

Grundeinstellungen

Sendertyp Graupner mx16
Sender ID 30000011DF
Firmware Version 1.722
Datei Version 1.001
Modelltyp Helicopter
Modellspeicher 0
Modellname SPACER-4X
Steueranordnung Mode3
Motor-Stopp Position: -100%
Limit: 1.200%
Schalter: ---
Gastrimm 0%
letzte Leerlaufposition 0%
Uhren Countdown: 0:00
Schalter: ---
Phase 2 Name: Hover
Schalter: ---
Phase 3 Name: Speed
Schalter: ---
Phase 4 Name: Autorotation
Schalter: ---
Empfängerausgang S1 => Ausgang 3
S2 => Ausgang 2
S3 => Ausgang 3
S4 => Ausgang 4
S5 => Ausgang 5
S6 => Ausgang 3
S7 => Ausgang 7
S8 => Ausgang 8
Epmfänger grbunden ja
Epmfänger ID 910000EA75

Servoeinstellungen

Servo Umkehr Mitte Weg - Weg +

S1	=>	0%	100%	100%
S2	=>	0%	100%	100%
S3	=>	0%	100%	100%
S4	=>	0%	100%	100%
S5	=>	0%	100%	100%
S6	=>	0%	100%	100%
S7	=>	0%	100%	100%

S8 => 0% 100% 100%

Gebereinstellungen

Eingang Geber Weg - Weg +

E5	frei	100%	100%
E6	frei	100%	100%
E7	frei	100%	100%
E8	frei	100%	100%
E9	frei	100%	100%

DualRate Expo

Phase 1: Normal

Dual Rate Expo Schalter

QR	100%	0%	---
	100%	0%	---
HR	100%	0%	---
	100%	0%	---
SR	100%	0%	---
	100%	0%	---

Phase 2: Hover

Dual Rate Expo Schalter

QR	100%	0%	---
	100%	0%	---
HR	100%	0%	---
	100%	0%	---
SR	100%	0%	---
	100%	0%	---

Phase 3: Speed

Dual Rate Expo Schalter

QR	100%	0%	---
	100%	0%	---
HR	100%	0%	---
	100%	0%	---
SR	100%	0%	---
	100%	0%	---

Phase 4: Autorotation

QR	100%	0%	---
	100%	0%	
HR	100%	0%	---
	100%	0%	
SR	100%	0%	---
	100%	0%	

Mixer	Type	von	zu	Schalter	Weg -	Weg +	Offset
M1	Normal	0	0	---	0%	0%	0%
M2	Normal	0	0	---	0%	0%	0%
M3	Normal	0	0	---	0%	0%	0%

	S1	S2	S3	S4	S5	S6	S7	S8
Mode	Position	Position	Position	Position	Position	Position	Position	Position
Position	0%	0%	-100%	1%	0%	0%	0%	0%

Mode Trainer Trainer Trainer Trainer Trainer Trainer Trainer Trainer