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Group: A1

Assignment: 3

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Assignment: In this assignment, you have to implement 1-persistent, non-persistent and p-persistent CSMA techniques. Measure the performance parameters like throughput (i.e., average amount of data bits successfully transmitted per unit time) and forwarding delay (i.e., average end-to-end delay, including the queuing delay and the transmission delay) experienced by the CSMA frames (IEEE 802.3). Plot the comparison graphs for throughput and forwarding delay by varying p. State your observations on the impact of performance of different CSMA techniques.

```
Code:
       from itertools import count, cycle
import random
max time=1000
max wait time=30
max send time=5
max loc=1000
permissible dist=20
station no=6
stations=list(random.sample(range(1,max loc+1),k=station no))
stations.sort()
back off=[None]*station no # (time to start sending,dest,sending time)
data=set()#tuple<int,int,int> # (source,destination,t start,t end)
class persistent 1:# pair<tuple<int,int,int>,tuple<int,int,int>>
 def init (self) -> None:
  pass
 def func(self,any true,data to send,t):
  if not any true:
   return (data_to_send,None)
  else:
   return (None,(t+1,data_to_send[1],data_to_send[3]-data_to_send[2]))
class persistent 0:
 def init (self) -> None:
  pass
 def func(self,any true,data to send,t):
  if not any true:
   return (data to send, None)
  else:
   return
(None,(t+random.randint(1,max wait time),data to send[1],data to send[3]-data to send[2]))
```

```
class persistent p:
 def init (self,p) -> None:
  self.p=p
 def func(self,any true,data to send,t):
  if not any true:
   val=random.randint(0,100)/100
   if val<=self.p:#send
    return (data_to_send,None)
   else:#wait random
    return
(None,(t+random.randint(1,max wait time),data to send[1],data to send[3]-data to send[2]))
  else:
   return (None,(t+1,data to send[1],data to send[3]-data to send[2]))
def calculate positions(data,t):
 listy=[]
 for i in data:
  velo=(i[1]-i[0])/(i[3]-i[2])
  cur_pos=i[0]+velo*(t-i[2])
  listy.append(cur pos)
 return listy
def is collision(pos1,pos2):
 return abs(pos1-pos2)<=permissible dist
# persistence method=persistent p(1/station no)
# persistence method=persistent 0()
persistence_method=persistent_1()
data generated=0
data_sent=0
#for(int t=0;;t++)
for t in count(0,1):
 print(f"at t:{t}")
 if t>10*max time:
  break
 if t>max time and len(data)==0 and not any(back off):
  break
 #take out the data that has already reached
 new data=set(i for i in data if i[-1]>t)
 data sent+=len(data)-len(new data)
 data=new data
```

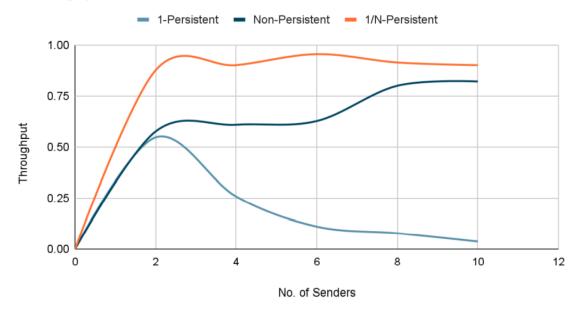
```
#randomly some stations will send the data
 for i in range(station no):
  data to send=None
  if back off[i] and back off[i][0]<=t:
   data_to_send=(i,back_off[i][1],t,t+back_off[i][2])
  else:
   if t>max time or random.randint(0,1)!=0:
     continue
   j=random.choice(range(station no))
   data generated+=1
   time needed to send=random.randint(1,max send time)
   data to send=(i,j,t,t+time needed to send)
  #add your scheme
  positions of data=calculate positions(data,t)
  any_true=any(is_collision(stations[i],pos) for pos in positions_of_data)
  tup=persistence method.func(any true,data to send,t)
  if tup[0]:# send
   print(f"st{i} sending data to st{j} at {t}")
   data.add(tup[0])
   back off[i]=None
  else:# hold
   print(f"st{i} backing off to {tup[1][0]}")
   back off[i]=tup[1]
 #see if there is a collision. if yes purge all the data
 if len(data)>1:
  print(f"collision detected at {t}. purging data")
  data=set()
  #data.clear()
print(f"{data_generated} {data_sent} {data_sent*100/data_generated}")
```

Design:

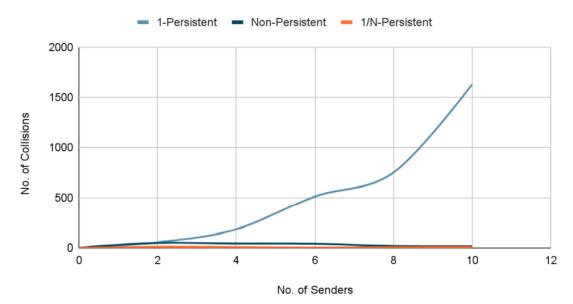
There is a channel and sender-receiver stations. The sender sends the data and if there is a collision then that data is purged and if there is no collision then that data is simply accepted. For control mechanism, various persistent algorithms are used like: 1 persistent, non persistent, p persistent algorithm.

Graph:

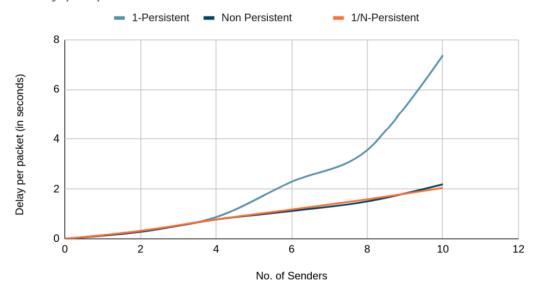
Throughput vs No. of Senders



Collisions vs No. of Senders



Delay per packet vs No. of Senders



ANALYSIS:

Collision In the 1-Persistent method, a frame is transmitted immediately after it senses the channel idle, it has the maximum chances of collision. When the number of senders increases, no. of collisions increases exponentially. In the Non-Persistent method, it waits for a random time when the channel is found to be busy. An average number of collisions remains almost the same with a slight increase with an increasing no. of senders, since the random waiting range also increases, hence reducing the chances of sensing the idle channel simultaneously. In the P-Persistent method, whenever it senses an idle channel, it generates a random value which must be less than p(1/no. of senders) to transmit the frame, else waits for a time, and tries again. It is unlikely for different senders to get in the same slot, which reduces the collision probability.

Average number of collisions remains almost same with a slight increase with increasing number of senders as value of p decreases too. Throughput In the 1-Persistent method, since no. of collisions increases with an increase in no. of senders, throughput decreases. In the Non-Persistent method, throughput increases slowly up to a certain point and then saturates. The P-Persistent method provides the best throughput. Throughput is greater than the other two methods and remains almost saturated at all times.

Average Delay per Packet: In the 1-Persistent method, since no. of collisions increases exponentially with an increase in no. of senders, delay per packet also increases exponentially. In the Non-Persistent method, with increasing no. of senders, delay per packet also increases linearly. In the P-Persistent method too, delay per packet increases linearly with the increase in no. of senders. Among all of the methods, the P-Persistent method with probability = 1/N, where N = no. of senders is the most efficient.

COMMENTS: Since the receiver sends an acknowledgment, which is also a form of the data packet, and the receiver is also a station, this assignment can be extended further such that, both the sender and the receiver follow the persistent methods.