

Lukas Schmid

Postdoctoral Research Fellow
MIT SPARK Lab
Dept. of Aeronautics and Astronautics
Massachusetts Institute of Technology
77 Massachusetts Avenue, Room 45-601N
Cambridge, MA 02139, USA

✉ lschmid@mit.edu
🌐 schmluk.github.io
🆔 0000-0002-3961-8145
🎓 Lukas Schmid

Updated July 2024.

Research Interests

I'm passionate about autonomy for intelligent mobile systems. In particular, my research focuses on active and passive perception and understanding of complex, dynamic, and changing environments for robotic interaction and augmented reality. This includes research on representations of dense geometric and semantic models of an environment, scene abstraction and understanding. I work on extending these map representations to model challenging and dynamic environments, by recognizing short-term moving and long-term changing entities, predicting spatial and temporal changes, and building systems that continuously learn, improve, and adapt over time. My third research area focuses on utilizing these world representations, predictions, and knowledge for active perception and interaction planning. This includes autonomously building such representations and knowledge in unknown environments, active adaptation and learning for robots, and utilizing these world models and knowledge for effective planning. I demonstrate these novel concepts and methods through implementation of the algorithms and approaches on-board compute constrained autonomous mobile robots in interactive real-time missions.

Robotics - AI - Perception - Autonomy - Learning - Mapping - Planning

Education

- 7.2019-10.2022 **Dr. Sc. with Autonomous Systems Lab (ASL) at ETH Zürich, CH.**
- Thesis: Robust Active Perception and Volumetric Mapping in Unknown Changing Environments. Cumulative thesis of 6 first-authored papers.
 - Supervised by Prof. Roland Siegwart, Cesar Cadena, and Juan Nieto, in collaboration with Prof. Marc Pollefeys, Jeffrey Delmerico, Johannes Schönberger, and Helen Oleynikova at Microsoft.
 - Awarded the ETH Medal for outstanding PhD Theses.
- 9.2017-6.2019 **M. Sc. Robotics, Systems and Control (RSC) at ETH Zürich, CH.**
- Graduated with Distinction.
 - Awarded the Willi Studer Prize for the best graduate of the year.
 - Awarded the ETH Medal for outstanding Master Theses.
- 9.2013-9.2016 **B. Sc. Mechanical Engineering at ETH Zürich, CH.**
- 9.2013-9.2016 **Grammar School in Frauenfeld, CH.**
- Graduated with Distinction.
 - Honored with the Outstanding Matura Thesis Award.

Employment

- 2.2023-current **Postdoctoral Research Fellow**, MIT, Cambridge, MA, USA.
 - Working with Prof. Luca Carlone at the MIT-SPARK Lab on higher-level scene understanding and dynamic 3D scene graphs.
- 10.2022-1.2023 **Postdoctoral Researcher**, ETH Zürich, CH.
 - Working with Prof. Roland Siegwart at the Autonomous Systems Lab.
- 11.2021-2.2022 **Visiting Researcher** at Microsoft Mixed Reality and AI Lab, Zürich, CH.
 - Working with Prof. Marc Pollefeys, Juan Nieto, Jeffrey Delmerico, and Johannes Schönberger on Panoptic Multi-TSDFs and Active Perception in Changing Scenes.
 - Proposed and started two joint Master Theses, one on Incremental 3D Scene Graph Generation and one on Active Perception for Visual Long-term Re-localization.
- 7.2019-10.2022 **Doctoral Researcher**, ETH Zürich, CH.
 - Working with Prof. Roland Siegwart at the Autonomous Systems Lab.
- 9.2018-2.2019 **Teaching Assistant** at ETH Zürich, with Prof. Joachim Buhmann, D-INFK.
- 2.2017-6.2017 **Maintenance Engineer** at BOSCH, sia Abrasives Industries AG, 8500 Frauenfeld, CH.
- 9.2016-2.2017 **Engineering Intern** at BOSCH, sia Abrasives Industries AG, 8500 Frauenfeld, CH, Department of Technical Functions.
- 1.2014-2.2014 **Workshop Intern**, at Phoenix Mechano, 8260 Stein am Rhein, CH.
- 2009-2013 5+ shorter periods of work (1-4 weeks) at different companies during breaks.

