files', num2cell(test labels)];
temp_test = temp_test(randperm(size(temp_test, 1)), :);
test_files = temp_test(:, 1)';
test_labels = cell2mat(temp_test(:, 2));
% Load training and test set images
train_img = imageDatastore(train_files);
test_img = imageDatastore(test_files);
```

```
numTrain = numel(train img.Files);
X_train = zeros(1024, numTrain);
for i = 1:numTrain
   img = readimage(train_img, i); % Read training set images
   img_gray = rgb2gray(img); % Convert to grayscale
   % img_gray = double(img_gray) / 255;
   X train(:, i) = img gray(:); % Flatten to 1024×1 and store in matrix
end
numTest = numel(test_img.Files);
X_test = zeros(1024, numTest);
for i = 1:numTest
   img = readimage(test_img, i); % Read test set images
   img_gray = rgb2gray(img);
   % img_gray = double(img_gray) / 255;
   X_test(:, i) = img_gray(:);
% Create a perceptron
net = perceptron();
% Set hyperparameters
net.trainParam.epochs = 2500;
net.trainParam.lr = 0.01;
net.trainParam.showWindow = true;
% Define labels for training and test sets
Y_train = train_labels;
Y_test = test_labels;
% Train the perceptron
net = train(net, X_train, Y_train');
% Evaluate classification accuracy on the training set
disp('Perceptron Model Training Completed.');
Y_pred_train = net(X_train);
Y_pred_train = round(Y_pred_train);
accuracy_train = sum(Y_pred_train == Y_train') / numel(Y_train) * 100;
disp(['Train Accuracy: ', num2str(accuracy_train), '%']);
% Evaluate classification accuracy on the test set
```

```
Y_pred_test = net(X_test);
Y_pred_test = round(Y_pred_test);
accuracy_test = sum(Y_pred_test == Y_test') / numel(Y_test) * 100;
disp(['Test Accuracy: ', num2str(accuracy_test), '%']);
% Randomly select 9 images from the test set to preview the classification results
figure;
sgtitle('Sample Predictions');
for i = 1:min(9, numTest)
   subplot(3, 3, i);
   img = readimage(test_img, i);
   imshow(img);
   actual = test_labels(i);
   predicted = Y_pred_test(i);
   if actual == 0
       actual_class = 'deer';
   else
       actual_class = 'ship';
   end
   if predicted == 0
       predicted_class = 'deer';
   else
       predicted_class = 'ship';
   end
   title_color = 'green';
   if actual ~= predicted
       title_color = 'red';
   end
   title({['Actual: ' actual_class], ['Pred: ' predicted_class]}, 'Color', title_color);
end
```

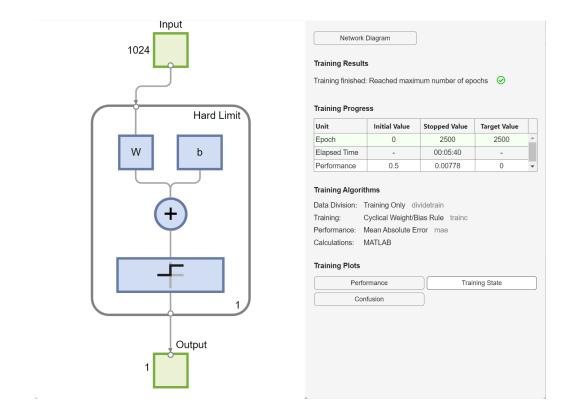
As shown in the program output, the classification accuracy for the training set is 99.2222%, the classification accuracy for the test set is 67%.

```
Perceptron Model Training Completed.

