AIList: an effective algorithm for searching genomic interval data

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ABSTRACT

Motivation: Genomic data are signals recorded as intervals on the genome coordinates.

Interval-based comparing operation is fundamental to nearly all genomic analysis. As the

available genomic data rapidly grows, developing effective and dedicated algorithms for

searching this data becomes necessary.

Results: An augmented interval-list (AIList) algorithm is presented. The interval list is first

sorted by interval start, then partitioned into two approximately normalized sub-lists, and

then an augmenting list of the maximum interval end is added to each sub-list. The query

time is O(n+logN), where n is the number of overlaps and N is the size of the dataset. Tested

with genomic interval datasets, code based on this algorithm runs significantly faster than

code based on existing algorithms such as augmented interval-tree (AITree), nested

containment list (NCList) and R-tree.

Availability: http://github.com/databio/AIList

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Supplementary information: an alternative algorithm of AIList, source code, genomic data

used in the study are provided.

1. Introduction

A genomic interval is defined by two coordinates that represent the *start* and *end* locations of a continuous signal on a chromosome. In general, an interval set can be collected or integrated from many experimental datasets and an interval may have attributes like signal level, tissue/cell type, chromatin state etc. The interval search becomes a problem when the interval set possesses the coverage or containment relationship, i.e., one interval contains another interval; which breaks the total order of the interval set: the order based on the *start* is different from the order based on the *end*. The general interval search problem can be defined as follows:

Given a set of N intervals $R = \{r_1, r_2, ..., r_N\}$ and a query interval q, find the subset S of R that intersect q:

$$S(q) = \{r \in R \mid (r.start < q.end \land r.end > q.start)\}$$

Following the literature standard, the interval here is defined as half open region r = [start, end] and the number of query intervals is assumed large.

This is a fundamental problem in genomic data analysis (Giardine, B. et al., 2005; Birney et al., 2006; Li, 2009) and several approaches have been developed or practiced (Cormen et al., 2001; Kent et al., 2002; Richardson, 2006; Alekseyenko et al., 2007; Quinlan, A. and Hall, I., 2011; Neph, S., 2012). Currently, the nested containment list (NCList) by Alekseyenko et al., the augmented interval-tree (AITree) by Cormen et al. and the R-tree by Kent et al. have gained popularity and practicality. Comparing to the naive solution that sequentially compares each of the Nintervals with the query, these algorithms successfully skip large portion of the comparison. Their time complexities are $O(\log N + n + m)$, where n is the number of overlaps (the query result set) and m is the average number of extra comparisons that are made in order to get the n overlaps; and for genomic interval datasets, N is usually several orders of magnitudes larger than n or m. Clearly, m is the main difference among these algorithms and it is resulted from different sources. For NCList, if the query covers two or more sublists, then extra binary searches are needed; for AITree, one needs to compare all interval nodes marked by the augmenting value and not all of them intersect the query; and for R-tree, intervals in the found bin are scanned, in which many intervals may not overlap the query.

In this paper, we present a new algorithm, the augmented interval-list (AIList), that can generally reduce the extra number of comparisons and thus achieve higher search efficiency.

2. AIList data structure and query algorithm

Augmenting is a common way to extend the functionality of the basic data structures (Cormen et al., 2001). Here, the genomic interval data is directly treated as an interval list and

then it is sorted by the *start*. Then an augmenting value is added to each data element (interval). Two different augmenting values may be used: the running maximum *end* value *MaxE*, or the sorted *end* value *SortedE*. In the following discussion, we will use *MaxE*, which is similar to the interval tree and the *SortedE* method can be found in the *Supplementary Information*.

Figure 1(a) shows a simple augmented interval list (AIList). The augmenting value MaxE is the maximum end value counting from the first interval. It reflects the containment relationship among the intervals: the 2^{nd} interval [3,8) contains the 3^{rd} interval [5,7) and they have the same MaxE value of 8; similarly the 4^{th} interval [7,20) contains the next three intervals and they all have the same MaxE value of 20. In another word, MaxE marks a list of containment sublists.

To find the overlaps for a query, such as [9,12), we first do a binary search over the list to get the index of the last interval I_E that has start < 12, which is the 5th element [9,10,20); then we only need to check intervals from the 5th to the 4th because their MaxE > 9 and stop at the 3rd [5,7,8) since its MaxE < 9 and we can skip all comparisons on the left. This is very efficient since we only checked one extra element at the stop. But if the query is [17,21), then we need to check 6 interval elements from the 8th [19,30,30) back to the 3rd [5,7,8), which contains 4 extras, so it is not as efficient. The first query represents the best case and the second is the worst case for this list. Since there is another long coverage with MaxE value of 30 in the list, the overall or average query efficiency would be more close to the worst case.

