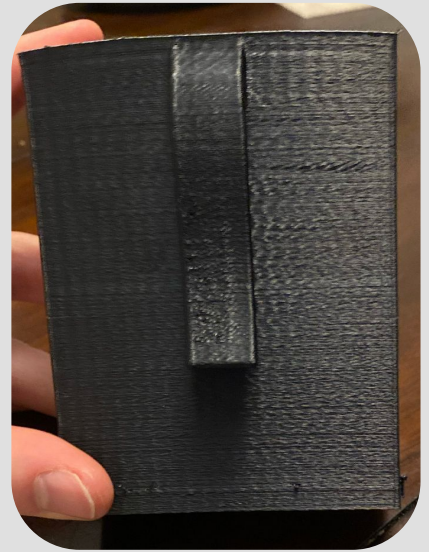
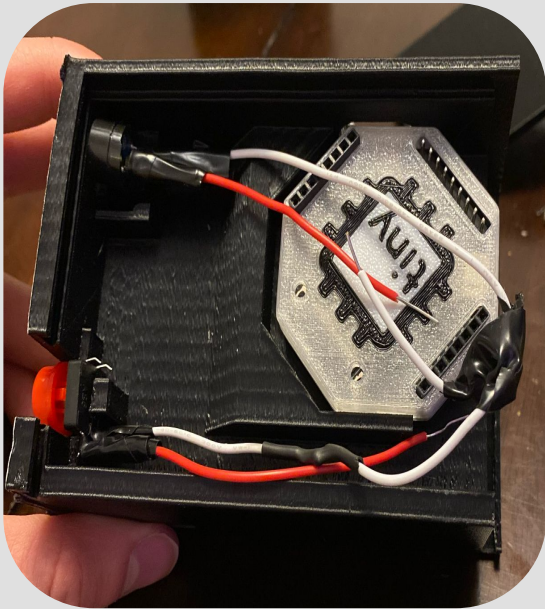


Posture Detector



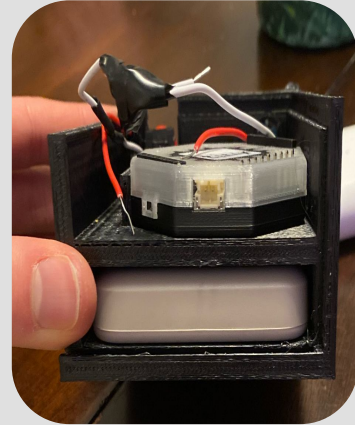
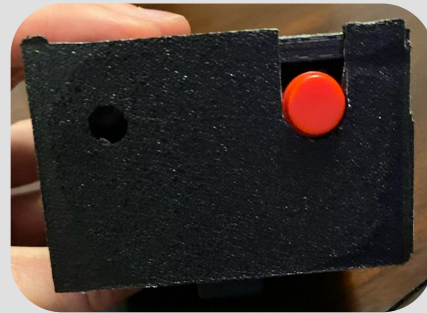
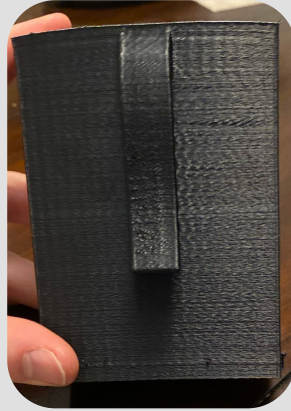
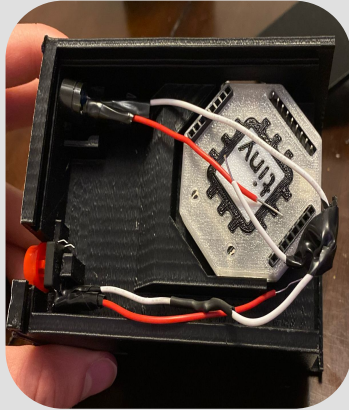
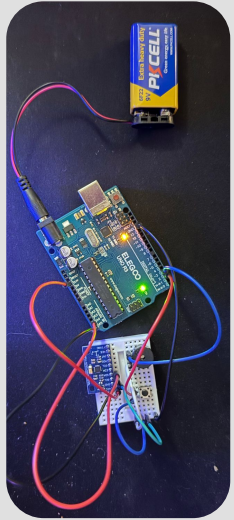
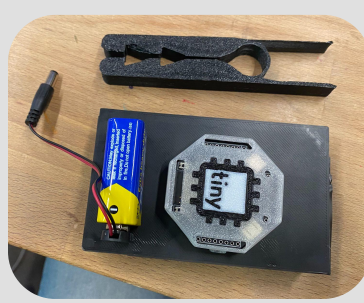
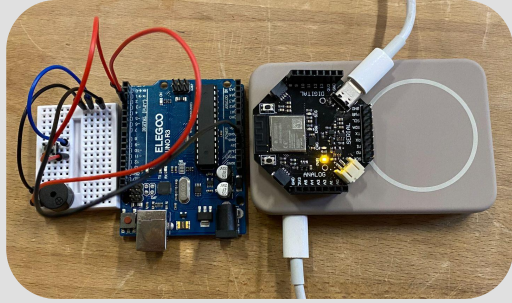
Keaton, Gage, Roman, Brett