Publications

Journal Articles

- [J7] A. Ahmad, I. Arora, S. Cataldi, J. Cottet, E. El Khoury, B. Gnanon, T. Kinder, R. Lafer-Sousa, M. Levinstein, L. Majure, L. Nguyen, **L. Schmid**, M. Smith, E. Ventriglia, and S. Wang, "What Does It Take to Successfully Advocate for Postdoctoral Scholars?", in *The Postdocket*, National Postdoctoral Association, vol. 22, no. 1, 2024. [Journal]
- [J6] **L. Schmid**, O. Andersson, A. Sulser, P. Pfreundschuh, and R. Siegwart, "Dynablox: Real-time Detection of Diverse Dynamic Objects in Complex Environments", in *IEEE Robotics and Automation Letters (RA-L)*, vol. 8, no. 10, pp. 6259-6266, 2023. [Journal] [ArXiv] [Code] [Video]
- [J5] R. Zurbrugg, H. Blum, C. Cadena, R. Siegwart, and **L. Schmid**, "Embodied Active Domain Adaptation for Semantic Segmentation via Informative Path Planning", in *IEEE Robotics and Automation Letters (RA-L)*, vol. 7, no. 4, pp. 8691-8698, 2022. [Journal] [ArXiv] [Code] [Video]

- [J4] **L. Schmid**, C. Ni, Y. Zhong, R. Siegwart, and O. Andersson, "Fast and Compute-efficient Sampling-based Local Exploration Planning via Distribution Learning", in *IEEE Robotics and Automation Letters (RA-L)*, vol. 7, no. 2, pp. 7810-7817, 2022. [Journal] [ArXiv] [Code] [Video]
- [J3] **L. Schmid**, V. Reijgwart, L. Ott, J. Nieto, R. Siegwart, and C. Cadena, "A Unified Approach for Autonomous Volumetric Exploration of Large Scale Environments under Severe Odometry Drift", in *IEEE Robotics and Automation Letters (RA-L)*, vol. 6, no. 3, pp. 4504-4511, 2021. [Journal] [ArXiv] [Code] [Video]
- [J2] **L. Schmid**, M. Pantic, R. Khanna, L. Ott, R. Siegwart, and J. Nieto, "An Efficient Sampling-based Method for Online Informative Path Planning in Unknown Environments", in *IEEE Robotics and Automation Letters (RA-L)*, vol. 5, no. 2, pp. 1500-1507, 2020. [Journal] [ArXiv] [Code] [Video]
- [J1] R. Khanna, **L. Schmid**, A. Walter, J. Nieto, R. Siegwart, and F. Liebisch, "A Spatio Temporal Spectral Framework for plant Stress Phenotyping", in *Plant Methods*, vol. 15, no. 1, pp. 1-18, 2019. [Journal] [Code]

