

# Computer Assignment - 01 - Spring 2019

Submitted by - Sayam Kumar S20180010158

## Signal Transformations

Task\_1. Given  $u[n]$  the unit step sequence, using the stem function plot the following -

a.  $u[n-5] - u[n-10]$

b.  $u[6-n] - u[3-n]$

c.  $u[8-n]$

Ans - % my unit step function

```
function y = unit_step(n)
```

```
    y = zeros(size(n));
```

```
    y(n>=0) = 1;
```

```
end
```

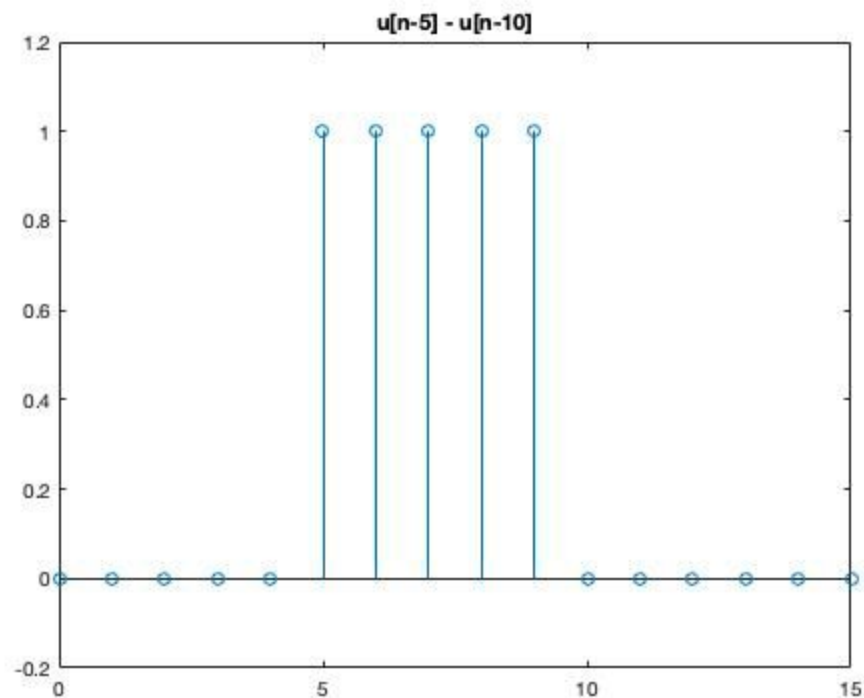
```
% a.  $u[n-5] - u[n-10]$ 
```

```
n = 0:1:15;
```

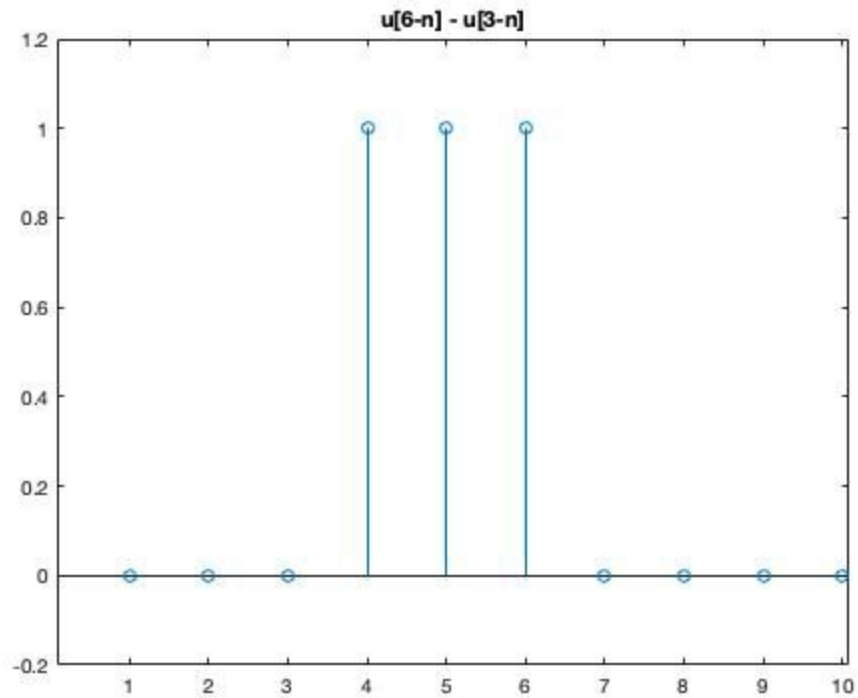
```
stem(n,unit_step(n-5)-unit_step(n-10),'o')
```

```
ylim([-0.2 1.2])
```