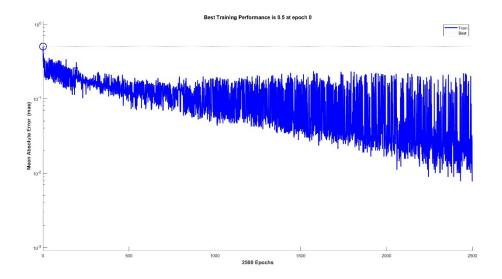
Train Accuracy: 99.2222%

Test Accuracy: 67%
```

The structure of the network and an overview of the neural network are shown in the following two figures:



The mean absolute error trajectory over the number of epochs is shown in the figure below:



After the model completes the inference of the test set, I randomly select 9 pictures from the test set to demonstrate the accuracy of the model's classification. The results are shown in the figure below. Among the 9 selected pictures, 6 pictures are correctly classified, which is consistent with the test set classification accuracy of 67% output by the program. Since the feature dimension of the image is expanded to one dimension and the network model is too simple, the classification effect of the model is not accurate.

# Sample Predictions

Actual: ship Pred: deer



Actual: ship Pred: ship



Actual: ship



Actual: ship Pred: deer



Actual: deer Pred: deer



Actual: deer



Actual: ship Pred: ship



Actual: deer



Actual: ship



b). The code for perceptron training by calculating the global mean and standard deviation for normalization is as follows:

```
clc;
clear;
close all;
% Folder path
deer_folder = './deer';
ship_folder = './ship';
% Number of images per class for training
num_train_img = 450;
% Traverse all the pictures in the folder
deer_img = dir(fullfile(deer_folder, '*.jpg'));
ship_img = dir(fullfile(ship_folder, '*.jpg'));
% Create empty cell arrays to store the image paths of the training set and test set
deer_train = {};
ship_train = {};
deer_test = {};
```

```
ship_test = {};
% Separate training set and test set of the deer pictures
for i = 1 : length(deer_img)
   [~, name, ~] = fileparts(deer_img(i).name);
   num = str2double(name);
   if num >= 0 && num < num_train_img</pre>
       deer_train{end + 1} = fullfile(deer_folder, deer_img(i).name);
   else
       deer_test{end + 1} = fullfile(deer_folder, deer_img(i).name);
   end
end
% Separate training set and test set of the ship pictures
for i = 1 : length(ship_img)
   [~, name, ~] = fileparts(ship_img(i).name);
   num = str2double(name);
   if num >= 0 && num < num_train_img</pre>
       ship_train{end + 1} = fullfile(ship_folder, ship_img(i).name);
   else
       ship_test{end + 1} = fullfile(ship_folder, ship_img(i).name);
   end
end
% Merge the training and test sets separately and correspond to the correct labels
train_files = [deer_train, ship_train];
test_files = [deer_test, ship_test];
train_labels = [zeros(length(deer_train), 1); ones(length(ship_train), 1)];
test_labels = [zeros(length(deer_test), 1); ones(length(ship_test), 1)];
% Randomly shuffle the training set to improve generalization ability
temp_train = [train_files', num2cell(train_labels)];
temp_train = temp_train(randperm(size(temp_train, 1)), :);
train_files = temp_train(:, 1)';
train_labels = cell2mat(temp_train(:, 2));
% Randomly shuffle the test set
temp_test = [test_files', num2cell(test_labels)];
temp_test = temp_test(randperm(size(temp_test, 1)), :);
test_files = temp_test(:, 1)';
test_labels = cell2mat(temp_test(:, 2));
% Load training and test set images
train_img = imageDatastore(train_files);
```

```
test_img = imageDatastore(test_files);
% Get the number of images
numTrain = numel(train_img.Files);
numTest = numel(test_img.Files);
% Store the pixel value of each image
all_pixels = [];
% Traverse the training set and test set to get all pixel values
for i = 1:numTrain
  img = readimage(train_img, i);
  img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
for i = 1:numTest
  img = readimage(test_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
% Get the global pixel mean and standard deviation
global_mean = mean(all_pixels);
global_std = std(all_pixels);
disp(['Global Mean: ', num2str(global_mean)]);
disp(['Global Standard Deviation: ', num2str(global_std)]);
X_train = zeros(1024, numTrain);
X_test = zeros(1024, numTest);
for i = 1:numTrain
   img = readimage(train_img, i); % Read training set images
   img_gray = rgb2gray(img); % Convert to grayscale
   img_gray = double(img_gray);
   \% Normalization by subtracting the mean value from each image and divide each image
by the standard deviation.
   img_gray = (img_gray - global_mean) / global_std;
   X_train(:, i) = img_gray(:); % Flatten to 1024×1 and store in matrix
end
for i = 1:numTest
   img = readimage(test_img, i);
```

