

Streamlining Development: Marrying the Code Base and GUI Simulation Software to Docker

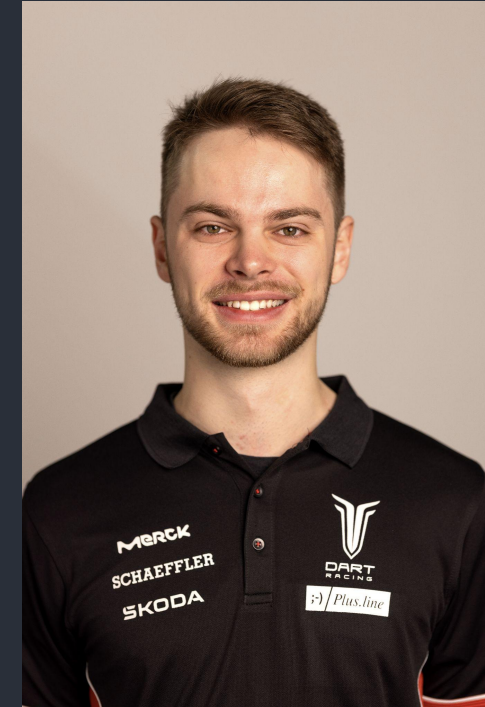
Short Talk by Oscar Fritzsche

Streamlining Development: Marrying the Code Base and GUI Simulation Software to Docker

Or: Why Good Developer Documentation is Crucial

Short Talk by Oscar Fritzsche

- Oscar Fritzsche
- B.Sc. Computer Science @ TU Darmstadt
- Member of the Autonomous System Department at DART Racing
- Responsible for:
 - Trajectory Optimization
 - Development Setup
 - PC Hardware



- Motivation
- Docker + Dev Containers
- Where the Magic Happens
- Short Demo
- Advantages & Drawbacks



Shitty installation instructions, anyone?



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https://www.reddit.com/r/ProgrammerHumor/comments/12fzve2/i_see_a_lot_of_screenshots_of_horribly_complex/lightbox

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[https://www.reddit.com/r/ProgrammerHumor/comments/12f7ye2/i see a lot of screenshots of horribly complex/lightbox](https://www.reddit.com/r/ProgrammerHumor/comments/12f7ye2/i_see_a_lot_of_screenshots_of_horribly_complex/lightbox)

Prerequisites

- You have to install ROS Noetic for Ubuntu 20.04 LTS and source it.
- (You need to install git-lfs.)
- To make it as convenient as possible add a SSH-Key to your Bitbucket account.
- If you are using conda, make sure to deactivate it while running ROS: `conda deactivate`

Additional needed packages

```
sudo apt install python3-catkin-tools
```

If you need to update CMake

```
wget -O - https://apt.kitware.com/keys/kitware-archive-latest.asc 2>/dev/null | sudo apt-key add -  
sudo apt-add-repository 'deb https://apt.kitware.com/ubuntu/ bionic main'  
sudo apt-get update  
sudo apt install cmake
```

- Shitty installation instructions
- Accidentally broke the installation (*again...*)
- Knowledge loss because someone left the team

→ Move fast, get work done, get the car to move even faster





docker®





docker®



How do you deal with GUI software inside a Container?

