

Partial Differential Eqⁿs

Zoology of Diff Eqⁿ

- Ordinary / Partial

Ordinary: function has only one variable

$$\frac{dy}{dx} = c \quad ; \quad y = xc + k \quad ; \quad y = y(x)$$

Partial: function has more than one variable!

$$\frac{\partial y}{\partial x} + \frac{\partial y}{\partial t} = c \quad ; \quad y = y(x, t)$$

↳ if variables are dependent

⇒ need to specify which variables are held constant

$$\left. \frac{\partial y(x, t)}{\partial x} \right|_t = c(x, t)$$

- Order: order of its highest derivative

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_0(x) y = f(x)$$

- Linearity: ⇒ written entirely as a linear function

(1) ⇒ w/ no powers above the first power ⇒ no products of the function or its derivatives
eg. $x^2 \frac{d^2 y}{dx^2} = 6xy + 10y = \cos x^2$ are inside another function (3)

non-linear: $\frac{d^2 \theta}{dt^2} + \frac{g}{l} \sin \theta = 0$ (take 3)

linear: $\frac{d^2 \theta}{dt^2} + \frac{g}{l} \theta = 0$
 $\sin \theta \approx \theta$

general form: $a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_0(x) y = b(x)$

- Homogeneous: if terms in the eqⁿ depend on the unknown function or its derivatives

$$P(x) \frac{d^2 y}{dx^2} + Q(x) \frac{dy}{dx} + R(x)y = G(x)$$

(1)

when $G(x) = 0$

\Rightarrow homogeneous

- Degree: - exponent of the highest order derivative involved

eg. $y^2 \left(\frac{dy}{dx} \right)^2 - \frac{d^2 y}{dx^2} = \sin(x^2)$

eg. $\sqrt{1 + \left(\frac{dy}{dx} \right)^2} = y \frac{d^2 y}{dx^2}$

Order = 2, degree = 1

$$1 + \left(\frac{dy}{dx} \right)^2 = y^2 \left(\frac{d^2 y}{dx^2} \right)^2$$

eg. $\frac{d^3 y}{dx^3} + \cos \frac{d^2 y}{dx^2} = 5x$

Order = 3,

degree \Rightarrow undefined

Order = 3,
degree = 2

- Solutions

$$f(x, y(x), \frac{dy}{dx}, \frac{d^2 y}{dx^2}) = 0$$

there is some function $y = u(x)$ in the range $(a < x < b)$

for which the problem is defined.

\Rightarrow question: Does $f(x, u(x), \frac{du}{dx}, \dots) = 0$?

\Rightarrow check solution by substituting into the eqⁿ

or
verifying using a posteriori:

- Uniqueness: - a diff eqⁿ has more than one solution

↳ for an n^{th} order diff eq. \Rightarrow usually n independent functions where n boundary conditions are required to determine the constants.

- Existence: - There is no guarantee that ~~a~~ a diff eqⁿ will have the form $u(x)$

- Superposition: if $y_1(x)$ & $y_2(x)$ are solutions to a linear homogeneous Diff eqⁿ

↳ $y = C y_1(x) + D y_2(x)$ is also a solution

eg. $\frac{d^2 y}{dx^2} = -k^2 y$ (harmonic oscillator)

$$y_1 = \cos kx, \quad y_2 = \sin kx$$

$$y = A \cos kx + B \sin kx$$

Separation of variables method:

Aim: transform a PDE in n variables into n separate ODEs

Consider:

$$a(x, y) \frac{\partial^2 u}{\partial x^2} + b(x, y) \frac{\partial^2 u}{\partial y^2} = 0$$

Assume hypothesis/ansatz: $u(x, y) = X(x)Y(y)$
What's the diff

$$\hookrightarrow a(x, y) Y(y) \frac{d^2 X}{dx^2} + b(x, y) X(x) \frac{d^2 Y}{dy^2} = 0$$

$$\frac{1}{X} \left(a(x, y) Y(y) \frac{d^2 X}{dx^2} \right) = \left(-b(x, y) X(x) \frac{d^2 Y}{dy^2} \right) \frac{1}{X} \\ \underbrace{a(x, y) \frac{1}{X} \frac{d^2 X}{dx^2}}_I = \underbrace{-b(x, y) \frac{1}{Y} \frac{d^2 Y}{dy^2}}_{II}$$

\hookrightarrow Separable provided that:

I : written solely in terms of $x \Rightarrow$ rearrange $a(x, y) \rightarrow A(x)$

II : " " " " " " y

$b(x, y) \rightarrow B(y)$

$$\frac{A(x) d^2 X}{X dx^2} = - \frac{B(y) d^2 Y}{Y dy^2}$$

or
 $f(x) = g(y)$

But x & y are independent variables:

\hookrightarrow each side must be equal to a constant:

$$\frac{A(x) d^2 X}{X dx^2} = c$$

$$\frac{B(y) d^2 Y}{Y dy^2} = -c$$

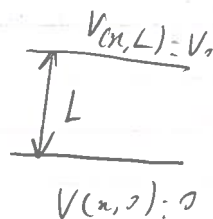
* linear eq^s w/ constant variables can often be solved by separation

* separability depends in general on the chosen system

* choose right 2D coordinate system

eg. In 2D:

$$\cancel{\frac{\partial^2 V}{\partial x^2}} + \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} = 0$$



ansatz / hypothesis:

$$V(x, y) = X(x) Y(y)$$

$$\frac{1}{Y} : Y(y) \frac{d^2 X(x)}{dx^2} + X(x) \frac{d^2 Y(y)}{dy^2} = 0$$

$$\frac{d^2 X(x)}{dx^2} \frac{1}{X} + \frac{d^2 Y(y)}{dy^2} \frac{1}{Y} = 0$$

$$C - C = 0$$

$$\frac{d^2 X}{dx^2} = CX ; \quad \frac{d^2 Y}{dy^2} = -CY$$

Possible solutions:

$$\cos(mx), \sin(mx)$$

$$\underbrace{e^{\pm imx}}$$

or

$$\cosh(mx), \sinh(mx)$$

$$\underbrace{e^{\pm mx}}$$

For $\frac{d^2 X}{dx^2} = CX$

$$X(x) = A_1 \cos(\lambda x) + B_1 \sin(\lambda x)$$

$$\frac{d^2 Y}{dy^2} = -\lambda^2 Y \quad \text{ie } C = -\lambda^2$$

For $\frac{d^2 Y}{dy^2} = -CY = \lambda^2 Y$

$$Y(y) = D_1 e^{\lambda y} + E_1 e^{-\lambda y}$$

Combine: $V(x, y) = X(x) Y(y)$

$$= (A_1 \cos(\lambda x) + B_1 \sin(\lambda x)) (D_1 e^{\lambda y} + E_1 e^{-\lambda y})$$

A general solution:

$$V(x, y) = \sum_{\lambda} (A_{\lambda} \cos(\lambda x) + B_{\lambda} \sin(\lambda x)) (D_{\lambda} e^{\lambda y} + E_{\lambda} e^{-\lambda y})$$

Special case where $C = 0$

$$\frac{d^2 X}{dx^2} = 0 \quad \text{and} \quad \frac{d^2 Y}{dy^2} = 0$$

$$X = A_0 + B_0 x \quad Y = D_0 + E_0 y$$

$$\hookrightarrow V(x, y) = (A_0 + B_0 x) (D_0 + E_0 y)$$

$$+ \sum_{\lambda \neq 0} (A_{\lambda} \cos(\lambda x) + B_{\lambda} \sin(\lambda x)) (D_{\lambda} e^{\lambda y} + E_{\lambda} e^{-\lambda y})$$

Solving w/ boundary conditions:

$$V(x, 0) = 0$$

$$V(x, 0) = (A_0 + B_0 x) D_0 + \sum_{\lambda \neq 0} (A_\lambda \cos \lambda x + B_\lambda \sin \lambda x) (D_\lambda e^{\lambda y} + E_\lambda e^{-\lambda y}) = 0$$

$$\text{For } \lambda = 0: (A_0 + B_0 x) D_0 = 0 \rightarrow D_0 = 0$$

$$\text{For } \lambda \neq 0: (A_\lambda \cos(\lambda x) + B_\lambda \sin(\lambda x)) (D_\lambda + E_\lambda) = 0$$

$$D_\lambda + E_\lambda = 0$$

$$D_\lambda = -E_\lambda$$

\Rightarrow now we have:

$$V(x, y) = (A_0 + B_0 x) E_0 y + \sum_{\lambda \neq 0} (A_\lambda \cos \lambda x + B_\lambda \sin \lambda x) (D_\lambda) (e^{\lambda y} - e^{-\lambda y})$$

another boundary condition:

$$V(x, L) = V_0$$

$$V(x, L) = (A_0 + B_0 x) E_0 (L) + \sum_{\lambda \neq 0} (A_\lambda \cos \lambda x + B_\lambda \sin \lambda x) (D_\lambda) (e^{\lambda L} - e^{-\lambda L}) = V_0$$

$\&$ we cannot have any x dependence as V_0 is a constant

$$\text{For } \lambda = 0: B_0 = 0$$

$$\lambda \neq 0: A_\lambda = B_\lambda = 0 \text{ and all } \lambda \neq 0 \text{ terms go}$$

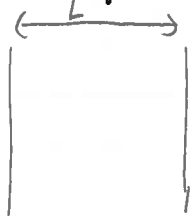
$$V(x, L) = A_0 E_0 L = V_0$$

$$A_0 E_0 = \frac{V_0}{L}$$

$$\Rightarrow V(x, y) = A_0 E_0 y$$

$$= \frac{V_0}{L} y$$

A different set of boundary conditions!



A diagram of a rectangular domain. The horizontal width is labeled L with a double-headed arrow above it. The left vertical boundary is labeled $V(0, y) = 0$ and the right vertical boundary is labeled $V(L, y) = 0$.

Start from general solution:

$$V(x, y) = (A_0 + B_0 x)(C_0 + E_0 y) + \sum_{\lambda \neq 0} (A_\lambda \cos(\lambda x) + B_\lambda \sin(\lambda x))(D_\lambda e^{\lambda y} + E_\lambda e^{-\lambda y})$$

3) Getting $\frac{\partial}{\partial y}$ isolating $\frac{\partial}{\partial y}$

from (A) (4)

$$r \sin \theta \frac{\partial}{\partial r} + \cos \theta \frac{\partial}{\partial \theta} = r \cos \phi \frac{\partial}{\partial x} + r \sin \phi \frac{\partial}{\partial y}$$

$$\rightarrow x \sin \theta \sin \phi$$

$$r \sin^2 \theta \sin \phi \frac{\partial}{\partial r} + \cos \theta \sin \theta \sin \phi \frac{\partial}{\partial \theta} = r \cos \phi \sin \theta \sin \phi \frac{\partial}{\partial x} + r \sin^2 \theta \sin \phi \frac{\partial}{\partial y}$$

(3) $x \cos \phi$

$$\cos \phi \frac{\partial}{\partial \phi} = -r \sin \theta \sin \phi \cos \phi \frac{\partial}{\partial x} + r \sin \theta \cos^2 \phi \frac{\partial}{\partial y}$$

Add:

$$r \sin^2 \theta \sin \phi \frac{\partial}{\partial r} + \cos \theta \sin \theta \sin \phi \frac{\partial}{\partial \theta} + \cos \phi \frac{\partial}{\partial \phi} = r \sin \theta \frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial y} = r \sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \theta \sin \phi}{r} \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi}$$

(4) getting $\frac{\partial}{\partial z}$

$$\frac{\partial}{\partial r} = \sin \theta \cos \phi \frac{\partial}{\partial x} + \sin \theta \sin \phi \frac{\partial}{\partial y} + \cos \theta \frac{\partial}{\partial z}$$

$$\frac{\partial}{\partial \theta} = r \cos \theta \cos \phi \frac{\partial}{\partial x} + r \cos \theta \sin \phi \frac{\partial}{\partial y} - r \sin \theta \frac{\partial}{\partial z}$$

$$\begin{aligned} \frac{\partial}{\partial r} &= \sin^2 \theta \cos^2 \phi \frac{\partial}{\partial r} + \frac{\sin \theta \cos \theta \cos^2 \phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin^2 \theta \cos \phi \sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \\ &+ \sin^2 \theta \sin^2 \phi \frac{\partial}{\partial r} + \frac{\sin \theta \sin^2 \phi \cos \theta}{r} \frac{\partial}{\partial \theta} + \frac{\sin^2 \theta \sin \phi \cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \\ &+ \cos \theta \frac{\partial}{\partial z} \end{aligned}$$

$$\frac{\partial}{\partial r} = \sin^2 \theta \frac{\partial}{\partial r} + \left(\frac{\sin \theta \cos \theta}{r} \right) \frac{\partial}{\partial \theta} + \cos \theta \frac{\partial}{\partial z}$$

$$\cos^2 \theta \frac{\partial}{\partial r} = \frac{\sin \theta \cos \theta}{r} \frac{\partial}{\partial \theta} + \cos \theta \frac{\partial}{\partial z}$$

$$\frac{\partial}{\partial z} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}$$

$$\nabla^2 = \left(\frac{\partial}{\partial x}\right)^2 + \left(\frac{\partial}{\partial y}\right)^2 + \left(\frac{\partial}{\partial z}\right)^2$$

$$= \left(\sin\theta \cos\phi \frac{\partial}{\partial r} + \frac{\cos\theta \cos\phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin\phi}{r \sin\theta} \frac{\partial}{\partial \phi} \right)^2$$

$$+ \left(\sin\theta \sin\phi \frac{\partial}{\partial r} + \frac{\sin\phi \cos\theta}{r} \frac{\partial}{\partial \theta} - \frac{\cos\phi}{r \sin\theta} \frac{\partial}{\partial \phi} \right)^2$$

$$+ \left(\cos\theta \frac{\partial}{\partial r} - \frac{\sin\theta}{r} \frac{\partial}{\partial \theta} \right)^2$$

long-ass expansion

$$= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2\theta} \left(\frac{\partial^2}{\partial \phi^2} \right)$$

Laplace's Equation $\nabla^2 V = 0$ in spherical polar coordinates

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0$$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$\nabla^2 V = 0$$

wrt r $\frac{\partial x}{\partial r} = \sin \theta \cos \phi$ $\frac{\partial y}{\partial r} = \sin \theta \sin \phi$ $\frac{\partial z}{\partial r} = \cos \theta$

wrt θ $\frac{\partial x}{\partial \theta} = r \cos \theta \cos \phi$ $\frac{\partial y}{\partial \theta} = r \cos \theta \sin \phi$ $\frac{\partial z}{\partial \theta} = -r \sin \theta$

wrt ϕ $\frac{\partial x}{\partial \phi} = -r \sin \theta \sin \phi$ $\frac{\partial y}{\partial \phi} = r \sin \theta \cos \phi$ $\frac{\partial z}{\partial \phi} = 0$

using chain rules

$$\frac{\partial}{\partial r} = \sin \theta \cos \phi \frac{\partial}{\partial x} + \sin \theta \sin \phi \frac{\partial}{\partial y} + \cos \theta \frac{\partial}{\partial z} \quad \text{--- (1)}$$

$$\frac{\partial}{\partial \theta} = r \cos \theta \cos \phi \frac{\partial}{\partial x} + r \cos \theta \sin \phi \frac{\partial}{\partial y} - r \sin \theta \frac{\partial}{\partial z} \quad \text{--- (2)}$$

$$\frac{\partial}{\partial \phi} = -r \sin \theta \sin \phi \frac{\partial}{\partial x} + r \sin \theta \cos \phi \frac{\partial}{\partial y} \quad \text{--- (3)}$$

\Rightarrow Rearrange getting $\frac{\partial}{\partial x}$ (4)

(1) $\times \sin \theta$

$$r \sin^2 \theta \frac{\partial}{\partial r} = r \sin^2 \theta \cos \phi \frac{\partial}{\partial x} + r \sin^2 \theta \sin \phi \frac{\partial}{\partial y} + r \sin \theta \cos \theta \frac{\partial}{\partial z}$$

(2) $\times \cos \theta$

$$r \cos^2 \theta \frac{\partial}{\partial \theta} = r \cos^2 \theta \cos \phi \frac{\partial}{\partial x} + r \cos^2 \theta \sin \phi \frac{\partial}{\partial y} - r \sin \theta \cos \theta \frac{\partial}{\partial z}$$

add

$$\Rightarrow r \sin \theta \frac{\partial}{\partial r} + r \cos \theta \frac{\partial}{\partial \theta} = r \cos \phi \frac{\partial}{\partial x} + r \sin \phi \frac{\partial}{\partial y} \quad \text{--- (4)}$$

$\times \sin \theta \cos \phi$

$$r \sin^2 \theta \cos \phi \frac{\partial}{\partial r} + r \cos \theta \sin \theta \cos \phi \frac{\partial}{\partial \theta} = r \sin \theta \cos^2 \phi \frac{\partial}{\partial x} + r \sin \theta \cos \phi \sin \phi \frac{\partial}{\partial y}$$

(3) $\times \sin \phi$

$$\sin \phi \frac{\partial}{\partial \phi} = -r \sin \theta \sin^2 \phi \frac{\partial}{\partial x} + r \sin \theta \cos \phi \sin \phi \frac{\partial}{\partial y}$$

Subtract:

$$r \sin^2 \theta \cos \phi \frac{\partial}{\partial r} + r \cos \theta \sin \theta \cos \phi \frac{\partial}{\partial \theta} - \sin \phi \frac{\partial}{\partial \phi} = r \sin \theta \frac{\partial}{\partial x}$$

$$\Rightarrow \frac{\partial}{\partial x} = \sin \theta \cos \phi \frac{\partial}{\partial r} + \frac{\cos \theta \cos \phi}{r} \frac{\partial}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi}$$

Laplace eqⁿ in spherical polar coordinates

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0$$

eg. $V = 2x^2 - y^2 - z^2$

$$\frac{\partial^2 V}{\partial x^2} = 4; \quad \frac{\partial^2 V}{\partial y^2} = -2; \quad \frac{\partial^2 V}{\partial z^2} = -2$$

In polar coordinates:

$$V = r^2 (2 \sin^2 \theta \cos^2 \phi - \sin^2 \theta \sin^2 \phi - \cos^2 \theta)$$

* check that $\nabla^2 V = 0$

Sep. Separation of Variables:

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0$$

Ansatz: $V(r, \theta, \phi) = R(r) \Theta(\theta) \Phi(\phi)$

$$\Theta \Phi \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + R \Phi \frac{1}{r^2 \sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + R \Theta \frac{1}{r^2 \sin^2 \theta} \left(\frac{d^2 \Phi}{d\phi^2} \right) = 0$$

\Rightarrow Now $\times \frac{r^2 \sin^2 \theta}{R \Theta \Phi}$

$$\Rightarrow \frac{\sin^2 \theta}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + \frac{\sin \theta}{\Theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = 0$$

$$\Rightarrow \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = -m^2$$

has solution $Ae^{\pm i m \phi}$

$\Rightarrow m$ is an integer
and

$\Phi(\phi)$ is a periodic function

$$\frac{\sin^2 \theta}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + \frac{\sin \theta}{\Theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) - m^2 = 0$$

\Rightarrow Now divide by $\sin^2 \theta$ & rearrange

$$\frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = \frac{m^2}{\sin^2 \theta} - \frac{1}{\Theta \sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right)$$

L.H.S is a function of r only

R.H.S is function of θ only

$$\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = \lambda R \quad \text{-(Radial eq.)}$$

$$\frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left(\lambda \sin \theta - \frac{m^2}{\sin \theta} \right) \Theta = 0 \quad \text{-(polar eq.)}$$

For the radial eq.

$$r^2 \frac{d^2 R}{dr^2} + 2r \frac{dR}{dr} - \lambda R = 0$$

\Rightarrow Ansatz: $R(r) \sim r^\beta$

$$r^2 \beta(\beta-1) r^{\beta-2} + 2r \beta r^{\beta-1} - \lambda r^\beta = 0$$

$$\beta(\beta-1) r^\beta + 2\beta r^\beta - \lambda r^\beta = 0$$

$$\beta^2 - \beta + 2\beta - \lambda = 0$$

Cancelling r^β

$$\beta^2 + \beta - \lambda = 0$$

$$\beta = \frac{-1 \pm \sqrt{1+4\lambda}}{2}$$

Define: $\lambda = \ell(\ell+1)$

$$\beta = \frac{-1 \pm \sqrt{1+4\ell(\ell+1)}}{2}$$

$$\beta = \ell \text{ or } \ell+1$$

$$R(r) = A r^\ell + \frac{B}{r^{\ell+1}}$$

For Polar eqⁿ:

$$\frac{d}{d\theta} \left(\sin\theta \frac{d\Theta}{d\theta} \right) + \left(l(l+1) \sin\theta - \frac{m^2}{\sin\theta} \right) \Theta = 0$$

$$\mu = \cos\theta \Rightarrow \frac{d\mu}{d\theta} = -\sin\theta$$

$$\frac{d}{d\theta} = -\sin\theta \frac{d}{d\mu} \quad \frac{d}{d\mu} = \frac{1}{\sqrt{1-\mu^2}} \frac{d}{d\mu}$$

$$\Rightarrow -\sqrt{1-\mu^2} \frac{d}{d\mu} \left(\sqrt{1-\mu^2} - \sqrt{1-\mu^2} \frac{d\Theta}{d\mu} \right) + \left(l(l+1) \sqrt{1-\mu^2} - \frac{m^2}{\sqrt{1-\mu^2}} \right) \Theta = 0$$

$$\frac{d}{d\mu} \left[(1-\mu^2) \frac{d\Theta}{d\mu} \right] + \left[l(l+1) - \frac{m^2}{1-\mu^2} \right] \Theta = 0$$

[Legendre equation] for Legendre Polynomials

E₅: One-dimension wave eqⁿ

eg. guitar string is clamped @ $x=0$ & $x=L$

The displacement obeys:

$t \rightarrow$ time

$v \rightarrow$ speed of wave propagation

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2} = 0$$

Ansatz: $y(x,t) = X(x)T(t)$

Solution:

$$X(x) = C \cos(kx) + D \sin(kx)$$

$$\Rightarrow T \frac{d^2 X}{dx^2} - \frac{1}{v^2} X \frac{d^2 T}{dt^2} = 0$$

Boundary conditions:

divide $y = XT$

$$y(0,t) = 0$$

$$y(L,t) = 0$$

$$\Rightarrow \frac{1}{X} \frac{d^2 X}{dx^2} = \frac{1}{v^2 T} \frac{d^2 T}{dt^2}$$

$$\text{At } x=0: X(0) = C \cos 0 + D \sin 0 = 0$$

$$\Rightarrow C = 0$$

[both sides are equal to a constant, $-k^2$

$$\text{At } x=L: X(L) = D \sin(kL) = 0$$

$$\Rightarrow k = \frac{n\pi}{L} \quad n=1,2,3,\dots$$

$$\frac{d^2 X}{dx^2} + k^2 X = 0$$

$$T(t): \frac{d^2 T}{dt^2} + \left(\frac{n\pi v}{L} \right)^2 T = 0$$

$$\frac{d^2 T}{dt^2} + k^2 v^2 T = 0$$

$$T = A \cos\left(\frac{n\pi v}{L} t\right) + B \sin\left(\frac{n\pi v}{L} t\right)$$

Complete solution:

$$y(x,t) = D \sin\left(\frac{n\pi}{L} x\right) \left[A \cos\left(\frac{n\pi v}{L} t\right) + B \sin\left(\frac{n\pi v}{L} t\right) \right]$$

using the superposition principle:

$$y(n,t) = \sum_{n=1}^{\infty} \sin\left(\frac{n\pi x}{L}\right) \left[A_n \cos\left(\frac{n\pi v}{L} t\right) + B_n \sin\left(\frac{n\pi v}{L} t\right) \right]$$

↳ General solution

Series Solutions of Differential Equations

- Harmonic Oscillator - 2.1
- Frobenius' method - 2.2
- Special pts & Fuchs's Theorem - 2.3
- Eg w/ singular pt - 2.4
- Eg - 2.5
- Quantum Harmonic Oscillator - 2.6

2.1 The Harmonic oscillator

$$\frac{d^2 y}{dx^2} + y = 0$$

- We know that $y = A \cos x + B \sin x$ is a solⁿ
- ↳ trying a series solⁿ

$$y = \sum_{n=0}^{\infty} a_n x^n$$

$$\frac{dy}{dx} = \sum_{n=0}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=0}^{\infty} a_n n(n-1) x^{n-2}$$

→ Inserting into H.O. eqⁿ

$$\sum_{n=0}^{\infty} a_n n(n-1) x^{n-2} + \sum_{n=0}^{\infty} a_n x^n = 0$$

∴ ⇒ each correspondence of x must cancel each other

→ Replacing indices in the first term

$$\text{ie. } n = n' + 2 \Rightarrow n' = n - 2$$

$$\sum_{n'=0}^{\infty} a_{n'+2} (n'+2)(n'+1) x^{n'} + \sum_{n=0}^{\infty} a_n x^n = 0$$

As n' is a dummy variable, we can call it anything, eg. n

$$\sum_{n=0}^{\infty} a_{n+2} (n+2)(n+1) x^n + \sum_{n=0}^{\infty} a_n x^n = 0$$

$$\left[\sum_{n=0}^{\infty} a_{n+2} (n+2)(n+1) + a_n \right] x^n = 0$$

→ implying

$$a_{n+2} (n+2)(n+1) + a_n = 0$$

⇒ for

$$a_{n+2} = -\frac{a_n}{(n+2)(n+1)}$$

$n=0, 1, 2, 3$

* Recurrence relation

Recurrence Index

$$\sum_{n=0}^{\infty} a_n(n(n-1))x^{n-2} = 0$$

$$= 0 + 0 + 2a_2 + 6a_3x + \dots$$

$$\sum_{n=0}^{\infty} a_{n+2}(n+2)(n+1)x^n = 2a_2 + 6a_3x + \dots$$

Terms from the recurrence relation:

$$n=0: a_2 = \frac{-a_0}{2!}$$

$$n=1: a_3 = \frac{-a_1}{3 \times 2} = -\frac{a_1}{3!}$$

$$n=2: a_4 = \frac{-a_2}{4(3)} = \frac{+a_0}{4!}$$

$$n=3: a_5 = \frac{-a_3}{(5)(4)} = \frac{+a_1}{5!}$$

$$n=4: a_6 = \frac{-a_4}{(6)(5)} = \frac{-a_0}{6!}$$

$$n=5: a_7 = \frac{-a_5}{(7)(6)} = \frac{-a_1}{7!}$$

General form:

$$a_{2m} = \frac{(-1)^m}{(2m)!} a_0 \quad [n \text{ is even}]$$

$$a_{2m+1} = \frac{(-1)^m}{(2m+1)!} a_1 \quad [n \text{ is odd}]$$

$$\Rightarrow y(x) = a_0 \left[1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \right] \Rightarrow \cos(x)$$

$$+ a_1 \left[x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \right] \Rightarrow \sin(x)$$

Taylor expansion

$$\underline{y(x) = a_0 \cos(x) + a_1 \sin(x)}$$

But how do we know these are linear independent solⁿ

\Rightarrow By using Wronskian test

$$\begin{bmatrix} y_1 = \cos x & y_2 = \sin x \\ y_1' = -\sin x & y_2' = \cos x \end{bmatrix}$$

$$\Rightarrow \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \neq 0 \Rightarrow y_1 y_2' - y_2 y_1' \neq 0$$

$$\cos^2 x + \sin^2 x = 1 \neq 0 \Rightarrow \text{linearly independent}$$

~~2.2 Fro~~ 2.2 Frobenius's Method

For a general 2nd ODE:

$$P(x) \frac{d^2 y}{dx^2} + Q(x) \frac{dy}{dx} + R(x)y = 0$$

or

$$\frac{d^2 y}{dx^2} + p(x) \frac{dy}{dx} + q(x)y = 0 \quad [\text{rewriting only}]$$

Method consists of:

$$p(x) = \frac{Q(x)}{P(x)}$$

$$q(x) = \frac{R(x)}{P(x)}$$

1/ Choose a pt x_0 , where series is centred

2/ Assume a solⁿ of the form: $y(x) = \sum_{j=0}^{\infty} a_j (x-x_0)^{k+j}$ ($a_0 \neq 0$)

3/ Derive a condition \Rightarrow Indicial Eqⁿ for parameter k
 \Rightarrow solve it to determine possible values of k

4/ Insert expression for $y(x)$ & its differentials into ^{original} "diff eqⁿ"

5/ For each value of k , derive conditions on the coefficients a_j ,
and solve to completely determine the solⁿ, $y(x)$

$a_0 \neq 0$ assumed \therefore can be imposed by defining parameter k

- solⁿ in series form do not always exist

\hookrightarrow even yes, may not converge for all values of x

- even if have solⁿ in series form

\hookrightarrow not always possible to analytically determine coefficients a_j

Indicial Eqⁿ

General form of the D.E.

$$\frac{d^2 y}{dx^2} + p(x) \frac{dy}{dx} + q(x)y = 0$$

$$y(x) = \sum_{j=0}^{\infty} a_j (x-x_0)^{k+j}$$

For simplicity $x_0 = 0$

$$y(x) = \sum_{j=0}^{\infty} a_j x^{k+j}$$

$$y' = \sum_{j=0}^{\infty} a_j (k+j) x^{k+j-1}$$

$$y'' = \sum_{j=0}^{\infty} a_j (k+j)(k+j-1) x^{k+j-2}$$

$$\Rightarrow \sum_{j=0}^{\infty} a_j (k+j)(k+j-1) x^{k+j-2} + p(x) \sum_{j=0}^{\infty} a_j (k+j) x^{k+j-1} + q(x) \sum_{j=0}^{\infty} a_j x^{k+j} = 0$$

→ Multiply by: x^{2-k} :

$$\Rightarrow \sum_{j=0}^{\infty} a_j (k+j)(k+j-1) x^j + x p(x) \sum_{j=0}^{\infty} a_j (k+j) x^j + x^2 q(x) \sum_{j=0}^{\infty} a_j x^j = 0$$

→ For $j=0$, $x^j = 1$, $a_0 \neq 0$ as $a_0 \neq 0$ → assumed $a_0 \neq 0$

$$k(k-1) + p_0 k + q_0 = 0 \quad \text{indicial eqⁿ}$$

[Quadratic eqⁿ in k , terms p_0 & q_0 are defined as:

$$p_0 = \lim_{x \rightarrow 0} x p(x) \quad - (1)$$

$$q_0 = \lim_{x \rightarrow 0} x^2 q(x) \quad - (2)$$

s_0 or = values of k]

Special points & Fuchs's Theorem

- Given the general

2nd order, linear, homogeneous diff eqⁿ

→ we have can distinguish 3 kinds of points

1. Ordinary / Analytic points

where $p(x)$ & $q(x)$ are analytic

↳ $p(x)$ & $q(x)$ are finite

↳ expressed as:

$$p(x) = \sum_{j=0}^{\infty} p_j (x-x_0)^j, \quad q(x) = \sum_{j=0}^{\infty} q_j (x-x_0)^j$$

→ x_0 is an ordinary point

IF both p & q diverge @ $x = x_0$

→ it is a singular pt

eg. $y' = \frac{1}{x^2} (x=0)$; $y' = \frac{1}{x^2} (x=1)$; $y = \tan(x \frac{\pi}{2})$

2. Regular singular points

where at least one of $p(x)$ or $q(x)$

is NOT analytic, BUT

$$\lim_{x \rightarrow x_0} (x-x_0) p(x) \quad \& \quad \lim_{x \rightarrow x_0} (x-x_0)^2 q(x)$$

are both analytic

3. Essential singular points

at least one of the functions, $(x-x_0)p(x)$ & $(x-x_0)^2 q(x)$ is not analytic

Fuchs's Theorem: given a linear, homogeneous diff eqⁿ

of 2nd order, at least one series solⁿ exist,

IF the expansion point is

- an ordinary point

or

- a regular singular point

2.4 / Example w/ singular point

$$\frac{d^2 y}{dx^2} + \frac{1}{2x} \frac{dy}{dx} + \frac{1}{4x} y = 0$$

✓ $\Rightarrow p(x) = \frac{1}{2x} ; q(x) = \frac{1}{4x}$

\rightarrow Both are not analytic @ $x=0$

\Rightarrow Rather than $y(x) = \sum_{n=0}^{\infty} a_n x^n$

1k 2./ \hookrightarrow we choose $y(x) = x^k \sum_{n=0}^{\infty} a_n x^n$ OR generally:

$$y(x) = \sum_{n=0}^{\infty} a_n (x-x_0)^{n+k}$$

$$p_0 = \lim_{x \rightarrow x_0} p(x)(x-x_0) = \lim_{x \rightarrow 0} \frac{1}{2x}(x-0) = \frac{1}{2}$$

$$q_0 = \lim_{x \rightarrow x_0} q(x)(x-x_0)^2 = \lim_{x \rightarrow 0} \frac{1}{4x}(x^2) = 0$$

} Both analytic ✓

3./ Finding k using the indicial eqⁿ

$$k(k-1) + p_0 k + q_0 = 0 \quad \downarrow$$

$$k^2 - k + p_0 k + q_0 = 0$$

$$k^2 - k + \frac{1}{2}k + 0 = 0$$

$$k^2 =$$

$$k(k - \frac{1}{2}) = 0$$

$$k=0 \text{ or } k=\frac{1}{2}$$

4./ ~~put~~ put $y = \sum_{n=0}^{\infty} a_n x^{n+k}$ into diff eqⁿ

$$\sum_{n=0}^{\infty} a_n (n+k)(n+k-1) x^{n+k-2} + \frac{1}{2x} \sum_{n=0}^{\infty} a_n (n+k) x^{n+k-1} + \frac{1}{4x} \sum_{n=0}^{\infty} a_n x^{n+k} = 0$$

$$\times \frac{4x}{x^k}$$

$$\Rightarrow \sum_{n=0}^{\infty} [4a_n (n+k)(n+k-1) + 2a_n (n+k)] x^{n-1} + \sum_{n=0}^{\infty} a_n x^n = 0$$

Changing dummy variable

$n' = n-1$, $n = n'+1$, dummy variable $n' \rightarrow n$

$$\sum_{n=1}^{\infty} [\psi_{n+1}(n+k+1)(n+k) + 2a_{n+1}(n+k+1)]x^n + \sum_{n=0}^{\infty} a_n x^n = 0$$

by comparing powers of x L.H.S, x^{-1} has to go

$$\Rightarrow \sum_{n=0}^{\infty} [\psi_{n+1}(n+k+1)(n+k) + 2a_{n+1}(n+k+1) + a_n]x^n = 0$$

$$a_{n+1} = \frac{-a_n}{2(n+k+1)(2n+k+1)}$$

$$k_1 = 0 : a_{n+1} = \frac{-a_n}{(2n+2)(2n+1)}$$

$$k_2 = \frac{1}{2} : a_{n+1} = \frac{-a_n}{(2n+3)(2n+2)}$$

For $k=0$,

$$a_1 = \frac{-a_0}{2!}$$

$$a_2 = \frac{-a_1}{(4)(3)} = \frac{a_0}{4!}$$

$$a_3 = \frac{-a_2}{(6)(5)} = \frac{-a_0}{6!}$$

For $k=\frac{1}{2}$

$$a_1 = \frac{-a_0}{3(2)} = -\frac{a_0}{3!}$$

$$a_2 = \frac{a_0}{5!}$$

$$a_3 = \frac{-a_0}{7!}$$

$$y(x) = \sum_{n=0}^{\infty} a_n x^{n+0}$$

$$= a_0 - \frac{a_0 x^2}{2!} + \frac{a_0 x^4}{4!} - \frac{a_0 x^6}{6!} + \dots$$

$$= a_0 - \frac{a_0 (\sqrt{x})^2}{2!} + \frac{a_0 (\sqrt{x})^4}{4!} - \frac{a_0 (\sqrt{x})^6}{6!} + \dots$$

$$= a_0 \cos(\sqrt{x})$$

$$y(x) = \sqrt{x} \sum_{n=0}^{\infty} a_n x^n$$

$$y(x) = a_0 \sqrt{x} - \frac{\sqrt{x}^3}{3!} a_0 + x^{\frac{5}{2}} \frac{a_0}{5!} - x^{\frac{7}{2}} \frac{a_0}{7!} + \dots$$

$$= a_0 \left[\sqrt{x} - \frac{(\sqrt{x})^3}{3!} + \frac{(\sqrt{x})^5}{5!} - \frac{(\sqrt{x})^7}{7!} + \dots \right]$$

$$= a_0 \sin(\sqrt{x})$$

$$\text{General sol}^n : y(x) = A \cos \sqrt{x} + B \sin \sqrt{x}$$

\Rightarrow linearly independent

(Put back & see if the solⁿ works)

2.5 Another example:

$$x(x-1) \frac{d^2 y}{dx^2} + 3x \frac{dy}{dx} - y = 0$$

$$\Rightarrow \frac{d^2 y}{dx^2} + \frac{3}{x-1} \frac{dy}{dx} + \frac{1}{x(x-1)} y = 0$$

$$p(x) = \frac{3}{x-1} \quad q(x) = \frac{1}{x(x-1)}$$

$p(x)$ is singular at $x=1$,

$q(x)$ is singular at $x=2$ or $x=0$

$$\text{For } x=0: \quad p_0 = \lim_{x \rightarrow 0} \frac{3}{x-1} \cdot x = 0$$

$$q_0 = \lim_{x \rightarrow 0} \frac{1}{x(x-1)} \cdot x^2 = \frac{x}{x-1} = 0$$

$$y(x) = \sum_{n=0}^{\infty} a_n x^{n+k}$$

$$y'(x) = \sum_{n=0}^{\infty} a_n (n+k) x^{n+k-1}$$

$$y''(x) = \sum_{n=0}^{\infty} a_n (n+k)(n+k-1) x^{n+k-2}$$

$$\Rightarrow \sum_{n=0}^{\infty} a_n (n+k)(n+k-1) x^{n+k-2} + \frac{3}{x-1} \sum_{n=0}^{\infty} a_n (n+k) x^{n+k-1}$$

$$+ \frac{1}{x(x-1)} \sum_{n=0}^{\infty} a_n x^{n+k} = 0 \quad \text{--- (A)}$$

$$\Rightarrow x \cdot x^{2-k}$$

$$\hookrightarrow \sum_{n=0}^{\infty} a_n (n+k)(n+k-1) x^n + \frac{3x}{x-1} \sum_{n=0}^{\infty} a_n (n+k) x^n$$

$$+ \frac{x^2}{x(x-1)} \sum_{n=0}^{\infty} a_n x^n = 0$$

$$x(x-1)$$

$$\Rightarrow \sum_{n=0}^{\infty} a_n x^n [(n-1)(n+k)(n+k-1) + 3n(n+k) + x] = 0$$

So set $x=0$, \Rightarrow all terms with the exponent of $x \geq 0$ vanishes

for $x=0$, $n=0$,

$$\left. \begin{aligned} (-1)(k)(k-1) &= 0 \\ \hookrightarrow k=0 \text{ or } k=1 \end{aligned} \right\} \begin{array}{l} \text{indicial} \\ \text{eq'n} \end{array}$$

Finding recurrence relationship, (A) $x[x(x-1)]$

$$\sum_{n=0}^{\infty} a_n (n+k)(n+k-1) (x^{n+k} - x^{n+k-1}) + \sum_{n=0}^{\infty} 3a_n (n+k) x^{n+k} + \sum_{n=0}^{\infty} a_n x^{n+k} = 0$$

$$\Rightarrow \sum_{n=0}^{\infty} a_n x^{n+k} [(n+k)(n+k-1) + 3(n+k) + 1] - \sum_{n=0}^{\infty} a_n (n+k)(n+k-1) x^{n+k-1} = 0$$

