

CSE 4/535 Information Retrieval

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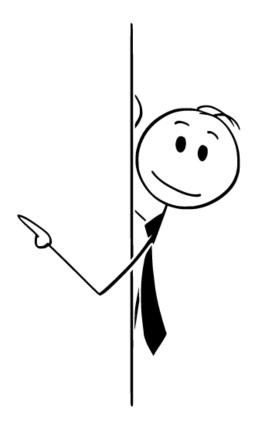
Before we start

- Project 1 released, due 27th September.
- Join office hours if you have questions



Recap - Previous Class

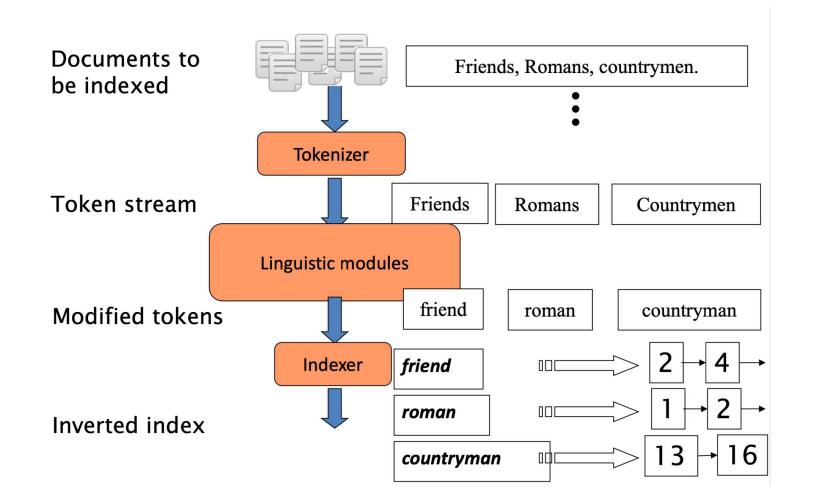
- What is tolerant Retrieval?
- Why spelling corrections are important?
- Soundex



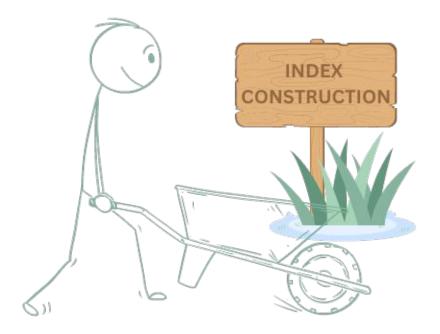




Recall the basic indexing pipeline



Index Construction



Index Construction... Hardwares?

How important is system memory (RAM)?

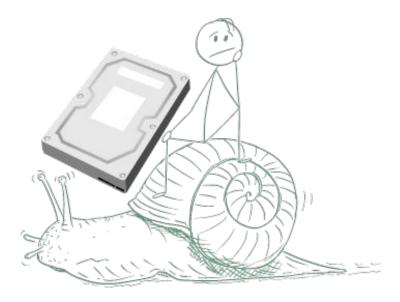
Where are the index stored when you search?

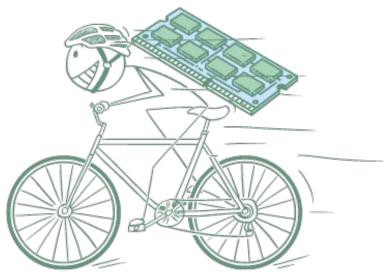
Do we have enough memory?

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Index Construction... Hardwares?

- How important is system memory (RAM)? Where are the index stored when you search? Do we have enough memory?
- Access to data in memory is much faster than access to data on disk.



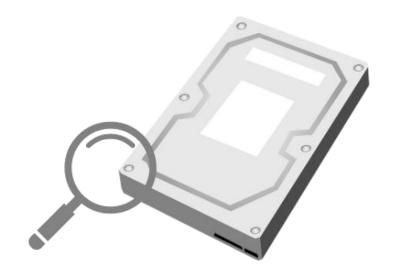






Index Construction... Hardwares?