```
img_gray = rgb2gray(img);
   img_gray = double(img_gray);
   img_gray = (img_gray - global_mean) / global_std;
   X_test(:, i) = img_gray(:);
end
Y_train = train_labels;
Y_test = test_labels;
% Create a perceptron
net = perceptron();
% Set hyperparameters
net.trainParam.epochs = 2500;
net.trainParam.lr = 0.01;
net.trainParam.showWindow = true;
% Train the perceptron
[net, tr] = train(net, X_train, Y_train');
% Evaluate classification accuracy on the training set
disp('Perceptron Model Training Completed.');
Y_pred_train = net(X_train);
Y_pred_train = round(Y_pred_train);
accuracy_train = sum(Y_pred_train == Y_train') / numel(Y_train) * 100;
disp(['Train Accuracy: ', num2str(accuracy_train), '%']);
% Evaluate classification accuracy on the test set
Y_pred_test = net(X_test);
Y_pred_test = round(Y_pred_test);
accuracy_test = sum(Y_pred_test == Y_test') / numel(Y_test) * 100;
disp(['Test Accuracy: ', num2str(accuracy_test), '%']);
% plot the training curve
figure;
plot(1:length(tr.epoch), tr.perf, 'b-', 'LineWidth', 2);
xlabel('Epochs');
ylabel('Training Performance');
title('Training Performance Over Epochs');
grid on;
% Randomly select 9 images from the test set to preview the classification results
figure;
sgtitle('Sample Predictions');
```

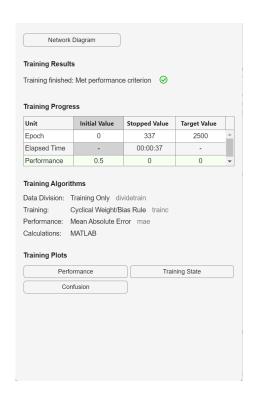
```
for i = 1:min(9, numTest)
   subplot(3, 3, i);
   img = readimage(test_img, i);
   imshow(img);
   actual = test_labels(i);
   predicted = Y_pred_test(i);
   if actual == 0
       actual_class = 'deer';
   else
       actual_class = 'ship';
   end
   if predicted == 0
       predicted_class = 'deer';
   else
       predicted_class = 'ship';
   end
   title_color = 'green';
   if actual ~= predicted
       title_color = 'red';
   title({['Actual: ' actual_class], ['Pred: ' predicted_class]}, 'Color', title_color);
end
```

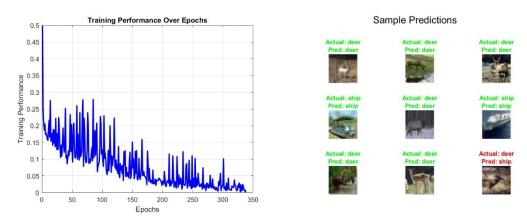
As shown in the program output, the classification accuracy for the training set is 100%, the classification accuracy for the test set is 78%. The global mean of the dataset is 123.9108 and the global standard deviation is 56.7739.

```
Global Mean: 123.9108
Global Standard Deviation: 56.7739
Perceptron Model Training Completed.
Train Accuracy: 100%
Test Accuracy: 78%
```

From the program output, we can see that the model completed training in the 337<sup>th</sup> epoch, which is much faster than the 2500 epochs required in a). The classification accuracy of the training set reached 100%, and the classification accuracy of the test set was also improved compared to a), reaching 78%. At this time, because standardization makes all input features at the same scale, the gradient update is more stable and smoother, which speeds up the convergence speed. At the same time, through the mean-variance normalization method, the network can more easily learn the structural characteristics of the data and is not affected by images with a large range of pixel values.

An overview of the training results, the trajectory of model optimization, and the results of the test set sampling verification are shown in the following figures.





c.) Since the mean-standard deviation normalization method has better classification and convergence effects in b), this method is continued in c). I used the *patternnet* function to create an MLP with 100 neurons in its hidden layer. The training method is *traingdx*, which means gradient descent w/momentum & adaptive learning rate backpropagation. This method can greatly speed up the training speed and adjust the learning rate autonomously. The loss function uses the mean squre error function. The code is as follows:

```
clc;
clear;
close all;

% Folder path
deer_folder = './deer';
ship_folder = './ship';
```

```
% Number of images per class for training
num train img = 450;
% Traverse all the pictures in the folder
deer_img = dir(fullfile(deer_folder, '*.jpg'));
ship_img = dir(fullfile(ship_folder, '*.jpg'));
% Create empty cell arrays to store the image paths of the training set and test set
deer train = {};
ship_train = {};
deer_test = {};
ship_test = {};
% Separate training set and test set of the deer pictures
for i = 1:length(deer_img)
   [~, name, ~] = fileparts(deer_img(i).name);
   num = str2double(name);
   if num < num_train_img</pre>
       deer_train{end + 1} = fullfile(deer_folder, deer_img(i).name);
   else
       deer_test{end + 1} = fullfile(deer_folder, deer_img(i).name);
   end
end
% Separate training set and test set of the ship pictures
for i = 1:length(ship_img)
   [~, name, ~] = fileparts(ship_img(i).name);
   num = str2double(name);
   if num < num_train_img</pre>
       ship_train{end + 1} = fullfile(ship_folder, ship_img(i).name);
   else
       ship_test{end + 1} = fullfile(ship_folder, ship_img(i).name);
   end
end
% Merge the training and test sets separately and correspond to the correct labels
train files = [deer train, ship train];
test_files = [deer_test, ship_test];
train_labels = [zeros(length(deer_train), 1); ones(length(ship_train), 1)];
test_labels = [zeros(length(deer_test), 1); ones(length(ship_test), 1)];
% Randomly shuffle the training set to improve generalization ability
temp_train = [train_files', num2cell(train_labels)];
temp_train = temp_train(randperm(size(temp_train, 1)), :);
```

```
train_files = temp_train(:, 1)';
train_labels = cell2mat(temp_train(:, 2));
% Randomly shuffle the test set
temp_test = [test_files', num2cell(test_labels)];
temp_test = temp_test(randperm(size(temp_test, 1)), :);
test_files = temp_test(:, 1)';
test_labels = cell2mat(temp_test(:, 2));
% Load training and test set images
train img = imageDatastore(train files);
test_img = imageDatastore(test_files);
% Get the number of images
numTrain = numel(train_img.Files);
numTest = numel(test_img.Files);
% Store the pixel value of each image
all_pixels = [];
% Traverse the training set and test set to get all pixel values
for i = 1:numTrain
   img = readimage(train_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
for i = 1:numTest
   img = readimage(test_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
% Get the global pixel mean and standard deviation
global_mean = mean(all_pixels);
global_std = std(all_pixels);
disp(['Global Mean: ', num2str(global_mean)]);
disp(['Global Standard Deviation: ', num2str(global_std)]);
X_train = zeros(1024, numTrain);
X_test = zeros(1024, numTest);
for i = 1:numTrain
```

```
img = readimage(train_img, i); % Read training set images
   img_gray = rgb2gray(img); % Convert to grayscale
   img_gray = double(img_gray);
   % Normalization by subtracting the mean value from each image and divide each image
by the standard deviation.
   img_gray = (img_gray - global_mean) / global_std;
   X_train(:, i) = img_gray(:); % Flatten to 1024×1 and store in matrix
end
for i = 1:numTest
   img = readimage(test_img, i);
  img_gray = rgb2gray(img);
  img_gray = double(img_gray);
   img_gray = (img_gray - global_mean) / global_std;
   X_test(:, i) = img_gray(:);
end
% Create an MLP
hidden_neurons = 100; % Number of hidden neurons
net = patternnet(hidden_neurons);
% Set hyperparameters
net.trainFcn = 'traingdx';
net.performFcn = 'mse';
net.trainParam.epochs = 1000;
net.trainparam.goal = 0;
net.trainParam.min_grad = 1e-6;
net.divideParam.trainRatio = 1;
net.divideParam.valRatio = 0;
net.divideParam.testRatio = 0;
net.trainParam.showWindow = true;
% Change label format
Y_{\text{train}} = \text{full(ind2vec(train\_labels' + 1)); } % [0,1] \rightarrow [1 0] & [0 1]
Y_test = full(ind2vec(test_labels' + 1));
% Train the MLP
[net, tr] = train(net, X_train, Y_train);
% Evaluate classification accuracy on the training set
Y_pred_train = net(X_train);
Y_pred_train = vec2ind(Y_pred_train) - 1;
accuracy_train = sum(Y_pred_train == train_labels') / numel(train_labels) * 100;
disp(['Train Accuracy: ', num2str(accuracy_train), '%']);
```

