

PS2

Q1. CE consists of prices $\{p_t, w_t, r_t\}_{t=0}^{\infty}$ and
allocations for firm $\{k_t^d, l_t^d, k_t^s, l_t^s, y_t\}_{t=0}^{\infty}$,
 $\{c_t, i_t, x_{t+1}, k_{t+1}\}_{t=0}^{\infty}$ s.t.

- given prices $\{p_t, w_t, r_t\}_{t=0}^{\infty}$, the allocation of repr. NY
 $\{c_t, i_t, x_{t+1}, k_t^s, l_t^s\}_{t=0}^{\infty}$ solves user's problem

$$\max \sum_{t=0}^{\infty} \beta^t u(c_t, l_t)$$

$$\text{s.t. } \begin{cases} c_t, i_t, x_{t+1}, k_t^s, l_t^s \\ \sum_{t=0}^{\infty} p_t (c_t + i_t) \leq \sum_{t=0}^{\infty} p_t (r_t k_t + w_t l_t) + \pi \end{cases}$$

$$x_{t+1} = (1-\delta)x_t + i_t$$

$$0 \leq k_t \leq x_t$$

$$0 \leq l_t \leq 1 \quad t \geq 0$$

$$c_t, x_{t+1} \geq 0$$

- given prices $\{p_t, w_t, l_t\}_{t=0}^{\infty}$

$\{k_t^d, l_t^d, y_t\}_{t=0}^{\infty}$, the allocation of repr. firms
 $\{y_t, k_t^s, l_t^s\}_{t=0}^{\infty}$ solves firm's problem:

$$\pi^* = \max \sum_{t=0}^{\infty} p_t (y_t - r_t k_t - w_t l_t)$$

$$\text{s.t. } y_t = F(k_t, l_t) \quad t \geq 0$$

$$y_t \geq r_t k_t, l_t \geq 0$$

- markets clear, i_t

$$i_t = c_t + i_t$$

$$l_t^d = l_t^s$$

$$k_t^d = k_t^s$$

$$u(c_t, l_t) = \frac{c_t^{1-\alpha}}{1-\alpha} - \gamma \frac{l_t^\alpha}{1+\gamma}$$

$$F(k_t, l_t) = \alpha K^\alpha L^{1-\alpha}$$

(2)

d) Rewrite the problem!

assume $t=0$

$$l_t = 1 \quad \forall t$$

 u is strictly η & concave.

$$k_t = x_t \quad \forall t$$

$$\max_{\{c_t, k_{t+1}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t \left(\frac{c_t^{1-\delta}}{1-\delta} - \gamma \frac{k_t^{1+\eta}}{1+\eta} \right)$$

$$\text{st. } \sum_{t=0}^{\infty} \beta^t \mu_t (c_t + k_{t+1} - (1-\delta)x_t) = \sum_{t=0}^{\infty} \beta^t (\pi_t k_t + \omega_t) \quad \forall t$$

$$c_t, k_{t+1} \geq 0 \quad \forall t$$

to given

$$\text{FOC}_c: \text{sat } c_t \sqrt{\frac{1-\delta}{1+\eta}} c_t^{-\delta} = \mu_t \quad \text{sat } k_t: \beta \frac{\pi_t}{1+\eta} (1+\eta) k_t^\eta = 0$$

$$\beta^{t+1} c_{t+1}^{-\delta} = \mu_{t+1}$$

$$\text{sat } k_{t+1}: \mu_{t+1} = \mu_t (1-\delta + r_{t+1}) / \mu_{t+1}$$

$$\frac{\beta c_{t+1}^{-\delta}}{c_t^{-\delta}} = \frac{\mu_{t+1}}{\mu_t} = \frac{1}{1+r_{t+1}-\delta} \quad \forall t$$

$$\beta \left(\frac{c_{t+1}}{c_t} \right)^{-\delta} = \frac{1}{1+r_{t+1}-\delta}$$

Firm's FOC: (same as in PS1)

$$-r_t \mu_t + \mu_t F_k(k_t, c_t) = 0$$

$$F_k(k_t, c_t) = \alpha \times k_t^{\alpha-1} \times c_t^{1-\alpha}$$

$$-\omega_t \mu_t + F_k(k_t, c_t) = 0$$

$$= (1-\alpha) \times \omega_t \times c_t^{1-\alpha} = 1$$

Substitute market clearing conditions & using firm's FOCs:

$$C = F(k_t, l_t) - [k_{t+1} - (1-\delta)k_t]$$

$$\frac{\beta \left(\frac{z k_t^{\alpha} l_t^{1-\alpha}}{z k_{t+1}^{\alpha} l_{t+1}^{1-\alpha}} - k_{t+1} + (1-\delta)k_t \right)^{-\delta}}{(z k_t^{\alpha} l_t^{1-\alpha} - k_{t+1} + (1-\delta)k_t)^{-\delta}} = \frac{1+r_{t+1}-\delta}{1}$$

$$(z k_{t+1}^{\alpha} l_{t+1}^{1-\alpha})^{-1}$$

at steady state:

$$C_t = C^* = C_{t+1}$$

$$k_{t+1} = k^* = k_{t+2}, r_t = r_{t+1} = r^*$$

$$l_t = l^* = l_{t+1}$$

$$\frac{1}{1+r-\delta} = \beta$$

$$1+r-\delta = \frac{1}{\beta}$$

$$r^* = \frac{1}{\beta} - 1 + \delta$$

$$\frac{1}{\beta} - 1 + \delta = \alpha z k^{*\alpha-1}$$

$$k^{*\alpha-1} = \frac{1}{\beta} - 1 + \delta \quad | \quad \frac{1}{\alpha-1}$$

$$k^* = \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{1}{\alpha-1}}$$

$$C^* = z k^{*\alpha} - k^* + (1-\delta)k^* =$$

$$= z k^{*\alpha} + k^*(1-\delta-1) = z k^{*\alpha} - k^*$$

$$= z \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{\alpha}{\alpha-1}} - \delta \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{1}{\alpha-1}}$$

$$y^* = C^* + k^* - (1-\delta)k^* =$$

$$= C^* + k^*(1-1+\delta) = C^* + k^*\delta =$$

$$= z \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{\alpha}{\alpha-1}} - \delta \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{1}{\alpha-1}} +$$

$$+ \delta \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{1}{\alpha-1}}$$

$$w^* = (1-\alpha)z k^{*\alpha} = (1-\alpha)z \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{\alpha}{\alpha-1}}$$

$$= z \left(\frac{1}{\beta} - 1 + \delta \right)^{\frac{\alpha}{\alpha-1}}$$

(4)

(3)

$$w(\bar{k}_0) = \max_{\{c_t, k_t\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t w(c_t, k_t)$$

$$\text{s.t. } F(k_t, c_t) = z k_t^\alpha c_t^{1-\alpha}$$

$$F(k_t, c_t) = c_t + k_{t+1} - (1-\delta)k_t$$

$$c_t \geq 0$$

$$k_t \geq 0$$

$$0 \leq c_t \leq k_t$$

$$k_0 \leq \bar{k}_0$$

k_0 given

$$u(c_t, k_t) = \frac{c_t^{1-\delta}}{1-\delta} + \frac{k_t^{\gamma}}{1+\gamma}$$

all info is contained
in past capital

bc choice is static,
so we can find it.
solution given k_t, k_{t+1}

$$c_t = F(k_t, k_{t+1}) + (1-\delta)k_t - k_{t+1}$$

$$w(k_0) = \max_{\substack{k', l \\ 0 \leq k' \leq z k_0^\alpha}} \underbrace{u(z k_0^\alpha + (1-\delta)k_0 - k', l)}_{c} -$$

$$k' \text{ given}$$

The idea is to use MRE,

$$\chi(k, k') = F(k, \tilde{\chi}(k, k')) -$$

$$- k' + (1-\delta)k$$

where $\tilde{\chi}(k, k')$ is from static problem.