Peer-reviewed Conference Papers

- [C5] **L. Schmid**, M. Abate, Y. Chang, and L. Carlone, "Khronos: A Unified Approach for Spatio-Temporal Metric-Semantic SLAM in Dynamic Environments", in *Robotics: Science and Systems (RSS)*, Delft, The Netherlands, July, 2024. [ArXiv] [Video] [Code] **[Best Paper Award]**
- [C4] S. Looper, J. Rodriguez-Puigvert, R. Siegwart, C. Cadena, and **L. Schmid**, "3D VSG: Long-term Semantic Scene Change Prediction through 3D Variable Scene Graphs", in *IEEE International Conference on Robotics and Automation (ICRA)*, London, UK, May, 2023. [IEEE] [ArXiv] [Code]
- [C3] **L. Schmid**, J. Delmerico, J. Schonberger, J. Nieto, M. Pollefeys, R. Siegwart, and C. Cadena, "Panoptic Multi-TSDFs: a Flexible Representation for Online Multi-resolution Volumetric Mapping and Long-term Dynamic Scene Consistency", in *IEEE International Conference on Robotics and Automation (ICRA)*, Philadelphia (PA), USA, May, 2022. [IEEE] [ArXiv] [Code] [Video]
- [C2] S. Lionar, **L. Schmid***, C. Cadena, R. Siegwart, and A. Cramariuc, "NeuralBlox: Real-Time Neural Representation Fusion for Robust Volumetric Mapping", in *IEEE International Conference on 3D Vision (3DV)*, London, United Kingdom, December, 2021. [IEEE] [ArXiv] [Code]
- [C1] T. Digumarti, **L. Schmid***, G. Rizzi, J. Nieto, R. Siegwart, P. Beardsley, and C. Cadena, "An Approach for Semantic Segmentation of Tree-like Vegetation", in *IEEE International Conference on Robotics and Automation (ICRA)*, Montreal, Canada, May, 2019. [IEEE]

Peer-reviewed Workshop Contributions

- [W1] M. Müller, J. Lim, **L. Schmid**, H. Blum, W. Stürzl, A. Gawel, R. Siegwart, and R. Triebel, "Interactive OAISYS: A photorealistic terrain simulation for robotics research", in *IEEE ICRA 2022 Workshop on Releasing Robots into the Wild: Simulations, Benchmarks, and Deployment*, Philadelphia(PA), USA, May, 2022. [Paper] [Code]

Preprints

- [P4] F. Rockenbauer, J. Lim, M. Müller, R. Siegwart, and **L. Schmid**, "Traversing Mars: Co-operative Informative Path Planning to Efficiently Navigate Unknown Scenes", in *ArXiv Preprint*, 2024. [ArXiv] [Code]
- [P3] D. Maggio, Y. Chang, N. Hughes, M. Trang, D. Griffith, C. Dougherty, E. Cristofalo, **L. Schmid**, and L. Carlone, "Clio: Real-time Task-Driven Open-Set 3D Scene Graphs", in *ArXiv Preprint*, 2024. [ArXiv] [Video] [Code]
- [P2] N. Gorlo, **L. Schmid**, and L. Carlone, "Long-Term Human Trajectory Prediction using 3D Dynamic Scene Graphs", in *ArXiv Preprint*, 2024. [ArXiv] [Video] [Code]
- [P1] **L. Schmid**, M. N. Cheema, V. Reijgwart, R. Siegwart, F. Tombari, and C. Cadena, "SC-Explorer: Incremental 3D Scene Completion for Safe and Efficient Exploration Mapping and Planning", in *ArXiv Preprint*, 2022. [ArXiv] [Video] [Code]

Other Publications

- [O2] **L. Schmid**, "Robust Active Perception and Volumetric Mapping in Unknown Changing Environments", in *Doctoral Thesis, Dr. Sc. ETH Zürich*, 2022. [ETH]
- [O1] **L. Schmid**, "Active Path Planning for 3D Reconstruction with UAVs", in *Master Thesis, M.Sc. Robotics, Systems and Control (RSC) ETH Zürich*, 2019. [ETH]

* Indicates shared first author, second listed.

Awarded Grants

2022	Swiss National Science Foundations (SNSF) Postdoc.Mobility Career Grant, "Robust Robotic Scene Understanding in Complex, Changing Environments using 3D Dynamic Scene Graphs".
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Awards and Honors

2024	Best Paper Award at Robotics: Science and Systems (RSS) 2024.
2024	First Place in the "Nothing Stands Still" 2024 Hilti SLAM Challenge.
2023	ETH Medal for outstanding PhD thesis.
2020	Willi Studer Prize for the best M.Sc. graduate of the year, ETH Zürich.
2020	ETH Medal for outstanding master thesis.
2013	Grammar School Frauenfeld Award for outstanding graduates.
2013	Grammar School Frauenfeld Award for outstanding matura thesis.

