



## Exp 3 part B: Sensor Fusion with complementary filter



Debraj Chakraborty Chakraborty • Oct 26, 2021

10 points

Due Oct 29, 2021, 11:59 PM

Submit a short report (max 3 pages) on fusing the accel-gyro-mag data and computing the attitude estimates. You should use the complementary filter for this purpose. Initial attitudes cannot be used directly in the algorithm.



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