

CS 325 - Analysis of Algorithms Prof. Julianne Schutford Spring 2021

**Homework 3** 

Greedy Approach

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- a) The crucial part of the description is that the distances from the starting point are given in a *sorted* list. Given this list, a greedy algorithm would be as follows.
  - Each day look at the map and highlight the farthest reachable hotel.
  - Drive to that hotel, stay there at night.
  - Do this until arriving at the destination.

This algorithm would minimize the number of days it takes to get to the destination. Also, we must assume that there is at least one hotel in reach every day.

Pseudocode for the algorithm is as follows.

```
FUNCTION roadtrip (Vector x, int d)
      LET stayed_hotels <- new Vector()
      LET i <- 1
      LET position <- 0
      WHILE position != x_n DO
                                            // do until reaching to the end
                                            // max position I can travel to today
           LET limit <- position + d
           IF x_i > limit THEN
                                            // hotel cannot be reached
                  RETURN []
            END IF
            WHILE limit >= x_i DO
                                            // find the furthest hotel within reach
                 position <-x_i
                 i++
            END WHILE
           stayed_hotels.insert(i)
                                           // mark it to stay at night
      END WHILE
      RETURN hotels
END FUNCTION
```

I would like to explain the pseudo code since some parts may not be clear.

// hotel cannot be reached **IF**  $x_i > limit$  **THEN** RETURN []

**END IF** 

This if check is necessary. If the gap between two hotels is greater than the distance we can travel per day, than we cannot complete the trip. For example,

x = [50, 100, 175, 200, 250]d = 50

First night, we will stay in the first hotel and second night in the second hotel. However, on the third day we will not reach the next hotel since the d < 175 - 100. Therefore, the function returns an empty list rather than the hotels we stayed in.

b) Running time of the algorithm is  $\Theta(n)$ .

There are two important points in the discussion. First, the input list is sorted. If it was not sorted, then we had to sort the list and that would make the running time  $\Theta(n \times log n)$ .

The second point is that we assume there is at least one hotel in reach every day. If this is not the case, the algorithm will return quicker for some inputs. In that case, we cannot have this algorithm's running time in  $\Theta$  notation. Instead, we have to use O notation.

Nested while loops may trick us to conclude that the running time is  $\Theta(n^2)$ . However, these while loops iterate over the same vector and the end condition is reaching to the end of this vector. Therefore, the running time is equivalent to traversing the list one time, which is  $\Theta(n)$ .

I don't know why the full mark is given to the algorithm with  $\Theta(n \ x \ log \ n)$  running time in the rubric. There was a similar question in the class and the difference is that that question had a penalty mechanism and we were to minimize the penalty not the number of days. In that case the running time was  $\Theta(n \ x \ log \ n)$ . However, the question in the homework does not have such a mechanism. So, I believe that something is confused with that problem.

### **Q2)**

A greedy solution maximizes the utility in each step and never looks back. Last to start is a greedy approach because it maximizes the "available time" interval for other activities by choosing an activity. Informally, it tries to justify the activities to the right so that it can fit more activities into the available time interval on the left side.

The algorithm has the optimal substructure property. When you sort the activities based on the start time, last to start will always choose the last activity in the list because we know that it has the latest starting time.

Below lines repeat the discussion above, formally.

 $s_i$ : start of the activity i

a<sub>i</sub>: activity j

 $S_{ij}$ : set of activities between activity i and activity j

$$s_m = max \{ s_k \colon a_k \in S_{ij} \}$$

then the following two conditions must hold

- 1.  $a_m$  is used in an optimal subset of  $S_{ii}$
- 2.  $S_{im} = \emptyset$ , leaving  $S_{mi}$  as the only subproblem

meaning that the greedy solution produces an optimal solution.

Let  $S_k = \{a_i \in S_k : f_i \le s_k\}$  be the set of activities that finish before activity  $a_k$  starts.

Consider any non-empty subproblem  $S_k$  with activity  $a_m$  having the latest starting time. Then,  $a_m$  included in some maximum-size subset of mutually compatible activities of  $S_k$ .

## Proof that produced solution is correct<sup>1</sup>

Let  $A_k$  be an optimal solution for  $S_k$  and  $a_j$  be the activity in  $A_k$  with the latest start time.