Invited Talks

- 7.2024 "Active Perception and Long-term Understanding of Dynamic Human Environments", presented at *INRIA de l'Université de Rennes*, Rennes, France.
- 6.2024 "Khronos: Towards Autonomous Robotic Perception and Understanding of Dynamic Human Environments", presented at the *Robotics Systems Lab Seminar*, ETH, Zurich, Switzerland.
- 5.2024 "Khronos: Towards Spatio-Temporal Perception of Dynamic Scenes", presented at the *Space Robotics Lab*, Tohoku University, Sendai, Miyagi, Japan.
- 4.2024 "Khronos: From Simultaneous Localization and Mapping to Spatio-temporal Perception of Shared Dynamic Scenes", presented at *Mobile Robotics: Methods and Algorithms*, University of Michigan, Ann Arbor, MI, USA.
- 3.2024 "Towards Fully Autonomous Actionable Perception of Shared Dynamic Scenes", presented at the *Amazon Consumer Robotics Symposium*, Sunnyvale, CA, USA.
- 10.2023 "Semantics and Learning for Active Robot Perception in Dynamic Environments", presented at the *MIT Machine Learning Tea Talk Series*, MIT, Cambridge, MA, USA.
- 12.2022 "Robust Active Perception and Volumetric Mapping in Unknown Changing Environments", presented at the *Joint Control and Robotics Seminar*, University of Manchester, Manchester, United Kingdom.
- 4.2022 "Semantics and Learning for Robust Active Perception in Changing Environments", presented at the *Semantic Perception Reading Group*, Google Zürich, Zürich, Switzerland.
- 3.2022 "Robust Volumetric Mapping in Changing Environments", presented at the *Microsoft Swiss Joint Research Center Workshop*, Lausanne, Switzerland.
- 4.2021 "Volumetric Mapping for Long-term Robot Interaction", presented at the *Microsoft Swiss Joint Research Center Workshop*, Virtual.
- 1.2020 "A Modular Approach for Lifelong Mapping from End-User Data", presented at the *Microsoft Swiss Joint Research Center Workshop*, Lausanne, Switzerland.

Professional Activities

Organization of Conferences

- 2025 **Robotics: Science and Systems.**
- Open Review co-chair.
 - Organize the review process and tools.
- 2024 **MIT LIDS Student Conference.**
- Conference scientific program co-chair.
 - Invited distinguished plenary speakers.
 - Organized and moderated the distinguished speaker panel discussion.
 - Program and session chair "Algorithms, Optimization, & Game Theory".

Organization of Workshops

- 2024 **Long-Term Perception for Autonomy in Dynamic Human-shared Environments: What Do Robots Need?** in conjunction with *IEEE International Conference on Intelligent Robots and Systems (IROS)*.
- Lead workshop organizer.

Editorial Board for International Journals and Conferences

- 2024-current **Associate Editor for International Journals.**
- IEEE Robotics and Automation Letters (RA-L), 2024.

Reviewer for International Journals and Conferences

- 2020-current **Reviewer for International Journals.**
- IEEE Transaction on Robotics (T-RO), 2022-2024.
 - International Journal on Robotics Research (IJRR), 2023-2024.
 - Autonomous Robots, 2023.
 - IEEE Robotics and Automation Letters (RA-L), 2020-2024.
 - Journal of Pattern Recognition, 2022.
 - IEEE/CAA Journal of Automatica Sinica, 2022.
- 2021-current **Reviewer for International Conferences.**
- Robotics: Science and Systems (RSS), 2023-2024.
 - IEEE Int. Conf. on Robotics and Automation (ICRA), 2021-2024.
 - IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS), 2021-2024.
- 2021-current **Reviewer for International Conference Workshops.**
- Robotics: Science and Systems (RSS): Pioneers, 2024.
 - Conf. on Neural Information Processing Systems (NeurIPS), 2021.