```
% Evaluate classification accuracy on the test set
Y_pred_test = net(X_test);
Y_pred_test = vec2ind(Y_pred_test) - 1;
accuracy_test = sum(Y_pred_test == test_labels') / numel(test_labels) * 100;
disp(['Test Accuracy: ', num2str(accuracy_test), '%']);
% plot the training curve
figure;
plot(tr.epoch, tr.perf, 'b-', 'LineWidth', 2);
xlabel('Epochs');
ylabel('Mean Squared Error (MSE)');
title('MLP Training Performance');
grid on;
% Randomly select 9 images from the test set to preview the classification results
sgtitle('Sample Predictions');
for i = 1:min(9, numTest)
   subplot(3, 3, i);
   img = readimage(test_img, i);
   imshow(img);
   actual = test_labels(i);
   predicted = Y_pred_test(i);
   if actual == 0
       actual_class = 'deer';
   else
       actual_class = 'ship';
   end
   if predicted == 0
       predicted_class = 'deer';
   else
       predicted_class = 'ship';
   end
   title_color = 'green';
   if actual ~= predicted
       title_color = 'red';
   end
   title({['Actual: ' actual_class], ['Pred: ' predicted_class]}, 'Color', title_color);
end
```

As shown in the program output, the classification accuracy for the training set is 99.6667%, the classification accuracy for the test set is 81%. The global mean of the dataset is 123.9108 and the global standard deviation is 56.7739. Since hidden layer is used and the number of neurons in the hidden layers is large, the nonlinear

transformation capability of the model is enhanced, and the classification performance of the test set is slightly better than that of using only a single neuron classification.

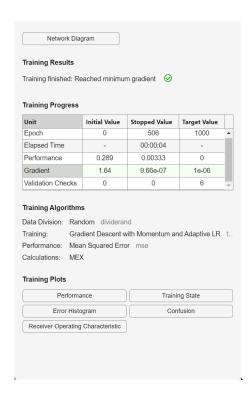
Global Mean: 123.9108

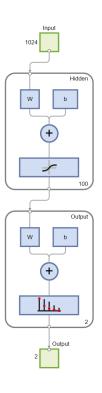
Global Standard Deviation: 56.7739

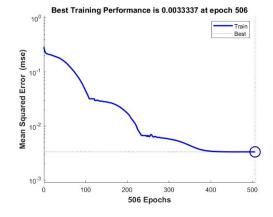
Train Accuracy: 99.6667%

Test Accuracy: 81%

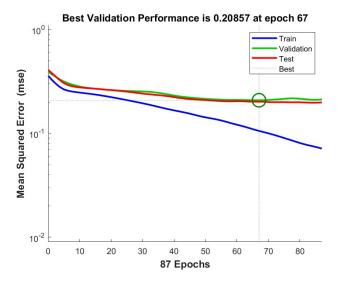
An overview of the training results, network structure, the trajectory of model optimization, and the results of the test set sampling verification are shown in the following figures.











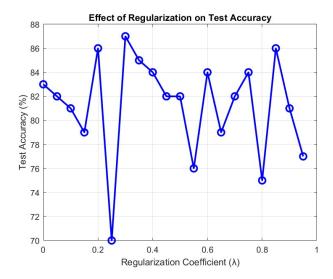
As can be seen from the figure, the MLP I trained overfitted in the 67th epoch. I adjusted the code and set the range of the regularization parameter to 0-0.95 with an interval of 0.05. The regularization parameter was adjusted with the help of *performParam.regularization* function, The curve of the test set classification accuracy as the regularization parameter size changes was plotted later. The code is shown below:

```
clc;
clear;
close all;
% Folder path
deer_folder = './deer';
ship_folder = './ship';
% Number of images per class for training
num_train_img = 450;
% Traverse all the pictures in the folder
deer_img = dir(fullfile(deer_folder, '*.jpg'));
ship_img = dir(fullfile(ship_folder, '*.jpg'));
% Separate training set and test set of the deer pictures
deer_train = {};
ship_train = {};
deer_test = {};
ship_test = {};
% Separate training set and test set of the deer pictures
for i = 1:length(deer_img)
   [~, name, ~] = fileparts(deer_img(i).name);
   num = str2double(name);
```