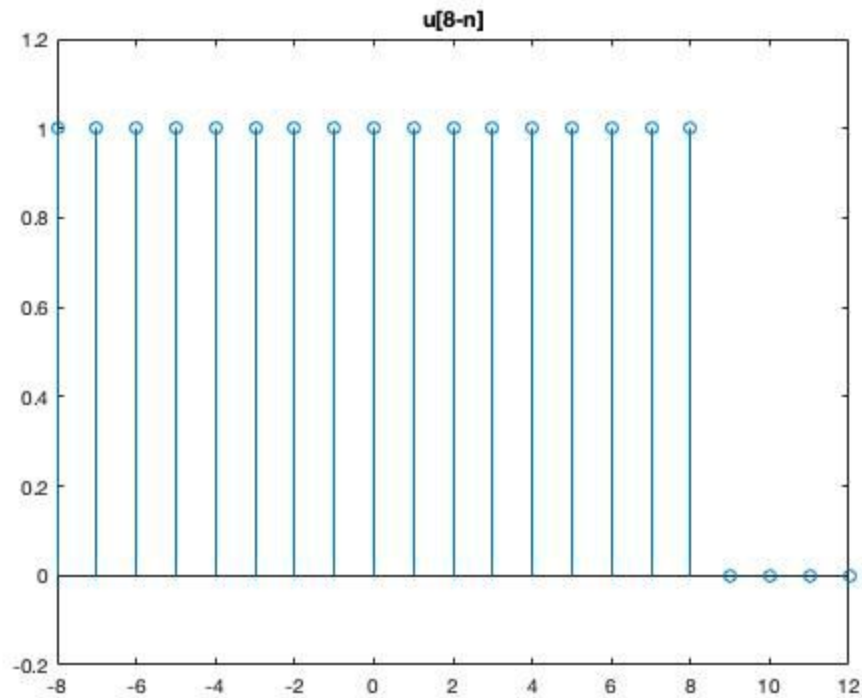
```
title('u[n-5] - u[n-10]')
```



```
% b.  $u[6-n] - u[3-n]$ 
n = 0:1:10;
stem(n,unit_step(6-n)-unit_step(3-n),'o')
ylim([-0.2 1.2])
title('u[6-n] - u[3-n]')
```



```
% c.  $u[8-n]$ 
stem(n,unit_step(8-n),'o')
ylim([-0.2 1.2])
title('u[8-n]')
```



Task\_2. Given the signal  $\sin[\omega_0 n]$ , plot the following: Assume the unknown values

a.  $\cos[\omega_0(n-n_0)]$

b.  $\cos[\omega_0(n+n_0)]$

Ans -

$w_0 = \pi/3;$

$n_0 = 1;$

$n = -10:0.1:10;$

$y_1 = \text{zeros}(\text{size}(n));$

$y_1 = \sin(w_0 * n);$

$y_2 = \text{zeros}(\text{size}(n));$

$y_2 = \sin(w_0 * (n-n_0) + \pi/2);$

$y_3 = \text{zeros}(\text{size}(n));$

$y_3 = \sin(w_0 * (n+n_0) + \pi/2);$

$\text{stem}(n, y_1, 'red')$

$\text{ylim}([-1.2 \ 1.2])$

$\text{title}(' \sin( w_0 * n)')$

$\text{stem}(n, y_2, 'blue')$

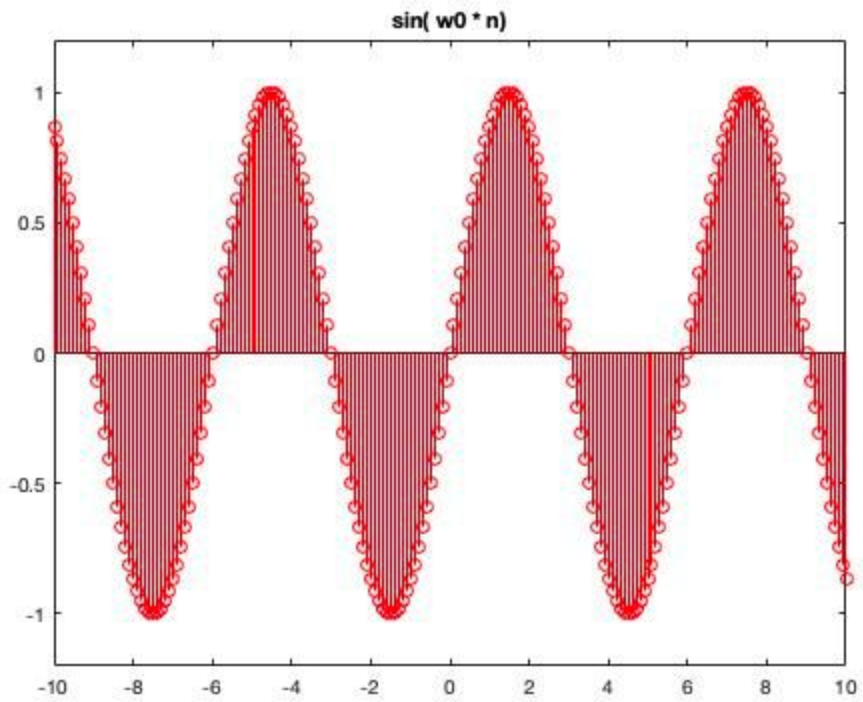
$\text{ylim}([-1.2 \ 1.2])$

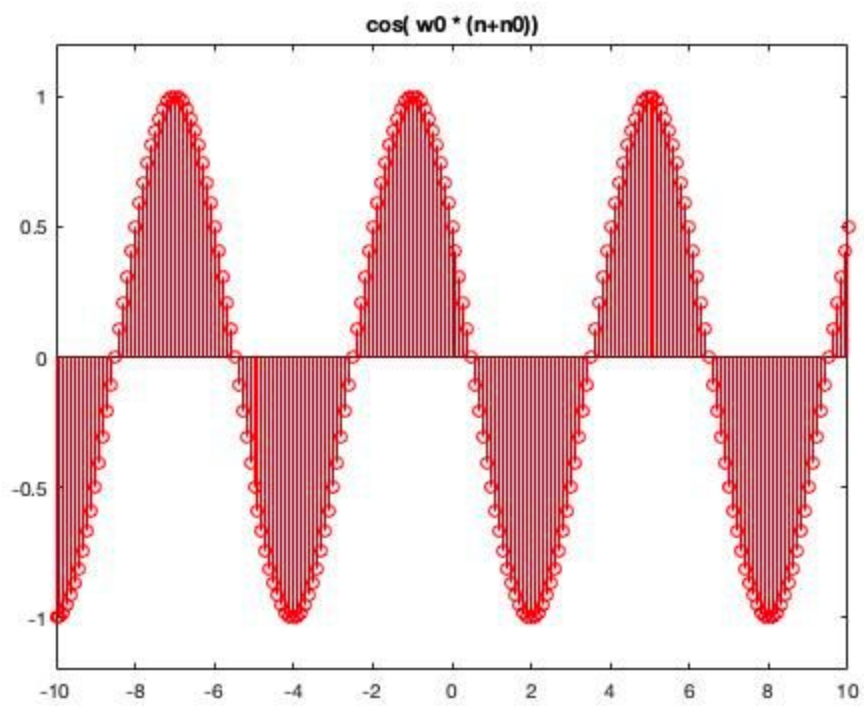
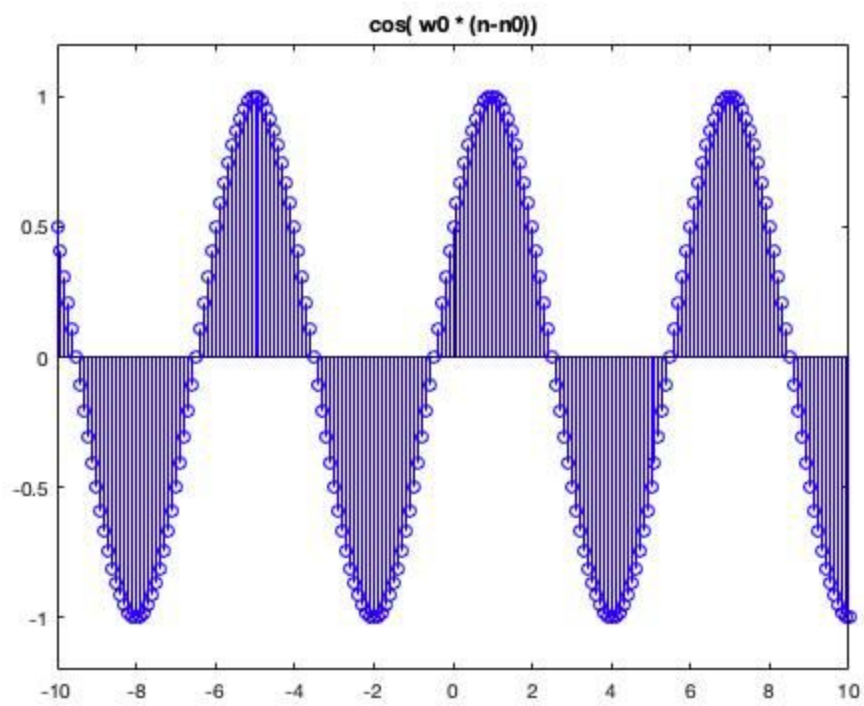
```
title('cos( w0 * (n-n0))')
```

```
stem(n,y3,'red')
```

```
ylim([-1.2 1.2])
```

```
title('cos( w0 * (n+n0))')
```





Task\_3. Given the signal  $x(t)$  -

$$\begin{aligned}x(t) &= 0 \quad t < 0 \\&= 2t \quad 0 \leq t < 1 \\&= 3-t \quad 1 \leq t < 3 \\&= -3+t \quad 3 \leq t < 5 \\&= 2 \quad 5 \leq t < 7 \\&= 0 \quad t \geq 7\end{aligned}$$