Overview

- Analyzes accelerometer data from the **tinyCore MCU** to track lower-neck/upper-spinal position.
- **Detects bad posture** by comparing current position to a user-set "good posture" state.

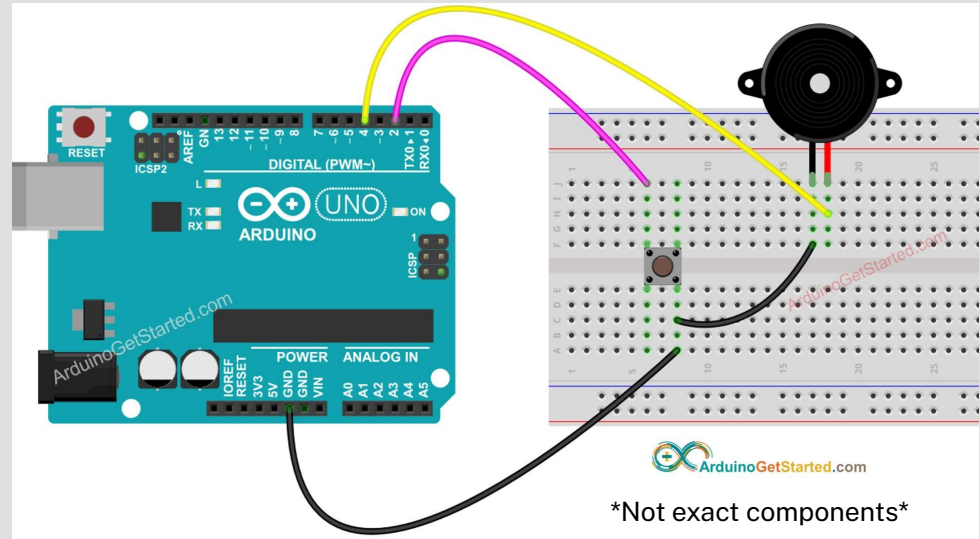
How It Works

- User clips the device to their **shirt collar (back-side)** and sets their **good posture** with a quick button press.
- A **Kalman Filter** optimizes sensor data for accuracy.
- If posture deviates, the device **activates a buzzer** to remind the user to straighten up.



