

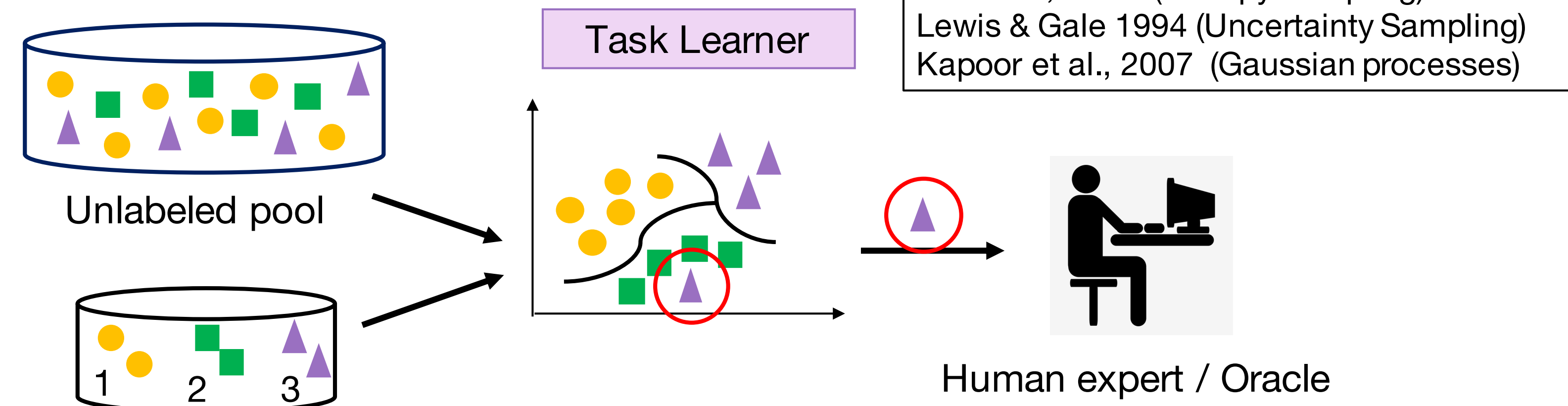
## Abstract

- **Motivation:** Obtaining labels is expensive and time consuming
- **Problem Statement:** Developing a task-agnostic algorithm to query the most *representative* unlabeled samples for labeling.
- **Strategy:** Using adversarial learning to measure *representativeness* of samples without training for the main-stream task.
- **Performance:** State-of-the-art on image classification + semantic segmentation