Ans - % my  $x(t)$  function

```
function y = x(t)
    y = zeros(size(t));
    y(t>=0 & t<1) = 2*t(t>=0 & t<1);
    y(t>=1 & t<3) = 3-t(t>=1 & t<3);
    y(t>=3 & t<5) = -3+t(t>=3 & t<5);
    y(t>=5 & t<7) = 2;
end
```

```
t = -5:0.1:11;
y1 = x(t-2);
y2 = x(t+3);
y3 = x(3*t-4);
y4 = x(1-3*t);
```

```
plot(t,y1)
title('x(t-2)')
ylim([-0.2 2.2])
xlim([-5 11])
```

```
plot(t,y2)
title('x(t+3)')
ylim([-0.2 2.2])
xlim([-5 11])
```

```
plot(t,y3)
title('x(3*t-4)')
ylim([-0.2 2.2])
```

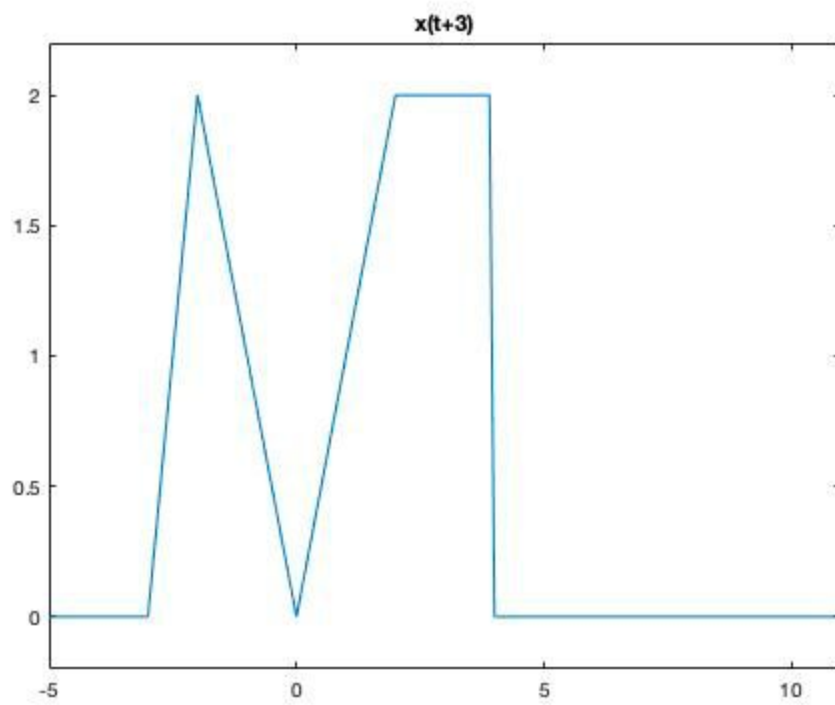
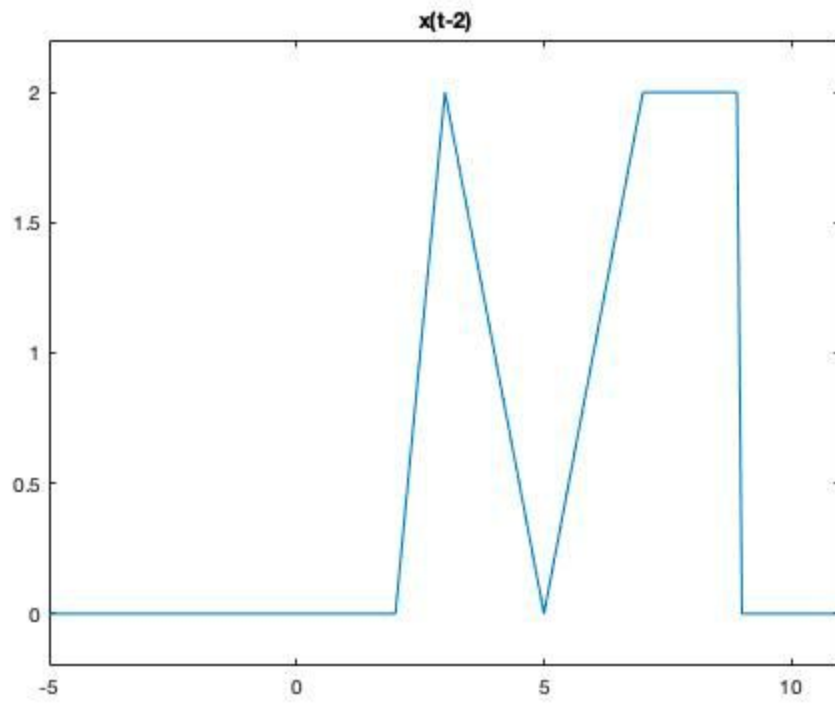
```
xlim([-5 11])
```