BE:

$$V(k) = \max_{\substack{k' \\ 0 \leq k' \leq z k^\alpha}} \{ F(k, \chi) + (1-\delta)k - k' + \beta V(k') \}$$

$$k' \text{ given}$$

$$k_t = \frac{(1-\delta)c_t^{\frac{1}{1-\alpha}} + R_t^{\frac{1}{1-\alpha}}}{\chi}$$

$$\Leftrightarrow (l_t)^{\frac{1}{1-\alpha}} = \frac{(1-\delta)c_t^{\frac{1}{1-\alpha}} + R_t^{\frac{1}{1-\alpha}}}{\chi}$$

$$\begin{aligned} & \text{Static problem:} \\ & \max_{c_t, k_t} \left(\frac{c_t^{1-\delta}}{1-\delta} + \frac{k_t^{\gamma}}{1+\gamma} \right) \\ & \text{s.t. } c_t = z k_t^\alpha l_t^{1-\alpha} - k_{t+1} + (1-\delta)k_t \\ & l_t, c_t \geq 0 \end{aligned}$$

$$\frac{\partial c_t}{\partial k_t} = \frac{1}{1-\delta} \cdot k_t^{-\delta} c_t^{-\delta} = \lambda$$

$$\begin{aligned} \partial k_t &: -\lambda \frac{\gamma(1+\gamma)}{1+\gamma} l_t^{\frac{\gamma}{1+\gamma}} + z k_t^\alpha l_t^{-\alpha} \cdot (1-\alpha) = 0 \\ & \lambda l_t^{\frac{\gamma}{1+\gamma}} = (1-\alpha) z k_t^\alpha l_t^{-\alpha} \end{aligned}$$

$$\lambda l_t^{\frac{\gamma}{1+\gamma}} = (1-\alpha) c_t^{-\delta} z k_t^\alpha l_t^{-\alpha}$$

$$\frac{l_t^{\frac{\gamma}{1+\gamma}}}{l_t^{-\alpha}} = \frac{(1-\alpha) c_t^{-\delta} z k_t^\alpha}{\chi}$$

(6)