- How important is system memory (RAM)?
- Access to data in memory is much faster than access to data on disk.
- Disk seeks: No data is transferred from disk while the disk head is being positioned.
- Therefore: Transferring one large chunk of data from disk to memory is faster than transferring many small chunks.



Analogy - Reading a book...

Assume 2 situations:

- You are reading a book and the information required is in the same page
- You are reading a book and the information required is in different pages. The time required to find the page is similar to the disk seek time.



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Let's talk about real world data

- RCV1 (Reuters Corpus Volume 1)
 - It is a collection of newswire articles produced by Reuters in 1996-1997.
 - It contains 804,414 manually labeled newswire documents.



RCV1 Corpus Stats

symbol	statistic	value
N	documents	800,000
L	avg. # tokens per document	200
M	term types	400,000
	avg. # bytes per token (incl. spaces/punct.)	6
	avg. # bytes per token (without spaces/punct.)	4.5
	avg. # bytes per term type	7.5
	non-positional postings	100,000,000

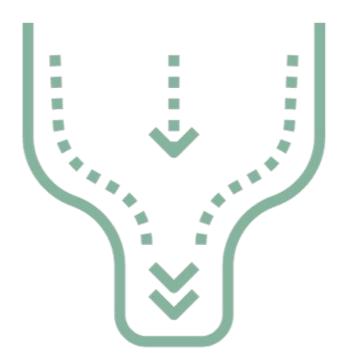
- Why #byter per token < #bytes per term type?</p>
- What is non-positional posting?





Main Bottleneck...

- 1. Except for small collections, basic sort cannot be done in memory
- 2. Need some form of external memory sort
- 3. Will also look at distributed and incremental versions







What if we do everything on disk?

- 1. The disk seek time is in milliseconds
- 2. If you have 100 million records, you will end up in months to sort the records
- 3. Do we have a faster alternative?

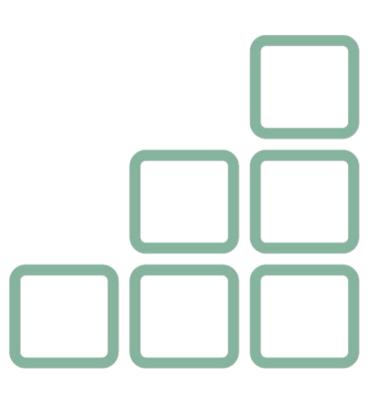






BSBI - Blocked sort-based Indexing (Sorting with fewer disk seeks)

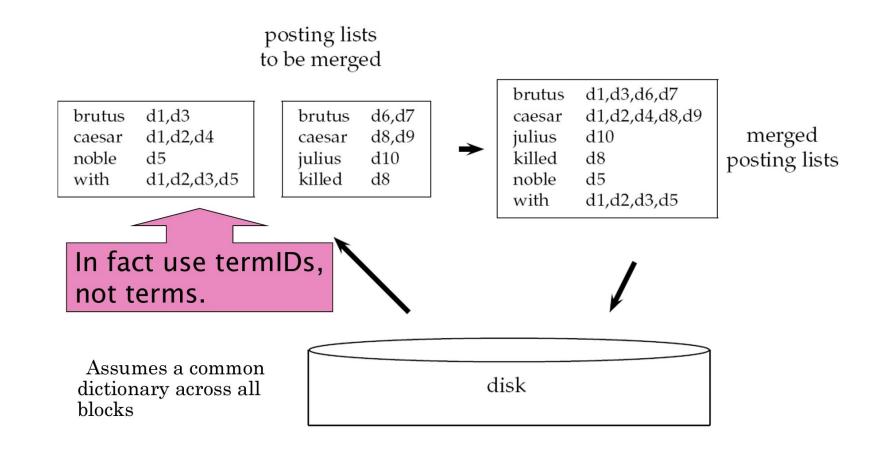
- 1. Basic idea of algorithm:
 - a. We create blocks that fit into the memory
 - b. Accumulate postings for each block, sort, write to disk.
 - c. Then merge the blocks into one long sorted order.