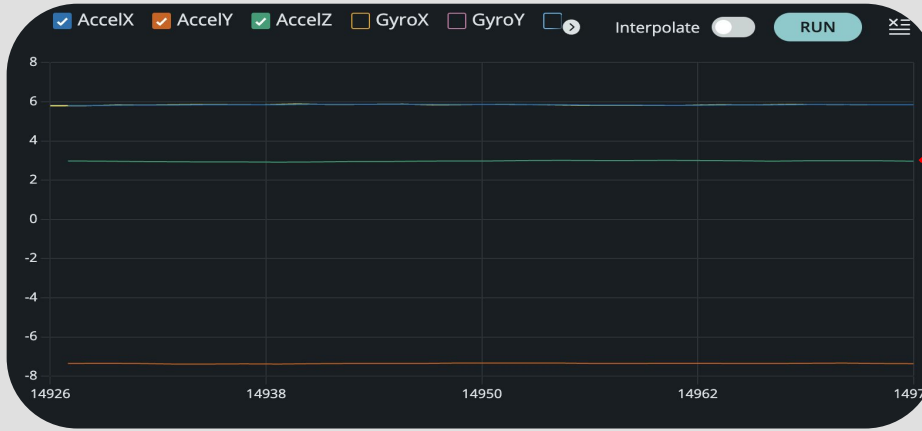
Design Iteration(s)

- tinyCore MCU
 - Accelerometer function & data
- PLA
 - Housing and lid
- Buzzer
- Button
- Battery
- Wires

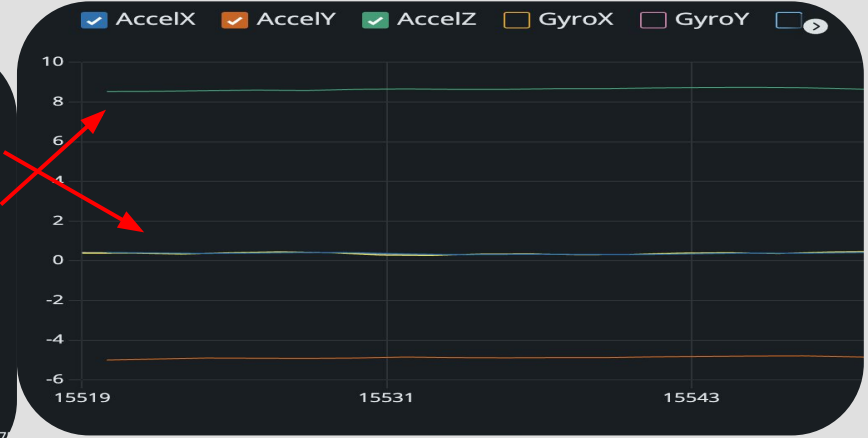


Circuitry + Components

Good Posture



Bad Posture



Thresholding Levels

```
float filteredAccelX = kalmanX.update(accel.acceleration.x);  
float filteredAccelZ = kalmanZ.update(accel.acceleration.z);
```

```
KalmanFilter kalmanX(0, 1.5, 0.08);  
KalmanFilter kalmanZ(0, 1.5, 0.08);
```

```
if (deviceOn && neutralSet) {  
    float deviationX = abs(filteredAccelX - neutralX);  
    float deviationZ = abs(filteredAccelZ - neutralZ);  
  
    if (deviationX > BAD_POSTURE_THRESHOLD || deviationZ > BAD_POSTURE_THRESHOLD) {  
        tone(buzzerPin, 700);  
    } else {  
        noTone(buzzerPin);  
    }  
}
```

Kalman Filter

Put simply, our Posture Detector analyzes accelerometer data from our tinyCore MCU in order to detect changes in lower-neck/upper-spinal position. In order to detect bad posture, the user sets the state of the device in accordance with their respective “good posture” after clipping the device to their back-side, shirt collar. Thereafter, utilizing a Kalman Filter to optimize our data, the MCU can detect a deviation from the set state, initializing a buzzer to inform the user they are slouching, gently encouraging them to fix it. The device is simple; housed in a PLA, 3D-printed case with a clip on the outside for ease of attachment. Aside from the MCU, our housing has built-in space for an internal battery pack, as well as the buzzer and button. The button is used to turn the device on and off with a single long press, as well as to set the “good posture” state for the accelerometer data using a single quick press.

Product Statement

Demo:

