Grundeinstellungen

Sendertyp Graupner mx16

Sender ID 206.158.434.783

Firmware Version 1.722

Datei Version 1.001

Modelltyp Winged

Modellspeicher 0

Modellname MERLIN

Steueranordnung Mode3

Motor an K1 Idle_Front

Motor-Stopp Position: -100%

Limit: 1.200%

Schalter: 3 invers

Gastrimm 0%

letzte Leerlaufposition 0%

Leitwerk Normal

Querruder/Wölbklappen TwoAil

Uhren Countdown: 0:00

Schalter: 23 normal

Phase 2 Name: Normal

Schalter: ---

Phase 3 Name: Distance

Schalter: ---

Phase 4 Name: Acro

Schalter: ---

Empfängerausgang S1 => Ausgang 1

S2=>Ausgang 2

S3=>Ausgang 3

S4=>Ausgang 4

S5 => Ausgang 5

S6=>Ausgang 6

S7 => Ausgang 7

S8=>Ausgang 8

Epmfänger ID gebunden 622.770.267.432

Servoeinstellungen

Servo Umkehr Mitte Weg - Weg +

- S1 => 0% 100% 100%
- S2 <= 0% 100% 100%
- S3 <= 0% 150% 150%
- S4 => 0% 150% 150%

S 5	<=	0%	100%	100%
S 6	=>	0%	100%	100%
S 7	=>	0%	100%	100%
S 8	=>	0%	100%	100%

Gebereinstellungen

Eingang Geber Weg - Weg +

E5	frei	100%	100%
E6	frei	100%	100%
E7	frei	100%	100%
E8	frei	100%	100%
E9	16	100%	100%

DualRate Expo

Phase 1: Normal

Dual Rate Expo Schalter

ΩD	75%	50%	2 invome	
QR	100%	0%	2 invers	
HR	75%	50%	2 invers	
пк	100%	0%	Z IIIVEIS	
SR	75%	50%	2 invers	
SK	100%	0%	∠ mvers	

Phase 2: Normal

Dual Rate Expo Schalter

OR	100%	0%	2 invers
ЛУ	100%	0%	2 invers
HR	100%	0%	2 invore
пк	100%	0%	2 invers
CD	100%	0%	2 invome
SR	100%	0%	2 invers

Phase 3: Distance

Dual Rate Expo Schalter

ΩD	100%	0%	2 invers
QR	100%	0%	2 mvers
HR	100%	0%	2 invom
пк	100%	0%	2 invers
SR	100%	0%	2 invom
	100%	0%	2 invers

Phase 4: Acro

Dual Rate Expo Schalter

ΩD	100%	0%	2 imryama
QR	100%	0%	2 invers
HR	100%	0%	2 invers
пк	100%	0%	2 invers
CD	100%	0%	2 invome
SR	100%	0%	2 invers

Phasentrimm

Phase WK QR HR

Normal 0% 0% 0%

Normal 0% 0% 0%

Distance 0% 0% 0%

Acro 0% 0% 0%

Fläschenmix

QR-Diff. 0%

WK-Diff. 0%

Diff.-Red. 0%

QR->SR 0%

QR->WK 0%

BR->HR 0%

BR->WK 0%

BR->QR 0%

HR->WK 0%

HR->QR 0%

WK->HR 0%

WK->QR 0%

Freie Mixer

Mixer	Typ	von	zu	Schalter	Weg -	weg +	Offset
M1	Normal	0	0		0%	0%	0%
M2	Normal	0	0		0%	0%	0%
M3	Normal	0	0		0%	0%	0%

Fail Safe

Verzögerung 0,75s FlailSafe Check ja S1 S2 S3 S4

S1 S2 S3 S4 S5 S6 S7 S8

Mode Position Position

Telemetrie

Ansage wiederholen 10s

Schalter ---

nächste Ansage ---

Vario ---

aktueller Sensor (Anzeige) Receiver aktueller Sensor (Telemetrie) Receiver aktuelle Seite (Telemetrie) 0

Lehrer/Schüler

Kabellos nein

Trainer ID 0

Schüler ID 0

Schalter 8 invers

S1 S2 S3 S4 S5 S6 S7 S8

Mode Pupil Pupil Pupil Pupil Pupil Trainer Trainer Trainer