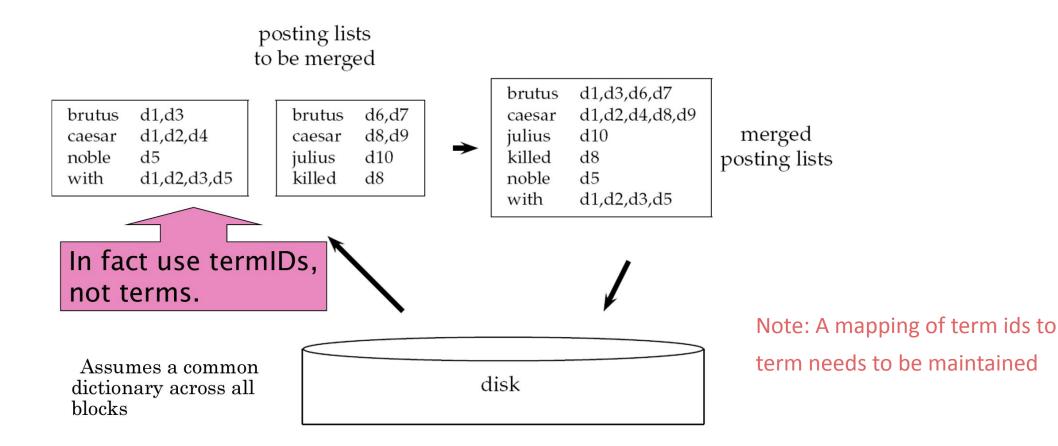
BSBI - Blocked sort-based Indexing







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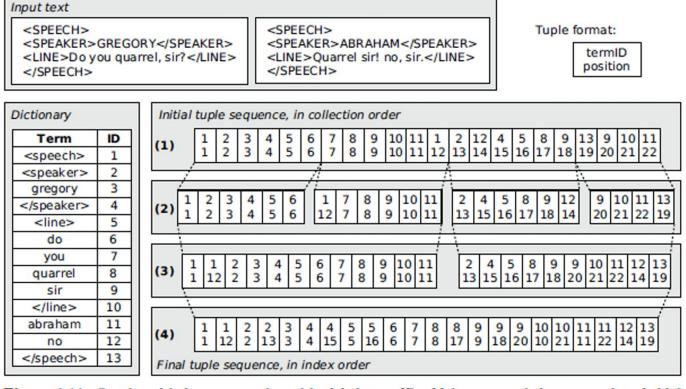


Figure 4.11 Sort-based index construction with global term IDs. Main memory is large enough to hold 6 (termID, position) tuples at a time. (1) \rightarrow (2): sorting blocks of size \leq 6 in memory, one at a time. (2) \rightarrow (3) and (3) \rightarrow (4): merging sorted blocks into bigger blocks.

BSBI - Blocked sort-based Indexing - Algorithm

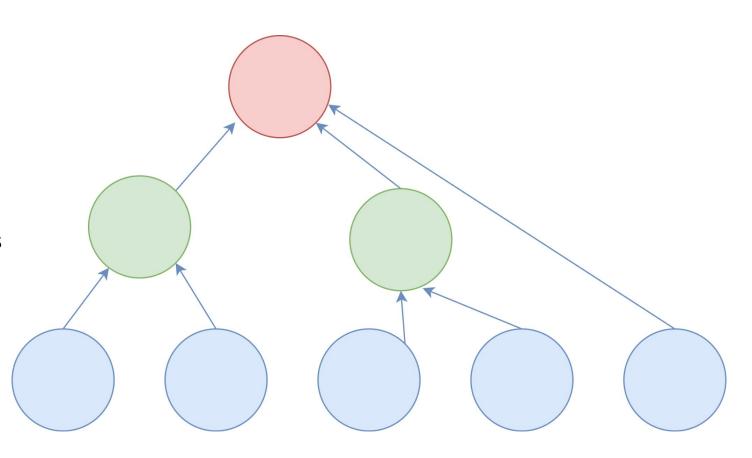
```
BSBINDEXCONSTRUCTION()
   n \leftarrow 0
    while (all documents have not been processed)
   do n \leftarrow n+1
        block \leftarrow ParseNextBlock()
5
        BSBI-INVERT(block)
        WRITEBLOCKTODISK(block, f_n)
    MERGEBLOCKS(f_1, \ldots, f_n; f_{\text{merged}})
```