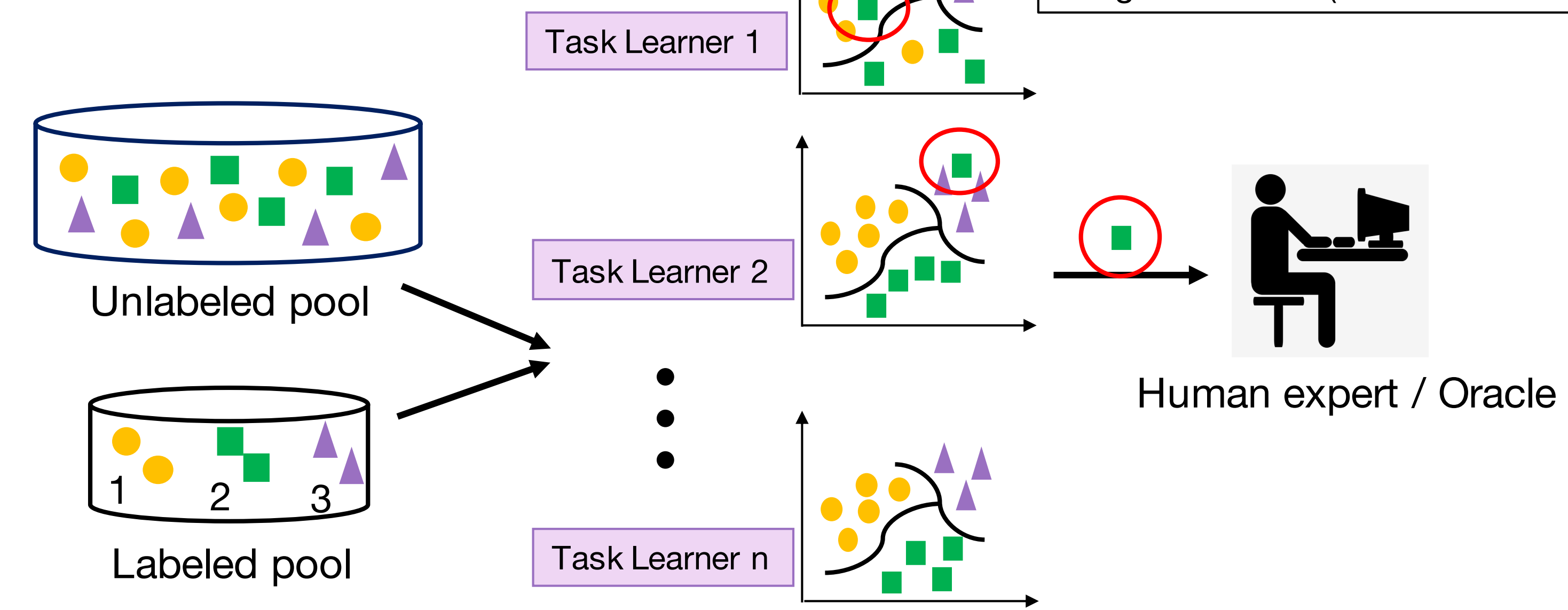
## Active Learning

Approaches in active learning have been all *task-dependent*.

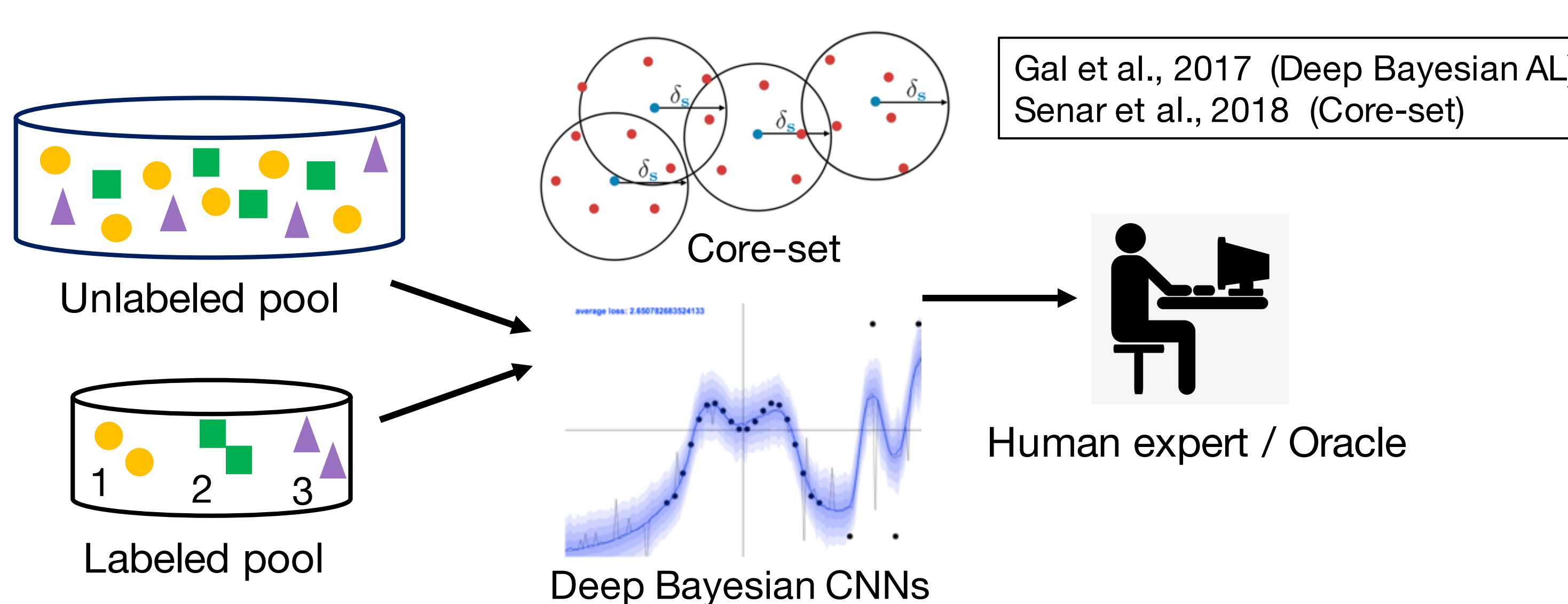
### Explicit uncertainty measurement



### Query-By-Committee



### Representation-based / Bayesian uncertainty



## Variational Adversarial Learning (VAAL)

### VAE's Objective Function

$$\mathcal{L}_{VAE} = \lambda_1 \mathcal{L}_{VAE}^{trd} + \lambda_2 \mathcal{L}_{VAE}^{adv}$$

where:

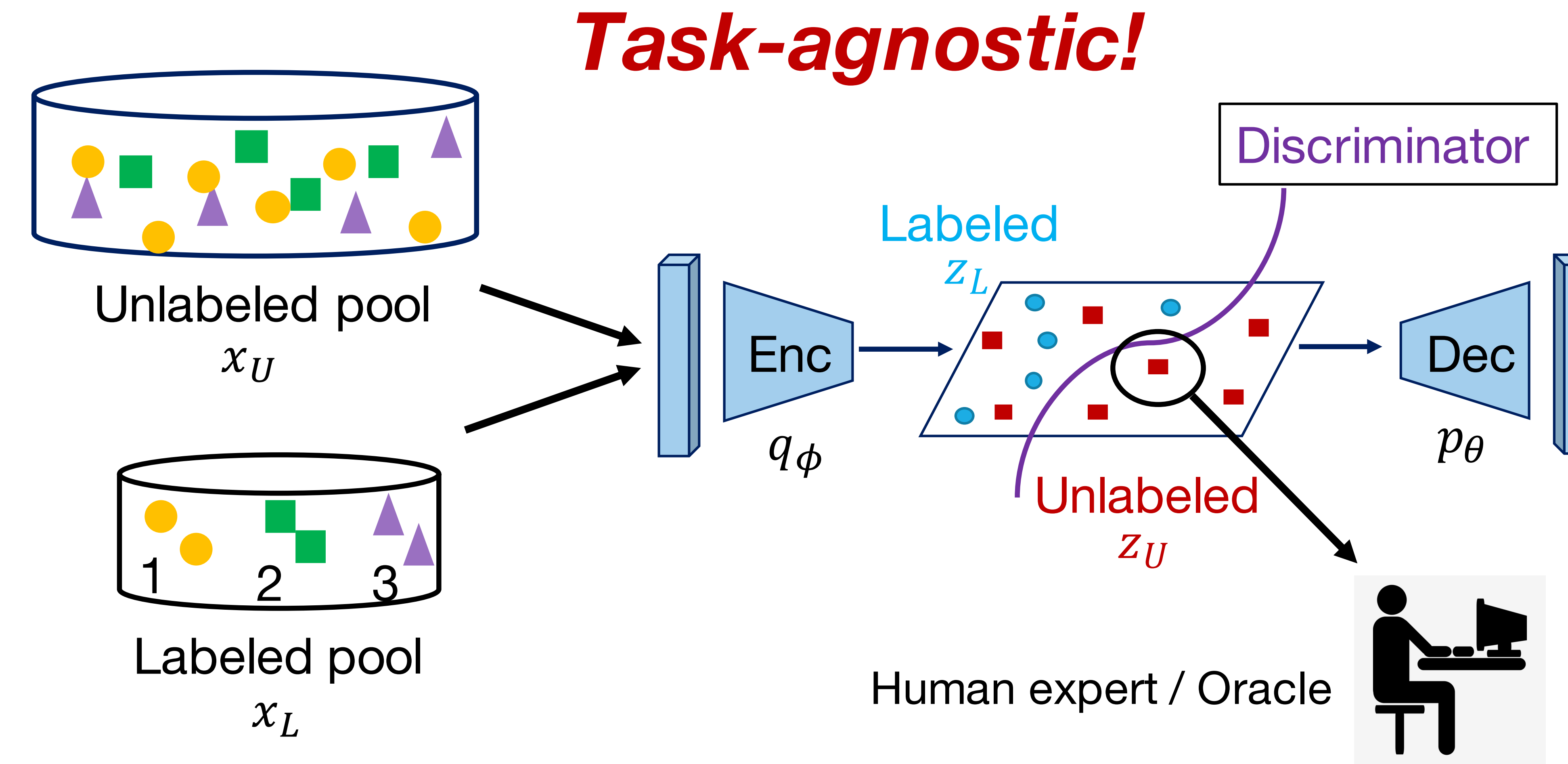
- $\mathcal{L}_{VAE}^{trd} \rightarrow$  VAE's transductive loss
- $\mathcal{L}_{VAE}^{adv} \rightarrow$  VAE's adversarial loss
- $\lambda_1, \lambda_2 \rightarrow$  Weighting factors