Built on top of a Docker image

```
50
51 # Switch from root to user
52 USER $USERNAME
53 # ros stuff
54 RUN git lfs install && \
55     sudo mkdir -p /etc/apt/keyrings && \
56     curl -s https://raw.githubusercontent.com/ros/rosdistro/master/ros.asc > /tmp/ros.asc && \
57     sudo -H gpg -o /etc/apt/keyrings/ros.gpg --dearmor /tmp/ros.asc && \
58     sudo sh -c 'echo "deb [signed-by=/etc/apt/keyrings/ros.gpg] http://packages.ros.org/ros/ubuntu fo
59     sudo apt-get update -y && \
60     sudo apt-get install -y --no-install-recommends ros-noetic-desktop-full ros-noetic-rosmon && \
61     echo "source /opt/ros/noetic/setup.bash" >> ~/.bashrc && \
62     source ~/.bashrc && \
63     sudo apt-get install -y --no-install-recommends python3-rosdep python3-rosinstall python3-rosinst
64     sudo rosdep init && \
65     rosdep update && \
66     sudo apt-get install -y --no-install-recommends python3-catkin-tools && \
67 # cmake
68 wget -O- https://apt.kitware.com/keys/kitware-archive-latest.asc > /tmp/kitware.asc && sudo -H gpg
69 sudo sh -c "echo 'deb [signed-by=/etc/apt/keyrings/kitware.gpg] https://apt.kitware.com/ubuntu/ f
70 sudo apt-get update -y && \
71 sudo apt-get install -y --no-install-recommends cmake && \
72 # Libtorch
73 curl https://download.pytorch.org/libtorch/cpu/libtorch-cxx11-abi-shared-with-deps-2.0.1%2Bcpu.zi
74 unzip /tmp/libtorch.zip -d ~/libtorch && \
75 echo "export Torch_DIR=$HOME/libtorch/libtorch" >> ~/.bashrc && \
76 source ~/.bashrc && \
77 # Trajectory Optimizer Dependencies
78 echo 'export PATH=$PATH:$HOME/.local/bin' >> ~/.bashrc && source ~/.bashrc && \
79 sudo apt-get install -y --no-install-recommends python3-pip && \
80 python3 -m pip install --upgrade pip && \
81 python3 -m pip install --upgrade numpy matplotlib \
82 trajectory_planning_helpers casadi scipy scikit-learn rospkg jax jaxlib && \
83 # clean up
84 sudo apt-get -y clean && \
85 sudo rm -rf /var/lib/apt/lists/* && \
86 rm -rf /tmp/*
87
88
89 # image optimization
90 FROM scratch
```

Further configuration via devcontainer.json

```
33 {
32   "name": "DART-AS-Devcontainer-Base",
31   "image": "dart-dev-base",
30   "runArgs": [
29     "--privileged",
28     "--network=host"
27   ],
26   "containerUser": "dart-dev",
25   "workspaceMount": "source=${localWorkspaceFolder},target=/home/dart-dev/${localWorkspaceFolderBas
24   "workspaceFolder": "/home/dart-dev/${localWorkspaceFolderBasename}",
23   "mounts": [
22     "source=${localEnv:HOME}${localEnv:USERPROFILE}/.bash_history,target=/home/dart-dev/.bash_his
21     "source=profile,target=/home/dart-dev,type=volume"
20   ],
19   "features": {
18     "ghcr.io/devcontainers/features/desktop-lite:1": {
17       "version": "latest",
16       "noVncVersion": "1.2.0",
15       "password": "noPassword",
14       "webPort": "6080",
13       "vncPort": "5901"
12     }
11   },
10   "forwardPorts": [6080, 5901],
9   "portsAttributes": {
8     "6080": {
7       "label": "desktop-browser"
6     },
5     "5901": {
4       "label": "desktop-VCN"
3     }
2   },
1   "onCreateCommand":
34   "cd ~/${localWorkspaceFolderBasename}; sudo apt-get update -y && rosdep update && rosdep inst
1   "postCreateCommand":
2     "git config --global --add safe.directory ${containerWorkspaceFolder} && echo 'source /home/c
3
4 }
```

- Prebuilt image
→ Faster startup for everyone else
- Upload image to Docker Hub

```
▼ .devcontainer
  {} devcontainer.json
▼ .prebuilt-image / .devcontainer
  {} devcontainer.json
  Dockerfile
```



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 - Don't be like me.
- Completely unrelated: <https://rtyley.github.io/bfg-repo-cleaner/>
 - Great tool for getting rid of large files in your commit history!

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Where Does the Magic Happen?



```
"features": {  
  "ghcr.io/devcontainers/features/desktop-lite:1": {  
    "version": "latest",  
    "noVncVersion": "1.2.0",  
    "password": "noPassword",  
    "webPort": "6080",  
    "vncPort": "5901"  
  }  
},  
"forwardPorts": [6080, 5901],  
"portsAttributes": {  
  "6080": {  
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  }  
},  
},
```

Demo Time



Drawbacks:

- Creating the base image can be *really* annoying
- The provided desktop environment is extremely bare-bones
- Images are huge (maybe a skill issue on my part)
- Running the container is resource intensive
 - Our setup requires at least 12 GB of RAM
- Windows containers not supported

Advantages:

- Easy onboarding once initial setup is done
- Fast recovery of broken installations
- No dependency hell ("But it works on my machine!")
- There is always a reproducible working state
- Works with any GUI software you might need
- Windows containers not supported

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Thank you very much for listening!

Feedback is much appreciated:

