

## MDS573C – Image and Video Analytics

### Lab Exercise 1

- Assume a binary image size 5 x 5 and perform the following: Let  $V = \{1\}$  be the set of intensity value to define the adjacency.
- (a) Find the following digital paths and print the path traversal from any source pixel 'p' to any other source pixel 'q' 4-Path, 8-Path and m-Path
- (b) Find all the regions present in the image and declare the adjacent regions and disjoint regions.

### Definitions:

- 4-Path: Two pixels are adjacent if they are horizontally or vertically neighbors.
- 8-Path: Two pixels are adjacent if they are neighbors horizontally, vertically, or diagonally.
- m-Path: It's a mixed path, which combines both 4-path and 8-path depending on the scenario (generally avoids ambiguities that arise from diagonal adjacency in certain configurations).

### Regions:

- Regions are groups of connected pixels based on adjacency (4-path or 8-path).
- Disjoint regions are separate groups of connected pixels.



In [1]:

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1  import numpy as np
2  from collections import deque
3
4  # Define a binary image (5x5) where 1 is part of the region and 0
5  image = np.array([[1, 0, 0, 1, 0],
6                    [1, 1, 0, 0, 0],
7                    [0, 0, 0, 1, 1],
8                    [0, 1, 1, 0, 1],
9                    [0, 0, 1, 0, 0]])
10
11 # Define possible movement directions for 4-path and 8-path
12 four_path_moves = [(-1, 0), (1, 0), (0, -1), (0, 1)] # Up, Down,
13 eight_path_moves = [(-1, -1), (-1, 0), (-1, 1), (0, -1), (0, 1),
14
15 # Function to check if a pixel is within bounds and is part of the
16 def is_valid(image, x, y, visited):
17     return 0 <= x < image.shape[0] and 0 <= y < image.shape[1] and
18
19 # Breadth-First Search for finding the path
20 def bfs(image, start, end, moves):
21     queue = deque([start])
22     visited = np.zeros_like(image, dtype=bool)
23     visited[start[0], start[1]] = True
24     parent = {start: None}
25
26     while queue:
27         current = queue.popleft()
28         if current == end:
29             # Reconstruct path
30             path = []
31             while current is not None:
32                 path.append(current)
33                 current = parent[current]
34             path.reverse()
35             return path
36
37         for move in moves:
38             new_x, new_y = current[0] + move[0], current[1] + move[1]
39             if is_valid(image, new_x, new_y, visited):
40                 visited[new_x, new_y] = True
41                 parent[(new_x, new_y)] = current
42                 queue.append((new_x, new_y))
43
44     return None # No path found
45
46 # Find regions using DFS
47 def find_regions(image, moves):
48     visited = np.zeros_like(image, dtype=bool)
49     regions = []
50
51     def dfs(x, y, region):
52         stack = [(x, y)]
53         visited[x, y] = True
54         region.append((x, y))
55
56         while stack:
57             current_x, current_y = stack.pop()
58             for move in moves:
59                 new_x, new_y = current_x + move[0], current_y + move[1]
60                 if is_valid(image, new_x, new_y, visited):
61                     visited[new_x, new_y] = True

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62         stack.append((new_x, new_y))
63         region.append((new_x, new_y))
64
65     for i in range(image.shape[0]):
66         for j in range(image.shape[1]):
67             if image[i, j] == 1 and not visited[i, j]:
68                 region = []
69                 dfs(i, j, region)
70                 regions.append(region)
71
72     return regions
73
74 # Part (a): Finding the paths
75 start_pixel = (0, 0) # Source pixel 'p'
76 end_pixel = (3, 2)   # Destination pixel 'q'
77
78 # 4-Path traversal
79 four_path = bfs(image, start_pixel, end_pixel, four_path_moves)
80 print(f"4-Path from {start_pixel} to {end_pixel}: {four_path}")
81
82 # 8-Path traversal
83 eight_path = bfs(image, start_pixel, end_pixel, eight_path_moves)
84 print(f"8-Path from {start_pixel} to {end_pixel}: {eight_path}")
85
86 # Mixed Path (m-Path)
87 m_path = bfs(image, start_pixel, end_pixel, four_path_moves + eig
88 print(f"m-Path from {start_pixel} to {end_pixel}: {m_path}")
89
90 # Part (b): Finding regions and identifying adjacent and disjoint
91 four_regions = find_regions(image, four_path_moves)
92 eight_regions = find_regions(image, eight_path_moves)
93
94 print(f"4-Path Regions: {four_regions}")
95 print(f"8-Path Regions: {eight_regions}")
96
97 # Declare adjacent and disjoint regions
98 def region_adjacency(regions, moves):
99     adjacent_regions = []
100     for i, region1 in enumerate(regions):
101         for j, region2 in enumerate(regions):
102             if i != j:
103                 for (x1, y1) in region1:
104                     for move in moves:
105                         x2, y2 = x1 + move[0], y1 + move[1]
106                         if (x2, y2) in region2:
107                             adjacent_regions.append((i, j))
108                             break
109                     else:
110                         continue
111                 break
112     return adjacent_regions
113
114 four_adjacent_regions = region_adjacency(four_regions, four_path_
115 eight_adjacent_regions = region_adjacency(eight_regions, eight_pa
116
117 print(f"4-Path Adjacent Regions: {four_adjacent_regions}")
118 print(f"8-Path Adjacent Regions: {eight_adjacent_regions}")
119
```

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4-Path from (0, 0) to (3, 2): None
8-Path from (0, 0) to (3, 2): None
m-Path from (0, 0) to (3, 2): None
4-Path Regions: [[(0, 0), (1, 0), (1, 1)], [(0, 3)], [(2, 3), (2, 4), (3, 4)], [(3, 1), (3, 2), (4, 2)]]
8-Path Regions: [[(0, 0), (1, 0), (1, 1)], [(0, 3)], [(2, 3), (2, 4), (3, 2), (3, 4), (3, 1), (4, 2)]]
4-Path Adjacent Regions: []
8-Path Adjacent Regions: []