$$\mathcal{L}_{VAE}^{trd} = \mathbb{E}[\log p_{\theta}(x_L|z_L)] - \beta D_{KL}(q_{\phi}(z_L|x_L)||p(z)) + \mathbb{E}[\log p_{\theta}(x_U|z_U)] - \beta D_{KL}(q_{\phi}(z_U|x_U)||p(z))$$

$$\mathcal{L}_{VAE}^{adv} = -\mathbb{E}[\log(D(q_{\phi}(z_L|x_L)))] - \mathbb{E}[\log(D(q_{\phi}(z_U|x_U)))]$$

### Discriminator's Objective Function

$$\mathcal{L}_D = -\mathbb{E}[\log(D(q_{\phi}(z_L|x_L)))] - \mathbb{E}[\log(1 - D(q_{\phi}(z_U|x_U)))]$$



## Algorithm & Sampling Strategy

### Algorithm 1 Variational Adversarial Active Learning

**Input:** Labeled pool  $(X_L, Y_L)$ , Unlabeled pool  $(X_U)$ , Initialized models for  $\theta_T, \theta_{VAE}$ , and  $\theta_D$

**Input:** Hyperparameters: epochs,  $\lambda_1, \lambda_2, \alpha_1, \alpha_2, \alpha_3$

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1: for e = 1 to epochs do
2:   sample  $(x_L, y_L) \sim (X_L, Y_L)$ 
3:   sample  $x_U \sim X_U$ 
4:   Compute  $\mathcal{L}_{VAE}^{trd}$ 
5:   Compute  $\mathcal{L}_{VAE}^{adv}$ 
6:    $\mathcal{L}_{VAE} \leftarrow \lambda_1 \mathcal{L}_{VAE}^{trd} + \lambda_2 \mathcal{L}_{VAE}^{adv}$ 
7:   Update VAE by descending stochastic gradients:
8:    $\theta'_{VAE} \leftarrow \theta_{VAE} - \alpha_1 \nabla \mathcal{L}_{VAE}$ 
9:   Compute  $\mathcal{L}_D$ 
10:  Update  $D$  by descending its stochastic gradient:
11:   $\theta'_D \leftarrow \theta_D - \alpha_2 \nabla \mathcal{L}_D$ 
12:  Train and update  $T$ :
13:   $\theta'_T \leftarrow \theta_T - \alpha_3 \nabla \mathcal{L}_T$ 
14: end for
15: return Trained  $\theta_T, \theta_{VAE}, \theta_D$ 

```

### Algorithm 2 Sampling Strategy in VAAL

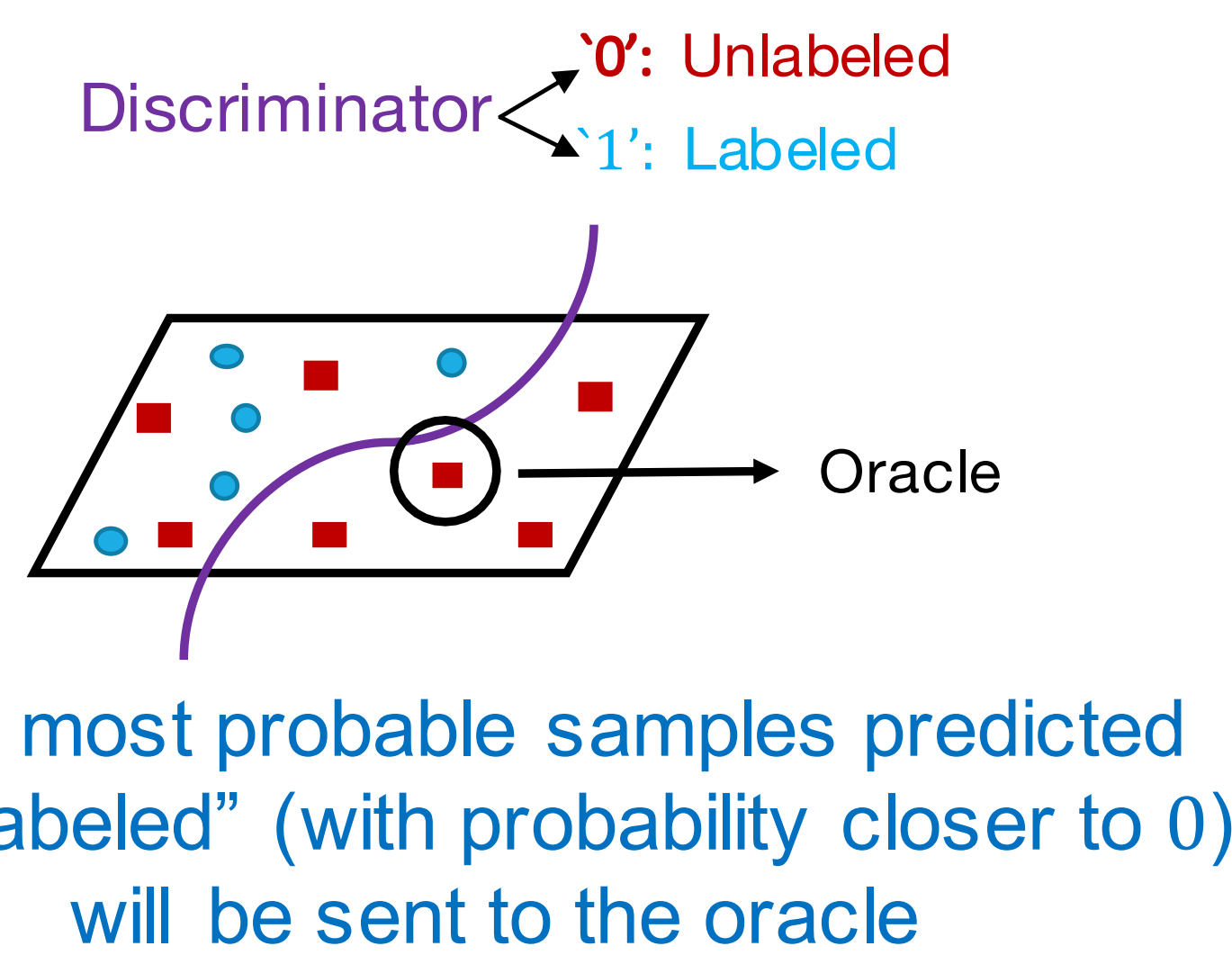
**Input:**  $b, X_L, X_U$

**Output:**  $X_L, X_U$

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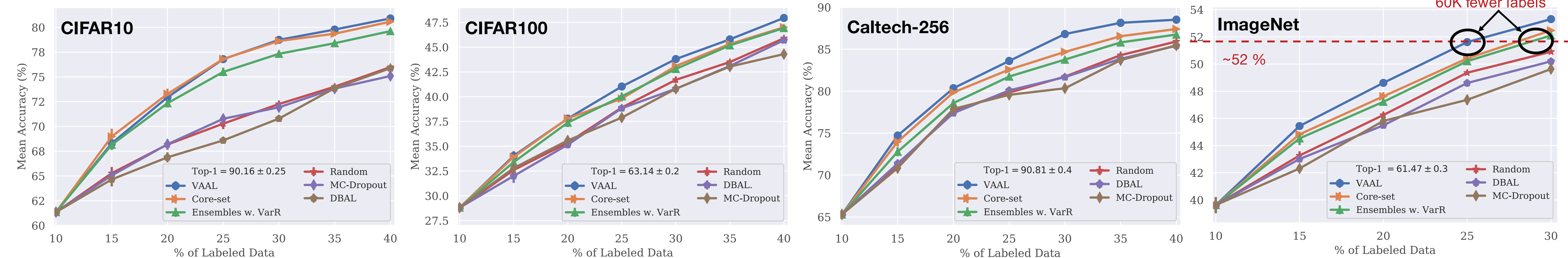
1: Select samples  $(X_s)$  with  $\min_b \{\theta_D(z_U)\}$ 
2:  $Y_o \leftarrow \mathcal{ORACLE}(X_s)$ 
3:  $(X_L, Y_L) \leftarrow (X_L, Y_L) \cup (X_s, Y_o)$ 
4:  $X_U \leftarrow X_U - X_s$ 
5: return  $X_L, X_U$ 

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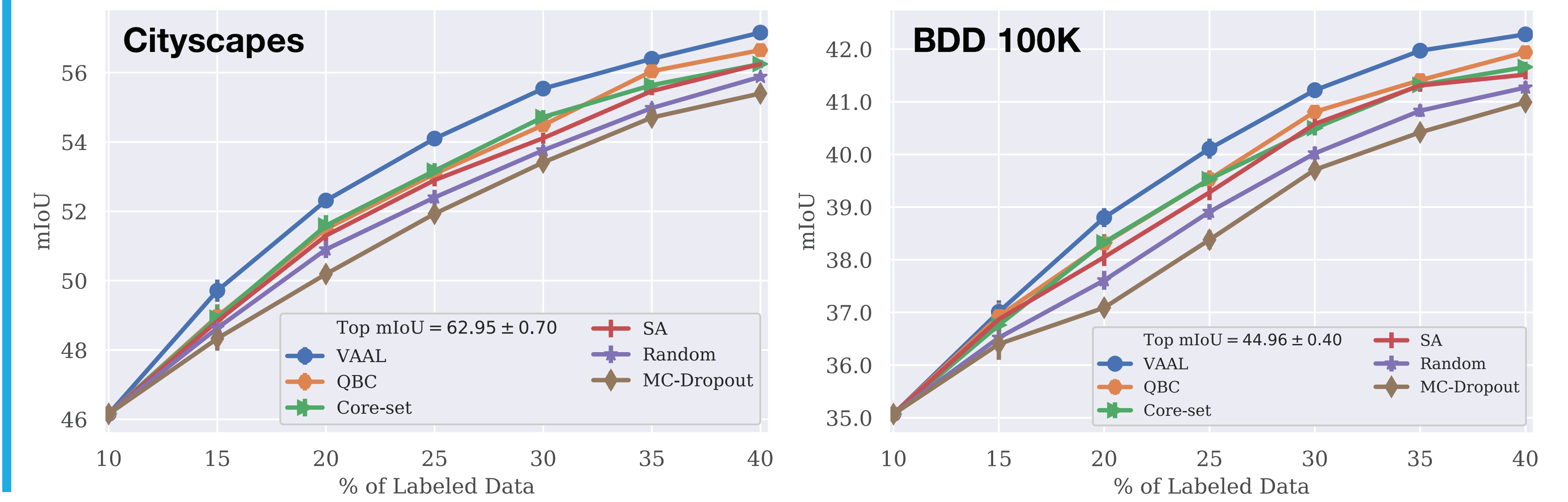


## Results on Image Classification and Semantic Segmentation Benchmarks

### Image Classification Benchmarks



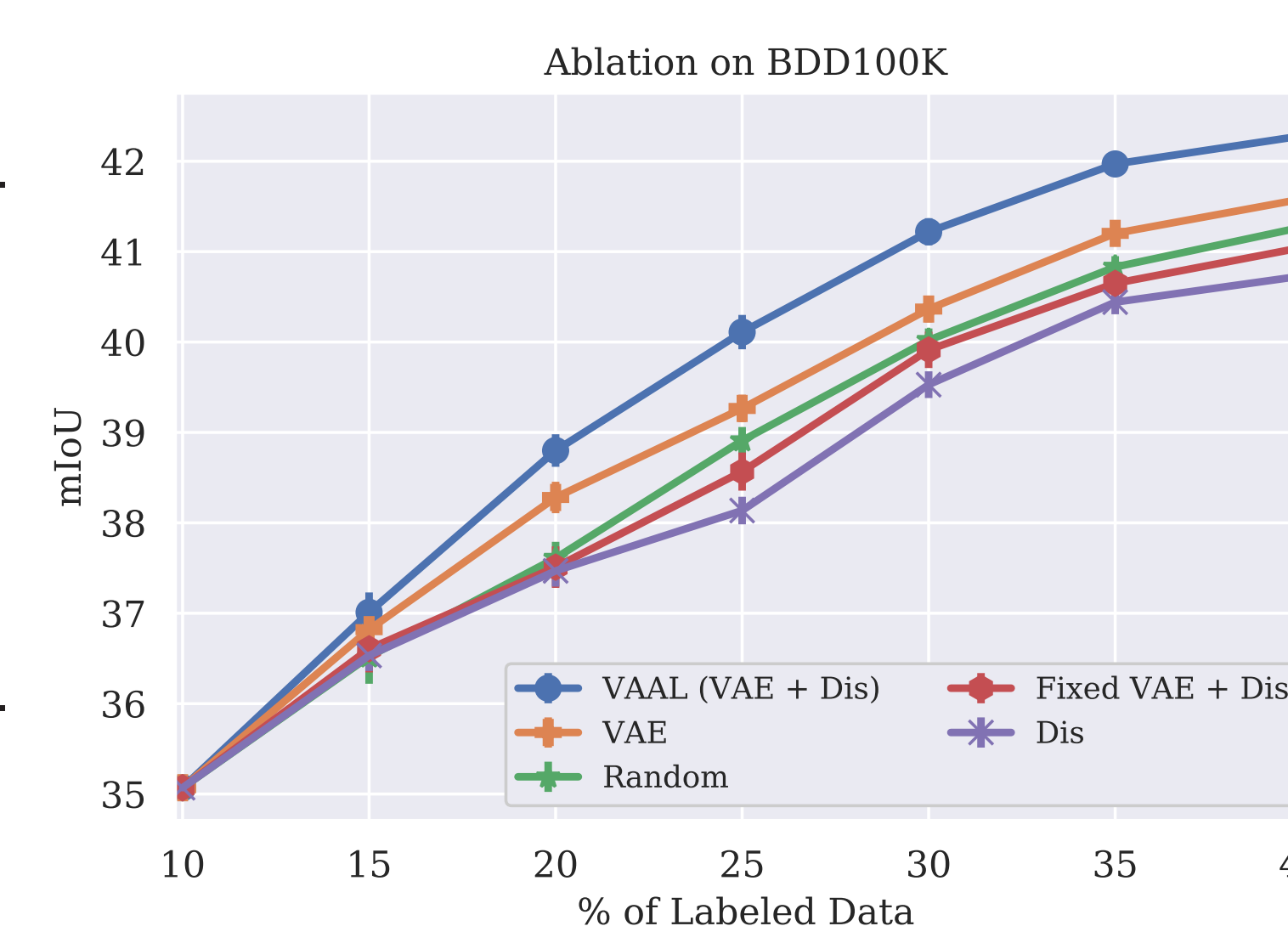
### Semantic Segmentation Benchmarks



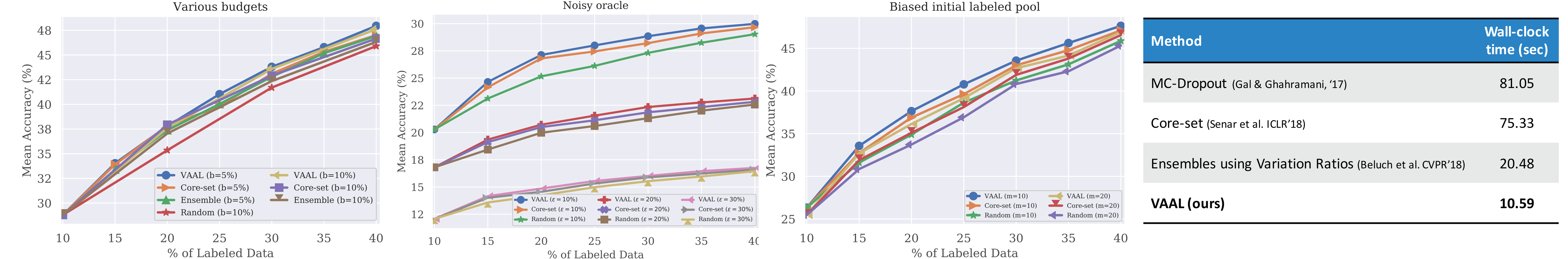
## Ablation

Key roles in VAAL in the order of importance:

1. VAE + Discriminator
2. VAE (no Discriminator)
3. Fixed VAE + Discriminator (no adversarial learning) < random
4. Discriminator (no VAE) < random



## Robustness & Time Analysis



## Source Code

## References

- [1] Kuo, Weicheng, et al. "Cost-Sensitive Active Learning for Intracranial Hemorrhage Detection." International Conference on Medical Image Computing and Computer-Assisted Intervention. Springer, Cham, 2018.
- [2] Sener, Ozan, and Silvio Savarese. "Active learning for convolutional neural networks: A core-set approach." ICLR (2017).
- [3] Gal, Yarin, Riashat Islam, and Zoubin Ghahramani. "Deep bayesian active learning with image data." ICML (2017)
- [4] Beluch, William H., et al. "The power of ensembles for active learning in image classification." CVPR (2018)