Technical Societies and Committees

- 2019-current **IEEE Robotics and Automation Society (RAS), Member.**
- 2023-current **IEEE RAS TC on Computer and Robot Vision, Member.**

Teaching

Lectures

- 2024 **ROB530: Mobile Robotics: Methods and Algorithms**, graduate class, University of Michigan, USA.
 ◦ Guest lecture on "Perception Algorithms for Dynamic Scenes".
- 2023 **MIT16.485: Visual Navigation for Autonomous Vehicles**, graduate class, MIT, USA.
 ◦ Guest lecture on "Visual Odometry".

Teaching Assistant

Selected topics, prepared materials, and taught theory review sessions. Selected topics, designed, and graded pen and paper problem sets. Designed, supported, and graded coding problem sets. Proposed and supervised research project works. Held Q&A sessions and colloquia. Designed and verified exam questions. Supervised and corrected final exams.

- 2023 **MIT16.485: Visual Navigation for Autonomous Vehicles**, graduate class, MIT, USA.
- 2020-2022 **Autonomous Mobile Robots**, M.Sc. class, ETH Zurich, CH.
- 2020-2022 **Perception and Learning for Robotics**, M.Sc. class, ETH Zurich, CH.
- 2018 **Advanced Machine Learning**, M.Sc. class, ETH Zurich, CH.

Didactic Education and Training

- 2023 **Preventing Sexual Harassment and Power Dynamics**, online course, MIT, 2023.
- 2022 **Power and Leadership**, 6 month course, ETH Zürich.
- 2022 **Selection Procedures and Bias**, half-day workshop, ETH Zürich.
- 2018 **Didactics for Teaching Assistants**, 1 full week training, ETH Zürich.

Mentoring

Advised 40+ students in research projects. Co-advised PhD student in research projects. Proposed, supervised, and graded M.Sc. and B.Sc. theses and other research projects.

PhD Students

2024-current	Turcan Tuna , "Large-scale Real-time Perception with Gaussian Splats", MIT and ETHZ.
2023-current	Marcus Abate and Yun Chang , "Spatio-temporal SLAM in Dynamic Scenes", MIT.
2023-2024	Dominic Maggio , "Open-set Scene Understanding with 3D Dynamic Scene Graphs", MIT.
2023	Julio Placed , "Active Perception for 3D Dynamic Scene Graphs", visiting student from University of Zaragoza, Spain, MIT.

M.Sc. Theses

The M.Sc. thesis is a 6 month full-time project.

2023	Nicolas Gorlo , "Long-term Human Motion Prediction with 3D Scene Graphs", visiting student from ETH Zurich, CH, MIT.
2022	Jiaqi (Julia) Chen , "Active Perception for Long-term Re-localization", in collaboration with Microsoft Mixed Reality and AI Lab, ETH Zurich.
2022	Samuel Looper , "Planning in Latent Neural Representations", ETH Zurich.
2022	Friedrich Rockenbauer , "Co-operative Informative Path Planning for Safe Navigation in Unknown Scenes", ETH Zurich.
2021	Giuliano Albanese , "Active Perception for Accurate Panoptic Segmentation", ETH Zurich.
2021	Ioannis Athanasiadis , "Spatio-temporally consistent Mapping using Collections of Submaps", ETH Zurich.
2021	Adrian Brandemühl , "Tightly Coupled Lidar-Visual-Inertial-Odometry with TSDFs", ETH Zurich.
2021	Mansoor Cheema , "Leveraging Scene Completion for Exploration", visiting Student from Technical University of Munich, Germany, ETH Zurich.
2021	Samuel Gull , "Towards Map-based Motion Detection", ETH Zurich.
2021	Stefan Lionar , "Neural Representation Fusion for Volumetric Mapping", ETH Zurich. <ul style="list-style-type: none">◦ Published at the IEEE Int. Conference on 3D Vision (3DV), 2021.
2021	Viviane Marty , "Incremental 3D Scene-Graph Construction", in collaboration with Microsoft Mixed Reality and AI Lab, ETH Zurich.

