Bayesian Inference

Ryan Henning Frank Burkholder

galvanıze

- Frequentists vs.
 Bayesian
- 2. Bayes' Rule
- 3. Prior, likelihood, posterior distributions



What is the probability that it rained in my city last night?

(No info is given about which city I'm currently in.)

$$P(\text{rain}) = 0.1$$

What is the probability that it rained in my city last night given that I'm in Seattle?

$$P(\text{rain}|\text{Seattle}) = 0.65$$



What is the probability that it rained in my city last night?

(No info is given about which city I'm currently in.)

$$P(\text{rain}) = 0.1$$

What is the probability that it rained in my city last night given that I live in Seattle and I see that the road is wet?

$$P(\text{rain}|\text{Seattle}, \text{wet roads}) = 0.97$$



Defining probability

Frequentist Probability

"Long Run" frequency of an outcome

Subjective Probability

A measure of degree of belief

Bayesians consider both types



Experiment 1:

A fine classical musician says he's able to distinguish Haydn from Mozart. Small excerpts are selected at random and played for the musician. Musician makes 10 correct guesses in exactly 10 trials.

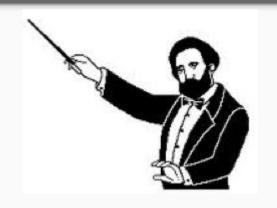


Experiment 2:

Drunken man says he is psychic and can correctly guess what face of the coin will fall down, mid-air. Coins are tossed and the drunken man shouts out guesses while the coins are mid-air. Drunken man correctly guesses the outcomes of the 10 throws.







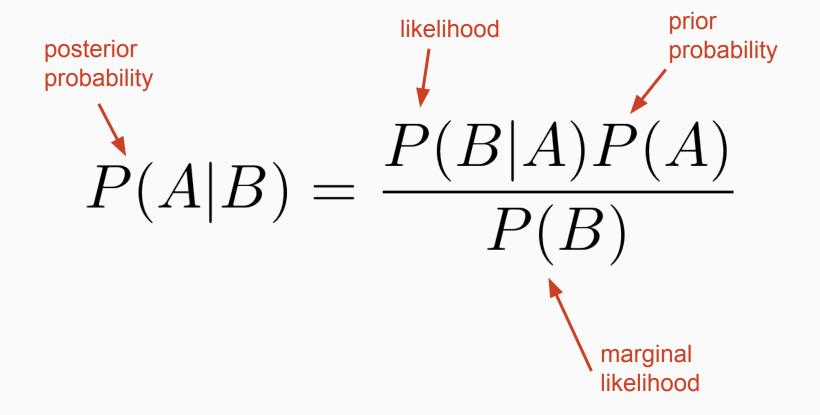


<u>Frequentist:</u> "They're both so skilled! I have **as much confidence** in musician's ability to distinguish Haydn and Mozart
as I do the drunk's psychic ability to predict coin tosses"

Bayesian: "I'm not convinced by the drunken man..."

The Bayesian approach is to incorporate prior knowledge into the experimental results.

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$



$$P(\text{psychic}|\text{correct}) = \frac{P(\text{correct}|\text{psychic})P(\text{psychic})}{P(\text{correct})}$$

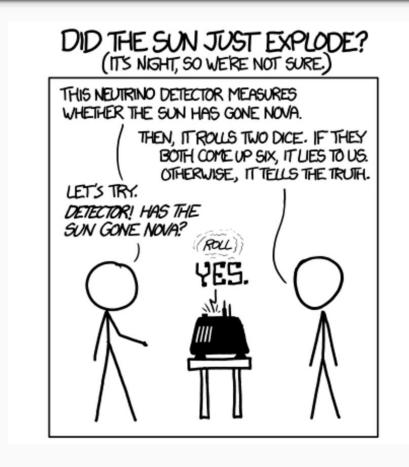
$$=\frac{1.0*0.0001}{0.5^{10}}$$

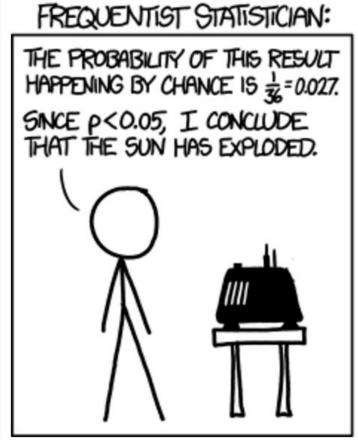
= 10.2%











BAYESIAN STATISTICIAN:







Is this coin fair? (i.e. is the probability of Heads = 0.5?)



A: the distribution associated with the probability of flipping heads (success)

B: the results of our flips (number of heads, number of trials)

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$



A: the distribution associated with the probability of flipping heads (success)

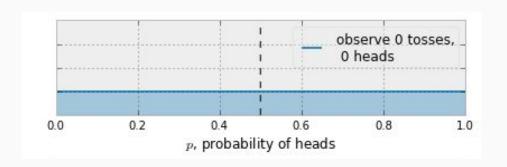
B: the results of our flips (number of heads, number of trials)

 $P(A|B) = \frac{1}{2}$ posterior probability (the probability of heads given the flips)

likelihood (the data gathered, #H #T)

prior probability (our belief about the probability of heads, initially, but after collecting data it's the old posterior)





No data

Uniform prior -> Uniform posterior

A: the distribution associated with the probability of flipping heads (successes)

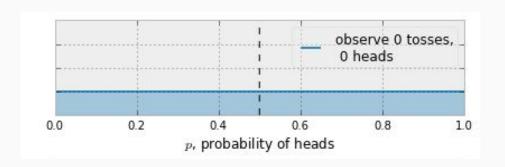
B: the results of our flips (number of heads, number of trials

posterior probability
(the probability of heads
given the flips)

likelihood (the data gathered, #H #T) $B) = \frac{P(B|A)P(A)}{P(B)}$ obability

prior probability (our belief about the probability of heads, initially, but after collecting data it's the old posterior)





No data

Uniform prior -> Uniform posterior Note that they are both continuous.

A: the distribution associated with the probability of flipping heads (successes)

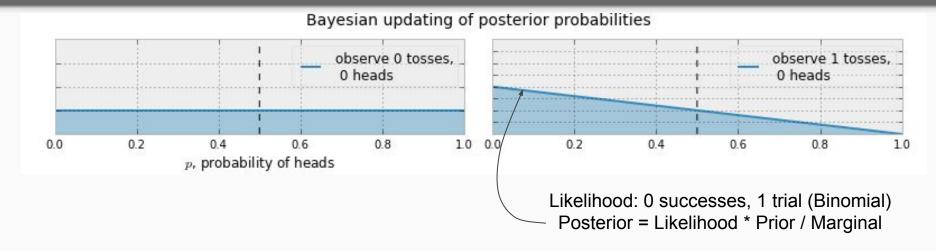
B: the results of our flips (number of heads, number of trials

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(the probability of heads
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Posterior becomes the *new prior* for the next posterior calculation

A: the distribution associated with the probability of flipping heads (successes)

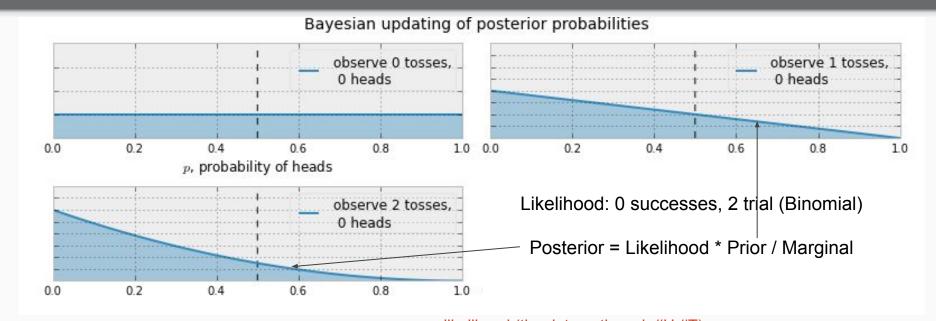
B: the results of our flips (number of heads, number of trials)

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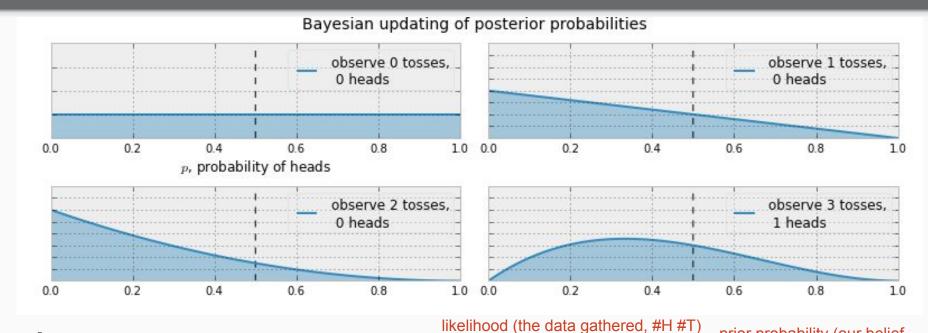
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B: the results of our flips (number of heads, number of trials)

posterior probability (the probability of heads given the flips)

likelihood (the data gathered, #H #T) prior probability (our belief about the probability of heads, initially, but after collecting data it's the old posterior)



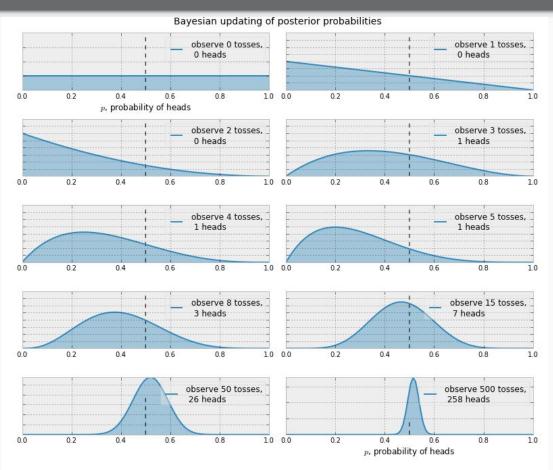


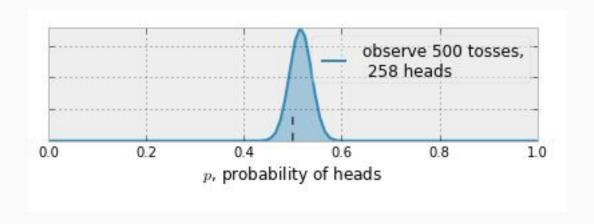
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B: the results of our flips (number of heads, number of trials)

posterior probability (the probability of heads given the flips) prior probability (our belief about the probability of heads, initially, but after collecting data it's the old posterior)







Bayesian Updating in Code



bayesian_updating_simple_example.ipynb