```

#### Explanation:

- **Paths:**
- We use Breadth-First Search (BFS) to find the shortest path between two points for both 4-path, 8-path, and m-path.
- The traversal is done using defined neighbor movements for each type of path.
- **Regions:**
- We identify regions using Depth-First Search (DFS). Regions are groups of connected pixels that share a common adjacency relation (either 4-path or 8-path).
- Adjacent and disjoint regions are determined by checking if any pixel in one region is adjacent to any pixel in another region based on the allowed movements (4-path or 8-path).

#### Output:

The code will output:

- The digital paths (4-path, 8-path, m-path) from a source pixel p to another pixel q.
- The regions in the image based on both 4-path and 8-path.
- The adjacency relations between regions based on their neighbors.

## Interpretation and Analysis of the Results:

### Part (a) – Digital Paths

- **4-Path:** The 4-path restricts movement between pixels to horizontal and vertical directions (up, down, left, right). This type of path ensures that only adjacent pixels in the strictest sense (not diagonal) are considered connected.
- **Interpretation:** The 4-path tends to result in a longer traversal for most images because it excludes diagonal moves, limiting the direct connectivity between certain pixels. This constraint makes the paths more step-by-step, which can increase the distance between pixels, especially if they are diagonally separated in the image.
- **Key Insight:** 4-path adjacency is useful when diagonal connections are undesirable (e.g., in certain medical images, where the definition of a region needs to be conservative).
- **8-Path:** The 8-path expands the idea of connectivity to include diagonal movements. This makes the path between two pixels shorter in many cases because diagonal moves can help traverse the image more efficiently.
- **Interpretation:** With 8-path, the traversal tends to be faster, and the path is shorter because diagonal neighbors provide more flexibility. It mimics a more natural connectivity (as we would expect in most real-life images).

- **Key Insight:** The 8-path is particularly useful in scenarios where diagonal connectivity is relevant or acceptable, such as when segmenting complex objects in images, as it can capture more pixel connections.
- **m-Path:** The m-path (mixed-path) combines both 4-path and 8-path, and is typically used to resolve situations where diagonal paths can introduce ambiguity. This path offers more flexibility while avoiding unnecessary diagonal connections that could merge regions that should remain separate.
- **Interpretation:** The m-path can adapt to different situations, using diagonal moves when appropriate but avoiding them if they would create visual or structural issues. It attempts to balance the strictness of 4-path and the flexibility of 8-path.
- **Key Insight:** The m-path is useful when we want to avoid ambiguities in segmentation tasks but still need flexibility in pixel connectivity.

## Part (b) – Regions

- **Region Identification:** In our binary image, we identified regions as connected sets of pixels with intensity value 1. These regions depend on the type of path used to define connectivity (4-path or 8-path).

### - 4-Path Regions:

Regions are generally smaller and more fragmented because of the restricted connectivity rules. This can result in multiple small regions being defined, even if they are diagonally connected.

- **8-Path Regions:** Regions are more likely to be larger and more unified since diagonal connections are allowed. As a result, pixels that might have been separated in the 4-path regions are now part of the same region.
- **Example:**

In the provided image, for 4-path, regions like the cluster of 1s near the bottom left and the cluster near the top right might be considered separate regions. For 8-path, these clusters might be connected diagonally, resulting in a single larger region.

- **Key Insight:** In practice, 8-path regions are often more relevant in applications where diagonal connections between objects are meaningful (e.g., detecting connected objects in natural images). However, for applications like grid-like data (city layouts, pixelated structures), 4-path regions provide more precise results.
- **Adjacent and Disjoint Regions:** After identifying the regions, we determine whether two regions are adjacent or disjoint. Adjacent regions share a boundary pixel, while disjoint regions do not.
- **Interpretation:** In real-world applications, knowing whether two regions are adjacent can help in merging regions or determining relationships between objects. For instance, in image processing tasks, adjacent regions might represent parts of a single larger object that were separated due to noise or other factors.
- **Key Insight:** Identifying adjacent and disjoint regions is critical for tasks like region

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