```
if num < num_train_img</pre>
       deer train{end + 1} = fullfile(deer folder, deer img(i).name);
   else
       deer_test{end + 1} = fullfile(deer_folder, deer_img(i).name);
   end
end
% Separate training set and test set of the ship pictures
for i = 1:length(ship_img)
   [~, name, ~] = fileparts(ship_img(i).name);
   num = str2double(name);
   if num < num_train_img</pre>
       ship_train{end + 1} = fullfile(ship_folder, ship_img(i).name);
   else
       ship_test{end + 1} = fullfile(ship_folder, ship_img(i).name);
   end
end
% Merge the training and test sets separately and correspond to the correct labels
train_files = [deer_train, ship_train];
test_files = [deer_test, ship_test];
train_labels = [zeros(length(deer_train), 1); ones(length(ship_train), 1)];
test_labels = [zeros(length(deer_test), 1); ones(length(ship_test), 1)];
% Randomly shuffle the training set to improve generalization ability
temp_train = [train_files', num2cell(train_labels)];
temp_train = temp_train(randperm(size(temp_train, 1)), :);
train_files = temp_train(:, 1)';
train_labels = cell2mat(temp_train(:, 2));
% Randomly shuffle the test set
temp_test = [test_files', num2cell(test_labels)];
temp_test = temp_test(randperm(size(temp_test, 1)), :);
test_files = temp_test(:, 1)';
test_labels = cell2mat(temp_test(:, 2));
% Load training and test set images
train_img = imageDatastore(train_files);
test_img = imageDatastore(test_files);
numTrain = numel(train_img.Files);
numTest = numel(test_img.Files);
% Get the global pixel mean and standard deviation
```

```
all_pixels = [];
for i = 1:numTrain
   img = readimage(train_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
for i = 1:numTest
   img = readimage(test_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
global_mean = mean(all_pixels);
global std = std(all pixels);
disp(['Global Mean: ', num2str(global_mean)]);
disp(['Global Standard Deviation: ', num2str(global_std)]);
X_train = zeros(1024, numTrain);
X_test = zeros(1024, numTest);
for i = 1:numTrain
   img = readimage(train_img, i);
   img_gray = rgb2gray(img);
   img_gray = double(img_gray);
   img_gray = (img_gray - global_mean) / global_std;
   X_train(:, i) = img_gray(:);
end
for i = 1:numTest
   img = readimage(test_img, i);
   img_gray = rgb2gray(img);
  img_gray = double(img_gray);
   img_gray = (img_gray - global_mean) / global_std;
   X_test(:, i) = img_gray(:);
% Record the test set accuracy of different regularization coefficients
lambda_values = 0:0.05:0.95; % λ ranges from 0 to 0.95, with every 0.05
test_accuracies = zeros(length(lambda_values), 1);
% Number of hidden neurons
```

```
hidden_neurons = 100;
\% Traverse different \lambda training MLP
for idx = 1:length(lambda_values)
   lambda = lambda_values(idx); % Take different values of \lambda
   disp(['Training with \lambda = ', num2str(lambda)]);
   % Create an MLP
   net = patternnet(hidden_neurons);
   % Set hyperparameters
   net.trainFcn = 'traingdx';
   net.performFcn = 'mse';
   net.trainParam.epochs = 500;
   net.performParam.regularization = lambda; % Set regularization parameters
   net.divideParam.trainRatio = 0.7;
   net.divideParam.valRatio = 0.2;
   net.divideParam.testRatio = 0.1;
   net.trainParam.showWindow = true;
   % Change label format
   Y_{train} = full(ind2vec(train_labels' + 1)); % [0,1] \rightarrow [1 0] & [0 1]
   Y_test = full(ind2vec(test_labels' + 1));
   % Train the MLP
   [net, ~] = train(net, X_train, Y_train);
   % Evaluate classification accuracy on the test set
   Y_pred_test = net(X_test);
   Y_pred_test = vec2ind(Y_pred_test) - 1;
   accuracy_test = sum(Y_pred_test == test_labels') / numel(test_labels) * 100;
   test_accuracies(idx) = accuracy_test;
   disp(['Lambda = ', num2str(lambda), ' -> Test Accuracy: ', num2str(accuracy_test),
'%']);
end
% Result visualization
figure;
plot(lambda_values, test_accuracies, 'bo-', 'LineWidth', 2, 'MarkerSize', 8);
xlabel('Regularization Coefficient (\lambda)');
ylabel('Test Accuracy (%)');
title('Effect of Regularization on Test Accuracy');
grid on;
```



As can be seen from the figure, different regularization parameters did not lead to a higher increase in the classification accuracy of the test set. Since the training of the neural network has an early stopping mechanism, the early stopping of training determined by parameters such as gradient and validation checks is sufficient to keep the classification accuracy of the test set at a high level. However, the intervention of regularization can effectively prevent overfitting.

e). The code for training the MLP using sequential mode is as follows:

```
clc;
clear;
close all;
% Folder path
deer_folder = './deer';
ship_folder = './ship';
% Number of images per class for training
num_train_img = 450;
% Traverse all the pictures in the folder
deer_img = dir(fullfile(deer_folder, '*.jpg'));
ship_img = dir(fullfile(ship_folder, '*.jpg'));
% Create empty cell arrays to store the image paths of the training set and test set
deer_train = {};
ship_train = {};
deer_test = {};
ship_test = {};
```

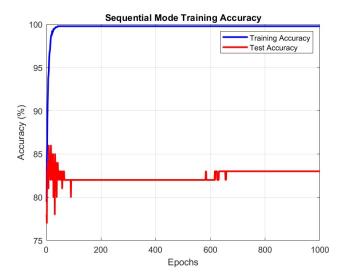
```
% Separate training set and test set of the deer pictures
for i = 1:length(deer_img)
   [~, name, ~] = fileparts(deer_img(i).name);
   num = str2double(name);
   if num < num_train_img</pre>
       deer_train{end + 1} = fullfile(deer_folder, deer_img(i).name);
   else
       deer_test{end + 1} = fullfile(deer_folder, deer_img(i).name);
   end
end
% Separate training set and test set of the ship pictures
for i = 1:length(ship_img)
   [~, name, ~] = fileparts(ship_img(i).name);
   num = str2double(name);
   if num < num train img</pre>
       ship_train{end + 1} = fullfile(ship_folder, ship_img(i).name);
   else
       ship_test{end + 1} = fullfile(ship_folder, ship_img(i).name);
   end
end
% Merge the training and test sets separately and correspond to the correct labels
train_files = [deer_train, ship_train];
test_files = [deer_test, ship_test];
train_labels = [zeros(length(deer_train), 1); ones(length(ship_train), 1)];
test_labels = [zeros(length(deer_test), 1); ones(length(ship_test), 1)];
% Randomly shuffle the training set to improve generalization ability
temp train = [train files', num2cell(train labels)];
temp_train = temp_train(randperm(size(temp_train, 1)), :);
train_files = temp_train(:, 1)';
train_labels = cell2mat(temp_train(:, 2));
% Randomly shuffle the test set
temp_test = [test_files', num2cell(test_labels)];
temp_test = temp_test(randperm(size(temp_test, 1)), :);
test_files = temp_test(:, 1)';
test_labels = cell2mat(temp_test(:, 2));
% Load training and test set images
train_img = imageDatastore(train_files);
test_img = imageDatastore(test_files);
```

```
% Get the number of images
numTrain = numel(train img.Files);
numTest = numel(test_img.Files);
% Store the pixel value of each image
all_pixels = [];
for i = 1:numTrain
   img = readimage(train_img, i);
   img_gray = rgb2gray(img);
   all pixels = [all pixels; double(img gray(:))];
end
for i = 1:numTest
   img = readimage(test_img, i);
   img_gray = rgb2gray(img);
   all_pixels = [all_pixels; double(img_gray(:))];
end
% Get the global pixel mean and standard deviation
global mean = mean(all pixels);
global_std = std(all_pixels);
disp(['Global Mean: ', num2str(global_mean)]);
disp(['Global Standard Deviation: ', num2str(global_std)]);
X_train = zeros(1024, numTrain);
X_test = zeros(1024, numTest);
for i = 1:numTrain
   img = readimage(train_img, i); % Read training set images
   img_gray = rgb2gray(img); % Convert to grayscale
   img_gray = double(img_gray);
   % Normalization by subtracting the mean value from each image and divide each image
by the standard deviation.
   img_gray = (img_gray - global_mean) / global_std;
   X train(:, i) = img gray(:); % Flatten to 1024×1 and store in matrix
end
for i = 1:numTest
   img = readimage(test_img, i);
   img_gray = rgb2gray(img);
   img_gray = double(img_gray);
   img_gray = (img_gray - global_mean) / global_std;
```