Changing dummy variables

$$\begin{aligned} n' &= n+1 \Rightarrow n' \\ n' &= n-1 \Rightarrow n' \rightarrow n \end{aligned}$$

$$\begin{aligned} \Rightarrow \sum_{n=0}^{\infty} a_n x^{n+k} [(n+k)(n+k-1) + 3(n+k) + 1] \\ = \sum_{n=-1}^{\infty} a_{n+1} x^{n+k} (n+k+1)(n+k) \end{aligned}$$

Equating powers of x :

$$\Rightarrow a_n (n+k+1) = a_{n+1} (n+k+1)(n+k)$$

$$a_{n+1} = \frac{a_n (n+k+1)}{n+k}$$

For $k \neq 1$:

$$a_{n+1} = a_n \frac{(n+2)}{n+1}$$

$$a_1 = a_0 \frac{2}{1} = 2a_0$$

$$a_2 = a_1 \cdot \frac{3}{2} = 3a_0$$

$$a_3 = a_2 \cdot \frac{4}{3} = 4a_0$$

$$\therefore y(n) = \sum_{n=0}^{\infty} a_n x^{n+k}$$

$$= a_0 x + 2a_0 x^2 + 3a_0 x^3 + 4a_0 x^4 + \dots$$

Putting $a_0 = 1$

$$\Rightarrow y(n) = x(1 + 2x + 3x^2 + 4x^3 + \dots)$$

$$y(n) = \frac{x}{(1-x)^2}$$

For $k=0$

$$a_{n+1} = a_n \left(\frac{n+1}{n} \right)$$

in this particular case,

doesn't work $\because \frac{n+1}{n} \neq$

$$c_{n+1} = a_{n+1} x^{n+2} ; c_n = a_n x^{n+1}$$

$$= a_n \left(\frac{n+2}{n+1} \right) x^{n+2}$$

$$\Rightarrow S = \lim_{n \rightarrow \infty} \left| \frac{a_n (n+2) \cdot x}{a_n (n+1)} \right|$$

$$= \lim_{n \rightarrow \infty} |x|$$

\Rightarrow convergence for $|x| < 1$

\Rightarrow divergence for $|x| \geq 1$

D'Alembert Ratio Test:

\hookrightarrow Given an infinite series of the form: $\sum_{j=0}^{\infty} c_j$

let s be defined as:

$$s = \lim_{j \rightarrow \infty} \left| \frac{c_{j+1}}{c_j} \right|$$

$$s < 1$$

converging series

$$s = 1$$

inconclusive

$$s > 1$$

divergence

2.6/ Quantum Harmonic Oscillator

for a particle in a potential well, $V = \frac{1}{2} kx^2$

$$-\frac{\hbar^2}{2m} \frac{d^2 \psi(x)}{dx^2} + \frac{1}{2} kx^2 \psi(x) = E \psi(x)$$

- Substitutions. $y = \left(\frac{mk}{\hbar^2} \right)^{1/4} x$; $\omega = \sqrt{\frac{k}{m}}$; $\epsilon = \frac{2E}{\hbar\omega}$

$$\Rightarrow \frac{d^2 \psi(y)}{dy^2} - y^2 \psi(y) = -\epsilon \psi(y)$$

$$\Rightarrow \text{1st solve } \frac{d^2 \psi}{dy^2} - y^2 \psi = 0$$

solⁿ: $\psi(y) = Ae^{-\frac{y^2}{2}} + Be^{\frac{y^2}{2}}$

$y \rightarrow \infty \Rightarrow \psi(y) \rightarrow 0$ $\beta = 0$

$$\psi(y) = Ae^{-\frac{y^2}{2}}$$

Assume full solⁿ is

$$\psi(y) = H(y) \exp(-\frac{y^2}{2})$$

$$\psi' = H'(y) \exp(-\frac{y^2}{2}) - y \psi$$

$$\psi'' = H'' \exp(-\frac{y^2}{2}) - y H' \exp(-\frac{y^2}{2}) - \psi - y H' \exp(-\frac{y^2}{2}) + y^2 \psi$$

$$\Rightarrow \frac{d^2 \psi}{dy^2} - y^2 \psi = \exp(-\frac{y^2}{2}) \left[\frac{d^2 H}{dy^2} - 2y \frac{dH}{dy} - 1 \right] = -\epsilon \psi$$

$$\Rightarrow \frac{d^2 H}{dy^2} - 2y \frac{dH}{dy} - H = +\epsilon H \quad (\text{vH on both sides of } \epsilon)$$

$$\frac{d^2 H}{dy^2} - 2y \frac{dH}{dy} + (\epsilon - 1)H = 0$$

\rightarrow no singular points, i.e. can obtain series solⁿ expanding about $y=0$

Assuming $H(y) = \sum_{n=0}^{\infty} a_n y^n$

$$\frac{dH}{dy} = \sum_{n=0}^{\infty} a_n n y^{n-1}$$

$$\frac{dH}{dy} = \sum_{n=0}^{\infty} a_n n(n-1) y^{n-2}$$

→ insert into diff eqⁿ

$$\sum_{n=0}^{\infty} a_n n(n-1) y^{n-2} - 2 \sum_{n=0}^{\infty} a_n n y^{n-1} + (\epsilon-1) \sum_{n=0}^{\infty} a_n y^n = 0$$

→ Combining terms & changing dummy variables in the first term

$$\sum_{n=0}^{\infty} a_{n+2} y^n (n+1)(n+2) + \sum_{n=0}^{\infty} (\epsilon-1-2n) a_n y^n = 0$$

$$\Rightarrow a_{n+2} (n+1)(n+2) = -(\epsilon-1-2n) a_n$$

$$a_{n+2} = \frac{2n+1-\epsilon}{(n+1)(n+2)} a_n$$

Testing convergence:

$$\lim_{n \rightarrow \infty} \frac{a_{n+2}}{a_n} = \frac{2\epsilon}{n^2} = 0$$

$$\text{Taking } e^{x^2} = \sum_{n=0}^{\infty} \frac{1}{n!} x^{2n}$$

→ set $2n = j$

$$\Rightarrow e^{x^2} = \sum_{j=0,2,4}^{\infty} \frac{1}{(j/2)!} x^j$$

$$\lim_{j \rightarrow \infty} \frac{c_{j+2}}{c_j} = \frac{(j/2)!}{((j+2)/2)!} = \frac{1}{j+2} = \frac{1}{j/2+1} = \frac{2}{j}$$

which means our function goes like e^{x^2} and even w/ a damping term, $e^{-x^2/2}$, we still have $e^{x^2/2}$ and the series is not converging

收敛

We need to truncate the series

→ We turn series into a polynomial

+ require @ some point, a term is zero,

→ ∴ series terminates → @ some pt, it stops

$$\text{I.e. } a_{n+2} = \frac{(2n+1-\epsilon) a_n}{(n+1)(n+2)} a_n = 0$$

BUT $a_n \neq 0$

$$\text{And } H(y) = \sum_{n=0}^j a_n y^n$$

$$\Rightarrow 2j+1-\epsilon=0$$

$$\epsilon = 2j+1$$

$$\text{Recalling } \epsilon = \frac{2E}{\hbar\omega}$$

$$E = \hbar\omega (j + \frac{1}{2}), j = 0, 1, 2, 3, \dots$$

Now writing down the polynomials

- Hermite polynomial

$$a_{n+2} = \frac{(2n+1-\epsilon) a_n}{(n+1)(n+2)} = \frac{2(n-j) a_n}{(n+1)(n+2)}$$

$$\epsilon = 2j+1$$

∴ $a_{n+2} \dots$ we can only equate even & odd parts separately for n, j

$$j=0, n=0 \Rightarrow a_2 = \frac{2(0-0)}{2} a_0 = 0$$

$$a_4 = a_2 = 0 \text{ etc}$$

$$j=1, n=1 \Rightarrow a_3 = \frac{2(0)}{(2)(3)} a_1 = 0$$

$$a_5 = 0, \text{ etc}$$

⇒

$$j=2$$

$$n=0$$

$$a_{n+2} = \frac{2(n-j)a_n}{(n+1)(n+2)}$$

$$a_2 = \frac{2(0-2)a_0}{(1)(2)} = -2a_0$$

$$a_4 = 0, \text{ etc...}$$

$$j=3, n=1 \Rightarrow a_3 = \frac{2(1-3)a_1}{(2)(3)} = -\frac{2}{3}a_1$$

$$a_5 = 0, \text{ etc...}$$

For convention on normalisation is that the highest term in a_j has a value 2^j .

$$H_0(y): a_0 = 1 \quad [a_0 = 2^0 = 1]$$

$$H_1(y) = a_1 y' = 2y \quad [a_1 = 2^1 = 2]$$

$$H_2(y) = a_0 - 2a_2 y^2 =$$

$$1 - 2y^2 \Rightarrow -2a_2 = 4$$

$$a_2 = -2$$

$$= -2 + 4y^2$$

$$H_3(y) = a_1 - \frac{2}{3}a_3 y^3$$

$$2y - \frac{2}{3}a_3 y^3 \Rightarrow -\frac{2}{3}a_3 = 8$$

$$a_3 = -12$$

$$= -12y + 8y^3$$

Back to the Schrödinger eqⁿ

$$\psi(y) = H(y) e^{-\frac{y^2}{2}}$$

$$\psi_0(x) = A \cdot 1 \cdot e^{-\frac{1}{2} \left(\frac{m\omega}{\hbar} \right)^{\frac{1}{2}} x^2}$$

$$= A e^{-\frac{1}{2} \left(\frac{m^2 \omega^2}{\hbar^2} \right)^{\frac{1}{2}} x^2}$$

$$= A e^{-\frac{1}{2} \left(\frac{m\omega}{\hbar} \right) x^2}$$

for $\psi_0(x)$

use $H_0(y) = 1$

For normalisation:

$$\int_{-\infty}^{\infty} |\psi_0|^2 dx = 1$$

$$\int_{-\infty}^{\infty} e^{-\frac{m\omega}{\hbar} x^2} dx = 1 \quad \text{Gaussian}$$

$$A^2 \int_{-\infty}^{\infty} e^{-\frac{m\omega}{\hbar} x^2} dx = 1$$

$$A = \left(\frac{m\omega}{\pi\hbar} \right)^{\frac{1}{4}}$$

$$\Rightarrow \psi_0(x) = \left(\frac{m\omega}{\pi\hbar} \right)^{\frac{1}{4}} e^{-\frac{m\omega x^2}{2\hbar}}$$

→ corresponds to energy level

$$E_0 = \frac{1}{2} \hbar \omega$$

2.6/ The radial part of Laplace's eqⁿ

$$\text{We had: } \frac{\sin^2 \theta}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + \frac{\sin \theta}{\theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\theta}{d\theta} \right) + \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = 0$$

$$\text{And } \frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = -m^2$$

$$\Rightarrow \frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = \frac{m^2}{\sin^2 \theta} - \frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\theta}{d\theta} \right)$$

$$= \lambda$$

$$= \lambda$$

$$\Rightarrow r^2 \frac{d^2 R}{dr^2} + 2r \frac{dR}{dr} - \lambda R = 0$$

$$\div r^2$$

$$\Rightarrow \frac{d^2 R}{dr^2} + \frac{2}{r} \frac{dR}{dr} - \frac{\lambda R}{r^2} = 0$$

$$p(r) = \frac{2}{r}; q(r) = -\frac{\lambda}{r^2}$$

Singularity around $r=0$

Checking if can use Frobenius's method

$$\begin{aligned} p_0 &= \lim_{r \rightarrow 0} \frac{2}{r} \cdot r = 2 \\ q_0 &= \lim_{r \rightarrow 0} \frac{-\lambda}{r^2} \cdot r^2 = -\lambda \end{aligned} \Rightarrow \text{regular singular pt}$$

$$\text{Assuming } R(r) = \sum_{n=0}^{\infty} a_n r^{n+k}$$

Indicial eqⁿ

$$k(k-1) + p_0 k + q_0 = 0$$

$$k^2 + k - \lambda = 0$$

$$k = \frac{-1 \pm \sqrt{1+4\lambda}}{2}$$

$$\text{As before: } \underline{\lambda = l(l+1)}$$

$$k_1 = l, k_2 = -l-1$$

$$\frac{dR}{dr} = \sum_{n=0}^{\infty} a_n (n+k) r^{n+k-1}$$

$$\frac{d^2 R}{dr^2} = \sum_{n=0}^{\infty} (n+k)(n+k-1) r^{n+k-2}$$

Put into:

$$r^2 \frac{d^2 R}{dr^2} + 2r \frac{dR}{dr} - \lambda R = 0$$

→ gives

$$\sum_{n=0}^{\infty} a_n (n+k)(n+k-1) r^{n+k} + 2 \sum_{n=0}^{\infty} a_n (n+k) r^{n+k} - \lambda \sum_{n=0}^{\infty} a_n r^{n+k} = 0$$

$$\Rightarrow \sum_{n=0}^{\infty} a_n r^{n+k} [(n+k)(n+k-1) + 2(n+k) - \lambda] = 0$$

$$\star a_0 \neq 0$$

For $n=0$:

$$a_0 [k(k-1) + 2k - \lambda] = 0$$

indicial eqⁿ

For all the n :

$$a_n [(n+k)(n+k-1) + 2(n+k) - \lambda] = 0$$

$$\Rightarrow a_n = 0 \quad (n=1, 2, 3, \dots)$$

=)

Given that $a_0 \neq 0$, $a_n = 0$
 $k_1 = l$, $k_2 = -l-1$

$$R(r) = C e^{r^l} + D \frac{1}{r^{l+1}}$$

\swarrow \searrow
 a_0 term a_0 term
 $r^{nlk} = r^l$ r^{0-l-1}

Polar Eqn:

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) - \frac{m^2}{\sin^2 \theta} = -\lambda$$

[Legendre equation] $= -l(l+1)$
 need use Legendre polynomial
 coming next.

One other example on series sol^y

$$2x^2 y'' - x y' + (1+x)y = 0$$

$$y'' - \frac{1}{2x} y' + \frac{1+x}{2x^2} y = 0$$

$$p_0 = -\frac{1}{2}$$

$$q_0 = \frac{1}{2}$$

$$k(k-1) - \frac{1}{2}k + \frac{1}{2} = 0$$

$$k^2 - k - \frac{1}{2}k + \frac{1}{2} = 0$$

$$k^2 - \frac{3}{2}k + \frac{1}{2} = 0$$

$$2k^2 - 3k + 1 = 0$$

$$(2k-1)(k-1) = 0$$

$$k = \frac{1}{2} \text{ or } k = 1$$

testing for convergence

$$S = \lim_{n \rightarrow \infty} \left| \frac{a_{n+1} x^{n+1}}{a_n x^n} \right| =$$

$$= |x| \lim_{n \rightarrow \infty} \left| \frac{3 \cdot 5 \cdot 7 \cdot (2n+1) n!}{[3 \cdot 5 \cdot 7 \cdot \dots (2n+1)(2n+2+1)(n+1)] n!} \right|$$

$$= |x| \lim_{n \rightarrow \infty} \left| \frac{n!}{(2n+3)(n+1)n!} \right| = 0$$

series converges for all x

general sol^y is $a_0 = 1$

$$y_1(x) = x \left[1 + \sum_{n=1}^{\infty} \frac{(-1)^n x^n}{(3 \cdot 5 \cdot 7 \cdot \dots (2n+1)) n!} \right]$$

for the series sol^y

$$2 \sum_{n=0}^{\infty} a_n (n+k-1)(n+k) x^{n+k} - \sum_{n=0}^{\infty} a_n x^{n+k} (n+k) + \sum_{n=0}^{\infty} a_n x^{n+k} + \sum_{n=0}^{\infty} a_n x^{n+k+1} = 0$$

$$2a_n [(n+k-1)(n+k) - (n+k) + 1] + a_{n-1} = 0 \quad n \geq 1$$

$$k=1$$

$$a_n = \frac{-a_{n-1}}{2(n+1)(n) - n - 1}$$

$$a_n = \frac{-a_{n-1}}{n(2n+1) - 1} = \frac{-a_{n-1}}{n(2n+1)}$$

$$a_n = \frac{-a_{n-1}}{n(2n+1)}$$

$$a_1 = \frac{-a_0}{3}$$

$$a_2 = \frac{-a_1}{2(5)} = \frac{a_0}{5 \times 3 \times 2}$$

$$a_3 = \frac{-a_2}{3(7)} = -\frac{a_0}{7 \times 5 \times 3 \times 2 \times 1}$$

$$\Rightarrow a_n = \frac{(-1)^n}{(3 \cdot 5 \cdot 7 \cdot \dots (2n+1)) n!}$$

for $k = \frac{1}{2}$

$$a_n = \frac{-a_{n-1}}{2(n+\frac{1}{2})(n-\frac{1}{2}) - n + \frac{1}{2}}$$

$$= \frac{-a_{n-1}}{2(n^2 - \frac{1}{4}) - n + \frac{1}{2}}$$

$$= \frac{-a_{n-1}}{2n^2 - \frac{1}{2} - n + \frac{1}{2}} = \frac{-a_{n-1}}{n(2n-1)}$$

$$a_n = \frac{-a_{n-1}}{n(2n-1)}$$

$$a_1 = \frac{-a_0}{1(-1)}$$

$$a_2 = \frac{-a_1}{2(3)} = \frac{a_0}{3 \times 2 \times 1}$$

$$a_3 = \frac{-a_2}{3(5)} = \frac{-a_0}{5 \times 3 \times 2 \times 1 \times 1}$$

$$a_4 = \frac{-a_3}{4(7)} = \frac{a_0}{7 \times 5 \times 3 \times 2 \times 1 \times 4 \times 3 \times 2 \times 1}$$

$$a_n = \frac{(-1)^n a_0}{n! (3 \times 5 \times 7 \cdots (2n-1))} \quad n \geq 1$$

$$y_2(x) = x^{\frac{1}{2}} \left[1 + \sum_{n=1}^{\infty} \frac{(-1)^n x^n}{[3 \times 5 \times 7 \cdots (2n-1)] n!} \right]$$

3. Legendre polynomials

3.1 Laplace's Eqⁿ in spherical Coordinates

3.2 E-field from a sphere of radius R

3.3 Generating function

3.4 Orthogonality

3.5 Expansion of a function in terms of Legendre polynomials

3.6 Spherical Harmonics

3.7 More Eqs.

3.1 Laplace's Eqⁿ in spherical Coordinates

$$\frac{d^2 \Phi}{d\phi^2} = -m^2 \Phi \quad [\text{Azimuthal Eq}^n]$$

$$\frac{1}{r} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = \lambda \quad [\text{Radial Eq}^n]$$

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) - \frac{m^2}{\sin^2 \theta} = -\lambda \quad [\text{Polar eq}^n]$$

$$= -l(l+1)$$

Rewrite in singular form

$$x = \cos \theta ; \quad \Theta(\theta) = y(x)$$

$$\sin^2 \theta = 1 - \cos^2 \theta = 1 - x^2$$

$$\frac{dx}{d\theta} = -\sin \theta = -\sqrt{1-x^2}$$

$$\frac{d\Theta}{d\theta} = \frac{d\Theta}{dx} \frac{dx}{d\theta} = -\sin \theta \frac{d\Theta}{dx} = -\sqrt{1-x^2} \frac{dy}{dx}$$

$$\hookrightarrow \frac{d}{d\theta} = -\sqrt{1-x^2} \frac{d}{dx}$$

$$\frac{d^2 \Theta}{d\theta^2} = \frac{d}{d\theta} \left[\frac{d\Theta}{d\theta} \right] = -\sqrt{1-x^2} \frac{d}{dx} \left(-\sqrt{1-x^2} \frac{dy}{dx} \right)$$

$$= -\sqrt{1-x^2} \left(-\frac{2x}{2\sqrt{1-x^2}} \frac{dy}{dx} - \sqrt{1-x^2} \frac{d^2 y}{dx^2} \right)$$

$$= -x \frac{dy}{dx} + (1-x^2) \frac{d^2 y}{dx^2}$$

using the polar eqⁿ ($x\Theta \sin \theta$)

$$\frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left[l(l+1) \sin \theta - \frac{m^2}{\sin \theta} \right] \Theta = 0$$

$$\cos \theta \frac{d\Theta}{d\theta} + \sin \theta \frac{d^2 \Theta}{d\theta^2} + \left[l(l+1) \sin \theta - \frac{m^2}{\sin \theta} \right] \Theta = 0$$