To improve the overall query efficiency, we need to reduce the length of the long coverage sublists. This can be achieved by taking out the intervals with longest coverage and put them in a separated list or attach them to the end of original list. Figure 1(b) shows an example. By taking out intervals that covers the next 3 (coverage length criterion) or more elements in the above list, we get two sublists L1 and L2. Now in L1 there are only two containment sublists and both have the minimum length of 2, and there is no containment in L2; so query in both lists would be or close to be the best. To get the index I_E in L1 and L2 now we need two separated binary searches. Since the index of an item in the original list is the sum of the index in L1 and the index in L2, an optional structure list Opt can be used to facilitate the search, see figure 1(c). Opt keeps the sorted start from 1(a) and the link start in start 1 is start 1 in start 2. In practice, the time taken by the binary search is only a very small portion of the total time, so it is not very necessary to use this optional structure.

It is apparent that a list can be split into three or more sublists with two or more coverage length criteria in a similar way as above. But this is not necessary for real genomic sequence datasets that we have tested. Also the optimal length criterion for a list to be split is found to be about 20; the size of the split L2 is usually much smaller than L1, and many

datasets do not need to be split. Similar to other algorithms mentioned above, the query time complexity for AIList is $O(\log N + n + m)$, but the average number of extra comparisons m should be, in general, smaller than others'.

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Algorithm 1: AIListSearch(L1, L2, Opt, start, end)
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```
H \leftarrow 0
i \leftarrow \text{BinarySearchStart}(Opt, end)
i1 \leftarrow Opt[i].index
i2 \leftarrow i - i1
while i1 > 0 and L1[i1].MaxE > start do
    if L1[i1].end > start:
    H \leftarrow H \cup L1[i1]
i1 \leftarrow i1 - 1
end while
... repeat the above while section for L2 with i2 ...
Return H
```

3. Results

AIList is implemented in C. To evaluate the efficiency of AIList, we compared the performance of AIList with interval tree (AITree), nested containment list (NCList) and R-tree. For AITree we used the rbtree-based interval tree from Linux kernel, which was implemented by Landley (2007); for NCList we used the C-code intervaldb.c implemented by the original authors; and for R-tree we used the popular C++ implementation BEDTools by Quinlan and Hall (2011). Seven genomic datasets that have number of intervals from ~ 200 thousand to 128 million are used in the evaluation, where the two small datasets are from BedTools site and the other five are from UCSC site. One of the median sized dataset chainRn4 is used as the query set, the other six are used as database set, see Table 1. Information about all these data and code can be found in Supplementary Information.

Figure 2 shows the total time with respect to the data size for AIList, AITree, NCList and BEDTools. The time includes the dataset loading, data structure construction and searching, so it reflects the overall efficiency of the algorithms. For small size datasets, AIList is about 2 times faster than AITree and NCList and 3 times faster than BEDTools and for large size datasets AIList can be 4-5 times faster than AITree and NCList and up to 18 times faster than BEDTools.

4. Conclusion

An augmented interval-list (AIList) algorithm is presented. The interval list is first sorted by interval start, then partitioned into two approximately normalized sub-lists, and then an augmenting list of the maximum interval end is added to each sub-list. The query time is O(n+logN), where n is the number of overlaps and N is the size of the dataset. Tested with genomic interval datasets, code based on this algorithm runs significantly faster than code based on existing algorithms such as augmented interval-tree (AITree), nested containment list (NCList) and R-tree.

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Supplementary Information

1. Interval list augmented with a list of sorted interval end

The augmenting list SortedE is the sorted list of all interval ends. First find the last interval I_E in R that satisfies r.start < q.end with a binary search, which excludes all intervals on the right. Since SortedE is sorted by the end, we can find the leftmost element I_S that is equal to or larger than q.start. This excludes all elements on the left of I_S . The number of intersections is $I_E - I_S + 1$. This algorithm does not directly find I_S , instead it simultaneously enumerates SortedE and R from I_E to the left.

```
Algorithm 1: AIListSearch(L1, L2, Opt, start, end)
```

```
H \leftarrow 0
i \leftarrow \text{BinarySearchStart}(Opt, end)
i1 \leftarrow Opt[i].index
i2 \leftarrow i - i1
t \leftarrow 0
while i1 > 0 and L1 [i1].SortedE > start do
         t \leftarrow t + 1
         if L1[i1].end > start:
                  H \leftarrow H \cup L1 \lceil i1 \rceil
                   t \leftarrow t - 1
         i1 \leftarrow i1 - 1
end while
while t > 0 do
         if L1[i1].end > start:
                  H \leftarrow H \cup L1[i1]
                   t \leftarrow t - 1
         i1 \leftarrow i1 - 1
end while
\dots repeat the above for L2 with i2 \dots
Return H
```

3. Source code

REFERENCES

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