- 2021 **Rene Zurbrügg**, "Continual Learning for Semantic Segmentation", ETH Zurich.
 ◦ Published in the IEEE Robotics and Automation Letters (RA-L), 2022.
 ◦ Awarded the ETH Medal for Outstanding Master Theses.
- 2020 **Davide Bagheri**, "Volumetric Exploration subject to Drift", visiting student from University di Pisa Sant'Anna, Italy, ETH Zurich.
- 2020 **Slaven Cvijetic**, "Biology-inspired Odometry Fusion", ETH Zurich.
- 2020 **Yves Schär**, "Path Planning for Art Installation", ETH Zurich.
- 2020 **Arno Vaillancourt**, "Leveraging Scene Completion for Exploration", visiting student from EPFL, CH, ETH Zurich.

Semester Theses

The semester thesis is a 14 weeks of 60% effort project of M.Sc. students.

- 2022 **Annamalai Lakshmanan**, "Efficient Neural Representations for Robotic Mapping", ETH Zurich.
- 2022 **Aurelio Sulser**, "Towards Map-based Motion Detection", ETH Zurich.
 ◦ Published in the IEEE Robotics and Automation Letters (RA-L), 2023.
- 2022 **Max Wilder-Smith**, "Autonomous Long-term Data Collection and Mapping", ETH Zurich.
- 2021 **Junting Chen**, "Incremental 3D Scene-Graph Construction", ETH Zurich.
- 2021 **Dominik Hollidt**, "Photo-realistic simulation for Autonomous Racing", ETH Zurich.
- 2021 **Zador Pataki**, "How to Fuse: Incremental Fusion of Neural Semantic Features", ETH Zurich.
- 2020 **Tiancheng Hu**, "Object Instance Re-localization from Pointclouds", ETH Zurich.
- 2020 **Konstantinos Skovolas**, "Semantic Abstractions for Localization", ETH Zurich.

B.Sc. Theses

The B.Sc. thesis is a 14 weeks of 60% effort project of B.Sc. students.

- 2022 **Samuel Bamert and Gabriel Käppeli**, "Geranos-Navigation: Path Planning and Obstacle Avoidance with an UAV Carrying Poles", ETH Zurich.
- 2020 **Pascal Auf der Maur and Patricia Hörman**, "IMU State Estimation for a Snake-like Robot", ETH Zurich.

Perception and Learning for Robotics

The perception and learning for robotics project is a 14 week part-time project of M.Sc. students.

- 2022 **Haoran Chen and Weining Ren**, "Neural Implicit Mapping of Dynamic Scenes", ETH Zurich.
- 2022 **Samuel Looper and Shao Zhou**, "Predicting the Future with Dynamic Scene Graphs", ETH Zurich.
 - Published at the IEEE International Conference on Robotics and Automation (ICRA), 2023.
- 2021 **Zador Pataki and Amir Hadzic**, "Incremental Map-based Object Segmentation", ETH Zurich.
- 2021 **Chunqiao Li and Yiming Zhao**, "Leveraging Object Completion for Re-localization", ETH Zurich.
- 2021 **Chao Ni and Yuliang Zhong**, "Towards Learning-based Exploration Planning", ETH Zurich.
 - Published in the IEEE Robotics and Automation Letters (RA-L), 2022.
- 2020 **Sirish Srinivasan and Yaswanth Mummaneni**, "Towards Learning-based Exploration Planning", ETH Zurich.

Other Students

- 2008-2015 **Supervised 10+ students in private mathematics and physics classes.**
 - Middle school, grammar school, and adult qualification to university entrance (TSME) students.
 - Admission or final exam preparations (with 100% success rate).

Service

Committees

- 2.2021-2.2023 **Department Commission, Department of Mechanical and Process Engineering (D-MAVT), ETHZ.**
 - Scientific staff representative in the department commission.
 - Voted on strategic and other departmental decisions together with all faculty and selected student, administrative, and scientific staff representatives.
- 2.2021-2.2023 **Teaching Commission, Department of Mechanical and Process Engineering (D-MAVT), ETHZ.**
 - Scientific staff representative in the teaching commission.
 - Reviewed and approved proposals to add, remove, or change classes taught at B.Sc. and M.Sc. level.