Replacing $\cos \theta$ & $\sin \theta$

$$x(-\sqrt{1-x^2}) \frac{dy}{dx} + (\sqrt{1-x^2}) \frac{d^2 y}{dx^2} \left[l(l+1) \sqrt{1-x^2} - \frac{m^2}{\sqrt{1-x^2}} \right] \Theta = 0$$

replacing Θ , Θ' , Θ'' :

$$-x\sqrt{1-x^2} y' + \sqrt{1-x^2} (-xy' + (1-x^2)y'') \left[l(l+1)\sqrt{1-x^2} - \frac{m^2}{\sqrt{1-x^2}} \right] y = 0$$

$$x \frac{1}{1-x^2} :$$

$$-xy' + (-xy' + (1-x^2)y'') + (l(l+1) - \frac{x^2}{1-x^2})y = 0$$

$$(1-x^2)y'' - 2xy' + (l(l+1) - \frac{x^2}{1-x^2})y = 0$$

first solving for $m=0$, i.e. no ϕ dependence \Rightarrow having cylindrical symmetry

$$(1-x^2)y'' - 2xy' + (l(l+1))y = 0 \quad \left| \begin{array}{l} l(l+1) = \lambda \\ \div (1-x^2) \end{array} \right.$$

$$y'' - \frac{2xy'}{1-x^2} + \frac{\lambda}{1-x^2}y = 0$$

$$p(x) = \frac{-2x}{1-x^2} \quad q(x) = \frac{\lambda}{1-x^2}$$

$x = \pm 1$ in a

singular pt

$$x_0 = +1$$

$$p_0(x) = \lim_{x \rightarrow 1} \frac{-2x}{(1-x)(1+x)} (x-1) = \lim_{x \rightarrow 1} \frac{2x}{1+x} = \frac{2}{2} = 1$$

$$q_0(x) = \lim_{x \rightarrow 1} \frac{\lambda}{(1-x)(1+x)} (x-1)^2 = \lim_{x \rightarrow 1} \frac{-\lambda(x-1)}{1+x} = 0$$

$$x_0 = -1$$

$$p_0(x) = \lim_{x \rightarrow -1} \frac{-2x}{(1-x)(1+x)} (1+x) = \lim_{x \rightarrow -1} \frac{-2x}{1-x} = 1$$

$$q_0(x) = \lim_{x \rightarrow -1} \frac{\lambda(1+x)^2}{(1-x)(1+x)} = 0$$

\rightarrow We can find a series solⁿ

We will expand around $x=0$ as this is an ordinary pt between the singular points

quick check

$$p_0 = \lim_{x \rightarrow 0} \frac{-2x}{1-x^2} \cdot x = 0$$

$$q_0 = \lim_{x \rightarrow 0} \frac{\lambda}{1-x^2} x^2 = 0$$

$$\text{Assume } y(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y' = \sum_{n=0}^{\infty} a_n n x^{n-1}$$

$$y'' = \sum_{n=0}^{\infty} a_n n(n-1) x^{n-2}$$

Indicial Eqⁿ

$$k(k-1) = 0$$

$$k=0 \text{ or } k=1$$

$$\sum_{n=0}^{\infty} a_n n(n-1) x^{n-2} - \sum_{n=0}^{\infty} a_n n(n-1) x^n - 2 \sum_{n=0}^{\infty} a_n n x^{n-1} + l(l+1) \sum_{n=0}^{\infty} a_n x^n = 0$$

$$\Rightarrow \sum_{n=1}^{\infty} a_{n+2} (n+1)(n+2) x^{n-1} = \sum_{n=0}^{\infty} a_n x^n [(n)(n+1) + 2n - l(l+1)]$$

$$a_{n+2} = \frac{n(n+1) - l(l+1)}{(n+1)(n+2)} a_n$$

Ex. $a_0 = 1$

$$\Rightarrow a_2 = \frac{-l(l+1)}{2}$$

$$a_4 = \frac{6 - l(l+1)}{(3)(4)} \cdot \frac{-l(l+1)}{2}$$

$$= \frac{l(l+1)(l-2)(l+3)}{4!}$$

$$y_1(x) = 1 - \frac{l(l+1)x^2}{2!} + \frac{l(l+1)(l-2)(l+3)x^4}{4!}$$

Convergence:

$$S = \lim_{n \rightarrow \infty} \left| \frac{a_{n+2}}{a_n} \frac{x^{n+2}}{x^n} \right|$$

$$= \lim_{n \rightarrow \infty} \left| \frac{n(n+1) - l(l+1)}{(n+1)(n+2)} x^2 \right|$$

$$= |x|^2 \Rightarrow \text{converges for } |x| < 1$$

But series diverges for $|x| > 1$

Recalling $x = \cos \theta$

$|x| < 1$ means $0 < \theta < \pi$

But $n=1 \Rightarrow \theta = 0$ or π

\rightarrow series diverges for $n=1$, \therefore we have to terminate the series, i.e. for some n , recurrence relation yields $a_{n+2} = 0$

\hookrightarrow that all higher terms also vanish

We have a set of polynomials

$$a_{n+2} = \frac{n(n+1) - l(l+1)}{(n+1)(n+2)} a_n = 0$$

$$a_n \neq 0$$

$$\Rightarrow n(n+1) = l(l+1)$$

$$\hookrightarrow y^{(l)}(x) = \sum_{n=0}^l a_n^{(l)} x^n = P_l(x)$$

$$a_3 = \frac{2 - l(l+1)}{3 \times 2} a_1 = \frac{-(l+1)(l+2)}{3!}$$

$$a_5 = \frac{12 - l(l+1)}{5 \times 4} \cdot \frac{-(l+2)(l+1)}{3!}$$

$$= \frac{(l-1)(l+3)(l-2)(l+4)}{5!}$$

$$y_2(x) = x - \frac{(l+2)(l+1)x^3}{3!} + \frac{x^5(l-1)(l+3)(l-2)(l+4)}{5!}$$

First terms:

$$l=0 \quad a_1 \neq 0, a_2 = \frac{0-0}{2} a_0 = 0$$

$$n=0 \quad \Rightarrow P_0(x) = a_0 = 1 \quad [\text{just setting up for convention that } P_l(1) = 1]$$

$$l \geq 1 \quad a_1 \neq 0, a_3 = 0$$

$$n=1 \quad P_1(x) = a_1(x) = x$$

$$l=2 \quad a_2 = \frac{-2(3)}{1 \cdot 2} a_0 = -3a_0$$

$$n=0$$

$$l=2 \quad a_1 = 0$$

$$n=2$$

$$P_2(x) = a_0(1 - 3x^2)$$

Normalisation $P_2(1) = a_0(1-1) = 1$

$$a_0 = -\frac{1}{2}$$

$$\Rightarrow P_2(x) = \frac{1}{2}(3x^2 - 1)$$

$$l=3 \quad a_3 = \frac{2-12}{2(3)} a_1 = -\frac{5}{3} a_1$$

$$n=1$$

Normalisation $P_3(1) = a_1(1 - \frac{5}{3}) = 1$

$$a_1 = -\frac{3}{2}$$

$$n=3 \quad a_5 = 0$$

$$P_3(x) = a_1(x - \frac{5}{3}x^3)$$

$$P_3(x) = \frac{1}{2}(5x^3 - 3x)$$

3.2 Electric field from a sphere of radius R

\Rightarrow looking for a solⁿ for Laplace's eqⁿ, $\nabla^2 V = 0$,
in 3D spherical coordinates

Consider the boundary condition

$$V(r=R, \theta, \phi) = V_0 \cos^2 \theta$$

$$V(r, \theta, \phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^l \left(C_l r^l + \frac{D_l}{r^{l+1}} \right) P_l(\cos \theta) A_m e^{-im\phi}$$

$$\begin{array}{ll} P_0(x) = 1 & P_0(\theta) = 1 \\ P_1(x) = x & P_1(\theta) = \cos \theta \\ P_2(x) = \frac{1}{2}(3x^2 - 1) & P_2(\theta) = \frac{1}{2}(3\cos^2 \theta - 1) \end{array} \quad x = \cos \theta$$

We have cylindrical symmetry, \therefore no ϕ dependence

$V \rightarrow 0$ as $r \rightarrow \infty \Rightarrow C_l r^l$ vanishes

$$V(r, \theta) = \sum_{l=0}^{\infty} \frac{D_l}{r^{l+1}} P_l(\cos \theta) \quad \text{Multipole expansion}$$

At $r=R$

$$V(R, \theta) = \frac{D_0}{R} P_0 \cos \theta + \frac{D_1}{R^2} P_1 \cos \theta + \frac{D_2}{R^3} P_2 \cos \theta + \dots$$

$$= V_0 \cos^2 \theta$$

Equating terms: + putting in L. Polynomials

$$\frac{D_0}{R} + \frac{D_1}{R^2} \cos \theta + \frac{D_2}{R^3} \frac{1}{2} (3\cos^2 \theta - 1) = V_0 \cos^2 \theta$$

$$1. \quad \frac{D_0}{R} - \frac{D_2}{R^3} \frac{1}{2} = 0 \quad V(r, \theta) = \frac{D_0}{r} P_0 + \frac{D_2}{r^3} P_2$$

$$= \frac{V_0 R}{3r} \left(1 + \frac{2}{3} \frac{V_0 R^2}{r^2} \cdot \frac{1}{2} (3\cos^2 \theta - 1) \right)$$

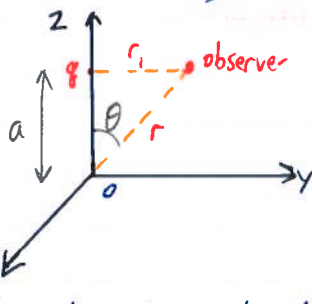
$$2. \quad \frac{D_1}{R^2} = 0 \Rightarrow D_1 = 0$$

$$3. \quad \frac{D_2}{R^3} \frac{3}{2} = V_0$$

$$\Rightarrow D_2 = \frac{2}{3} V_0 R^3$$

$$\Rightarrow D_0 = \frac{D_2}{2R^2} = \frac{1}{3} V_0 R$$

3.3 Generating function



- considering a single charge q
located on the z -axis @ a distance from 0

Electrostatic potential, V_1 @ a distance

$$r_1 \text{ in } V = \frac{q}{4\pi\epsilon_0} \frac{1}{r_1}$$

re-write in terms of r, θ

$$r_1^2 = r^2 + a^2 - 2ra \cos \theta$$

$$\therefore V(r, \theta) = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{r^2 + a^2 - 2ra \cos \theta}}$$

Comparing to the multipole expansion:

$$V(r, \theta) = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{r^2 + a^2 - 2ra \cos \theta}} = \sum_{l=0}^{\infty} \frac{P_l}{r^{l+1}} \cdot P_l(\cos \theta)$$

Holds for all r, θ , so take $\theta = 0$

$$V(r, 0) = \sum_{l=0}^{\infty} \frac{P_l}{r^{l+1}} P_l(1) = \sum_{l=0}^{\infty} \frac{1}{r^{l+1}} \frac{D_l}{r^l}$$

$$\text{Also } V(r, 0) = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{r^2 + a^2 - 2ra}} = \frac{q}{4\pi\epsilon_0} \frac{1}{r-a}$$

Assume $r \gg a$

$$V(r, 0) = \frac{q}{4\pi\epsilon_0} \frac{1}{r} \cdot \frac{1}{1 - \frac{a}{r}} = \frac{q}{4\pi\epsilon_0} \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{a}{r} \right)^l$$

Recalling Taylor expansion:

$$\frac{1}{1-x} = \sum_{l=0}^{\infty} x^l \text{ for } |x| < 1$$

Now we have: $\frac{1}{r} \sum_{l=0}^{\infty} \frac{D_l}{r^l} = \frac{q}{4\pi\epsilon_0} \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{a}{r} \right)^l$ for $r > a$

$$D_l = \frac{q}{4\pi\epsilon_0} a^l$$

Putting $V_0 = \frac{q}{4\pi\epsilon_0} \frac{a^l}{r^{l+1}}$ into our original expression

$$V(r, \theta) = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{r^2 + a^2 - 2ar\cos\theta}} = \sum_{l=0}^{\infty} \frac{q}{4\pi\epsilon_0} \frac{a^l}{r^{l+1}} P_l \cos\theta$$

$$\hookrightarrow \frac{1}{\sqrt{r^2 + a^2 - 2ar\cos\theta}} = \frac{a^l}{r^{l+1}} P_l \cos\theta$$

$$= \frac{1}{\sqrt{1 + \frac{a^2}{r^2} - 2\frac{a}{r}\cos\theta}} = \frac{1}{r} \sum_{l=0}^{\infty} \left(\frac{a}{r}\right)^l P_l \cos\theta$$

Set $\mu = \cos\theta$; $t = \frac{a}{r}$

$$\frac{1}{\sqrt{1+t^2-2t\mu}} = \sum_{l=0}^{\infty} (t)^l P_l(\mu) \quad |t| < 1$$

\therefore the function

$$g(t, \mu) = \frac{1}{\sqrt{1+t^2-2t\mu}}$$

is the generating function of the Legendre polynomials

Using the general form of the binomial expression

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2!} x^2 + \frac{n(n-1)(n-2)}{3!} x^3 + \dots$$

$$n = -\frac{1}{2}; \quad x = t^2 - 2t\mu$$

$$g(t) = 1 - \frac{1}{2}(t^2 - 2t\mu) + \frac{(-\frac{1}{2})(-\frac{3}{2})(t^2 - 2t\mu)^2}{2!} + \dots$$

$$= 1 - \frac{t^2}{2} + t\mu + \frac{3}{8}(t^4 - 4t^2\mu^2 + 4t^3\mu)$$

$$= 1 + \mu t + \frac{1}{2}(3\mu^2 - 1)t^2 + O(t^3)$$

$$P_0(\mu) = 1$$

$$P_1(\mu) = \mu$$

$$P_2(\mu) = \frac{1}{2}(3\mu^2 - 1)$$

$$g(t, \mu) = \sum_{l=0}^{\infty} P_l(\mu) t^l$$

Electric Multipoles:

$$V(r, \theta) = \frac{q}{4\pi\epsilon_0 r} \sum_{l=0}^{\infty} \left(\frac{a}{r}\right)^l P_l \cos\theta$$

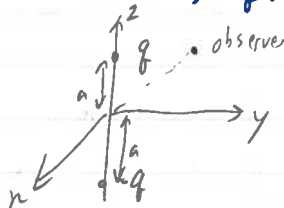
\Rightarrow leading term: $\frac{q}{4\pi\epsilon_0 r}$

which can also be seen from

$$V(r, \theta) = \frac{q}{4\pi\epsilon_0} \frac{1}{\sqrt{r^2 + a^2 - 2ar\cos\theta}}$$

$$\text{as } r \rightarrow \infty : V(r, \theta) = \frac{q}{4\pi\epsilon_0 r}$$

Consider charge $-q$ as $z = -a$ also:



$$V = \frac{+q}{4\pi\epsilon_0 r} \sum_{l=0}^{\infty} \left(\frac{a}{r}\right)^l P_l \cos\theta + \frac{-q}{4\pi\epsilon_0 r} \sum_{l=0}^{\infty} \left(\frac{-a}{r}\right)^l P_l \cos\theta$$

$$= \frac{2q}{4\pi\epsilon_0 r} \left[0 + P_1 \cos\theta \frac{a}{r} + 0 + P_3 \cos\theta \left(\frac{a}{r}\right)^3 + \dots \right]$$

$$= \frac{2q}{4\pi\epsilon_0 r} \left[\cos\theta \frac{a}{r} \right] \rightarrow \text{the leading term}$$

$$V = \frac{2qa}{4\pi\epsilon_0 r^2} \cos\theta \quad [\text{dipole term}]$$

3.4 Orthogonality & Normalizations

We now have the Legendre eqⁿ:

$$(1-x^2)y'' - 2xy' + \lambda y = 0$$

Polynomial solutions are of: $y_{(l)} = P_l(x)$

$$(1-x^2)P_l''(x) - 2xP_l'(x) + l(l+1)P_l(x) = 0 \quad (1)$$

Renaming another label: $l \rightarrow m$

$$(1-x^2)P_m''(x) - 2xP_m'(x) + m(m+1)P_m(x) = 0 \quad (2)$$

① $\times P_m$ & integrate

$$\int_{-1}^1 (1-x^2)P_l'' P_m dx - \int_{-1}^1 2xP_l' P_m dx + l(l+1) \int_{-1}^1 P_l P_m dx = 0$$

② $\times P_l$ & integrate

$$\int_{-1}^1 (1-x^2)P_m'' P_l dx - \int_{-1}^1 2xP_m' P_l dx + m(m+1) \int_{-1}^1 P_m P_l dx = 0$$

Integrating first term by parts

$$u = (1-x^2)P_m \quad v' = P_l''$$

$$u' = (-2x)P_m - 2xP_m' \quad v' = P_l'$$

$$\int_{-1}^1 (1-x^2)P_l'' P_m dx = \left[(1-x^2)P_m P_l' \right]_{-1}^1 - \int_{-1}^1 2xP_m P_l' dx - \int_{-1}^1 (1-x^2)P_l' P_m' dx$$

* 2nd Term cancels w/ the 2nd term of the original expression from the full eqⁿ

$$\Rightarrow - \int_{-1}^1 (1-x^2)P_l' P_m' dx + l(l+1) \int_{-1}^1 P_l P_m dx = 0$$

and likewise

$$- \int_{-1}^1 (1-x^2)P_m' P_l' dx + m(m+1) \int_{-1}^1 P_m P_l dx = 0$$

Subtracting:

$$[l(l+1) - m(m+1)] \int_{-1}^1 P_l(x) P_m(x) dx = 0$$

If $l = m$, L.H.S. = 0

If $l \neq m$:

$$\int_{-1}^1 P_l(x) P_m(x) dx = 0 \quad \text{if } l \neq m$$

Definition of orthogonality

For $l = m$ case:

$$P_l(x) \cdot P_l(x) = \int_{-1}^1 P_l(x) P_l(x) dx = \frac{2}{2l+1} \quad \Rightarrow \frac{1}{\sqrt{\frac{2}{2l+1}}}$$

Using the generating function

$$\sum_{n=0}^{\infty} P_n(x) t^n = \frac{1}{\sqrt{1-2xt+t^2}}$$

$$\sum_{n=0}^{\infty} P_n(x) t^n = \frac{1}{\sqrt{1-2xt+t^2}}$$

Multiply:

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} P_n(x) P_m(x) t^{n+m} = \frac{1}{1-2xt+t^2}$$

Integrate:

$$\int_{-1}^1 \frac{dx}{1-2xt+t^2} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \int_{-1}^1 P_n(x) P_m(x) t^{n+m} dx$$

$$\text{L.H.S.} = -\frac{1}{2t} \left[\ln(1-2xt+t^2) \right]_{-1}^1$$

$$= -\frac{1}{2t} \left[\ln(1-t^2) - \ln(1+t^2) \right]$$

$$= \frac{1}{t} \ln\left(\frac{1+t}{1-t}\right)$$

Using Taylor expansions:

$$\ln(1+x) = \sum_{n=1}^{\infty} (-1)^{n+1} \frac{x^n}{n}$$

$$\ln(1-x) = -\sum_{n=1}^{\infty} \frac{x^n}{n}$$

$$\begin{aligned} \Rightarrow \ln(1+x) - \ln(1-x) &= x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots \\ &\quad + x + \frac{x^2}{2} + \frac{x^3}{3} + \frac{x^4}{4} + \dots \\ &= 2 \sum_{n=0}^{\infty} \frac{x^{2n+1}}{2n+1} \end{aligned}$$

$$\Rightarrow \text{L.H.S.} = 2 \sum_{n=0}^{\infty} \frac{t^{2n+1}}{2n+1} = 2 \sum_{n=0}^{\infty} \frac{t^{2n}}{2n+1}$$