BSBI - Blocked sort-based Indexing - Merging

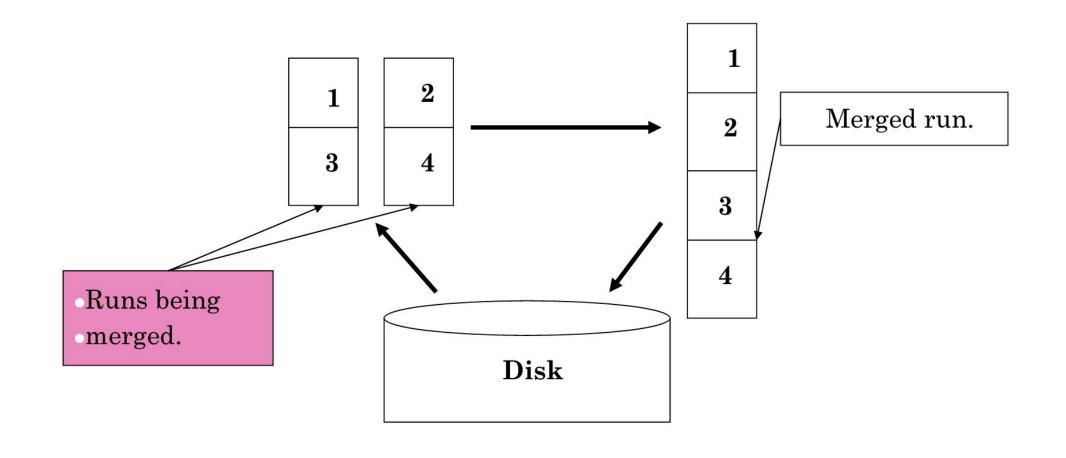
- 1. Two ways
 - a. Binary pairs and merge (has more disk seeks)
 - Priority Queue or Multiway Merge
 where you are reading from all blocks
 simultaneously







BSBI - Blocked sort-based Indexing - Binary Merging







BSBI - Blocked sort-based Indexing - N-way Merging

- 1. But it is more efficient to do a n-way merge, where you are reading from all blocks simultaneously
- 2. Providing you read decent-sized chunks of each block into memory, you're not killed by disk seeks





Single pass In-memory Indexing (SPIMI)

- 1. Key Idea: Generate separate dictionaries for each block, no need for term IDs
- 2. No sorting needed, accumulate postings as they occur
- 3. Finally merge
- 4. TC: O(T)

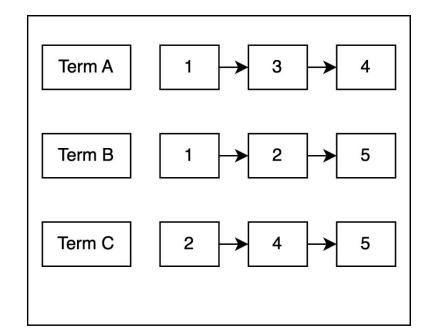
Term A	1	
Term B	1	

Term B	2
--------	---

Term B	5
Term C	5

Term A 3

Term A	4	
Term C	4	



Single pass In-memory Indexing (SPIMI) - Algorithm

```
SPIMI-INVERT(token_stream)
 1 output\_file = NewFile()
    dictionary = NewHash()
    while (free memory available)
    do token \leftarrow next(token\_stream)
        if term(token) ∉ dictionary
          then postings_list = ADDTODICTIONARY(dictionary, term(token))
          else postings_list = GETPOSTINGSLIST(dictionary, term(token))
        if full(postings_list)
          then postings_list = DoublePostingsList(dictionary, term(token))
        AddToPostingsList(postings_list, doclD(token))
10
     sorted\_terms \leftarrow SortTerms(dictionary)
     WRITEBLOCKTODISK(sorted_terms, dictionary, output_file)
    return output_file
       Merging of blocks is analogous to BSBI.
```

