Exp 3 part C: Sensor Fusion using Kalman filter

⋮

Debraj Chakraborty Chakraborty • Oct 26, 2021 (Edited Nov 2, 2021)

10 points

Due Nov 29, 2021, 11:59 PM

Submit a report (max 5 pages) on fusing accel-gyro-mag readings using a 12- state Kalman filter. Compute the attitude estimates. Compare with complimentary filter estimates and the true values.

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Exp_3c.pdf
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