# STAT5003

Week 3 : Density Estimation

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### Readings **and q** functions covered

- For the bias variance tradeoff see Section 2.2 James, Witten, Hastie, and Tibshirani (2013)
- **R** functions
  - dbinom dnorm (density functions)
  - rnorm (generate random values)
  - hist (Histogram)
  - density (nonparametric density estimation)
  - stats4::mle (Maximum Likelihood estimation)

# Review on probability distribution functions



### Discrete distributions

For any random variable X with a discrete distribution, there is a sample space  $\Omega$  with finite number of possible values (outcomes)  $x = \{x_1, x_2, ...\}$  and associated probabilities  $\{p_1, p_2, ...\}$ .

The point probabilities for each value of x are denoted f(x) and the cumulative distribution function denoted F(x) where

$$f(x) = P(X = x),$$
  $F(x) = P(X \le x)$ 

#### Properties:

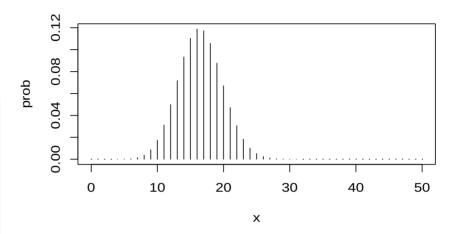
- There is a *countable* number of possible values;
- $\sum_{i=1}^{\infty} p_i = 1$
- $\bullet \ p_i \geq 0$

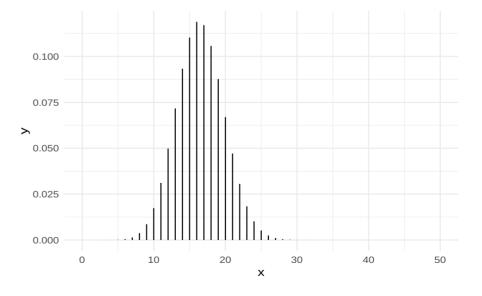
### **Binomial distribution**

$$f(x) = \{ \begin{pmatrix} n \\ x \end{pmatrix} p^{x} (1-p)^{n-x}, \quad x = 0, 1, 2, ..., n \\ 0, \quad \text{otherwise}$$

The  $\binom{n}{x}$  are known as the binomial coefficients. The parameter p is the probability of success.

```
x <- 0:50
prob <- dbinom(x, size = 50, prob = 0.33)
# Base R graphics
plot(x, prob, type = "h")
dat <- data.frame(x = x, y = prob)
# ggplot2 version
ggplot(dat, aes(x = x, y = y, xend = x, yend = 0)) +
    geom_segment() + theme_minimal()</pre>
```





### Continuous distributions

- A continuous random variable X is where the outcome can take an infinite (uncountable) number of possible values.
  - These values may be within a fixed or unbounded interval.
- For example, the height of male in cm may be within the range of [50, 300].

The point probabilities for each value of x is P(X = x) = 0 and the cumulative distribution function

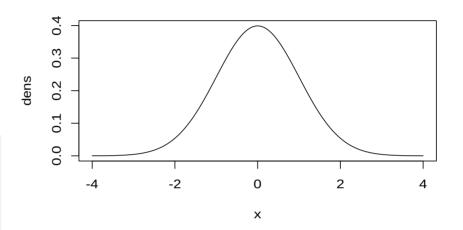
$$F(x) = \int_{-\infty}^{x} f(t) dt = P(X \le x)$$

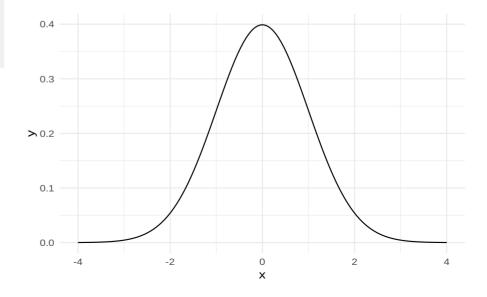
#### Properties:

- There are an infinite (uncountable) number of possible values;
- f(x) is called the density function
- $f(x) \ge 0$  (non-negative)
- $\int_{-\infty}^{\infty} f(x) dx = 1$  (unit measure)

# Normal(Gaussian) distribution: $f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

- The most famous continuous distribution
- Fully specified by two parameters
  - μ the location parameter (mean)
  - $\circ \sigma$  the scale parameter (sd)
- Notation  $X \sim N(\mu, \sigma)$ ,





# Density estimation - Likelihoood approach



### **Density estimation**

In exploratory data analysis, an estimate of the density function can be used

- to assess multimodality, skew, tail behaviour, etc.
- in decision making, classification, and summarizing Bayesian posteriors
- as a useful visualisation tool (a simple summary of a distribution)

Suppose random variables  $X_1, X_2, ..., X_n$  have been observed and assumed to be sampled independently from the distribution with density f.

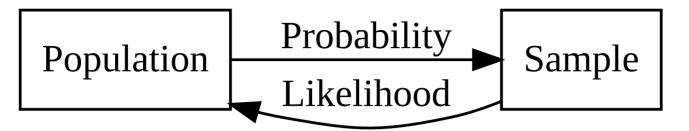
**Goal**: The estimation of the density function f.

### Parametric density estimation

- The parametric approach to density estimation assumed a parametric model.
- That is,  $X_1, X_2, \ldots, X_n \overset{i.i.d.}{\sim} f_\theta$  where  $\theta$  is a parameter vector.
  - For example,  $\theta = (\mu, \sigma)$  when  $X \sim N(\mu, \sigma)$
- Typically the parameter  $\theta$  is estimated using the method of maximum likelihood.
- Density function is then estimated as  $f(x|\hat{\theta})$

Maximum likelihood the best value for the parameters is the one for which the probability of obtaining the observed samples is the largest.

### What is a likelihood?



#### Simple example:

- Population has girl:boy ratio of 2:1 (100 girls for 50 boys)
- If I draw a sample of 50 people, what is the probability of picking 10 boys
- If I draw a sample of 50 people, and picked 10 boys, what is the likelihood that the girl:boy ratio is 2:1

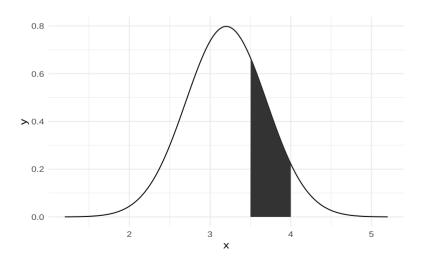
### Normal distribution example

- Consider a random variable  $X \sim N(3.5, 0.2)$
- What is the probability that  $\mathbf{X}$  is between 3.5 and 4?
  - ∘ Compute the area under the density.  $P(3.5 \le X \le 4) = \int_{3.5}^{4} f(t) dt$

```
mu = 3.2; sig = 0.5
pnorm(4, mean = mu, sd = sig) -
   pnorm(3.5, mean = mu, sd = sig)
```

#### ## [1] 0.2194538

```
# Or in one line
## diff(pnorm(c(3.5, 4), mean = mu, sd = sig))
```



### Likelihood

- Consider a single value is observed from  $X \sim N(\mu, 0.2)$ , say x = 3.7
- Determine the likelihood of drawing this value. Flip the perspective  $f(x|\theta) \rightarrow L(\theta|x)$

```
dnorm(3.7, mean = 3.5, sd = 0.2)

## [1] 1.209854

dnorm(3.7, mean = 3.6, sd = 0.2)

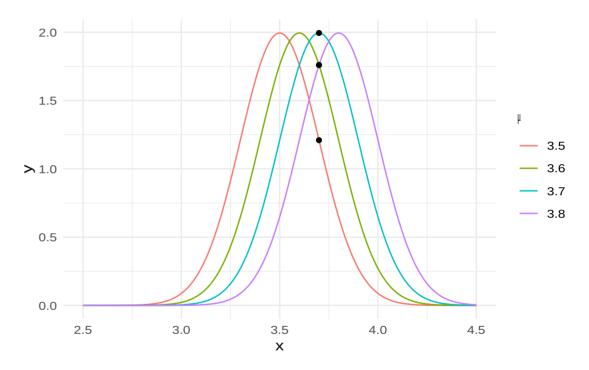
## [1] 1.760327

dnorm(3.7, mean = 3.7, sd = 0.2)

## [1] 1.994711

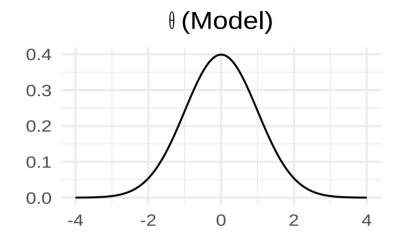
dnorm(3.7, mean = 3.8, sd = 0.2)

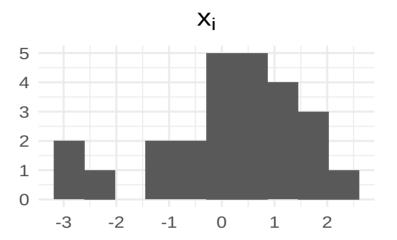
## [1] 1.760327
```



### Maximum likelihood approach

•  $f(x_1, x_2, ..., x_n | \theta)$  is the probability density of observing  $x_1, x_2, ..., x_n$  given the parameter  $\theta$ .