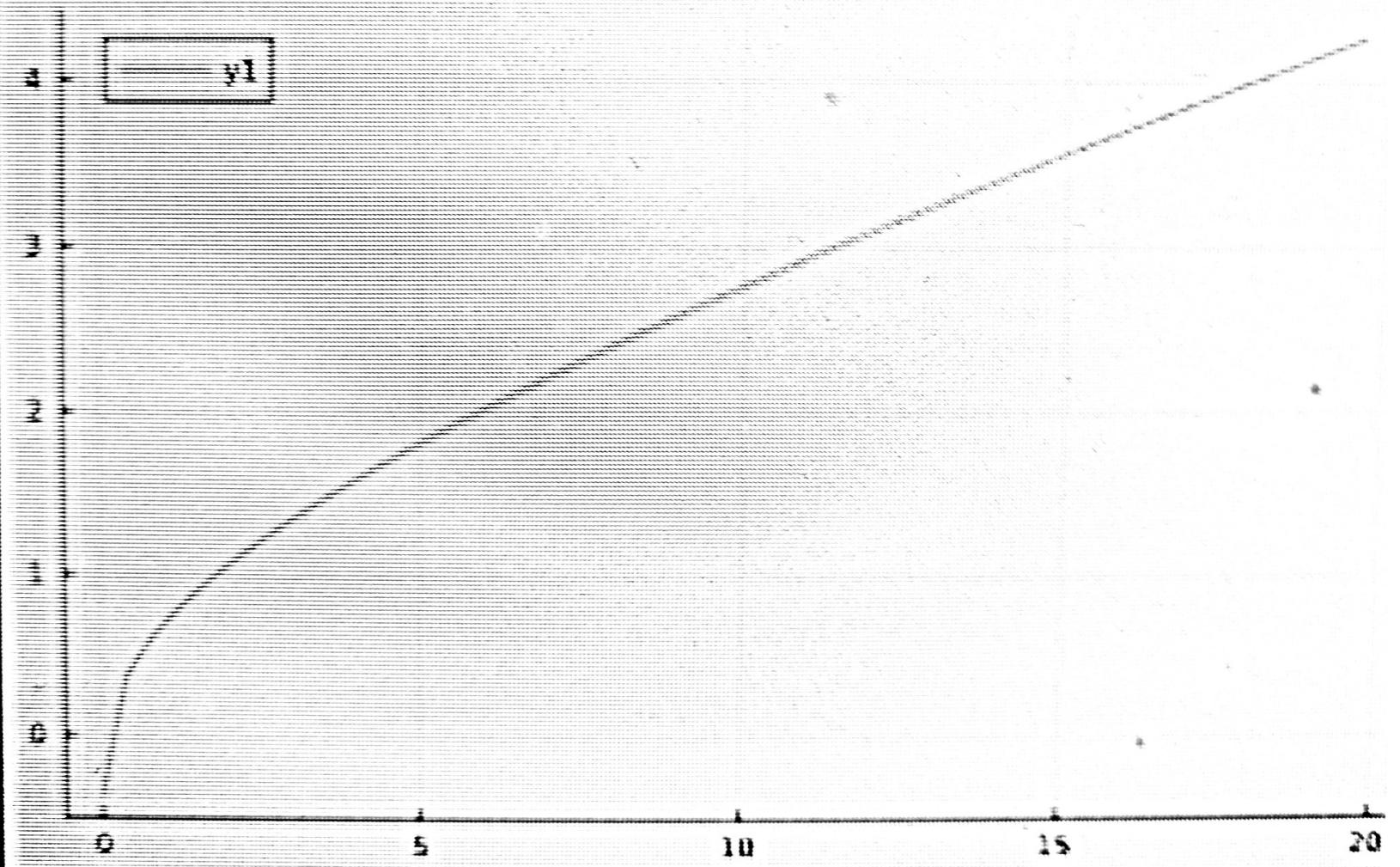
$$t_K \geq 0$$

$$\begin{aligned}
 v_{\pi^*} - v_{\pi_K} &= T_{\pi^*} v_{\pi^*} - T_{\pi_K} v_{\pi_{K-1}} + T_{\pi_K} v_{\pi_{K-1}} - \\
 &\quad - T_{\pi_K} v_{\pi_{K-1}} + T_{\pi_K} v_{\pi_{K-1}} - T_{\pi_K} v_{\pi_K} \leq \\
 &\leq \beta(v_{\pi^*} - v_{\pi_{K-1}}) + \beta(v_{\pi_{K-1}} - v_{\pi_K}) \leq \\
 &\leq \beta(v_{\pi^*} - v_{\pi_{K-1}})
 \end{aligned}$$

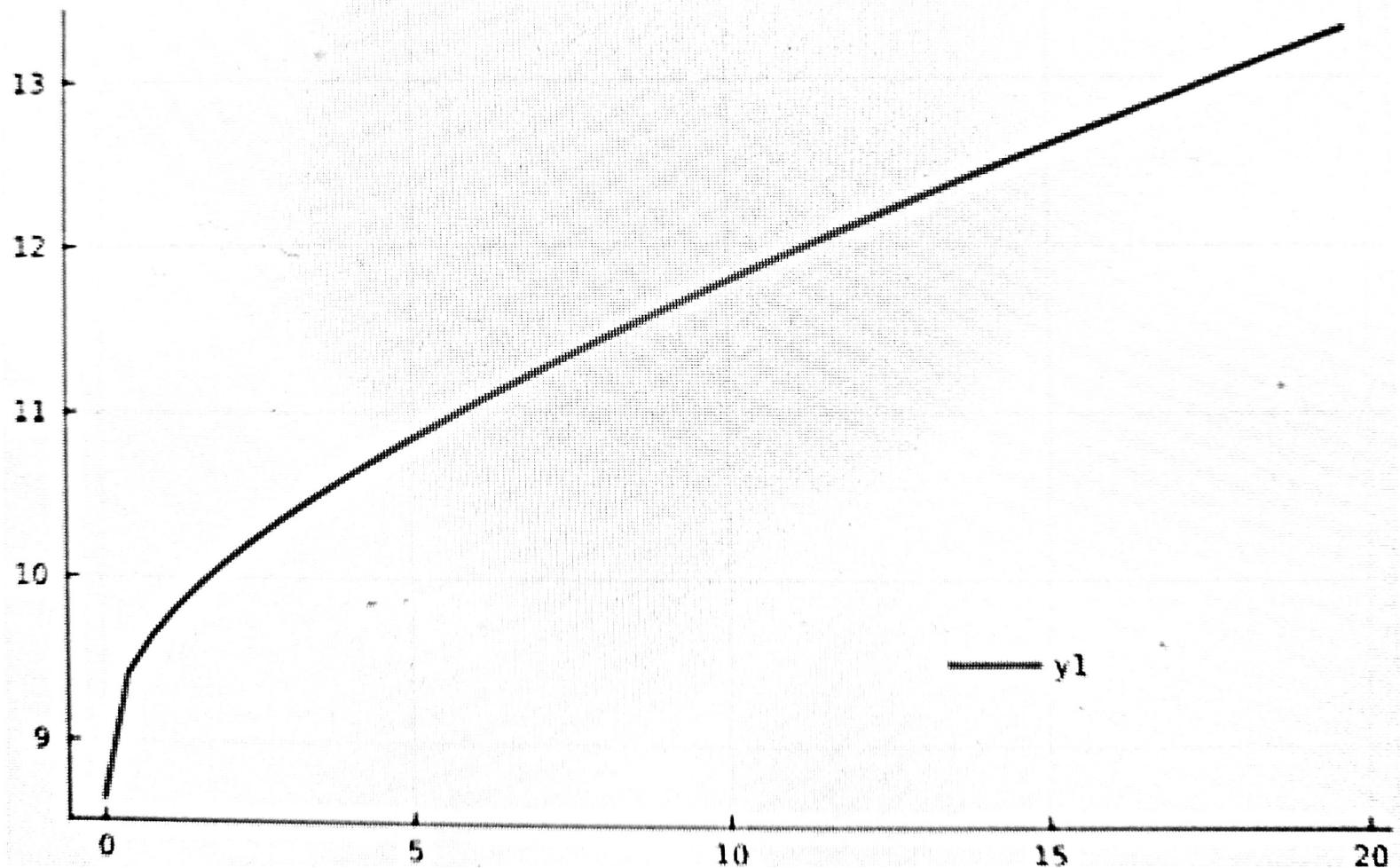
Because $v_{\pi^*} - v_{\pi_K}$ is non-negative,

$$\|v_{\pi^*} - v_{\pi_K}\|_\infty \leq \beta \|v_{\pi^*} - v_{\pi_{K-1}}\|_\infty \Rightarrow \text{contradiction.}$$

Consumption



Value Function



(4)

$$l_{ss} = 0.4$$

$$l_{ss} = \left[\frac{(1-\alpha)C^{*-2}ZK^{*\alpha}}{X} \right]^{1/\beta+\alpha}$$

$$\alpha = \frac{1}{3}$$

$$Z = 1$$

$$\sigma = 2$$

$$\gamma = 1$$

$$0.4 = \left[\frac{(1-\frac{1}{3})C^{*-2} - 1 \cdot K^{*1/3}}{X} \right]^{1/1/3}$$

$$K^* = \left(\frac{\frac{1}{0.96} - 1 + 1}{\frac{1}{3} \cdot 1} \right)^{\frac{1}{1/3-1}}$$

$$\det \beta = 0.96$$

$$\delta = 0.9$$

$$C^* = 1 \cdot \left(\frac{\frac{1}{0.96} - 1 + 1}{\frac{1}{3} \cdot 1} \right)^{\frac{1}{1/3-1}} - 1 \sqrt{\frac{\frac{1}{0.96} - 1 + 1}{\frac{1}{3} \cdot 1}}^{\frac{1}{1/3-1}}$$

From screen

Code is attached.

$$\gamma = 0.0817 \text{ based on code}$$

VFT-Grid search - h, k=50
Iterations = 431
Distance = 9. 8932
430.89 seconds

(5), (6) Code and figures attached.

(7) Below is based on paper "Improved & Generalised Upper bounds on the Complexity of POMDP" by B. Scherrer
State space X is finite; A , action space, at each stage 2018.
a reward function $r(a)$; $\pi: X \rightarrow A$, policy map. max $\pi(a|s)$ there is a discounted sum of rewards from t state ; $\beta \in (0, 1)$
 $v_\pi = \max_a v_\pi$ optimal value; $V_\pi = r_\pi + \beta V_\pi$ is BE with

V_π is a fixed point of operator $T_\pi: v \rightarrow r_\pi + \beta v$;

$v_* = \max \{ r_\pi + \beta v_* \} = \max T_\pi v_*$, where v_* is a fixed point of operator $T: v \rightarrow \max_\pi T_\pi v$.

WTS, one sequence $|v_{\pi_k} - v_{\pi_{k+1}}|$ will be built by Howard's PT is contraction with coeff. β .

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(5)