Grundeinstellungen

Sendertyp	Graupner mx16
Sender ID	30000011DF
Firmware Version	1.722
Datei Version	1.001
Modelltyp	Winged
Modellspeicher	0
Modellname	MERLIN
Steueranordnung	Mode3
Motor an K1	Idle_Front
Motor-Stopp	Position: -100% Limit: 1.200% Schalter: 3 invers
Gastrimm	0%
letzte Leerlaufposition	0%
Leitwerk	Normal
Querruder/Wölbklappen	TwoAil
Uhren	Countdown: 0:00 Schalter: 23 normal
Phase 2	Name: Normal Schalter: ---
Phase 3	Name: Distance Schalter: ---
Phase 4	Name: Acro Schalter: ---
Empfängerausgang	S1 => Ausgang 1 S2 => Ausgang 2 S3 => Ausgang 3 S4 => Ausgang 4 S5 => Ausgang 5 S6 => Ausgang 6 S7 => Ausgang 7 S8 => Ausgang 8
Epmfänger grbunden	ja
Epmfänger ID	9100002528

Servoeinstellungen

Servo	Umkehr	Mitte	Weg -	Weg +
S1	=>	0%	100%	100%
S2	<=	0%	100%	100%
S3	<=	0%	150%	150%
S4	=>	0%	150%	150%

S5	<=	0%	100%	100%
S6	=>	0%	100%	100%
S7	=>	0%	100%	100%
S8	=>	0%	100%	100%

Gebereinstellungen

Eingang	Geber	Weg -	Weg +
E5	frei	100%	100%
E6	frei	100%	100%
E7	frei	100%	100%
E8	frei	100%	100%
E9	16	100%	100%

DualRate Expo

Phase 1: Normal

	Dual Rate	Expo	Schalter
QR	75% 100%	50% 0%	2 invers
HR	75% 100%	50% 0%	2 invers
SR	75% 100%	50% 0%	2 invers

Phase 2: Normal

	Dual Rate	Expo	Schalter
QR	100% 100%	0% 0%	2 invers
HR	100% 100%	0% 0%	2 invers
SR	100% 100%	0% 0%	2 invers

Phase 3: Distance

	Dual Rate	Expo	Schalter
QR	100% 100%	0% 0%	2 invers
HR	100% 100%	0% 0%	2 invers
SR	100% 100%	0% 0%	2 invers

Phase 4: Acro

	Dual Rate	Expo	Schalter
QR	100%	0%	2 invers
	100%	0%	
HR	100%	0%	2 invers
	100%	0%	
SR	100%	0%	2 invers
	100%	0%	

Phasentrimm

Phase	WK	QR	HR
Normal	0%	0%	0%
Normal	0%	0%	0%
Distance	0%	0%	0%
Acro	0%	0%	0%

Fläschenmix

QR-Diff.	0%
WK-Diff.	0%
Diff.-Red.	0%
QR->SR	0%
QR->WK	0%
BR->HR	0%
BR->WK	0%
BR->QR	0%
HR->WK	0%
HR->QR	0%
WK->HR	0%
WK->QR	0%

Freie Mixer

Mixer	Typ	von	zu	Schalter	Weg -	Weg +	Offset
M1	Normal	0	0	---	0%	0%	0%
M2	Normal	0	0	---	0%	0%	0%
M3	Normal	0	0	---	0%	0%	0%

Fail Safe

Verzögerung 0,75s
FlailSafe Check ja

	S1	S2	S3	S4	S5	S6	S7	S8
Mode	Position	Position	Position	Position	Position	Position	Position	Position
Position	-100%	0%	0%	0%	0%	0%	0%	0%

Telemetrie

Ansage wiederholen 10s
Schalter ---
nächste Ansage ---
Vario ---
aktueller Sensor (Anzeige) Receiver
aktueller Sensor (Telemetrie) Receiver
aktuelle Seite (Telemetrie) 0

Lehrer/Schüler

Kabellos nein
Trainer ID 0
Schüler ID 0
Schalter 8 invers

	S1	S2	S3	S4	S5	S6	S7	S8
Mode	Pupil	Pupil	Pupil	Pupil	Pupil	Trainer	Trainer	Trainer