• Assuming independent and identically distributed variables  $f(x_1, x_2, ..., x_n | \theta) = \prod_{i=1}^n f(x_i | \theta)$ 

Maximising the log-likelihood is often easier so it is common to maximise

$$L(\theta|x) = \prod_{i=1}^{n} f(x_i|\theta) \rightsquigarrow L(\theta|x) = \ln L(\theta|x) = \sum_{i=1}^{n} \ln f(x_i|\theta)$$

# Density estimation - Non-parametric approach

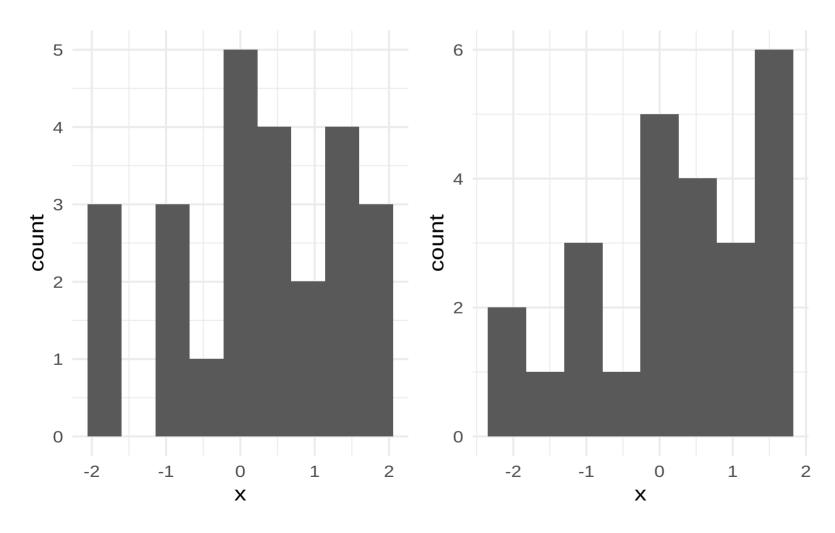


### Non-parametric density estimation

- Danger of misspecification with parametric approach
  - $\circ$  If the assumed  $f_{\theta}$  is incorrect.
  - Serious danger of inferential errors.
- Non-parametric approaches to density estimations
  - Assume little about the structure of f
  - $\circ$  use *local information* to estimate f at a point x
- · Histograms are
  - one type of nonparametric density estimators
  - piecewise constant density estimators
  - o produced automatically by most software packages

### Histograms

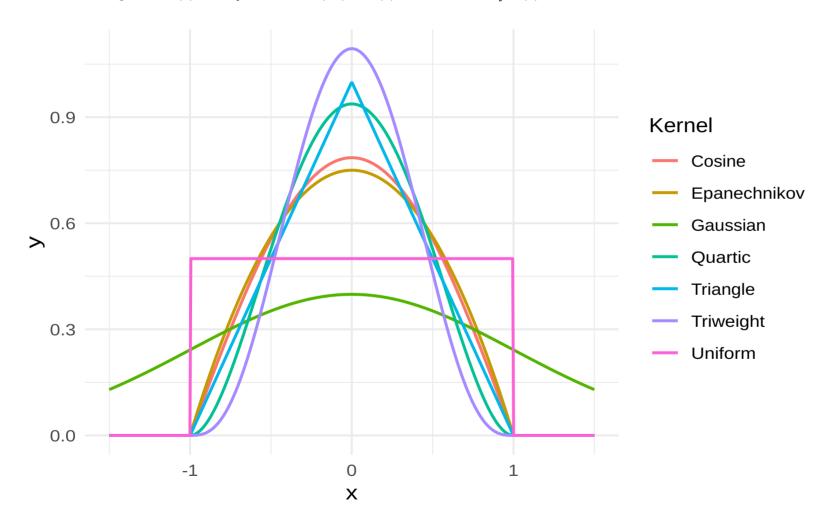
- Very simple visualization
- Sensitive to the number of bins chosen and bin width



