INTRODUCTION

- Eigen Vector-
- In linear algebra, an eigenvector or characteristic vector of a square matrix is a vector that does not changes its direction under the associated linear transformation.
- In other words If V is a vector that is not zero, than it is an
 eigenvector of a square matrix A if Av is a scalar multiple of v.
 This condition should be written as the equation:

$$AV = \lambda v$$

Contd....

- Eigen Value-
- In above equation λ is a scalar known as the **eigenvalue** or **characteristic value** associated with eigenvector **v**.

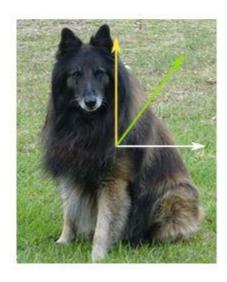
 We can find the eigenvalues by determining the roots of the characteristic equation-

$$|A - \lambda I| = 0$$

Eigenvector and Eigenvalue

They have many uses!

A simple example is that an eigenvector **does not change direction** in a transformation:

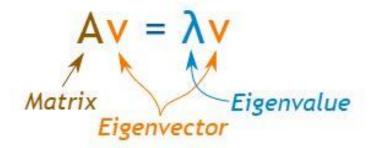




How do we find that vector?

The Mathematics Of It

For a square matrix A, an Eigenvector and Eigenvalue make this equation true:



an eigenvector is

with a matching eigenvalue of 6

Let's do some <u>matrix multiplies</u> to see if that is true.

Av gives us:

$$\begin{bmatrix} -6 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = \begin{bmatrix} -6 \times 1 + 3 \times 4 \\ 4 \times 1 + 5 \times 4 \end{bmatrix} = \begin{bmatrix} 6 \\ 24 \end{bmatrix}$$

λν gives us:

$$6\begin{bmatrix}1\\4\end{bmatrix}=\begin{bmatrix}6\\24\end{bmatrix}$$

Yes they are equal!

So we get $Av = \lambda v$ as promised.

How do we find these eigen things?

We start by finding the eigenvalue. We know this equation must be true:

$$Av = \lambda v$$

Next we put in an (identity matrix) so we are dealing with matrix-vs-matrix:

$$Av = \lambda Iv$$

Bring all to left hand side:

$$Av - \lambda Iv = 0$$

If v is non-zero then we can (hopefully) solve for λ using just the determinant:

$$|A - \lambda I| = 0$$

Let's try that equation on our previous example:

Start with
$$|A - \lambda I| = 0$$

Example: Solve for λ

$$\left| \begin{bmatrix} -6 & 3 \\ 4 & 5 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right| = 0$$
Which is:

$$\begin{vmatrix} -6-\lambda & 3 \\ 4 & 5-\lambda \end{vmatrix} = 0$$

Calculating that determinant gets:

$$(-6-\lambda)(5-\lambda)-3\times 4=0$$

$$\lambda^2 + \lambda - 42 = 0$$

$$\lambda = -7 \text{ or } 6$$



What is the purpose of these?

One of the cool things is we can use <u>matrices</u> to do <u>transformations</u> in space, which is used a lot in computer graphics.

In that case the eigenvector is "the direction that doesn't change direction" !

And the eigenvalue is the scale of the stretch:

- · 1 means no change,
- · 2 means doubling in length,
- -1 means pointing backwards along the eigenvalue's direction
- etc

Why "Eigen"



Eigen is a German word meaning "own" or "typical"

"das ist ihnen eigen" is German for "that is typical of them"

Sometimes in English we use the word "characteristic", so an eigenvector can be called a "characteristic vector".

Solution

We have

Which are eigenvectors? What are their eigenvalues?

 $A = \begin{pmatrix} 2 & 2 \\ -4 & 8 \end{pmatrix}$ and vectors $v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ $w = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

 $Av = \begin{pmatrix} 2 & 2 \\ -4 & 8 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \end{pmatrix} = 4v.$

 $Aw = \begin{pmatrix} 2 & 2 \\ -4 & 8 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 0 \end{pmatrix}.$

v is an eigenvector

w is not an eigenvector

Hence, ν is an eigenvector of A, with eigenvalue $\lambda = 4$. On the other hand,

which is not a scalar multiple of w. Hence, w is not an eigenvector of A.

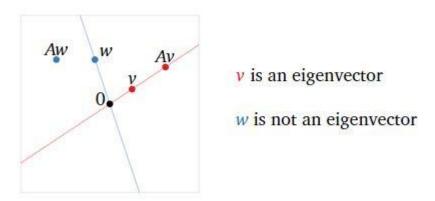
Aw

Av

W

Example (An eigenvector with eigenvalue 0). 🕶

To say that $Av = \lambda v$ means that Av and λv are collinear with the origin. So, an eigenvector of A is a nonzero vector v such that Av and v lie on the same line through the origin. In this case, Av is a scalar multiple of v; the eigenvalue is the scaling factor.



For matrices that arise as the standard matrix of a linear transformation, it is often best to draw a picture, then find the eigenvectors and eigenvalues geometrically by studying which vectors are not moved off of their line. For a transformation that is defined geometrically, it is not necessary even to compute its matrix to find the eigenvectors and eigenvalues.

Examples

Two-dimensional matrix example-

Ex.1 Find the eigenvalues and eigenvectors of matrix A.

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

Taking the determinant to find characteristic polynomial A-

$$|A - \lambda I| = 0 \Rightarrow \begin{vmatrix} 2 - \lambda & 1 \\ 1 & 2 - \lambda \end{vmatrix} = 0$$
$$\Rightarrow 3 - 4\lambda + \lambda^2 = 0$$

It has roots at $\lambda = 1$ and $\lambda = 3$, which are the two eigenvalues of A.

Eigenvectors v of this transformation satisfy the equation,

$$Av = \lambda v$$

Rearrange this equation to obtain-

$$(A - \lambda I)v = 0$$

For $\lambda = 1$, Equation becomes, (A-I)v = 0

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

which has the solution, $v = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

For $\lambda = 3$, Equation becomes,

$$(A-3I)u=0$$

$$\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

which has the solution-
$$u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Thus, the vectors $v_{i=1}$ and $v_{i=3}$ are eigenvectors of A associated with the eigenvalues $\lambda = 1$ and $\lambda = 3$, respectively.

Three-dimensional matrix example-

Ex.2 Find the eigenvalue and eigenvector of matrix A.

$$A = \begin{bmatrix} -4 & 1 & 0 \\ 0 & -3 & 1 \\ 0 & 0 & -2 \end{bmatrix}$$

the matrix has the characteristics equation-

$$|\lambda I - A| = \begin{vmatrix} \lambda + 4 & -1 & 0 \\ 0 & \lambda + 3 & -1 \\ 0 & 0 & \lambda + 2 \end{vmatrix}$$
$$= (\lambda + 4)(\lambda + 3)(\lambda + 2) = 0$$

therefore the eigen values of A are-

$$\lambda_1 = -2, \lambda_2 = -3, \lambda_3 = -4$$

For $\lambda = -2$, Equation becomes,

$$(\lambda_I I - A)v_I = 0$$

$$\begin{bmatrix} 2 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

which has the solution-

$$v = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$