- If  $a_i = a_m$  then the condition holds.
- If  $a_i \neq a_m$  then construct  $A_k' = A_k \{a_i\} \cup \{a_m\}$ .

Since  $s_m \ge s_i \Rightarrow A_k'$  is still optimal.

The activities in  $A_k$  are disjoint since the activities in  $A_k$  are disjoint,  $a_j$  is the last activity in  $A_k$  to start and  $s_m \le s_j$ . Since  $|A_k| = |A_k'|$ , we conclude that  $A_k$  is a maximum-size subset of mutually compatible activities for  $S_k$  and include  $a_m$ .

Another proof would be having first to finish proof and reversing the time, but mathematics does not work that way I guess:)

# **Q3**)

# Description:

Given id, start time and finish time of activities, for each test case, last to start activity selection can be described as follows.

- Store all activities in an Activity struct that has id, start time and finish time attributes.
- Put all activities in a vector.
- Sort them according to the start time in ascending order.
- Take the last Activity in the vector since it has the latest start time.
- Go back in the vector and find other Activities that does not collide with the last selected Activity and have the latest start time.
- Print the results.
- Do this until reaching the end of the file.

<sup>&</sup>lt;sup>1</sup> I've taken the proof in the course book (Introduction to Algorithms, Third Edition) and the course notes for first-to-finish choice then modified it to have a proof for last-to-start algorithm

#### Pseudocode:

I used the same merge sort algorithm from the first homework assignment. It sorts the Activities according to the starting time. So, I will not include the pseudocode for that.

```
STRUCT Activity
      INT id, start, finish
END STRUCT
FUNCTION last_to_start ( Vector sorted_activities )
      LET n <- length (sorted_activities)
      LET selected activities <- new Vector()
      selected_activities.insert( last element of sorted_activities ) // last element is always
                                                                  // included
      LET itr <- n-1
      FOR m <- n-2 to 0 DO
                                                                   // start from the end
            IF sorted_activities[m].finish <= sorted_activities[itr].start THEN
                  selected_activities.insert (sorted_activities[m]) // take if the activity
                                                                      // does not collide
                  itr <- m:
            END IF
      END FOR
      RETURN selected_activities
END FUNCTION
FUNCTION main()
      FILE input := read(act.txt)
      IF file is NOT correctly opened THEN
            print "Error reading file"
            exit
      END IF
      LET test_case <- 1
                                                               // Set number
                                                               // number of activities in this set
      LET test_size <- 0
```

```
// read number of activities
WHILE test size <- cin DO
      LET all_activities = new Vector<Activity>()
                                                                    // read the attributes
      FOR i <- 0 to test_size DO
            LET id <- 0
            LET start <- 0
            LET finish <- 0
            all_activities.insert (new Activity<id, start finish>) // put them to a vector
      END FOR
      // sort activities based on start time in ascending order
      LET sorted_activities <- merge_sort( all_activities )
      // run last to start greedy algorithm and take the result
      LET selected_activities <- last_to_start (sorted_activities)
      // Print the results
      LET size <- length ( selected_activities )
      print "Set " + test_case
      print "Maximum number of activities = " + size
      FOR i <- size to 0 DO
            print " " + selected_activities[ i ]
      END FOR
      Clear all the variables
      test_case++
END WHILE
```

**END FUNCTION** 

## Explanation

In main, id, start time and end time of the activities are read from the act.txt file and saved into a vector. Then, activities are sorted based on the start time by using merge sort in ascending order and sorted list is given to the last-to-start function.

Explanation is the same as in Q2. Algorithm right justifies the activities based on the start time by choosing the last-to-start activity that does not collide with any other activity chosen before. By doing that, it opens up space on the left hand side so that it can put more activities.

### Theoretical Running Time

Last-to-start function iterates over the activities one time and spends constant time on each activity. So, the running time of the algorithm is  $\Theta(n)$  if we are given a list of activities sorted according to the start time. In any other case, we have to sort the list. Sorting takes  $\Theta(n \, x \, log \, n)$  time and makes the overall running time  $\Theta(n \, x \, log \, n)$  as well.