• Preferable to have a smooth estimate and not have columns

### **Kernel functions**

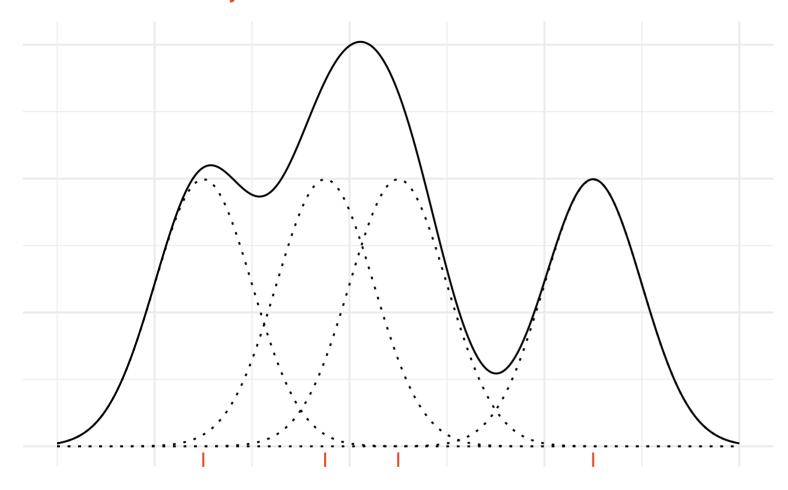
- A kernel is a special type of probability density function (PDF) having the properties.
  - ∘ non-negative  $K(x) \ge 0$ , symmetric K(-x) = K(x), unit measure  $\int K(x) dx = 1$



### Kernel density esimation

- Kernel density estimation is a non-parametric approach estimating densities
  - Knowledge of the structure of f is not required
- Essentially, at every data point, a kernel function is created with the point at its centre.
- The PDF is estimated by adding all of these kernel functions and dividing by the number of data to ensure that it satisfies
  - every possible value of the PDF is non-negative.
  - the definite integral of the PDF over its support set equals 1

## Normal kernel density estimate



• E.g. Four sampled variables marked in red with Gaussian weights sum together to give the overall density estimate

### Kernel density estimator (KDE)

• A simple one weights all points within a window h of x equally

$$\hat{f}(x) = \frac{1}{2nh} \sum_{i=1}^{n} 1_{\{|X_i - x| < h\}}$$

• More generally a univariate kernel density estimator has a general weight function (Kernel)

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^{n} K\left(\frac{X_i - x}{h}\right)$$

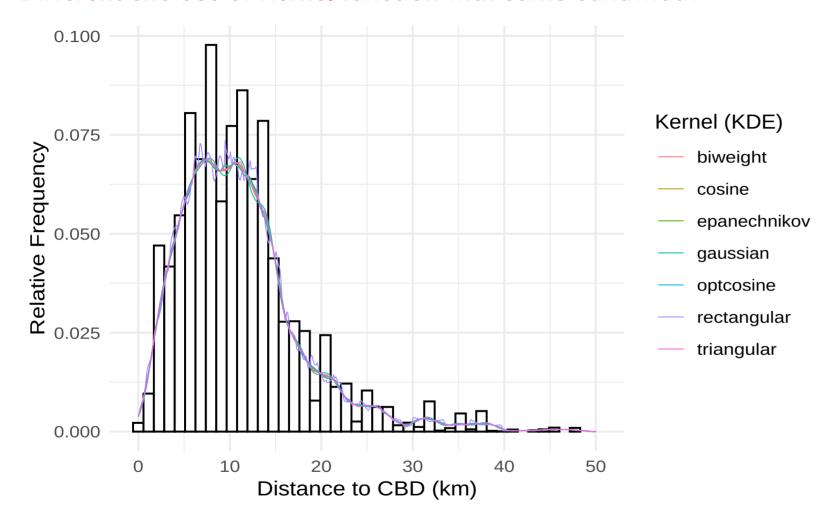
- K is a Kernel function
- h is a bandwidth parameter (possibly fixed or varying)
- Consider only h fixed for this course.

