#### **OS Notes:**

#### 1) What is OS?

- 1) Manages the processes and the memory
- 2) It helps in managing the s/w and the h/w
- 3) It helps us to interact with the computer without knowing the assembly language(Language of 0's and 1's)

## 2) Functions of OS?

- 1) Memory Management
- 2) Device Management
- 3) Processor Management
- 4) Security
- 5) Error Detection
- 6) Coordination between s/w and the user
- 7) Job Accounting
- 8) File Management

## 3) Kernel:

1) Contains the minimum requirements for the OS to run eg: all the system call like wait() etc are contained inside the kernel.

## 4) BSP(Bootstrap Program):

- 1) First program that runs when we start the OS
- 2) Initialises the OS

## 5) Types of OS:

- 1) Real Time OS(RTOS)
- Single User OS-> Single Task(eg: MS-DoS), Multi-Tasking(MacOS, Windows)
- 3) Multi-User OS

## 6) Processor:

- It is a chip or a logical circuit that responds and processes the basic instructions
- 2) Or, in layman terms we can say: processor executes the processes, inside the CPU
- 3) Lifecycle of Processor:
  - 1) Fetching -> Decode -> Execute -> write-back
- 4) Interacts with the input/output devices and also the memory based on the type of tasks it needs to perform.
- 5) H/W component capable of executing instructions

## 7) Process:

## 1) Definition:

- 1) Instance of a Program under execution
- 2) Process is an active-entity whereas program is a passiveentity

3) Processor is one of the resource that is required for the process to execute

#### 2) Management:

- 1) Functions:
  - 1) To keep track of the status of each process
  - To suspend and choose some processes based on certain criteria
  - 3) To coordinate inter-process communication

#### 3) Structure:

- 1) Code Region:
  - 1) Contains the executable instructions of the process
- 2) Data Region:
  - 1) Hold the data areas used by the process
- 3) Stack Region:
  - 1) Holds the dynamic data: eg: local variables, arguments to a function
- 4) Program Counter(PC):
  - 1) Address of the next instruction to be executed.

#### 4) Lifecycle/States:

 New -> Ready -> Running -> Waiting -> Ready -> Running -> Terminated

## 5) Context-Switching:

- The task of switching the processor/CPU to another process by saving the state of the old-process and loading the savedstate of the new-process
- 2) Features:
  - 1) Keeps the processor/CPU busy all the time
- 3) Occurs:
  - 1) An I/O operation is initiated
  - 2) And interrupt occurs
  - 3) An I/O operation is completed
  - 4) A process terminates

## 6) Scheduling:

1) Ready-State -> 50 processes -> how to know which process to run first? ->

# Scheduler(to pass the process from Ready->Running state)

## 2) Policies:

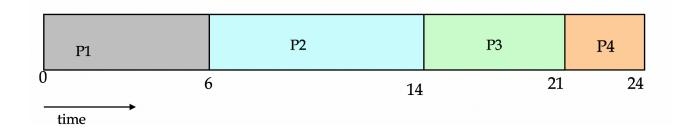
- 1) Non-Preemptive:
  - CPU is allocated to the process unless the job/execution is over
  - 2) Eg: FCFS(First Come First Serve)

- 2) Preemptive:
  - 1) The processes will switch based on various factors like priority, time-quantum etc.
  - 2) Eg: Round Robin
- 3) Important Formulas:
  - 1) Burst Time/CPU Time: The time the process will take to execute when it is assigned to the processor
  - 2) Turn Around Time(TAT) = Completion Time Arrival Time
  - **3) Waiting Time(WT)** = Turn Around Time Burst Time(CPU Time)
  - 4) Response Time(RT) = The difference between the arrival time and the time at which the process first gets the processor/CPU
- 4) Arrival Time:

Processes	Arrival Time	Burst Time	TAT
P1	0		
P2	2		
P3	0		
P4	0		

# 5) FCFS(Non-Preemptive):

Processes	Arrival Time	<b>Burst Time</b>	TAT	Waiting Time	Response Time
P1	0	6	6	0	0
P2	0	8	14	6	6
P3	0	7	21	14	14
P4	0	3	24	21	21
			65	41	41



Avg TAT: 65/4 = 16.25 Avg WT: 41/4 = 10.25 Avg RT: 41/4 = 10.25

## 6) Round Robin:

Time-Quantum(The time for which the CPU will execute the process)

Eg:

Time-Quantum: 5ms

2)

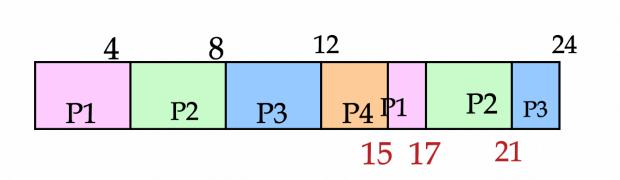
Time-Quantum: 5ms

#### Time Quantum = 4ms

Process	Arrival Time	<b>Burst Time</b>	TAT	Waiting Time	Response Time
P1	0	6	17	11	0
P2	0	8	21	13	4
P3	0	7	24	17	8
P4	0	3	15	12	12
			77	53	24

$$t=0 -> [P1,P2,P3,P4]$$

$$P1 -> 6 -> 2 -> 0$$



Avg TAT: 77/4 = 19.25

Avg WT: 53/4 = 13.25

Avg RT: 24/4 = 6

## 7) Priority Based Scheduling:

## **Non-Preemptive:**

Processes	Arrival Time	<b>Burst Time</b>	Priority	TAT	WT	Response Time
P1	0	10	2	10	0	0
P2	2	4	1	12	8	8
Р3	0	6	3	20	14	14
				42	22	22

## Ready Queue: [P1,P3],[P1,P3],[P1,P2,P3]

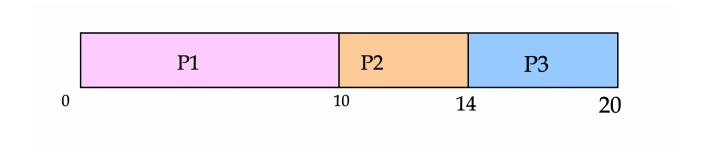
t=0 -> P1, P3

t=1 -> P1, P3

t=2 -> P1,P2,P3

t=10 -> P2,P3 {P1 has completed its execution}

t=14 -> P3



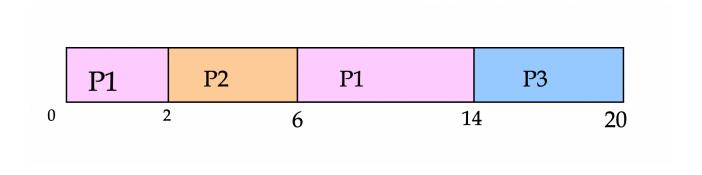
Avg TAT: 42/3 = 14 Avg WT: 22/3 = 7.33 Avg RT: 22/3 = 7.33

## **Preemptive:**

Process	Arrival Time	<b>Burst Time</b>	Priority	TAT	Waiting Time	Response Time
P1	0	10	2	14	4	0
P2	2	4	1	4	0	0
P3	0	6	3	20	14	14
				38	18	14

Ready Queue: [P1,P3],[P1,P3],[P1,P2,P3]

$$t=1 -> P1, P3$$



Avg TAT: 38/3 = 12.67

Avg WT: 18/3 = 6

Avg RT: 14/3 = 4.67

## Disadvantage:

Some lower priority process have to wait for a longer time because of higher priority processes

**Solution: Aging:** we increase the priority of the process after sometime.

#### 7) Threads:

#### 1) Basics:

- 1) Lightweight as compared to processes.
- 2) Process-> Complete Program, Threads-> Segment of a program
- 3) In case of multi-threading two parts of the same program can execute simultaneously
  - 4) Thread share same Address Space, Data Section,

#### Resources

- 5) Threads have different Stack Section(local data), PC
- 6) Context-Switching is easy in case of threads

#### 2) Lifecycle/States:

New -> Runnable -> Running -> wait/sleep/block -> Runnable-> Running -> Terminated

## 3) Lifecycle methods:

- 1) wait(): Running->waiting
- 2) sleep(): Running->sleeping
- 3) suspend(): Running->blocking
- 4) Running->Runnable:
- 1) yield(){it can stop the currently executing thread and give chance to threads that are in the waiting state but of the same priority}:
  - 2) notify()/notifyAll() {waiting state}
  - 3) sleep time is up {sleeping state}
  - 4) resume() {blocking state}

#### 8) Memory:

- 1) Component to store information for immediate usage
- 2) Types:
  - 1) Primary(RAM):
    - 1) Expensive
    - 2) Fast
    - 3) Works directly with the processor
    - 4) Implemented using Stack data-structure
- 5) Stores local-data, returns addresses, used for parameter passing
- 6) Stack overflow error will occur when too much of the stack is used
- 7) Maximum size is already determined when the program starts
  - 2) Secondary(HDD):
    - 1) Cheap
    - 2) Slow
    - 3) Does not directly work with the processor
  - 3) Cache:
    - 1) Very high speed semi-conductor memory
    - 2) Acts as a buffer between main-memory and CPU
  - 4) Heap:
    - 1) Variables must be destroyed manually
    - 2) On Demand allocation
    - 3) Can have fragmentations
    - 4) Used for Dynamic allocations
    - 5) Responsible for memory leaks
  - 3) Process Register:
    - 1) Every processor has a local storage -> Register
    - 2) Holds the data that is being processed by the processor/

**CPU** 

- 3) Two Types:
  - 1) General-Purpose
  - 2) Special-Purpose
- 4) Cache V/S Register

Cache	Register
Less faster and less efficient	Accessing it is faster and more efficient
Contains instruction code	It cannot
Machine instructions can be stored	Cannot
	In multiple-core processor all the processors share common cache

## 5) Management:

- 1) Core functionality of OS
- 2) Decides the location of memory to allocate and deallocate based on the process requirement.

## 6) Address Space:

## 1) Physical Address:

- 1) Actual locations in the main-memory
- 2) Since it cannot be accessed directly by the user-

program:

- ——-a logical/virtual address need to mapped to make the respective physical address available
- 3) The above address mapping -> **MMU(**Memory-Management-Unit**)**
- **4) MMU:** is a h/w component responsible for translating a logical address to a physical address

## 2) Logical Address:

- 1) Created by CPU during Program execution
- 2) Do not exist physically
- 3) Used as a reference to access the physical address

#### 7) Fragmentation:

#### 1) Defintion:

- 1) during allocation and de-allocation, the memory is broken into pieces
- 2) because of the above it happens that we cannot assign that memory and memory space remains free even-though available

## 2) Types:

#### 1) Internal:

Occurs when allocated>requested

#### 2) External:

Occurs when memory is available but in noncontiguous manner

#### 8) Swapping:

- 1) We swap the process from the main-memory to the secondary memory.
  - 2) Swapping is done w.r.t secondary memory.
  - 3) Swap-in -> main-memory-> secondary-memory
  - 4) Swap-out-> secondary-memory-> main-memory

## 8) File Systems:

- 1) Organising and retrieving files from the Hard-Disk
- 2) Stored in the form Directories(Folders)-> we can have other files/directories
  - 3) Windows -> NTFS -> New Technology File System

## 4) Management:

1) All the file related operations like moving, locating, opening etc. all are handled by this

## 9) Security in OS:

1) Providing protection to computer resources like memory, CPU, data etc

Using:

- 1) Authentication
  - 1) Using username/password
  - 2) Using card/key
  - 3) Using attributes, like bio-metrics
- 2) Authorisation
- 3) OTPs, Random Numbers(ICICI cards), Secret Keys, Network Login

#### 10) Program Threats:

- 1) Trojan horse: Captures the credentials and sends to malicious users
- 2) Trap Door: Can access certain parts of the program without logging in
- 3) Logic Bomb: program misbehaves when met with certain conditions, harder to detect
  - 4) Virus: replicate themselves, cause system crash, file changes

#### 11) System Threats:

- 1) Worm: replicate files, using up the computer resources
- 2) Port scanning: hackers, can detect system vulnerabilities
- 3) Denial of Service

#### NOTE:

1) SJF(Shortest Job First): It can be both non-preemptive as well as preemptive.

# **Assignment:**

# 1) Have a brief reading about:

- 1) Micro-controller
- 2) Micro-processor3) Embedded-processor
- 4) DSP and Media-processor