R.H.S. \Rightarrow integral is zero if $n \neq m$

$$\sum_{n=0}^{\infty} t^{2n} \int_{-1}^1 P_n(x) P_n(x) dx$$

L.H.S. = R.H.S.

$$2 \sum_{n=0}^{\infty} \frac{t^{2n}}{2n+1} = \sum_{n=0}^{\infty} t^{2n} \int_{-1}^1 P_n(x) P_n(x) dx$$

Comparing coefficients t^{2n}

$$\int_{-1}^1 P_n(x) P_n(x) dx = \frac{2}{2n+1}$$

\Rightarrow We can write:

$$\int_{-1}^1 P_n(x) P_n(x) dx = \frac{2}{2n+1} \delta_{nn}$$

$\delta_{nn} = \begin{cases} 1 & \text{for } l=n \\ 0 & \text{for } l \neq n \end{cases}$

$$\frac{5}{2} n^3 - \frac{3}{2} n$$

$$\frac{5}{2} \left(n^3 - \frac{3}{5} n \right)$$

$$\frac{1}{2} (5n^3 - 3n)$$

3.5 Expansion of a function in terms of Legendre Polynomials

For any reasonable, continuous function $f(x)$ in the interval $-1 \leq x \leq 1$

$$f(x) = \sum_{l=0}^{\infty} C_l P_l(x)$$

To find C_l :

Multiply by $P_m(x)$ & integrate:

$$\int_{-1}^1 f(x) P_m(x) dx = \sum_{l=0}^{\infty} C_l \int_{-1}^1 P_l(x) P_m(x) dx$$

$$= \sum_{l=0}^{\infty} C_l \delta_{lm} \frac{2}{2l+1}$$

$$[\text{can only hold for } l=m]$$

$$\Rightarrow C_m = \frac{2m+1}{2} \int_{-1}^1 f(x) P_m(x) dx$$

eg. $e^{\alpha x}$

$$C_0 = \frac{1}{2} \int_{-1}^1 e^{\alpha x} P_0(x) dx$$

$$= \frac{1}{2} \int_{-1}^1 e^{\alpha x} dx$$

$$= \frac{1}{2} \left[\frac{e^{\alpha x}}{\alpha} \right]_{-1}^1$$

$$= \frac{1}{2\alpha} (e^{\alpha} - e^{-\alpha})$$

$$= \frac{1}{\alpha} \sinh \alpha$$

$$C_1 = \frac{3}{2} \int_{-1}^1 e^{\alpha x} P_1(x) dx$$

$$= \frac{3}{2} \int_{-1}^1 e^{\alpha x} x dx$$

$$= \frac{3}{2} \left[\frac{x}{\alpha} e^{\alpha x} \right]_{-1}^1 - \frac{3}{2} \int_{-1}^1 \frac{1}{\alpha} e^{\alpha x} dx$$

$$= \frac{3}{2} \left[\frac{e^{\alpha} - e^{-\alpha}}{\alpha} \right] - \frac{3}{2\alpha} \left[\frac{e^{\alpha x}}{\alpha} \right]_{-1}^1$$

$$= \frac{3}{\alpha} \left(\cosh \alpha - \frac{\sinh \alpha}{\alpha} \right)$$

3.6 / Spherical harmonics

Well-behaved ("physical") solⁿ of Legendre's equation are possible if:

- l is a non-negative integer
- m is an integer w/ $-l \leq m \leq l$

for $m > 0$, P_l^m can be derived from P_l using:

$$P_l^m(x) = (-1)^m (1-x^2)^{m/2} \frac{d^m}{dx^m} P_l(x)$$

The orthogonality relation:

$$\int_{-1}^1 P_l^m(x) P_n^m(x) dx = \frac{2}{2l+1} \frac{(l+m)!}{(l-m)!} \delta_{ln}$$

Relationship between $P_n^m(x)$ & $P_n^{-m}(x)$ is:

$$P_n^{-m}(x) = (-1)^m \frac{(n-m)!}{(n+m)!} P_n^m(x)$$

The orthogonality relation when m is different:

$$\int_{-1}^1 P_n^m(x) P_n^k(x) \frac{dx}{1-x^2} = \frac{(n+m)!}{m(n-m)!} \delta_{mk}$$

First terms:

$$\begin{aligned} l=1 \quad m=1 \quad P_1^1(x) &= (1-x^2)^{\frac{1}{2}} \frac{d}{dx} x \\ &= (1-x^2)^{\frac{1}{2}} \quad | \quad x = \cos \theta \\ &= \sin \theta \end{aligned}$$

$$\begin{aligned} l=2 \quad m=1 \quad P_2^1(x) &= (1-x^2)^{\frac{1}{2}} \frac{d}{dx} \left[\frac{1}{2} (3x^2-1) \right] \\ &= (1-x^2)^{\frac{1}{2}} \cdot 3x \end{aligned}$$

$$\begin{aligned} l=2 \quad m=2 \quad P_2^2(x) &= (1-x^2)^{\frac{1}{2}} \frac{d^2}{dx^2} \left[\frac{1}{2} (3x^2-1) \right] \\ &= (1-x^2)^{\frac{1}{2}} \cdot 3 = 3 \sin^2 \theta \end{aligned}$$

Checking orthogonality

$$\begin{aligned} * \int_{-1}^1 P_2^1(x) P_2^1(x) dx &= \int_{-1}^1 3x(1-x^2)^{\frac{1}{2}} (1-x^2)^{\frac{1}{2}} dx \\ &= \int_{-1}^1 3x(1-x^2) dx \\ &= 0 \quad \Rightarrow \text{should get } 0 \quad \therefore \text{not the same} \end{aligned}$$

$$\begin{aligned} * \int_{-1}^1 P_2^1(x) \cdot P_2^{-1}(x) dx &= \int_{-1}^1 9x^2(1-x^2) dx \\ &= \left[3x^3 - \frac{9}{5}x^5 \right]_{-1}^1 \\ &= 2 \left[3 - \frac{9}{5} \right] \\ &= \frac{12}{5} \end{aligned}$$

$$* \int_{-1}^1 P_l^m(x) P_n^m(x) dx = \frac{2}{2l+1} \frac{(l+m)!}{(l-m)!} \delta_{ln}$$

$$\begin{aligned} \Rightarrow \int_{-1}^1 P_2^1(x) P_2^1(x) dx &= \frac{2}{l=2} \frac{3!}{5} \frac{1}{1!} \cdot 1 \\ &= \frac{12}{5} \end{aligned}$$

In quantum mechanics, we write

spherical harmonics $Y_l^m(\theta, \phi)$ as

$$Y_l^m(\theta, \phi) = c_{l,m} P_l^m(\cos \theta) e^{im\phi}$$

ψ is a solⁿ of the Legendre eqⁿ

By convention: Y_l^m is normalized as:

$$\int_{-1}^1 d(\cos \theta) \int_0^{2\pi} d\phi Y_l^m(\theta, \phi) Y_l^m(\theta, \phi) = \delta_{ll} \delta_{mm}$$

$$\therefore c_{l,m} = (-i)^m \sqrt{\frac{(l-m)! (2l+1)}{4\pi (l+m)!}}$$

$$\therefore Y_0^0(\theta, \phi) = \frac{1}{\sqrt{4\pi}}$$

$$Y_1^1(\theta, \phi) = -\sqrt{\frac{3}{8\pi}} \sin\theta e^{i\phi}$$

$$Y_2^0(\theta, \phi) = \sqrt{\frac{5}{4\pi}} \cos\theta$$

$$Y_2^1(\theta, \phi) = \sqrt{\frac{15}{8\pi}} \sin\theta e^{-i\phi}$$

Eg 1

A function $f(x) = 1 + 3x^2 + 4x^3$
is defined in the range $x = -1$ to 1

We can write the function as

$$f(x) = \sum_{n=0}^3 C_n P_n(x)$$

Obtain the values for the coefficients C_n
with $n \leq 3$

Eg 2 Spherical Harmonics are given by:

$$Y_l^m(\theta, \phi) = C_{l,m} P_l^m(\cos\theta) e^{im\phi}$$

$$\text{where } C_{l,m} = (-1)^m \sqrt{\frac{(l-m)! (2l+1)}{4\pi (l+m)!}}$$

& the associated Legendre function, P_l^m ,
can be derived from the Legendre polynomials

$$\text{using } P_l^m(x) = (-1)^m (1-x^2)^{m/2} \frac{d^m}{dx^m} P_l(x)$$

Derive $Y_2^1(\theta, \phi)$ & $Y_2^0(\theta, \phi)$
using the above

4. Lagrangian & Hamiltonian mechanics

4.1 The Euler-Lagrange eqⁿ

4.2 Lagrangian Mechanics

4.3 Hamiltonian mechanics

4.4 Extra examples.

4.1 Euler-Lagrange eqⁿ

Consider the integral:

$$J = \int_{x_1}^{x_2} f(y, y', x) dx$$

But

→ dependence of y on x is not fixed.

→ Choose a path through (x_1, y_1) & (x_2, y_2)
to minimize J

Assume: existence of a stationary path

& look for arbitrary deformations around it.

→ described by $\eta(x)$ & a scale factor α
to give the magnitude of variation

Impose: $\eta(x_1) = \eta(x_2) = 0$

$$\hookrightarrow y(x, \alpha) = y(x, 0) + \alpha \eta(x)$$

$$\delta y = y(x, \alpha) - y(x, 0) = \alpha \eta(x)$$

→ Choose $y(x, \alpha=0)$ as the unknown path
that will minimize J

$$J(\alpha) = \int_{x_1}^{x_2} f[y(x, \alpha), y'(x, \alpha), x] dx$$

$$\left. \frac{\partial J}{\partial \alpha} \right|_{\alpha=0} = 0$$

$$\frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} \left[\frac{\partial f}{\partial y} \frac{\partial y}{\partial \alpha} + \frac{\partial f}{\partial y'} \frac{\partial y'}{\partial \alpha} \right] dx$$

$$\left. \frac{\partial y}{\partial \alpha} = \eta(x) \right| \quad \left. \frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} \frac{\partial f}{\partial y} \eta(x) + \frac{\partial f}{\partial y'} \eta'(x) dx \right|$$

$$\left. \frac{\partial y'}{\partial \alpha} = \eta'(x) \right|$$

Integrating 2nd half term by parts:

$$\int_{x_1}^{x_2} \frac{\partial f}{\partial y'} \frac{d\eta}{dx} dx = \left[\eta(x) \frac{\partial f}{\partial y'} \right]_{x_1}^{x_2} - \int_{x_1}^{x_2} \eta(x) \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) dx$$

First term = 0 $\because \eta(x_1) = \eta(x_2) = 0$

For this to be true for arbitrary $\eta(x)$

$$\frac{\partial J}{\partial \alpha} = \int_{x_1}^{x_2} \left[\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} \right] \eta(x) dx = 0$$

$$\frac{\partial f}{\partial y} = \frac{d}{dx} \frac{\partial f}{\partial y'} \quad \text{Euler-Lagrange eqⁿ}$$

* when $\frac{\partial f}{\partial y} = 0$, $\frac{\partial f}{\partial y'} = \text{constant}$

$$* \frac{\partial f}{\partial x} - \frac{d}{dx} \left(f - y' \frac{\partial f}{\partial y'} \right) = 0$$

if $f = f(y, y')$

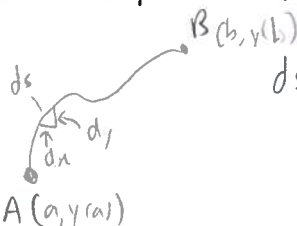
$$\hookrightarrow \frac{d}{dx} \left(f - y' \frac{\partial f}{\partial y'} \right) = 0 \quad \text{Boltzmann}$$

$$f - y' \frac{\partial f}{\partial y'} = \text{constant}$$

Eg A straight line: \hookrightarrow Boltzmann identity

determine the shortest distance

between two pts in the x - y plane



$$ds = \sqrt{dx^2 + dy^2} = \left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{\frac{1}{2}} dx$$

The total path length along the curve:

$$L = \int_{a, y(a)}^{b, y(b)} ds = \int_a^b (1 + y'^2)^{\frac{1}{2}} dx$$

Using the Euler-Lagrange Eqⁿ

$$\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0$$

where $f(y, y', x) = (1 + y'^2)^{\frac{1}{2}}$

$$\frac{\partial f}{\partial y} = 0 \quad \frac{\partial f}{\partial y'} = \frac{y'}{(1 + y'^2)^{\frac{1}{2}}}$$

$$\Rightarrow \frac{d}{dx} \frac{\partial f}{\partial y'} = \frac{d}{dx} \left(\frac{y'}{(1 + y'^2)^{\frac{1}{2}}} \right) = 0$$

$$\frac{y'}{(1 + y'^2)^{\frac{1}{2}}} = C$$

$$\frac{y'^2}{1 + y'^2} = C^2$$

$$y'^2 = \frac{C^2}{1 - C^2}$$

$\Rightarrow y'(x)$ is a constant, say m

Integrate:

$$\underline{y(x) = mx + b}$$

^{4.2}
Lagrangian mechanics
Several dependent variables:

Original integral eqⁿ is modified to:

$$J = \int_{x_1}^{x_2} f(y_1, y_1', y_2, y_2', \dots, y_n, y_n', x) dx$$

where each of y_n, y_n' depend on x .

\rightarrow leads to a set of E.L. eqⁿ

$$\frac{\partial f}{\partial y_i} - \frac{d}{dx} \left(\frac{\partial f}{\partial y_i'} \right) = 0 \quad i = 1, 2, 3, \dots, n$$

Several independent variables

\hookrightarrow dependency on x, y, z ,
rather than just x for
 n independent variables

$$J = \iint \dots \int f \left(y, \frac{\partial y}{\partial x_1}, \frac{\partial y}{\partial x_2}, \dots, \frac{\partial y}{\partial x_n}, x_1, x_2, \dots, x_n \right)$$

$$\frac{\partial f}{\partial y} = \sum_{i=1}^n \frac{\partial}{\partial x_i} \left(\frac{\partial f}{\partial y_{x_i}} \right) \quad dx_1, dx_2, \dots, dx_n$$

where $y_{x_i} = \frac{\partial y}{\partial x_i}$

\therefore for 3-D, we have $u(x, y, z)$

$$\frac{\partial f}{\partial u} - \frac{\partial}{\partial x} \frac{\partial f}{\partial u_x} - \frac{\partial}{\partial y} \frac{\partial f}{\partial u_y} - \frac{\partial}{\partial z} \frac{\partial f}{\partial u_z} = 0$$

\hookrightarrow generalize further to more than 1 dependent
& more than one independent variable:

Eg.

$$f = f(p(x, y, z), p_x, p_y, p_z, q(x, y, z), q_x, q_y, q_z, x, y, z)$$

We then have:

$$\frac{\partial f}{\partial p} - \frac{\partial}{\partial x} \frac{\partial f}{\partial p_x} - \frac{\partial}{\partial y} \frac{\partial f}{\partial p_y} - \frac{\partial}{\partial z} \frac{\partial f}{\partial p_z} = 0$$

& similarly for q & r .

The Lagrangian is defined to be the difference between the K.E.s & P.E.s

$$L \equiv T - V$$

The physical system is defined in terms of

- coordinates $x_i(t)$
- velocity $\dot{x}_i(t) = \frac{dx_i}{dt}$

for a particle i as a function of time (t) .

Hamilton's principle states that in moving from one configuration @ time t_1 to another @ t_2 , the motion of such a system is such to make

$$\mathcal{L} = \int_{t_1}^{t_2} L(x_1, x_2, \dots, x_n, \dot{x}_1, \dot{x}_2, \dots, \dot{x}_n, t) dt$$

E.L. eqn: $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) - \frac{\partial L}{\partial x_i} = 0$

Application: A moving particle & Newton's 2nd Law

Lagrangian: $L = T - V$

moving particle has $T = \frac{1}{2} m \dot{x}^2$ \rightarrow no x dependence
P.E., $V(x)$ as usual, the force is given by the -ve gradient of the potential

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}} - \frac{\partial L}{\partial x} = 0 \quad P.E. = -\frac{dV(x)}{dx}$$

$$\frac{d}{dt} (m\dot{x}) - \frac{\partial}{\partial x} (T - V) = 0$$

$$m\ddot{x} - F(x) = 0$$

$F = ma \Rightarrow$ Newton's 2nd Law

Hamiltonian Mechanics

Hamiltonian formulation describes a system in terms of generalized coordinates (q_i)

- generalized momentum (p_i)

$$L = L(q, \dot{q}) \quad - L \text{ w/ spatial \& velocity parts}$$

$$\hookrightarrow dL = \sum_i \frac{\partial L}{\partial q_i} dq_i + \sum_i \frac{\partial L}{\partial \dot{q}_i} d\dot{q}_i$$

Defining generating momentum

$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

from E.L

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = \frac{\partial L}{\partial q_i}$$

$$\frac{d}{dt} p_i = \frac{\partial L}{\partial q_i}$$

$$\dot{p}_i = \frac{\partial L}{\partial q_i}$$

$$\hookrightarrow \therefore dL = \sum_i \dot{p}_i dq_i + \sum_i p_i d\dot{q}_i$$

Note that

$$d(p_i \dot{q}_i) = \underbrace{\sum_i \dot{q}_i dp_i}_{\rightarrow} + \sum_i p_i d\dot{q}_i$$

$$\Rightarrow dL = \sum_i \dot{p}_i dq_i + d(p_i \dot{q}_i) - \sum_i \dot{q}_i dp_i$$

Rearranging:

$$d(p_i \dot{q}_i - L) = -\sum_i \dot{p}_i dq_i + \sum_i \dot{q}_i dp_i$$

Hamiltonian, defined as:

$$H = \sum_i p_i \dot{q}_i - L$$

$$dH = -\sum_i \dot{p}_i dq_i + \sum_i \dot{q}_i dp_i$$

~~Hamiltonian~~

$$H = \sum_i p_i \dot{q}_i - L$$

$$dH = -\sum_i \dot{p}_i dq_i + \sum_i \dot{q}_i dp_i$$

$$dH = \sum_i \frac{\partial H}{\partial q_i} dq_i + \sum_i \frac{\partial H}{\partial p_i} dp_i$$

$$\Rightarrow -\dot{p}_i = \frac{\partial H}{\partial q_i} dq_i \quad \& \quad \dot{q}_i = \frac{\partial H}{\partial p_i}$$

Also $\frac{\partial H}{\partial t} = -\frac{\partial L}{\partial t}$ Hamilton's eqⁿ of motion