Indexing Times

Table 4.7 Building a schema-independent index for various text collections, using merge-based index construction with 512 MB of RAM for the in-memory index. The indexing-time dictionary is realized by a hash table with 2^{16} entries and move-to-front heuristic. The extensible in-memory postings lists are unrolled linked lists, linking between groups of postings, with a pre-allocation factor k = 1.2.

	Reading, Parsing & Indexing	Merging	Total Time
Shakespeare	1 sec	$0 \sec$	1 sec
TREC45	$71 \mathrm{sec}$	$11 \mathrm{sec}$	$82 \sec$
GOV2 (10%)	20 min	4 min	24 min
$\mathrm{GOV2}\ (25\%)$	51 min	$11 \min$	$62 \min$
$\mathrm{GOV2}\ (50\%)$	102 min	$25 \min$	$127 \min$
$\mathrm{GOV2}\ (100\%)$	$205 \min$	58 min	263 min

GOV2 is 426GB of text; using SPIMI

Note that parsing, dictionary construction and indexing all happen in conjunction with each other





Distributed Indexing

- 1. Data that cannot fit into a single hard disk :(
- 2. For web-scale indexing (don't try this at home!)
 - a. must use a distributed computing cluster
- 3. Individual machines are fault-prone
 - a. Can unpredictably slow down or fail
- 4. How do we exploit such a pool of machines?



Google data centers

- 1. Google data centers mainly contain commodity machines.
- 2. Data centers are distributed around the world (around 15 data centers?)
- 3. Estimate: a total of 2.5 million servers?
- 4. Estimate: Google installs 100,000 servers each quarter.
 - a. Spent \$30B on data centers from 2014-2017
- 5. This would be 10% of the computing capacity of the world!?!





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Exercise: If in a non-fault-tolerant system with 1,000 nodes, each node has 99.9% uptime, what is the uptime of the system?

Answer: ~37%

Parallel tasks

- We will use two sets of parallel tasks
 - **Parsers**
 - **Inverters**
- Break the input document collection into splits
- Each split is a subset of documents
- Master assigns a split to an idle parser machine
- Parser reads a document at a time and emits <termID,docID> pairs
- Parser writes pairs into j partitions
- Each for a range of terms' first letters
 - (e.g., a-f, g-p, q-z) here j=3.

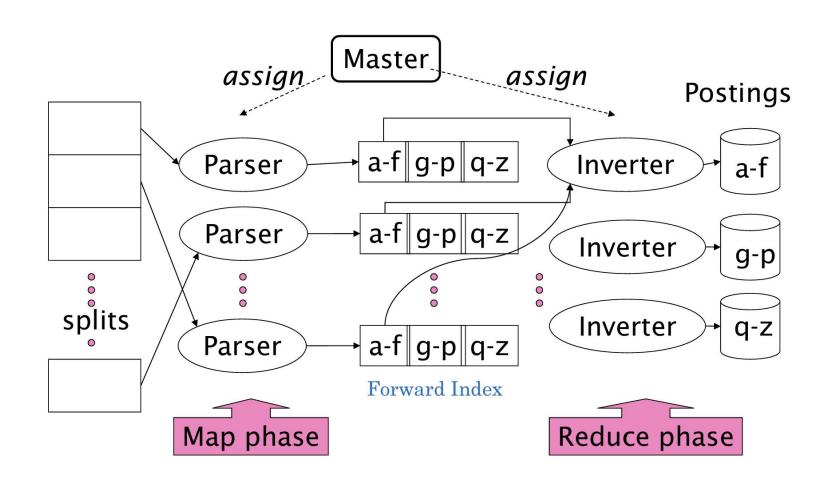
Inverter

- Collect all (term, doc) pairs for a partition
- Sorts and writes to postings list
- Each partition contains a set of postings