- Analyzed and approved class satisfaction evaluations inquired from all students. Discussed and addressed unsatisfactory class ratings with the corresponding PIs.
- Analyzed and approved exam satisfaction evaluations and grade distributions for examination sessions. Discussed and addressed unsatisfactory exam ratings with the corresponding PIs.

Working Groups

- 2.2022-8.2023 **Working Group designing the New Curriculum of B.Sc. Mechanical Engineering at ETHZ.**
- Co-developed strategic goals to best equip B.Sc. Mechanical Engineering (ME) students for the future.
 - Successfully advocated for increased training in computer science, programming, and machine learning for ME students.
 - Helped balance class and project work for strong theoretical and practical skill development of ME students.
 - Helped streamline offered classes for optimal subject coverage and reduced overlap.

Associations

- 7.2023-current **Member of Board, MIT Postdoctoral Association (MIT-PDA), MIT.**
- Chair of the Advocacy Committee.
 - Represented and advocated for all postdocs at MIT in collaboration with the Office of the Vice President for Research.
 - Organized seminars on US Visa and Permanent Residence for international postdocs.
- 2.2021-2.2023 **Member of Board, Association of Scientific Staff of the Department of Mechanical and Process Engineering (AV-MAVT), ETH Zürich.**
- Represented PhDs and postdocs in the department commission.
 - Represented PhDs and postdocs in the dept. teaching commission.
 - Organized events connecting scientific staff from different labs.
- 6.2018-6.2022 **Member of Board, Student Wine Association Zürich (SWAZ).**
- Joint association of ETHZ and University Zürich.
 - Organized multi-disciplinary networking events connecting students from various backgrounds and interests.
 - Organized and taught seminars about specific wines, regions, or varietals.
 - Co-managed collaboration with industry partners (Landolt, Zweifel, Baur au Lac, Mövenpick, Smith&Smith, Rare Wines, Provins, and others).

Languages

German	Mother Tongue. Also includes Swiss German.
English	Fluent. Level C2, Cambridge Certificate in Advanced English (CAE), Grade A, 2013. 10+ years of study and work in English.
French	Conversant. Level B2, Diplôme d'Études en Langue Française (DELFI), 2012.

Skills

Programming	C++, Python, LaTeX, C#, Matlab, and VisualBasic.
Open-source	I am a strong proponent of open-source code and make most of my projects publicly available, which has received 2000+ stars and 300+ forks on github. Selected projects (full list available here): https://github.com/MIT-SPARK/Khronos , https://github.com/MIT-SPARK/config_utilities , https://github.com/ethz-asl/dynablox , https://github.com/ethz-asl/panoptic_mapping , https://github.com/ethz-asl/mav_active_3d_planning , https://github.com/ethz-asl/glocal_exploration
Simulation	Unreal Engine 4, AirSim, Unity, Gazebo, CoppeliaSim, Siemens NX CAD, and COMSOL Multiphysics FEM.
Robotics	ROS, Matlab, and Simulink.
UAVs	BAZL/EASA UAV Operator License Categories A1/A3.
Deep Learning	PyTorch, Tensorflow, Keras, and SciKit Learn.
Multi Media	DaVinci Resolve, Shotcut, GIMP.
IT	Maintained websites and newsletters for multiple associations.

Interests

Besides my work, I am a passionate classical pianist (four times winner of the 1st prize at the Thurgauer Youth Music Competition, 3 times with award). Furthermore, I enjoy team sports such as volleyball, especially beach volleyball during summer. I love exploring, tasting, and presenting wines (WSET Level 2 Award in Wines, WSET Level 2 Award in Spirits, both passed with distinction) and sharing these experiences with others. For recreation, I relish various water sports such as scuba diving (PADI Advanced Open Water Diver), sailing (Swiss Yachting Certificate) as well as wave, wake, and wind surfing.