

Grundeinstellungen

Sendertyp Graupner mx16
Sender ID 30000011df
Firmware Version 1.722
Datei Version 1.001
Modelltyp Winged
Modellspeicher 0
Modellname MERLIN
Steueranordnung Mode3
Motor an K1 Idle_Front
Motor-Stopp Position: -100%
Limit: 1.200%
Schalter: 3 invers
Gastrimm 0%
letzte Leerlaufposition 0%
Leitwerk Normal
Querruder/Wölbklappen TwoAil
Uhren Countdown: 0:00
Schalter: 23 normal
Phase 2 Name: Normal
Schalter: ---
Phase 3 Name: Distance
Schalter: ---
Phase 4 Name: Acro
Schalter: ---
Empfängerausgang S1 => Ausgang 1
S2 => Ausgang 2
S3 => Ausgang 3
S4 => Ausgang 4
S5 => Ausgang 5
S6 => Ausgang 6
S7 => Ausgang 7
S8 => Ausgang 8
Epmfänger grbunden ja
Epmfänger ID 9100002528

Servoeinstellungen

Servo Umkehr Mitte Weg - Weg +

S1	=>	0%	100%	100%
S2	<=	0%	100%	100%
S3	<=	0%	150%	150%
S4	=>	0%	150%	150%

S5	<=	0%	100%	100%
S6	=>	0%	100%	100%
S7	=>	0%	100%	100%
S8	=>	0%	100%	100%

Gebereinstellungen

Eingang Geber Weg - Weg +

E5	frei	100%	100%
E6	frei	100%	100%
E7	frei	100%	100%
E8	frei	100%	100%
E9	16	100%	100%

DualRate Expo

Phase 1: Normal

Dual Rate Expo Schalter

QR	75%	50%	2 invers
	100%	0%	
HR	75%	50%	2 invers
	100%	0%	
SR	75%	50%	2 invers
	100%	0%	

Phase 2: Normal

Dual Rate Expo Schalter

QR	100%	0%	2 invers
	100%	0%	
HR	100%	0%	2 invers
	100%	0%	
SR	100%	0%	2 invers
	100%	0%	

Phase 3: Distance

Dual Rate Expo Schalter

QR	100%	0%	2 invers
	100%	0%	
HR	100%	0%	2 invers
	100%	0%	
SR	100%	0%	2 invers
	100%	0%	

Phase 4: Acro

Dual Rate Expo Schalter			
QR	100%	0%	2 invers
	100%	0%	
HR	100%	0%	2 invers
	100%	0%	
SR	100%	0%	2 invers
	100%	0%	

Phasentrimm

Phase	WK	QR	HR
Normal	0%	0%	0%
Normal	0%	0%	0%
Distance	0%	0%	0%
Acro	0%	0%	0%

Flaschenmix

QR-Diff.	0%
WK-Diff.	0%
Diff.-Red.	0%
QR->SR	0%
QR->WK	0%
BR->HR	0%
BR->WK	0%
BR->QR	0%
HR->WK	0%
HR->QR	0%
WK->HR	0%
WK->QR	0%

Freie Mixer

Mixer Typ	von	zu	Schalter	Weg -	Weg +	Offset
M1	Normal	0	0 ---	0%	0%	0%
M2	Normal	0	0 ---	0%	0%	0%
M3	Normal	0	0 ---	0%	0%	0%

Fail Safe

Verzögerung 0,75s
FlailSafe Check ja

	S1	S2	S3	S4	S5	S6	S7	S8
Mode	Position	Position	Position	Position	Position	Position	Position	Position
Position	-100%	0%	0%	0%	0%	0%	0%	0%

Telemetrie

Ansage wiederholen 10s
Schalter ---
nächste Ansage ---
Vario ---
aktueller Sensor (Anzeige) Receiver
aktueller Sensor (Telemetrie) Receiver
aktuelle Seite (Telemetrie) 0

Lehrer/Schüler

Kabellos nein
Trainer ID 0
Schüler ID 0
Schalter 8 invers

	S1	S2	S3	S4	S5	S6	S7	S8
Mode	Pupil	Pupil	Pupil	Pupil	Pupil	Trainer	Trainer	Trainer