Data Flow







Dynamic Indexing

- Up to now, we have assumed that collections are static.
- They rarely are:
 - Documents come in over time and need to be inserted.
 - Documents are deleted and modified.
- This means that the dictionary and postings lists have to be modified:
 - Postings updates for terms already in dictionary
 - New terms added to dictionary





Simplest approach

- Maintain "big" main index
- New docs go into "small" auxiliary index
- Search across both, merge results
- Deletions
 - Invalidation bit-vector for deleted docs
 - Filter docs output on a search result by this invalidation bit-vector
- Periodically, re-index into one main index

Issues with main and auxiliary indexes

- Problem of frequent merges
 - you touch stuff a lot
- Poor performance during merge
- Actually:
 - Merging of the auxiliary index into the main index is efficient if we keep a separate file for each postings list.
 - Merge is the same as a simple append.
 - But then we would need a lot of files
 - inefficient for O/S.
- Assumption for the rest of the lecture: The index is one big file.
- In reality: Use a scheme somewhere in between (e.g., split very large postings lists, collect postings lists of length 1 in one file etc.)





Logarithmic Merge

- Maintain a series of indexes, each twice as large as the previous one.
- Keep smallest (Z₀) in memory
- Larger ones (I₀, I₁, ...) on disk
- If Z₀ gets too big (> n), write to disk as I₀
- or merge with IO(if I₀ already exists) as Z₁
- Either write merge Z₁ to disk as I₁ (if no I₁)
- Or merge with I₁to form Z₂, etc.
- Search Request: query in memory Z₀ and all currently valid indexes I_i on disk; merge results

Logarithmic Merge Algorithm

```
LMERGEADDTOKEN(indexes, Z_0, token)
  1 Z_0 \leftarrow \text{MERGE}(Z_0, \{token\})
  2 if |Z_0| = n
         then for i \leftarrow 0 to \infty
                do if I_i \in indexes
                       then Z_{i+1} \leftarrow \text{MERGE}(I_i, Z_i)
                               (Z_{i+1} \text{ is a temporary index on disk.})
                              indexes \leftarrow indexes - \{I_i\}
                       else I_i \leftarrow Z_i (Z_i becomes the permanent index I_i.)
                              indexes \leftarrow indexes \cup \{I_i\}
                              Break
 10
                Z_0 \leftarrow \emptyset
 11
LogarithmicMerge()
 1 Z_0 \leftarrow \emptyset (Z_0 is the in-memory index.)
 2 indexes \leftarrow \emptyset
 3 while true
     do LMERGEADDTOKEN(indexes, Z_0, GETNEXTTOKEN())
```

Logarithmic Merge

- Auxiliary and main index: index construction time is O(T²) as each posting is touched in each merge.
- Logarithmic merge: Each posting is merged O(log T) times, so complexity is O(T log T)
- So logarithmic merge is much more efficient for index construction
- But query processing now requires the merging of O(log T) indexes
 - Whereas it is O(1) if you just have a main and auxiliary index

Further issues with multiple indexes

- Corpus-wide statistics are hard to maintain
- E.g., when we spoke of spell-correction: which of several corrected alternatives do we present to the user?
 - We said, pick the one with the most hits
- How do we maintain the top ones with multiple indexes and invalidation bit vectors?
 - One possibility: ignore everything but the main index for such ordering
- Will see more such statistics used in results ranking

References

- 1. Slides provided by Sougata Saha (Instructor, Fall 2022 CSE 4/535)
- 2. Materials provided by Dr. Rohini K Srihari
- 3. https://nlp.stanford.edu/IR-book/information-retrieval-book.html