### Tuning the Kernel density estimator (KDE)

- There are two main components for the KDE  $\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^{n} K(\frac{X_i X}{h})$ 
  - The choice of K
  - o The choice of h
- The choice of Kernel is less important and generally gives similar results
- The choice of bandwidth is important and can vary the result greatly.
- Some standard kernels

Uniform 
$$K(x) = \frac{1}{2} \mathbf{1}_{\{|x| \le 1\}}$$
 Gaussian 
$$K(x) = \frac{1}{\sqrt{2\pi}} \exp\{-\frac{x^2}{2}\}$$
 Epanechnikov 
$$K(x) = \frac{3}{4} (1 - x^2) \mathbf{1}_{\{|x| \le 1\}}$$

### Different choices of Kernel function with same bandwidth



### Computing density in **Q**

- Base **Q** there is density
  - density computes the KDE
  - Can wrap in plot, i.e. plot(density(x)), to visualize
  - Can inspect details in summary
- For plotting ggplot there is geom\_density
  - Can specify the bandwidth with bw argument

### Choosing the bandwidth

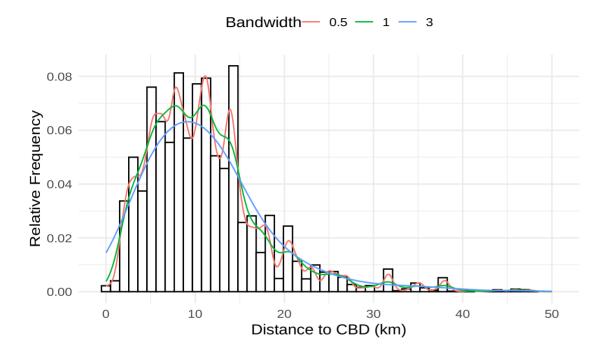
• The density estimator

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^{n} K\left(\frac{X_i - x}{h}\right)$$

- is a fixed-bandwidth kernel density estimator since h is constant.
- If h is too small, the density estimator will tend to assign probability density too locally near observed data
  - a wiggly estimated density function with many false modes.
- If h is too large, the density estimator will spread probability density contributions too diffusely
  - o smooths away important features of f

### Choice of bandwidth

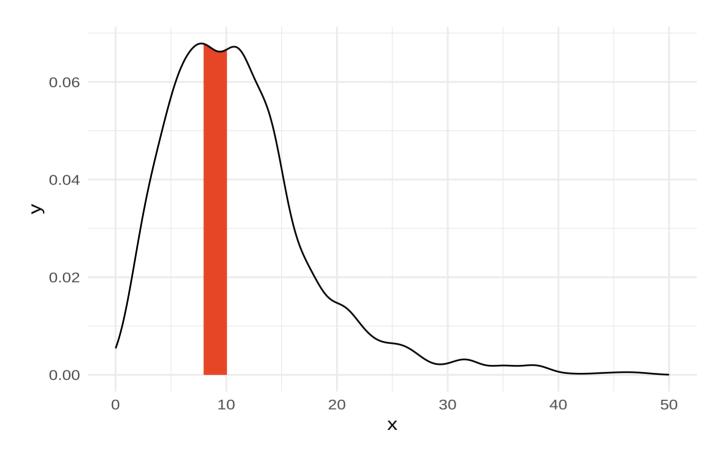
• Consider the distance from CBD variable again with three bandwidths



- A bias and variance trade-off.
  - A small bandwidth gives high variance
  - A large bandwidth gives high bias

### Uses of the density estimate

- Compute probabilities: Consider the probability a property is between 8-10km of CBD
- Integrate the density function between 8 and 10 yields p = 0.13 13% chance of finding a property between 8-10km of CBD



### Mean squared error, Bias and Variance

We can decompose the mean squared error (MSE) into the sum of three quantities: The variance, the squared bias and the variance of the error.

$$E(Y - \hat{f}(X))^{2} = V \operatorname{ar}(\hat{f}(X)) + \left[\operatorname{Bias}(\hat{f}(X))\right]^{2} + V \operatorname{ar}(\epsilon)$$

- Variance here denoting how much would  $\hat{f}(x)$  change if we estimate using a different training set.
- Bias
  - Error introduced by approximating the data using a model.

### Kernel density estimation type equivalent

$$V \operatorname{ar}(\hat{f}(x)) = O(\frac{1}{nh})$$
  
Bias(\hat{f}(x)) = O(h)

### References

James, G., D. Witten, T. Hastie, et al. (2013). *An introduction to statistical learning*. Vol. 112. Springer.