We can also write H in terms of the KE & PE

$$T = \sum_i \frac{1}{2} p_i \dot{q}_i$$

$$H = \sum_i p_i \dot{q}_i - L$$

$$= \sum_i p_i \dot{q}_i - (T - V)$$

$$= \sum_i p_i \dot{q}_i - \frac{1}{2} \sum_i p_i \dot{q}_i + V$$

$$= \frac{1}{2} \sum_i p_i \dot{q}_i + V = T + V$$

$$H = T + V$$

Example w/ the Harmonic Oscillator

is a mass oscillating back & forth in 1-D on a spring

$$KE = T = \frac{1}{2} m v^2 = \frac{1}{2} m \dot{x}^2$$

$$P.E. = V = \frac{1}{2} k x^2 \quad | \quad k \text{ is the spring constant}$$

$$L = T - V$$

$$= \frac{1}{2} m \dot{x}^2 - \frac{1}{2} k x^2$$

Using the E.L. Lagrangian eqⁿ

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) - \frac{\partial L}{\partial x} = 0$$

$$\frac{d}{dt} (m \dot{x}) - kx = 0$$

$$m \ddot{x} + kx = 0$$

$$\ddot{x} = -\frac{k}{m} x \quad \left| \quad \omega = \sqrt{\frac{k}{m}} \right.$$

$$= -\omega^2 x$$

Or using the Hamiltonian

$$H = \frac{p^2}{2m} + \frac{1}{2} k x^2$$

using Hamilton's eqⁿ of motion

$$\dot{q}_i = \frac{\partial H}{\partial p_i} \Rightarrow \dot{x} = \frac{p}{m}$$

$$\frac{dx}{dt} = \frac{p}{m} \quad - (1)$$

$$-\dot{p}_i = \frac{\partial H}{\partial q_i} \Rightarrow -\dot{p} = \frac{\partial H}{\partial x} = kx$$

$$\dot{p} = -kx \quad - (2)$$

Combining (1) & (2)

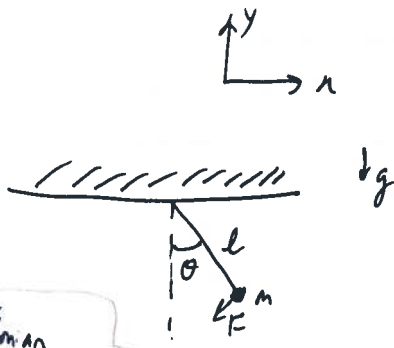
$$\dot{x} = \frac{p}{m} = -\frac{kx}{m}$$

$$\ddot{x} = -\frac{k}{m} x \quad \omega = \sqrt{\frac{k}{m}}$$

$$= -\omega^2 x$$

4.4 Extra Examples:

Eg. 1. Simple Pendulum



Newtonian

$$ma = -mg \sin \theta$$

$$a = -g \sin \theta$$

The displacement from the vertical is an arc length s , & so the acceleration is \ddot{s}

$$\ddot{s} = -g \sin \theta$$

BUT $s = l\theta$

$$\ddot{s} = l\ddot{\theta}$$

$$\Rightarrow l\ddot{\theta} = -g \sin \theta$$

$$\ddot{\theta} = -\frac{g}{l} \sin \theta$$

Hamiltonian Approach

$$H = T + V$$

$$p = \frac{\partial L}{\partial \dot{\theta}} = ml^2 \dot{\theta} \Rightarrow \dot{\theta} = \frac{p}{ml^2}$$

$$\dot{\theta} = \frac{p}{ml^2} \quad \text{--- (A)}$$

$$H = \frac{1}{2} ml^2 \dot{\theta}^2 + mgl(1 - \cos \theta)$$

$$= \frac{1}{2} ml^2 \frac{p^2}{m^2 l^4} + mgl(1 - \cos \theta)$$

$$= \frac{1}{2} \frac{p^2}{ml^2} + mgl(1 - \cos \theta)$$

Lagrangian approach:

Position $x = l \sin \theta$, $y = -l \cos \theta$

Velocity $\dot{x} = l \dot{\theta} \cos \theta$, $\dot{y} = l \dot{\theta} \sin \theta$

$$T = \frac{1}{2} m(\dot{x}^2 + \dot{y}^2)$$

$$= \frac{1}{2} ml^2 \dot{\theta}^2$$

→ Defining the potential energy: gravitational P.E., 0 when $\theta = 0$

$$V = mgl(1 - \cos \theta)$$

The Lagrangian:

$$L = T - V$$

$$= \frac{1}{2} ml^2 \dot{\theta}^2 - mgl(1 - \cos \theta)$$

$$\frac{\partial L}{\partial \theta} = -mgl \sin \theta \quad ; \quad \frac{\partial L}{\partial \dot{\theta}} = ml^2 \dot{\theta}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = ml^2 \ddot{\theta}$$

Using E.L.

$$\Rightarrow ml^2 \ddot{\theta} + mgl \sin \theta = 0$$

$$\ddot{\theta} + \frac{g}{l} \sin \theta = 0$$

$$-p = \frac{\partial H}{\partial \theta} = mgl \sin \theta$$

$$p = -mgl \sin \theta \quad \text{--- (B)}$$

Combining (A) & (B)

$$\dot{\theta} = \frac{p}{ml^2} = \frac{-mgl \sin \theta}{ml^2}$$

$$\ddot{\theta} = -\frac{g}{l} \sin \theta$$

SAME
RESULT

Ex 2 : Soap film

Consider a surface of revolution generated by revolving a curve $y(x)$ about a axis.
The curve passes through fixed end pts (n_1, y_1) & (n_2, y_2) .

Find the curve such that the area of the surface is minimum.

let the curve be $y(x)$ $x_i(t_i), y_i(t_i) \quad i=1,2$
 $x_1(t_1)$

$$dS_x = 2\pi y(x) ds$$

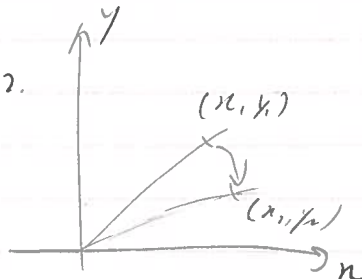
$$ds = \sqrt{(dx)^2 + (dy)^2}$$

$$ds = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

$$dS_x = 2\pi y(x) \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

$$S_x = 2\pi \int_{x_1, y_1}^{x_2, y_2} y(x) \sqrt{1 + y'^2} dx$$

$$\begin{aligned} x &\in [x(t_1), x(t_2)] \\ y &\in [y(t_1), y(t_2)] \\ t &\in [t_1, t_2] \end{aligned}$$



$$\delta S_x = 0$$

$$f = f(y, y', x) = y \sqrt{1 + y'^2}$$

$$E.L. \quad \frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0$$

$$\frac{d}{dx} \left[f - y' \frac{\partial f}{\partial y'} \right] = 0$$

$$\frac{\partial f}{\partial y} = \sqrt{1 + y'^2}$$

$$y \sqrt{1 + y'^2} - y' \frac{y y'}{\sqrt{1 + y'^2}} = a$$

$$\frac{\partial f}{\partial y'} = \frac{\partial}{\partial y'} \left(y(x) (1 + y'^2)^{\frac{1}{2}} \right)$$

$$y(1 + y'^2 - y'^2) = a \sqrt{1 + y'^2}$$

$$\frac{y^2}{a^2} = 1 + y'^2$$

$$y'^2 = \frac{y^2}{a^2} - 1$$

$$y' = \sqrt{\frac{y^2 - a^2}{a^2}}$$

$$\int \frac{dx}{dy} = \int \frac{a dy}{y^2 - a^2} dy$$

$$\sqrt{1 + y'^2} - \frac{d}{dx} \left[\frac{y y'}{\sqrt{1 + y'^2}} \right] = 0$$

$$x = a \operatorname{arccosh} \left(\frac{y}{a} \right) + C$$

$$\frac{d}{dx} \left(\frac{y y'}{\sqrt{1 + y'^2}} \right) = \sqrt{1 + y'^2}$$

$$\frac{x - C}{a} = \operatorname{arccosh} \frac{y}{a}$$

$$y = a \cosh \left(\frac{x - C}{a} \right)$$

and C can be determined by:
 $y_1 = a \cosh \left(\frac{x_1 - C}{a} \right)$

$$y_2 = a \cosh \left(\frac{x_2 - C}{a} \right)$$

→ can't be solved analytically

$$y = x^p$$

$$y' = p x^{p-1}$$

$$y' = p(p-1)x^{p-2}$$

$$y = \frac{1}{x}$$

$$y' = -\frac{1}{x^2}$$

$$y'' = \frac{2}{x^3}$$

$$y = \ln x$$

$$y = \ln(x+1)$$

$$y' = \frac{1}{x+1}$$

$$y'' = -\frac{1}{(x+1)^2}$$

$$\int_0^1 \left(\frac{c_1}{1+n} \right)^2 (1+n) \, dn$$

Fourier Series

Orthogonality of sine & cosine

Period of $2L$, $L = \pi$

Consider:

$$\cos(n\pi), \sin(n\pi) \quad n \in \mathbb{N}$$

$$f(x) \cdot g(x) = \int_{-\pi}^{\pi} f(x) g(x) dx$$

$$\sin(\alpha) \sin(\beta) = \frac{1}{2} [\cos(\alpha - \beta) - \cos(\alpha + \beta)] \quad \text{--- ①}$$

$$\cos(\alpha) \cos(\beta) = \frac{1}{2} [\cos(\alpha - \beta) + \cos(\alpha + \beta)] \quad \text{--- ②}$$

$$\sin(\alpha) \cos(\beta) = \frac{1}{2} [\sin(\alpha - \beta) + \sin(\alpha + \beta)] \quad \text{--- ③}$$

Evaluating the scalar product between two functions

using ① $m \neq n$

$$\begin{aligned} \int_{-\pi}^{\pi} \sin(mx) \sin(nx) dx &= \frac{1}{2} \int_{-\pi}^{\pi} [\cos(m-n)x - \cos(m+n)x] dx \\ &= \frac{1}{2} \left[\frac{\sin(m-n)x}{m-n} - \frac{\sin(m+n)x}{m+n} \right]_{-\pi}^{\pi} = 0 \end{aligned}$$

for $m = n$

$$\begin{aligned} \Rightarrow \frac{1}{2} \int_{-\pi}^{\pi} [1 - \cos(2nx)] dx \\ = \frac{1}{2} \left[x - \frac{\sin(2nx)}{2n} \right]_{-\pi}^{\pi} \\ = \frac{1}{2} 2\pi \\ = \pi \end{aligned}$$

for \cos i.e. $(n=m=0)$

$$\int_{-\pi}^{\pi} \cos^2(nx) dx = \int_{-\pi}^{\pi} dx = 2\pi$$

$$\int_{-\pi}^{\pi} \sin(mx) \sin(nx) dx = \pi \delta_{mn} \quad \text{for } \max(m, n) > 0$$

$$\int_{-\pi}^{\pi} \sin(mx) \sin(nx) dx = 0 \quad m = n = 0$$

$$\int_{-\pi}^{\pi} \cos(mx) \cos(nx) dx = \pi \delta_{mn} \quad \text{for } \max(m, n) > 0$$

$$\int_{-\pi}^{\pi} \cos(mx) \cos(nx) dx = 2\pi \quad \text{for } m = n = 0$$

$$\int_{-\pi}^{\pi} \sin(mx) \cos(nx) dx = 0$$

↑
Orthogonality of the
set of periodic functions
 $\sin(nx)$ and $\cos(nx)$

Fourier series expansion (period 2π)

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [a_n \cos(nx) + b_n \sin(nx)]$$

with coefficients:

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \cos(nx) f(x) dx$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \sin(nx) f(x) dx$$

Multiply definition of $a_n \times \frac{1}{\pi} \cos(mx)$

\Rightarrow integrate both sides $-\pi \rightarrow +\pi$

$$\begin{aligned} \frac{1}{\pi} \int_{-\pi}^{\pi} \cos(mx) f(x) dx &= \frac{1}{\pi} \int_{-\pi}^{\pi} \cos(mx) \frac{a_0}{2} dx \\ &+ \frac{1}{\pi} \sum_{n=1}^{\infty} \left[\int_{-\pi}^{\pi} a_n \cos(mx) \cos(nx) dx \right. \\ &\quad \left. + b_n \int_{-\pi}^{\pi} \cos(mx) \sin(nx) dx \right] \end{aligned}$$

$$\frac{1}{\pi} \int_{-\pi}^{\pi} \cos(mx) f(x) dx = \delta_{m0} a_0 + \sum_{n=1}^{\infty} \delta_{mn} a_n = a_m$$

$$\frac{1}{\pi} \int_{-\pi}^{\pi} \sin(mx) f(x) dx = b_m$$

\swarrow similar for def of b_n

General period, $2L$

$$x \rightarrow \frac{xL}{\pi}, \quad f\left(\frac{xL}{\pi}\right)$$

$$f\left(\frac{nxL}{\pi}\right) = f\left(\frac{nL}{2}\right)$$

$$f\left(\frac{xL}{\pi}\right) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [a_n \cos(nx) + b_n \sin(nx)]$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \cos(nx) f(x) dx$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} \sin(nx) f\left(\frac{xL}{\pi}\right) dx$$

multiply n by $\frac{\pi}{L}$

\rightarrow definition of Fourier series w/ period $2L$

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos\left(n \frac{\pi}{L} x\right) + b_n \sin\left(n \frac{\pi}{L} x\right) \right]$$

$$a_n = \frac{1}{L} \int_{-L}^L \cos\left(n \frac{\pi}{L} x\right) f(x) dx$$

$$b_n = \frac{1}{L} \int_{-L}^L \sin\left(n \frac{\pi}{L} x\right) f(x) dx$$

Scalar product $\int_{-L}^L f(x) g(x) dx$

w/ orthogonality set $\sin\left(n \frac{\pi}{L} x\right)$
 $\cos\left(n \frac{\pi}{L} x\right)$

Writing again the orthogonality relationships:

$$\int_{-L}^L \sin\left(m \frac{\pi}{L} x\right) \sin\left(n \frac{\pi}{L} x\right) dx = L \delta_{mn} \quad m, n > 0$$

$$\int_{-L}^L \sin\left(m \frac{\pi}{L} x\right) \sin\left(n \frac{\pi}{L} x\right) dx = 0 \quad m \neq n > 0$$

$$\int_{-L}^L \cos\left(m \frac{\pi}{L} x\right) \cos\left(n \frac{\pi}{L} x\right) dx = L \delta_{mn} \quad m, n > 0$$

$$\int_{-L}^L \cos\left(m \frac{\pi}{L} x\right) \cos\left(n \frac{\pi}{L} x\right) dx = 2L \quad m = n = 0$$

$$\int_{-L}^L \sin\left(m \frac{\pi}{L} x\right) \cos\left(n \frac{\pi}{L} x\right) dx = 0$$

even function $f(x) = f(-x)$ } b_n vanish
 \therefore they would multiply sines

odd function $f(x) = -f(-x)$ } a_n vanish
 \therefore they would multiply cosines

Parseval's Identity

$$\underline{u} = u_1 \underline{i} + u_2 \underline{j} \quad \underline{i} \cdot \underline{i} = 1$$

$$|\underline{u}|^2 = u_1^2 + u_2^2 \quad \begin{array}{l} \underline{j} \cdot \underline{j} = 0 \\ \underline{j} \cdot \underline{i} = 0 \end{array}$$

Parseval's Identity will be analogous to the above case

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos\left(\frac{n\pi}{L}x\right) + b_n \sin\left(\frac{n\pi}{L}x\right) \right]$$

$$\Rightarrow \frac{1}{2L} \int_{-L}^L [f(x)]^2 dx = \left(\frac{a_0}{2}\right)^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

Proof

$$= \frac{1}{2L} \int_{-L}^L \left(\frac{a_0}{2} + \sum_{m=1}^{\infty} \left[a_m \cos\left(\frac{m\pi}{L}x\right) + b_m \sin\left(\frac{m\pi}{L}x\right) \right] \right) \left(\frac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos\left(\frac{n\pi}{L}x\right) + b_n \sin\left(\frac{n\pi}{L}x\right) \right] \right) dx$$

↓ using orthogonality relationships.

$$= \left(\frac{a_0}{2}\right)^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

(see extra notes)

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[a_n \cos\left(\frac{n\pi}{L}x\right) + b_n \sin\left(\frac{n\pi}{L}x\right) \right]$$

$$\langle f(x) \rangle = \frac{1}{2L} \int_{-L}^L [f(x)]^2 dx$$

$$= \left(\frac{a_0}{2}\right)^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

Complex Fourier series

using Euler's Formula:

$$\cos(x) = \frac{e^{ix} + e^{-ix}}{2}$$

$$\sin(x) = \frac{e^{ix} - e^{-ix}}{2}$$

$$c_n := \frac{(a_n - ib_n)}{2}$$

Complex Fourier Series

$$f(x) = \sum_{n=-\infty}^{+\infty} c_n e^{i\frac{n\pi}{L}x}$$

with c_n given by:

$$c_n = \frac{1}{2L} \int_{-L}^L e^{-i\frac{n\pi}{L}x} f(x) dx$$

$$f(x) \cdot g(x) = \int_{-L}^L f^*(x) g(x) dx$$

"Hilbert-Schmidt" scalar product

$$\int_{-L}^L e^{im\frac{\pi}{L}x} e^{in\frac{\pi}{L}x} dx = 2L \delta_{mn} \quad \text{orthogonality}$$

Parseval's Identity:

$$\frac{1}{2L} \int_{-L}^L |f(x)|^2 dx = \sum_{n=-\infty}^{+\infty} |c_n|^2$$

* forming orthonormal set for identical function
orthonormal / orthogonal set

(can be functions, vectors)

$$(x_i, x_j) = \delta_{ij} \rightarrow \text{orthogonal set}$$

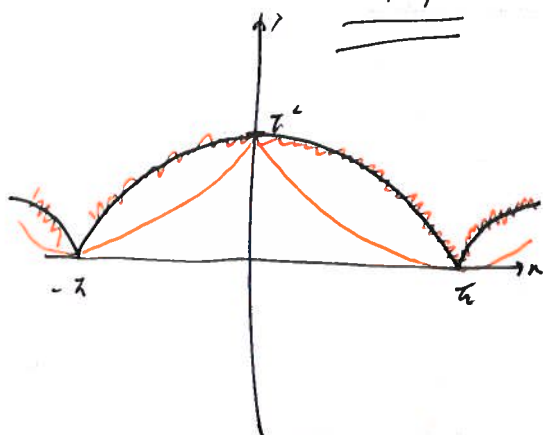
(orthonormal)

\Rightarrow always 1

$m=n \Rightarrow$ orthonormal

Sketching

$$-\pi < x < \pi, \quad f(x) = (|x| - \pi)^2$$



$$(|x| - \pi)^2 = \frac{\pi^2}{3} + 4 \sum_{n=1}^{\infty} \frac{\cos(nx)}{n^2}$$

2. Take $x=0$

$$\pi^2 = \frac{\pi^2}{3} + 4 \sum_{n=1}^{\infty} \frac{1}{n^2}$$

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$

2. Take $x=\pi$

$$0 = \frac{\pi^2}{3} + 4 \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2}$$

$$\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n^2} = + \frac{\pi^2}{12}$$

$\sum_{n=1}^{\infty} \frac{1}{n^2}$ Parseval's identity state that

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} [f(x)]^2 dx = \left(\frac{a_0}{2}\right)^2 + \frac{1}{2} \sum_{n=1}^{\infty} (a_n^2 + b_n^2)$$

$$\frac{1}{2\pi} \int_{-\pi}^0 (-x-\pi)^4 dx + \frac{1}{2\pi} \int_0^{\pi} (x-\pi)^4 dx$$

$$= \frac{1}{2\pi} \left[\frac{1}{5} (x+\pi)^5 \right]_{-\pi}^0 + \frac{1}{2\pi} \left[\frac{1}{5} (x-\pi)^5 \right]_0^{\pi}$$

$$= \frac{\pi^4}{5} \quad \text{Parseval's identity then gives}$$

$$\frac{\pi^4}{5} = \left(\frac{\pi^2}{3}\right)^2 + \frac{16}{2} \sum_{n=1}^{\infty} \frac{1}{n^4}$$

$$\sum_{n=1}^{\infty} \frac{1}{n^4} = \frac{\pi^4}{90}$$

Fourier Transforms

$$f(x) = \lim_{L \rightarrow \infty} \sum_{-\infty}^{\infty} c_n e^{i \frac{\pi}{L} n x}$$

inserting our expression for c_n

$$f(x) = \lim_{L \rightarrow \infty} \sum_{-\infty}^{\infty} \frac{1}{2L} \int_{-L}^L e^{-i \frac{\pi}{L} y} f(y) dy e^{i \frac{\pi}{L} n x}$$

$$= \frac{1}{2\pi} \lim_{L \rightarrow \infty} \sum_{-\infty}^{\infty} \frac{\pi}{L} \int_{-\infty}^{\infty} e^{i \frac{\pi}{L} (x-y)} f(y) dy$$

for any integrable function $g(k)$

$$\lim_{L \rightarrow \infty} \sum_{-\infty}^{\infty} \frac{\pi}{L} g\left(\frac{\pi}{L} k\right) = \int_{-\infty}^{\infty} g(k) dk$$

$$\therefore f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{ik(x-y)} f(y) dy dk$$

Assuming this is integrable

IF $\int_{-\infty}^{\infty} |f(y)|^2 dy$ is finite square integrable

Defining the Fourier transform $\tilde{f}(k)$ of $f(x)$

$$\tilde{f}(k) := \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

Any complex function $f(x)$ such that $\int_{-\infty}^{\infty} |f(x)|^2 dx$ is finite, can be expressed as:

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{ikx} \tilde{f}(k) dk$$

where Fourier transform $\tilde{f}(k)$ is defined as:

$$\tilde{f}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

eg. QM

$$\begin{cases} \Psi(x) \rightarrow \text{position} \\ \tilde{\Psi}(k) \rightarrow \text{momentum} \end{cases}$$

$$\begin{cases} \tilde{\Psi}(t) \rightarrow \text{time} \\ \tilde{\Psi}(\omega) \rightarrow \text{frequency} \end{cases}$$

Trickery, Lies & Deceit

→ variable when integrating over when taking a Fourier transform is a dummy variable
 $\int_{-\infty}^{\infty} f(x) dx \rightarrow$ keep diff integration variables distinct

$$\Psi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{ikx} \tilde{\Psi}(k) dk$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i2\pi z} \tilde{\Psi}(z) dz$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i(y-w)x} \tilde{\Psi}(y-w) d(y-w)$$

$$\tilde{\tilde{f}}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ikx} f(x) dx$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} (\cos(kx) - i \sin(kx)) f(x) dx$$

if $f(x)$ is odd $\Rightarrow f(x) = -f(-x)$ odd

$$\tilde{\tilde{f}}(k) = \frac{i}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \sin(kx) f(x) dx$$

if $f(x)$ is even $\Rightarrow f(x) = f(-x)$ even

$$\tilde{\tilde{f}}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \cos(kx) f(x) dx$$

differentiating:

$$f(n) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{ikn} \tilde{f}(k) dk$$

$$\text{if } f(n) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ikn} \tilde{f}(k) dk$$

$$\hookrightarrow f'(n) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} ik e^{ikn} \tilde{f}'(k) dk$$

$$\Rightarrow \tilde{f}'(k) = ik \tilde{f}(k)$$

Also: if $x \rightarrow x+a$

$$f(n+a) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{ika} e^{ikn} \tilde{f}(k) dk$$

\hookrightarrow F.T. of the shifted function $f(n+a)$ is given by $e^{ika} \tilde{f}(k)$ if $\tilde{f}(k)$ is the F.T. of $f(n)$

The Dirac Delta function

$$f(n) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{ik(n-y)} f(y) dy dk$$

$$= \int_{-\infty}^{\infty} \delta(n-y) f(y) dy$$

$$\delta(n-y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ik(n-y)} dk$$



\hookrightarrow picking the value when $x=y$ while integrating over whole of the axis

similar to the Kronecker delta:

$\delta_{mn} = 1$ if $m=n$ or 0 if $m \neq n$ \hookrightarrow discrete version of the Dirac Delta function

$$\delta(n-y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ik(n-y)} dk$$

\Rightarrow only really has defined meaning inside an integral

\hookrightarrow more of a distribution than a function

$$C_n = \sum_{m=-\infty}^{\infty} \delta_{mn} C_m$$

Parseval's Identity for F.T.

$$\int_{-\infty}^{\infty} |f(n)|^2 dn = \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk$$

$$f^*(n) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-ikn} \tilde{f}^*(k) dk$$

$$\int_{-\infty}^{\infty} |f(n)|^2 dn = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{ik(n-z)} \tilde{f}(k) \tilde{f}^*(z) dk dz dn$$

use Dirac Delta func

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \underbrace{\delta(k-z)}_{\text{if } k=z} \tilde{f}^*(z) \tilde{f}(k) dk dz$$

picking out the value if $z=k$

$$= \int_{-\infty}^{\infty} \tilde{f}^*(k) \tilde{f}(k) dk$$

$$= \int_{-\infty}^{\infty} |\tilde{f}(k)|^2 dk = \int_{-\infty}^{\infty} |f(n)|^2 dn$$

Convolution Theorem

when measuring a physical quantity: $f(x)$
 ↳ apparatus w/ resolution function $g(y)$

$$h(z) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dx f(x) g(z-x)$$

$h(z)$ will be what actually is measured

⇒ convolution of the signal w/

resolving power of the apparatus

★ and true value x is smeared
 by some resolution function g

ideally ⇒ $g(z-x) = \sqrt{2\pi} \delta(z-x)$
 so that $h(z) = f(z)$

$$h = f * g = f \otimes g$$

which says that:

eg. $FT[h] = FT[f] \times FT[g]$

Defining:

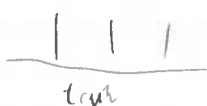
$$F(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{i\omega x} dx$$

$$G(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) e^{i\omega x} dx$$

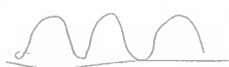
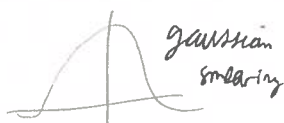
$$H(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} h(x) e^{i\omega x} dx$$

⇒ using $h = f * g$

$$H(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega x} dx \int_{-\infty}^{\infty} dz f(z) g(x-z)$$



evaluating a function



evaluating the smearing
 function around $|||$

FTL(2)

$$\Rightarrow H(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dz f(z) \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i\omega z} dx g(x-z)$$

★ z is held constant ⇒ $dx(z-z) = dx$

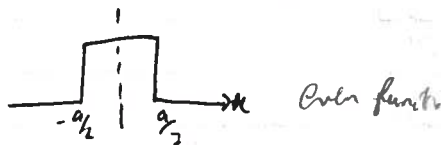
$$H(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} dz f(z) e^{i\omega z} G(\omega)$$

$$H(\omega) = F(\omega) G(\omega)$$

Examples:

Evaluate the FT of "Tophat" or box

$$f(x) = \begin{cases} 1 & |x| < a/2 \\ 0 & |x| > a/2 \end{cases}$$



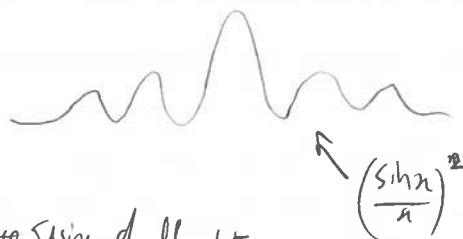
$$\hat{f}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{-ikx} dx$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) \cos(kx) dx$$

$$= \frac{1}{\sqrt{2\pi}} \int_{-a/2}^{a/2} \cos(kx) dx$$

$$= \frac{2 \sin(ak/2)}{\sqrt{2\pi} k} = \frac{4a}{\sqrt{2\pi}} \text{sinc}\left(\frac{ak}{2}\right)$$

1
 diffraction
 pattern
 $\frac{2 \sin(ak/2)}{ak/2}$



use using double slit

using convolution theorem

$$G(x) = \begin{cases} 1 & 0 \leq x \leq a \\ 0 & \text{otherwise} \end{cases}$$

$$G(x) = F(x \cdot \frac{1}{2})$$

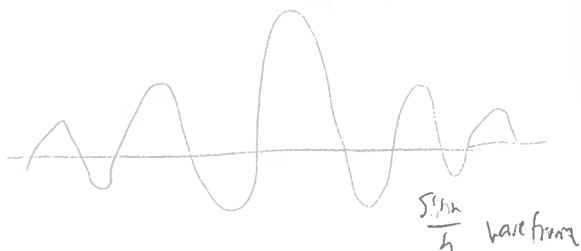
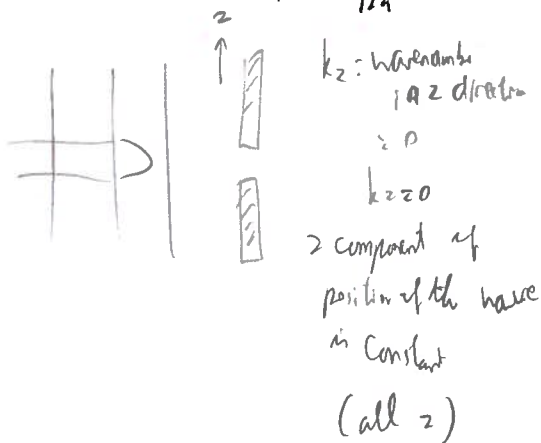
$$\tilde{G}(k) = e^{-\frac{ia k}{2}} \tilde{F}(k)$$

FT of the dirac delta

$$\tilde{f}(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \delta(x - x_0) e^{-ikx} dx$$

$$= \frac{1}{\sqrt{2\pi}} e^{-ikx_0} \quad \text{if } x = x_0$$

$$\text{if } k=0 \quad \tilde{f}(k) = \frac{1}{\sqrt{2\pi}}$$

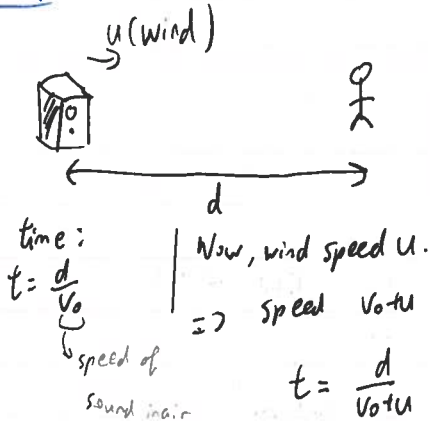


Special Relativity

"Absolute, true, & mathematical time of itself, & by its own true nature, flows uniformly on, w/o regard to anything external." ~ Newton's Principia

"Luminiferous aether" - how to detect?
↳ kind of "disproved" by Michelson-Morley

Example sound in air Expt.



frequency of sound $\propto f$

observer hears f

$$\lambda = \frac{\text{speed}}{\text{freq}}$$

$$= \frac{v_0 + u}{f} \quad (u \rightarrow \text{speaker to observer})$$

$$\lambda = \frac{v_0 - u}{f} \quad (u \leftarrow \text{observer})$$

number of wave lengths fitting into the distance d is

$$\frac{d}{\lambda} = \frac{fd}{v_0 + u}$$

$$\frac{d}{\lambda} = \frac{fd}{v_0 - u}$$

"There are observers for whom all isolated bodies move w/ a uniform velocity"

\Rightarrow Inertial observers

An inertial coordinate system

↳ a system of coordinates such that all isolated bodies move w/ uniform velocity in the coordinate

Einstein's Postulates:

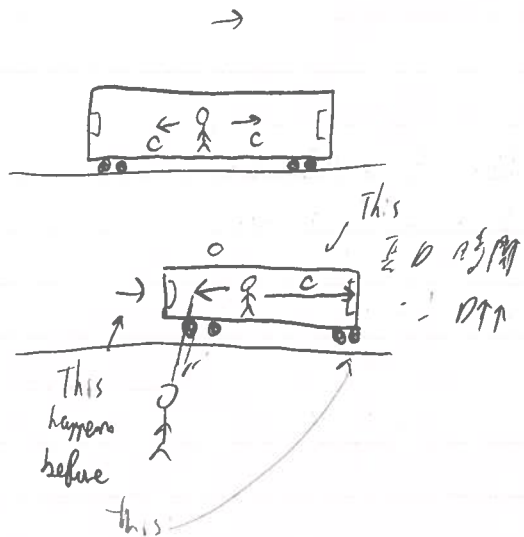
1. The laws of physics have the same form in all inertial systems

↳ from Maxwell's eq's

2. The velocity of light in empty space is a universal constant, the same for all observers.

implies

The relativity of simultaneity



Events & Transformations

Event

$S \Rightarrow (t, x, y, z)$
 $S' \Rightarrow (t', x', y', z')$

relationship of S & S' ??
 i.e. relationship between frames

$$S \rightarrow S'$$

$$t, x, y, z \rightarrow t', x', y', z'$$

The Galilean Transform

S, S'

S' moves w/ velocity v w.r.t. S ,
 along the z direction

Set them up so that:

$$\begin{aligned}
 &\text{Clock in } S: t=0 \\
 &\text{Clock in } S': t'=0
 \end{aligned}
 \left. \begin{array}{l} \text{origins:} \\ x, y, z=0 \\ x', y', z'=0 \end{array} \right\}$$

Event in $S (t, x, y, z)$

Same event $S' (t', x', y', z')$

After time t : the origin of S'
 is at $z=vt$ in frame S .

$$t'=t$$

$$x'=x$$

$$y'=y$$

$$z'=z-vt$$

Galilean

Transformation

$$\Rightarrow \begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -v & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

$$z'=z-vt$$

Lorentz Transformation

$$\begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\frac{\gamma v}{c^2} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma v & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

$$\gamma \equiv \frac{1}{\sqrt{1-v^2/c^2}} \quad \beta \equiv \frac{v}{c}$$

$$t' = \frac{t - v z / c^2}{\sqrt{1 - v^2/c^2}}$$

$$x' = x$$

$$y' = y$$

$$z' = \frac{z - vt}{\sqrt{1 - v^2/c^2}}$$

Derivation:

$x=y=z=0, t=0 \Rightarrow S$ } light emitted
 $x'=y'=z'=0, t'=0 \Rightarrow S'$

Arrives @ z_0 on z axis in S

$$S: t = \frac{z_0}{c} \quad \left(\frac{z_0}{c}, 0, 0, z_0 \right)$$

using Galilean Transformation:

$$S': \left(\frac{z_0}{c}, 0, 0, z_0 - vt \right)$$

$$\text{Speed: } \frac{z_0 - vt}{z_0/c} = c - v \left(\frac{c}{z_0} \right)$$

$z_0 = ct$

$$= c - v$$

Contradiction
 Einstein's postulate

$$(t', x', y', z') \Leftrightarrow (t, x, y, z)$$

$S' \qquad S$

$$z' = Ct + Dz + \dots$$

$$t' = At + Bz$$

$$\Rightarrow \begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} A & 0 & 0 & B \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ C & 0 & 0 & D \end{pmatrix} \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

Finding A, B, C, D

1. Event at origin of S' ($z'=0$)

z, t are given by

$$\frac{z}{t} = v$$

$$0 = z' = ct = vt \Rightarrow c = -v \checkmark$$

2. S' sees origin of S move w/ $-v$ along z axis

$$\Rightarrow \frac{z'}{t'} = -v \quad z' = ct + D \Big|_{z=0}$$

$$\Rightarrow \frac{z'}{t'} = \frac{ct}{At} \Rightarrow \frac{c}{A} = -v \quad \& \quad c = -v$$

$$\therefore A = D$$

3. Light pulse emitted at $t: t'=0$ from the origin

Event when the pulse arrives @ z, t (in S)

z', t' (in S')

$$\frac{z'}{t'} = c = \frac{z}{t} = \frac{ct + D}{At + B}$$

$$= \frac{c + Dc}{A + Bc}$$

$$\textcircled{c = -v} \Rightarrow c = \frac{-v + Dc}{D + Bc} = \frac{c - v}{1 + \frac{v}{c} \frac{B}{D}}$$

solving for B/D ; then,

$$B = -\frac{v}{c^2} D \quad \text{finding } D \text{ then}$$

4. Light pulse emitted @ $t=t'=0$ along y axis

y on y -axis $\Rightarrow z=0$

$$z' = ct, \quad y' = y, \quad t' = At$$

Distance traveled by the pulse in S' is:

$$= \sqrt{(z')^2 + (y')^2} \quad \frac{y'}{t'} = c$$

$$\Rightarrow \frac{(z')^2 + (y')^2}{(t')^2} = c^2 = \frac{c^2 t^2 + y^2}{A^2 t^2} = \left(\frac{c}{A}\right)^2 \left(\frac{c^2}{A}\right)$$

$$\Rightarrow c = -v, \quad A = D$$

$$\Rightarrow c^2 = v^2 + \frac{c^2}{D^2}$$

$$D = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$A = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$B = \frac{-v/c^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$C = \frac{-v}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$t' = \frac{t - \frac{vz}{c^2}}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$x' = x$$

$$y' = y$$

$$z' = \frac{z - vt}{\sqrt{1 - \frac{v^2}{c^2}}}$$

lorentz

transformation

Invariance of the velocity of light



$$S: c^2 t^2 = x^2 + y^2 + z^2$$

$$c^2 t'^2 - x'^2 - y'^2 - z'^2 = 0$$

Sphere of light:

∴ c is spreading
in all directions

$$S': 0 = c^2 (t')^2 - (x')^2 - (y')^2 - (z')^2$$

showing
 $S = S'$

using
Lorentz transform:

$$c^2 (t')^2 - (x')^2 - (y')^2 - (z')^2 = \gamma^2 c^2 \left(t^2 - \frac{v^2 z^2}{c^2} + \frac{v^2 z^2}{c^2} \right) - \gamma^2 (z^2 - 2zv + vt^2) - y^2 - x^2$$

$$\Rightarrow \gamma^2 (c^2 t^2 - z^2 + \frac{v^2}{c^2} (z^2 - c^2 t^2)) - y^2 - x^2$$

$$= \gamma^2 (c^2 t^2 - z^2) \left(1 - \frac{v^2}{c^2} \right) - y^2 - x^2$$

$$= c^2 t^2 - z^2 - y^2 - x^2$$

∴ invariant

↳ 1x3D vector
long 0 length
invariant w/
rotations/translations

Four-vectors

$\begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$ Four vectors are objects
w/ transform according
to the Lorentz transformation
when boosted between inertial

4D not 3D

↳ -ve sign in scalar products

Metric $G = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

$$(V \cdot W) = V^T G W$$

$$(V_0 \ V_1 \ V_2 \ V_3) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} W_0 \\ W_1 \\ W_2 \\ W_3 \end{pmatrix}$$

$$= V_0 W_0 - V_1 W_1 - V_2 W_2 - V_3 W_3$$

We are in Claussim space

Metric \Rightarrow encoding the structure
of spacetime in the metric
↳ distinguishing the
timeline coordinates
from the 3 spatial
coordinates

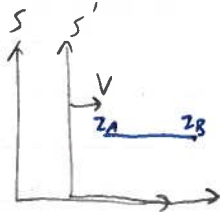
$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \text{4 vector specifying an event}$$

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

symmetric

Length Contraction

having a stick of length L_0 in rest frame
@ rest in S'



$$\begin{pmatrix} ct \\ 0 \\ 0 \\ z_A \end{pmatrix}, \begin{pmatrix} ct \\ 0 \\ 0 \\ z_B \end{pmatrix} \quad \text{in frame } S$$

$$\begin{pmatrix} ct'_A \\ 0 \\ 0 \\ z'_A \end{pmatrix}, \begin{pmatrix} ct'_B \\ 0 \\ 0 \\ z'_B \end{pmatrix} \quad \text{in frame } S'$$

going from one frame to another:

$$\begin{pmatrix} ct'_A \\ 0 \\ 0 \\ z'_A \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} ct \\ 0 \\ 0 \\ z_A \end{pmatrix}$$

$$\Rightarrow z'_A = -\frac{\gamma v}{c} ct + \gamma z_A$$

$$= -\gamma vt + \gamma z_A = \gamma(z_A - vt)$$

Similarly for B:

$$\Rightarrow z'_B = -\gamma(z_B - vt)$$

$$L_0 = z'_B - z'_A = \gamma(z_B - z_A)$$

$$L_0 = \gamma L$$

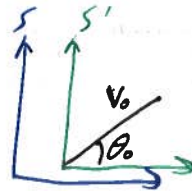
$$L = L_0 \sqrt{1 - \frac{v^2}{c^2}}$$

rest length

length in moving
frame is
smaller

$L =$ length contraction

Orientation of stick



- considering the positions of the
ends of the stick in S'

$$y'_A = 0, z'_A = 0$$

$$y'_B = L_0 \sin \theta_0; z'_B = L_0 \cos \theta_0$$

$$\begin{pmatrix} ct'_A \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ y_A \\ z_A \end{pmatrix}$$

AND

$$\begin{pmatrix} ct'_B \\ 0 \\ L_0 \sin \theta_0 \\ L_0 \cos \theta_0 \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ y_B \\ z_B \end{pmatrix}$$

$$z_A = 0; y_A = 0$$

$$z'_B = L_0 \cos \theta_0 = \gamma z_B$$

$$y'_B = L_0 \sin \theta_0 = y_B$$

$$L^2 = (z_B^2 + y_B^2) = L_0^2 \cos^2 \theta_0 (1 - \frac{v^2}{c^2}) +$$

$$z_A = 0 \quad z_B' = L_0 \cos \theta_0 = \gamma z_0$$

$$y_A = 0 \quad y_B' = L_0 \sin \theta_0 = y_0$$

$$L = (z_0^2 + y_0^2)^{\frac{1}{2}} = [L_0^2 \cos^2 \theta_0 (1 - \frac{v^2}{c^2}) + L_0^2 \sin^2 \theta_0]^{\frac{1}{2}}$$

$$= L_0 [1 - \frac{v^2}{c^2} \cos^2 \theta_0]^{\frac{1}{2}}$$

measuring the hypotenuse:

$$\theta = \tan^{-1} \left(\frac{y_B}{z_0} \right) \quad \parallel \quad \tan \theta_0 = \frac{y_B'}{z_B'}$$

$$\theta = \tan^{-1} (\gamma \tan \theta_0)$$

$$= \tan^{-1} \left(\frac{\gamma y_B'}{z_B'} \right)$$

Time dilation

- helpful to have

$$S = \gamma$$

S in terms of S' , rather than the other way around.
i.e. \Rightarrow inverse eqn

S moves at $-v$ relative to S'

\therefore the transformation factor will just be the same, but with v switching signs

Inverse Lorentz transformation:

$$\begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & \frac{\gamma v}{c} \\ 0 & \gamma & 0 & 0 \\ 0 & 0 & \gamma & 0 \\ \frac{\gamma v}{c} & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix}$$

- clocks occur at: t_A' & t_B' [everything @ origin]

$$ct_A = \gamma ct_A'$$

$$ct_B = \gamma ct_B'$$

$$\Delta t = t_B - t_A = \gamma (t_B' - t_A')$$

$$\Delta t = \frac{\Delta t'}{\sqrt{1 - \frac{v^2}{c^2}}} \quad \gamma > 1$$

$$\Delta t > \Delta t'$$

Relativity of simultaneity

\Rightarrow quantifying the question of simultaneity

$$\begin{pmatrix} ct_A \\ x_A \\ y_A \\ z_A \end{pmatrix} \propto \begin{pmatrix} ct_B \\ x_B \\ y_B \\ z_B \end{pmatrix} \quad \Rightarrow \text{specified in } S$$

$$\begin{pmatrix} ct_A' \\ x_A' \\ y_A' \\ z_A' \end{pmatrix} \propto \begin{pmatrix} ct_B' \\ x_B' \\ y_B' \\ z_B' \end{pmatrix} \quad \Rightarrow \text{same events specified in } S'$$

$$t_B - t_A \parallel ct_B - ct_A = \gamma (ct_B' - ct_A' + (z_B' - z_A') \frac{v}{c})$$

suppose:

events are simultaneous

in frame $S \Rightarrow t_B - t_A = 0$

$$t'_B - t'_A = -\frac{(z'_B - z'_A)v}{c^2}$$

$$\gamma(ct'_B - ct'_A + (z'_B - z'_A)\frac{v}{c}) = 0$$

$$(t'_B - t'_A)c = -\frac{(z'_B - z'_A)v}{c}$$

$$t'_B - t'_A = -\frac{(z'_B - z'_A)v}{c^2}$$

if $t_B - t_A = 0$ i.e. events are simultaneous in S

⇒ they are only

simultaneous in S' if $z'_B = z'_A$

$$\begin{pmatrix} ct_A \\ x_A \\ y_A \\ z_A \end{pmatrix} - \begin{pmatrix} ct_B \\ x_B \\ y_B \\ z_B \end{pmatrix} = \begin{pmatrix} c\Delta t \\ \Delta x \\ \Delta y \\ \Delta z \end{pmatrix} = q$$

also a 4-vector

→ magnitude of 4-vector is invariant under Lorentz transformation

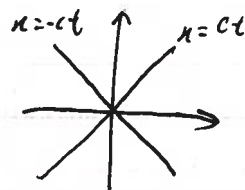
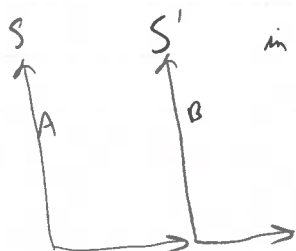
$$q^2 = c^2(\Delta t)^2 - (\Delta x)^2 - (\Delta y)^2 - (\Delta z)^2$$

- squared separation in space between

$$A, B \text{ is } S^2 = (\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2$$

$$\Rightarrow q^2 = (c\Delta t)^2 - S^2$$

distance between events
light can travel in Δt



if $q^2 > 0$:

$$S^2 < (c\Delta t)^2$$

- distance between events < light travelled in Δt between events

↳ particle can travel from one event to another less than c
 ↳ one event can plausibly cause another

or: can find ~~first~~ on inertial frame at both events happening @ the same time

→ in that frame, distance will be zero

→ inertial frame can move from A to B

or: can find an inertial system that both events occur at the same position but @ diff times

* A can cause B

* A always happens before B

* There is a frame where A happens before B @ the same pt in space

if $q^2 = 0$: $S^2 = (c\Delta t)^2$

⇒ only light can move between events

⇒ only a light signal can go from one event to the other [light-like]

if $q^2 < 0$: $S^2 > (c\Delta t)^2$ AOB

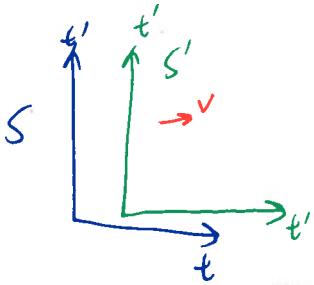
⇒ nothing can get between A & B in Δt

⇒ nothing can travel in the spatial coordinates to the spatial coordinates

↳ no causal relation possible

↳ there will be an inertial system where the events are simultaneous, but in different places (when $\Delta t = 0$)

Addition of velocities



$$u_x = \frac{x_B - x_A}{t_B - t_A}, u_y = \frac{y_B - y_A}{t_B - t_A}, u_z = \frac{z_B - z_A}{t_B - t_A}$$

↓ primed version

$$u'_x = \frac{x'_B - x'_A}{t'_B - t'_A}$$

↓ convert

Converting from unprimed to primed using Lorentz transform

$$x'_B - x'_A = x_B - x_A$$

$$z'_B - z'_A = \gamma(z_B - z_A - v(t_B - t_A))$$

$$t'_B - t'_A = \gamma(t_B - t_A - \frac{v}{c^2}(z_B - z_A))$$

$$\Rightarrow u'_z = \frac{z'_B - z'_A}{t'_B - t'_A} = \frac{z_B - z_A - v(t_B - t_A)}{t_B - t_A - \frac{v}{c^2}(z_B - z_A)} \cdot \frac{t_B - t_A}{t_B - t_A}$$

$$u'_z = \frac{u_z - v}{1 - u_z \frac{v}{c^2}}$$

y changes as well

$$u'_y = \frac{y'_B - y'_A}{t'_B - t'_A} = \frac{y_B - y_A}{\gamma(t_B - t_A - \frac{v}{c^2}(z_B - z_A))}$$

Time change

$$u'_y = \frac{1}{\gamma} \frac{u_y}{1 - u_z \frac{v}{c^2}}$$

$$u'_x = \frac{1}{\gamma} \frac{u_x}{1 - u_z \frac{v}{c^2}}$$

inverse version,
swap sign of v

$$u_x = \frac{1}{\gamma} \frac{u'_x}{1 - u'_z \frac{v}{c^2}}$$

$$u_y = \frac{1}{\gamma} \frac{u'_y}{1 - u'_z \frac{v}{c^2}}$$

$$u_z = \frac{u'_z + v}{1 + u'_z \frac{v}{c^2}}$$

$$u_x = \frac{u'_x}{\gamma(1 + u'_z \frac{v}{c^2})}$$

$$u_y = \frac{u'_y}{\gamma(1 + u'_z \frac{v}{c^2})}$$

$$u_z = \frac{u'_z + v}{1 + u'_z \frac{v}{c^2}}$$

Example
Z_{gns}

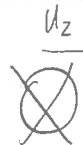


$$v = 0.5c$$



relative to Earth

$$u'_z = 0.5c$$



relative to the Earth

$$u_z = \frac{u'_z + v}{1 + u'_z \frac{v}{c^2}} = \frac{0.5c + 0.5c}{1 + 0.5c \frac{0.5c}{c^2}} = \frac{c}{1 + 0.25} = \frac{c}{1.25}$$

$$u_z = 0.8c$$

what if spaceship fire laser

$$u'_z = c$$

$$v = 0.5c$$

$$u_z = \frac{u'_z + v}{1 + u'_z \frac{v}{c^2}}$$

from earth

$$= \frac{c + 0.5c}{1 + \frac{c \cdot 0.5c}{c^2}} = \frac{1.5c}{1.5} = c$$

still in c

Relativistic Doppler effect

T_0 = time between emission of pulses
in rest frame of emitter

Emitter recedes w/ speed v
(from the observer)

T_1 = time between arrival of pulses
@ the observer

using Time dilation

T = interval between emission as
seen by observer

$$T = \gamma T_0$$

Take $\frac{d}{c}$ for a pulse to travel
distance d between emitter & observer
↳ measured in observer's
rest frame

In time T between emission

↳ source travels: vT

$$T_1 = T + \underbrace{\frac{d + vT}{c}}_{\text{how far 2nd pulse travels}} - \underbrace{\frac{d}{c}}_{\text{how far first pulse travels}}$$

$$T_1 = T \left(1 + \frac{v}{c}\right)$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} = \frac{1}{\sqrt{\left(1 + \frac{v}{c}\right)\left(1 - \frac{v}{c}\right)}}$$

$$T_1 = \gamma T_0 \left(1 + \frac{v}{c}\right) = \frac{T_0 \left(1 + \frac{v}{c}\right)}{\sqrt{\left(1 + \frac{v}{c}\right)\left(1 - \frac{v}{c}\right)}}$$

$$T_1 = T_0 \sqrt{\frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}}$$

getting frequency:

$$f = \frac{1}{T_1} = \frac{1}{T_0} \sqrt{\frac{1 - \frac{v}{c}}{1 + \frac{v}{c}}}$$

$$f = f_0 \sqrt{\frac{1 - \frac{v}{c}}{1 + \frac{v}{c}}}$$

∴ dropped.

$$\lambda = \lambda_0 \sqrt{\frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}}$$

$\lambda \uparrow$ red

$\lambda \downarrow$ blue

* time between pulses is still dilated,
even for transverse motion

$$f = \frac{f_0}{\gamma} \quad // \quad T = \gamma T_0$$

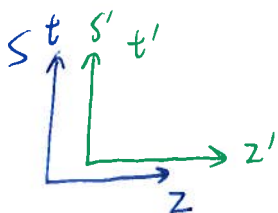
a source moving

⊥ to the line between it
& the observer

Mom & Energy

$$p = mv$$

$$p_x = m \frac{dx}{dt}, \quad p_y = m \frac{dy}{dt}, \quad p_z = m \frac{dz}{dt}$$



We want both observers to agree on p_x & p_y if boost is along z

\therefore We need to use proper time, to

time defined in an object's rest frame

$$p_z = m \frac{dz}{dt_0} = m \frac{dz}{dt} \frac{dt}{dt_0}$$

$$t = t_0 \gamma$$

$$\frac{dt}{dt_0} = \gamma$$

$\boxed{E = \gamma m c^2}$ for $v \ll c: \gamma \approx 1$
 $p = \gamma m v$

Energy:

force does work on a body

\hookrightarrow causes acceleration

$\Rightarrow \uparrow \uparrow KE$

$$\text{Work} = F \delta x = \delta K$$

if body moves with speed v ,

$$\delta x = v \delta t$$

$$\frac{dK}{dt} = F \frac{dx}{dt} = F \cdot v$$

$$F = \frac{dp}{dt} = m \frac{dv}{dt}$$

$$\frac{dK}{dt} = v \frac{dp}{dt} = mv \frac{dv}{dt} = \frac{d}{dt} \left(\frac{1}{2} m v^2 \right)$$

$$\therefore KE = \frac{1}{2} m v^2 \quad \left\| \begin{array}{l} K=0 \\ \text{when } v=0 \end{array} \right.$$

Consider now relativistic effects:

$$\frac{dK}{dt} = v \frac{dp}{dt} = mv \frac{d(\gamma v)}{dt}$$

$$\frac{d(\gamma v)}{dt} = \frac{d}{dt} \left(\frac{v}{\sqrt{1 - \frac{v^2}{c^2}}} \right)$$

$$= \frac{1 - \frac{v^2}{c^2} + v^2 \frac{1}{c^2}}{\left(1 - \frac{v^2}{c^2}\right)^{3/2}} \frac{dv}{dt}$$

$$= \left[\left(1 - \frac{v^2}{c^2}\right)^{-1/2} + \frac{v^2}{c^2} \left(1 - \frac{v^2}{c^2}\right)^{-3/2} \right] \frac{dv}{dt}$$

$$= \left(1 - \frac{v^2}{c^2}\right)^{-3/2} \frac{dv}{dt}$$

$$\therefore \frac{dK}{dt} = mv \left(1 - \frac{v^2}{c^2}\right)^{-3/2} \frac{dv}{dt}$$

$$\int dK = m \int v \left(1 - \frac{v^2}{c^2}\right)^{-3/2} dt$$

$$m c^2 \left(1 - \frac{v^2}{c^2}\right)^{-1/2}$$

$$\downarrow d$$

$$c^2 \frac{v}{c^2} \left(1 - \frac{v^2}{c^2}\right)^{-3/2}$$

$$\Rightarrow K = \gamma m c^2 - m c^2$$

imposing $KE=0$ when $v=0$

$$K = \gamma m c^2 - m c^2$$

$$\boxed{KE = \gamma m c^2 - m c^2}$$

for $v \ll c$

$$KE = m c^2 \left(1 - \frac{v^2}{c^2}\right)^{-1/2} - m c^2$$

$$= m c^2 + \frac{1}{2} m v^2 - m c^2 + O\left(\frac{v^2}{c^2}\right)^2$$

$$= \frac{1}{2} m v^2$$

increasing in energy due to
a body moving w/ speed v

$$KE = \gamma mc^2 - mc^2$$

"Total energy"

$$E = \text{rest energy} + KE$$

$$E = \gamma mc^2 - mc^2 + mc^2$$

At rest $v=0, \gamma=1$

$$E = \gamma mc^2$$

$$E = mc^2$$

Boojiboo

a particle @ rest still has energy

Energy in terms of momentum

$$E^2 = \frac{m^2 c^4}{1 - \frac{v^2}{c^2}} - m^2 c^4 + m^2 c^4$$

$$E^2 = \frac{m^2 c^4 - m^2 c^4 + m^2 v^2 c^2}{1 - \frac{v^2}{c^2}} + m^2 c^4$$

$$\text{rest frame, } m^2 c^4 + \frac{m^2 v^2 c^2}{1 - \frac{v^2}{c^2}} = m^2 c^4 + \frac{m^2 v^2 c^2}{1 - \frac{v^2}{c^2}}$$

$$E^2 = \boxed{m^2 c^4} + p^2 c^2$$

-ve solⁿ
important in QM

$$E = \pm \sqrt{m^2 c^4 + p^2 c^2}$$

m is Lorentz invariant

$$E^2 - p^2 c^2 = m^2 c^4$$

Scalar relation
space-like components \Rightarrow 4-momentum

Scalar product

Four momentum:

$$p = \begin{pmatrix} E/c \\ p_x \\ p_y \\ p_z \end{pmatrix}$$

In the rest frame S :

$$p = \begin{pmatrix} E/c \\ p_x \\ p_y \\ p_z \end{pmatrix} = \begin{pmatrix} mc \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

In frame S' :

$$p' = \begin{pmatrix} E'/c \\ p'_x \\ p'_y \\ p'_z \end{pmatrix}$$

$$= \begin{pmatrix} \gamma & 0 & 0 & -\gamma \frac{v}{c} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma \frac{v}{c} & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} mc \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} \gamma mc \\ 0 \\ 0 \\ -\gamma mv \end{pmatrix}$$

transforming
like a

4-vector

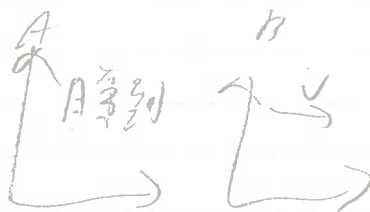
$$E = \gamma mc^2$$

$$p = -\gamma mv$$

magnitude of a 4-vector p^2

$$p^2 = \frac{E^2}{c^2} - p_x^2 - p_y^2 - p_z^2$$

$$= E_c^2 - p^2 = m^2 c^2$$



$$B = \begin{pmatrix} \gamma & 0 & 0 & -\gamma \frac{v}{c} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma \frac{v}{c} & 0 & 0 & \gamma \end{pmatrix} (A)$$

Massless particle:

$$E = \sqrt{m^2 c^4 + p^2 c^2}$$

$$m \rightarrow 0$$

$$E = \pm \sqrt{p^2 c^2}$$

$$E = |p|c$$

$$E = \gamma m c^2 = \frac{m c^2}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$m \rightarrow 0$
 $v \rightarrow \infty$ } to have finite energy

- * A particle can only travel at c if it is massless (otherwise $\gamma \rightarrow \infty$, $E \rightarrow \infty$)
- Particle MUST travel @ c if it is massless otherwise $E \rightarrow \infty$

In QM

$$E = hf = \frac{hc}{\lambda}$$

$$|p| = \frac{h}{\lambda}$$

$$h = 6.626 \times 10^{-34}$$

4-momentum of photon:

$$\begin{pmatrix} E/c \\ p_x \\ p_y \\ p_z \end{pmatrix} = \begin{pmatrix} \frac{hc}{\lambda} \\ 0 \\ 0 \\ \frac{hc}{\lambda} \end{pmatrix}$$

Magnitude of 4-momentum is zero for a photon: massless

$$p^2 = E^2/c^2$$

In any given inertial frame
* Four momentum is conserved component by component

$$\begin{pmatrix} E/c \\ p_x \\ p_y \\ p_z \end{pmatrix} \quad \begin{matrix} \text{Energy} \\ \& \\ \text{Momentum} \end{matrix} \quad \text{are } \underline{\text{conserved}}$$

$$E = \gamma m c^2, \quad p = \gamma m v$$

Under Lorentz transform, magnitude of 4-momentum is invariant

$$m = \gamma m_0$$

$$E = \gamma m c^2$$

γ with

$$\gamma = \frac{\gamma m c^2}{m c^2} = \frac{E}{m c^2}$$

photon boost in Lorentz frames

$$\frac{\gamma m v c}{\gamma m c^2} = \frac{hf c}{\gamma m c^2} = \frac{|p| c}{E} = \frac{v}{c}$$