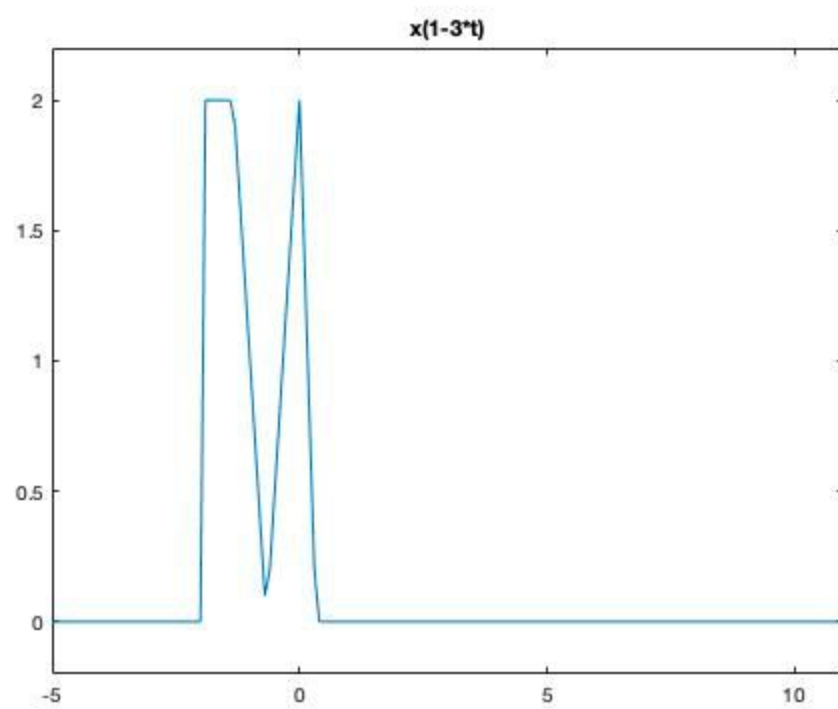
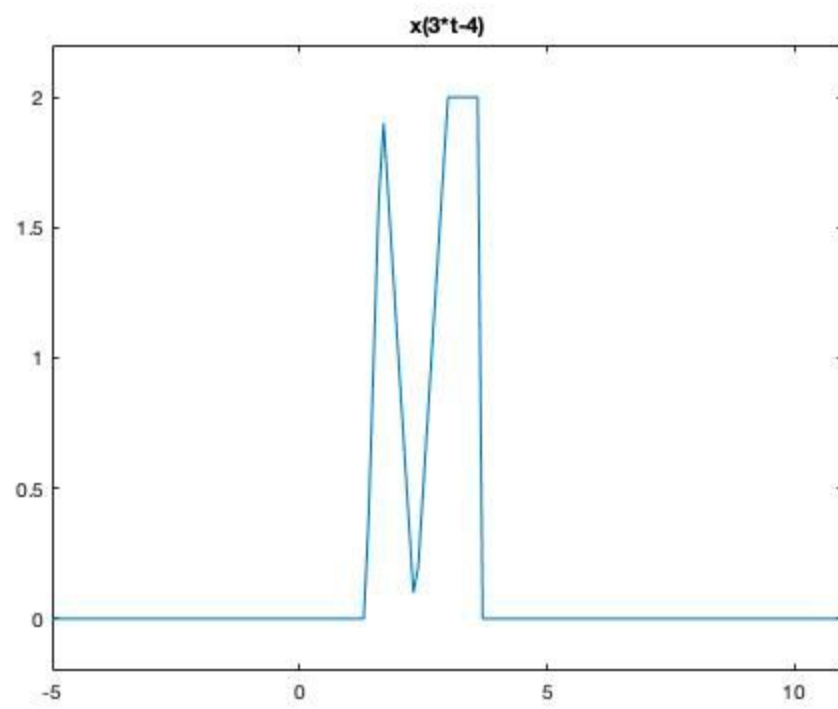
```
plot(t,y4)
```

```
title('x(1-3*t)')
```

```
ylim([-0.2 2.2])
```

```
xlim([-5 11])
```







Task\_4. Given the discrete signal,  $x[n] = [-1, -2, -3, 4, -2]$

- a.  $x[n+1]$
- b.  $x[n-2]$
- c.  $x[3-n]$
- d.  $x[3-2n]$
- e.  $x[4n+5]$

Ans - % my function x[n]

```
function y = x(n)
    y = zeros(size(n));
    y(n == 0) = -1;
    y(n == 1) = -2;
    y(n == 2) = -3;
    y(n == 3) = 4;
    y(n == 4) = -2;
end
```

```
n = -5:10;
y1 = x(n+1);
y2 = x(n-2);
y3 = x(3-n);
y4 = x(3-2*n);
y5 = x(4*n+5);
```

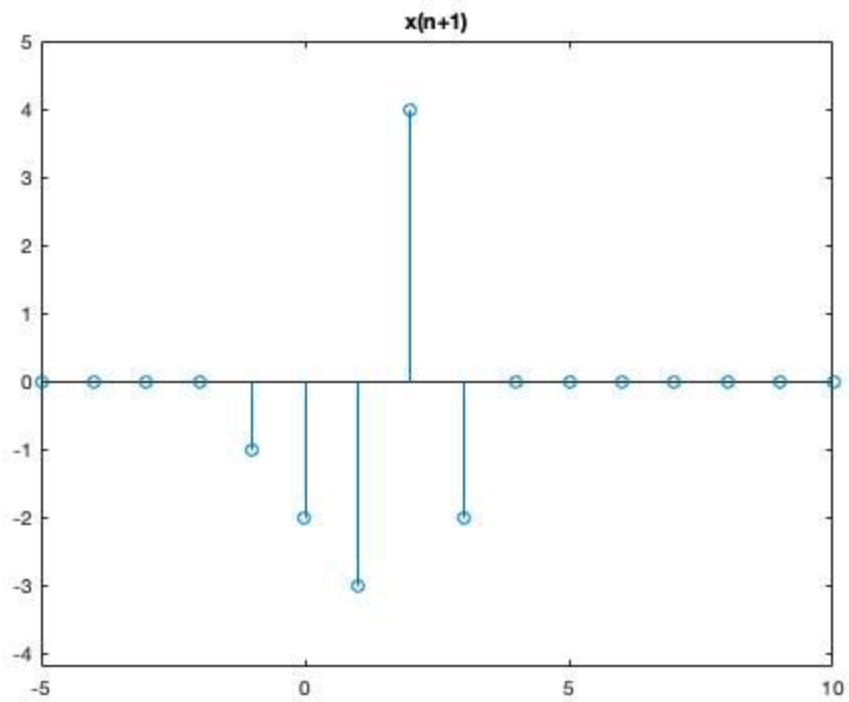
```
stem(n,y1);
ylim([-4.2 5])
title('x(n+1)')
```

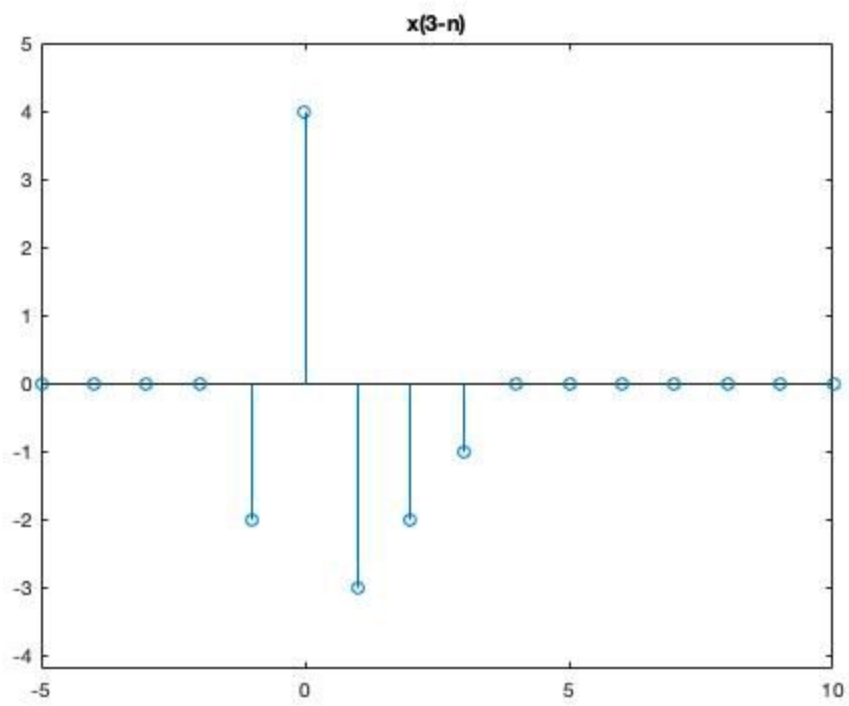
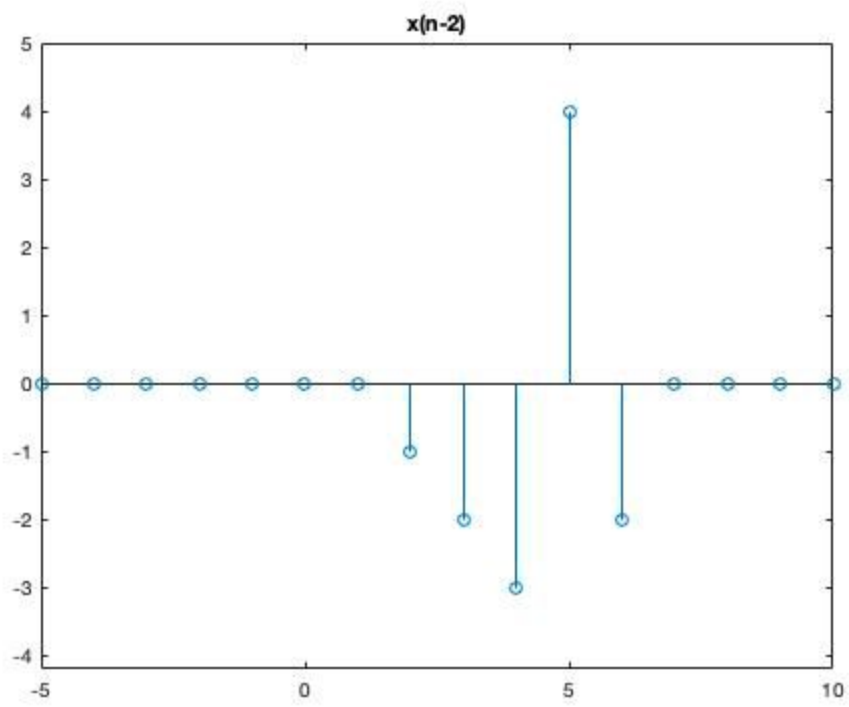
```
stem(n,y2);
ylim([-4.2 5])
title('x(n-2)')
```

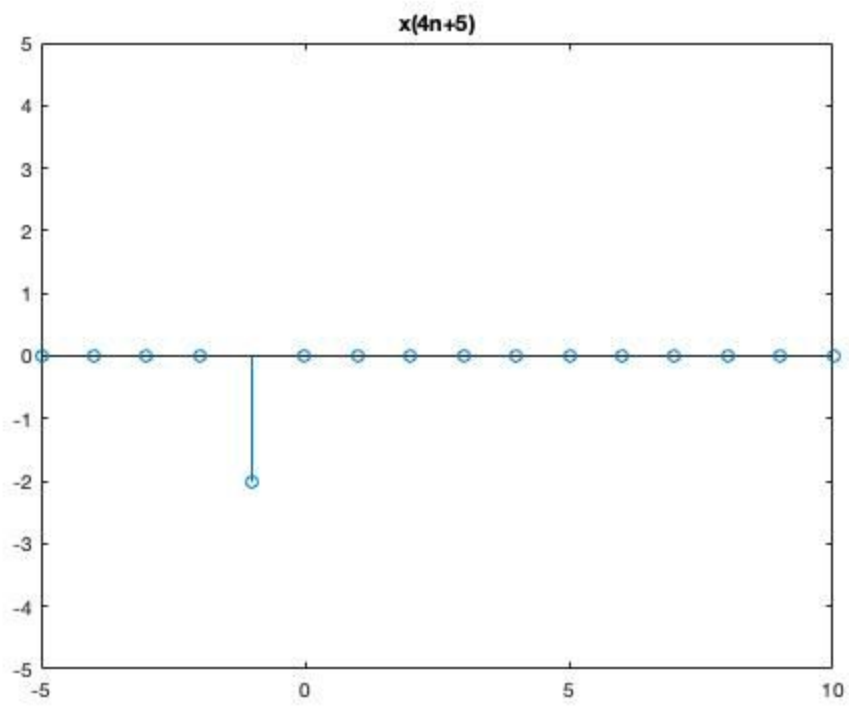
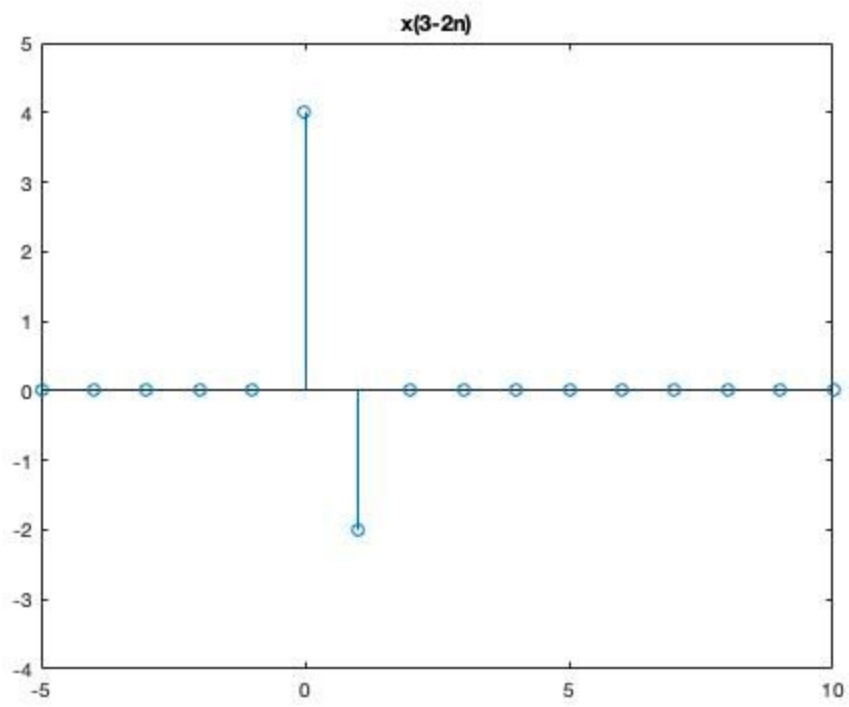
```
stem(n,y3);
ylim([-4.2 5])
title('x(3-n)')
```

```
stem(n,y4);  
ylim([-4 5])  
title('x(3-2n)')
```

```
stem(n,y5);  
ylim([-5 5])  
title('x(4n+5)')
```







## Signal Generation

Task\_1. Consider the signal

$$x(t) = \begin{cases} \exp(2t) & -1 < t < 0 \\ \exp(-2t) & 0 < t < 1 \\ 0 & \text{otherwise} \end{cases}$$

Answer/do the following

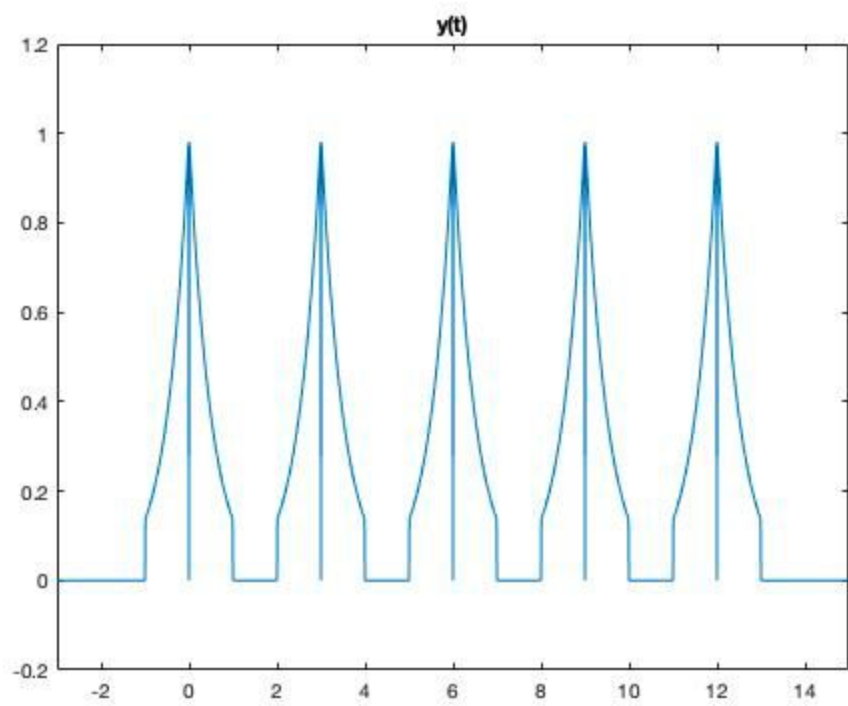
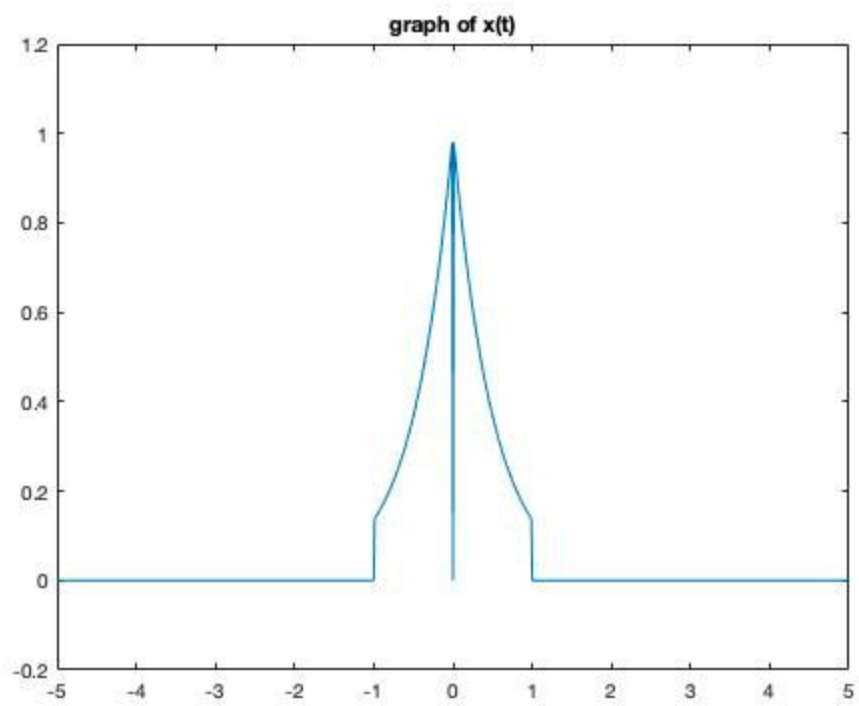
1. Plot  $x(t)$
2. Define  $y(t)$  as a periodic signal equal to  $x(t)$  in the fundamental period  $T = 3$ . Plot  $y(t)$ . Assume the number of pulses to be plotted as 5.

Ans - %my function  $x(t)$

```
function y = x(t)
    y = zeros(size(t));
    y((t>-1) & (t<0)) = exp(2*t((t>-1) & (t<0)));
    y((t>0) & (t<1)) = exp(-2*t((t>0) & (t<1)));
end
```

```
t = -10:0.01:20;
T = 3;
graph = x(t);
plot(t,graph)
title('graph of x(t)')
xlim([-5 5])
ylim([-0.2 1.2])
```

```
y = zeros(size(t));
for n = 1:5
    a = n-1;
    y = y+x(t-(a*T));
end
plot(t,y)
title('y(t)')
xlim([-3 15])
ylim([-0.2 1.2])
```



Thanks

Submitted by - Sayam Kumar

Roll No - S20180010158