```
X_test(:, i) = img_gray(:);
end
% Convert data format (suitable for adapt training)
X_train_c = num2cell(X_train, 1);
Y_train_c = num2cell(train_labels', 1);
X_test_c = num2cell(X_test, 1);
Y_test_c = num2cell(test_labels', 1);
% Create an MLP
hidden_neurons = 100;
net = patternnet(hidden_neurons);
% Set hyperparameters
net.trainFcn = 'traingdx';
net.performFcn = 'mse';
net.trainParam.epochs = 1000;
net.trainParam.lr = 0.01;
net.performParam.regularization = 0.25;
net.trainParam.showWindow = true;
num epochs = 1000;
train_acc = zeros(num_epochs, 1);
test_acc = zeros(num_epochs, 1);
% Disable data set splitting to ensure that all data is used for training
net.divideFcn = 'dividetrain';
for epoch = 1:num_epochs
   disp(['Epoch ', num2str(epoch), ' / ', num2str(num_epochs)]);
   % Randomly shuffle training set
   idx = randperm(numTrain);
   X_train_c = X_train_c(:, idx);
   Y_train_c = Y_train_c(:, idx);
   % Update weights sample by sample
   net = adapt(net, X_train_c, Y_train_c);
   % Evaluate classification accuracy on the training set
   pred_train = round(net(X_train));
   train_acc(epoch) = sum(pred_train == train_labels') / numel(train_labels) * 100;
   % Evaluate classification accuracy on the test set
   pred_test = round(net(X_test));
```

```
test_acc(epoch) = sum(pred_test == test_labels') / numel(test_labels) * 100;
end
% Plot the curves for training and test classification accuracy
figure;
plot(1:num_epochs, train_acc, 'b-', 'LineWidth', 2);
hold on;
plot(1:num_epochs, test_acc, 'r-', 'LineWidth', 2);
xlabel('Epochs');
ylabel('Accuracy (%)');
title('Sequential Mode Training Accuracy');
legend('Training Accuracy', 'Test Accuracy');
grid on;
% Compare the results
disp('Comparing Sequential Mode and Batch Mode:');
disp('Batch Mode Training Accuracy: 96.6667%');
disp('Batch Mode Test Accuracy: 81%');
disp('Sequential Mode Training Accuracy: ' + string(train_acc(end)) + '%');
disp('Sequential Mode Test Accuracy: ' + string(test_acc(end)) + '%');
```

```
Comparing Sequential Mode and Batch Mode:
Batch Mode Training Accuracy: 96.6667%
Batch Mode Test Accuracy: 81%
Sequential Mode Training Accuracy: 99.4444%
Sequential Mode Test Accuracy: 82%
```



As shown in the program output, the classification accuracy for the training set is 99.4444%, the classification accuracy for the test set is 82% by sequential mode. The classification accuracy for the training set is 96.6667%, the classification accuracy for the test set is 81% by batch mode. Combining the accuracy curves of the training set

and test set of the MLP trained in sequential mode, batch mode and sequential mode do not have a clear advantage over each other. However, using batch mode to train the model can significantly reduce the training time because the weights can be updated after all samples are input. In summary, I recommend using batch mode to train the model.

f).

- 1. Randomly rotate, scale, translate, flip, and other operations are performed on the training set images to generate more diverse training samples. That can help the MLP learn more robust features, reduce overfitting and improve generalization ability.
- 2. A more complex network structure will have stronger feature learning capabilities and can capture more complex patterns. But it's also necessary to pay attention of the risk of overfitting.
- 3. Carefully select the hyperparameters for neural network training, adjust and compare them multiple times, and try to find the hyperparameters that are suitable for the current training object to maximize the performance of the MLP.