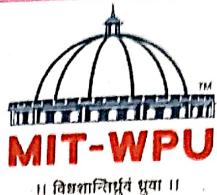


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Dr. Vishwanath Karad

**MIT WORLD PEACE  
UNIVERSITY | PUNE**

TECHNOLOGY, RESEARCH, SOCIAL INNOVATION &amp; PARTNERSHIPS

**Instruction to Candidate :**

- Candidate has to confirm seat number, subject and centre number printed on Bar code and write it on attendance sheet.
- Paste Bar Code in prescribed space.
- Do not write anything on bar code sticker, otherwise it will be treated as unfair means.

**Supplements Attached**

Main Answer Booklet	No. of Supplement(s)	Total
1	+	=

**Specific remarks of ACoE / Dean .**

Total Marks	Total Marks in Words	Sign

QNo	Evaluer					Moderator					Revaluer				
	A	B	C	D	Total	A	B	C	D	Total	A	B	C	D	Total
1															
2															
3															
4															
5															
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11															
12															
<b>Total</b>															

## Operating Systems

Q. 1. The operating system is a computer is a complex piece of software that interacts with the hardware for us.

→ Naturally, it has evolved over the years and people have found several ways to create and interact with this software.

These methods are what define the architecture of the OS.

→ Broadly speaking : It is of 3 types

1. layered
2. Microkernel
3. Monolithic



### The Monolithic Architecture :

→ This is one of the primitive and simple OS architectures

→ Everything important and key to hardware communication is part of the Kernel itself

→ It is difficult to program and manage

Only the user applications and utilities run in the user space. Rest of the services like system processes, IPC modules, system libraries, I/O buffers, device drivers etc run in Kernel mode.

Q.No.

(\*)

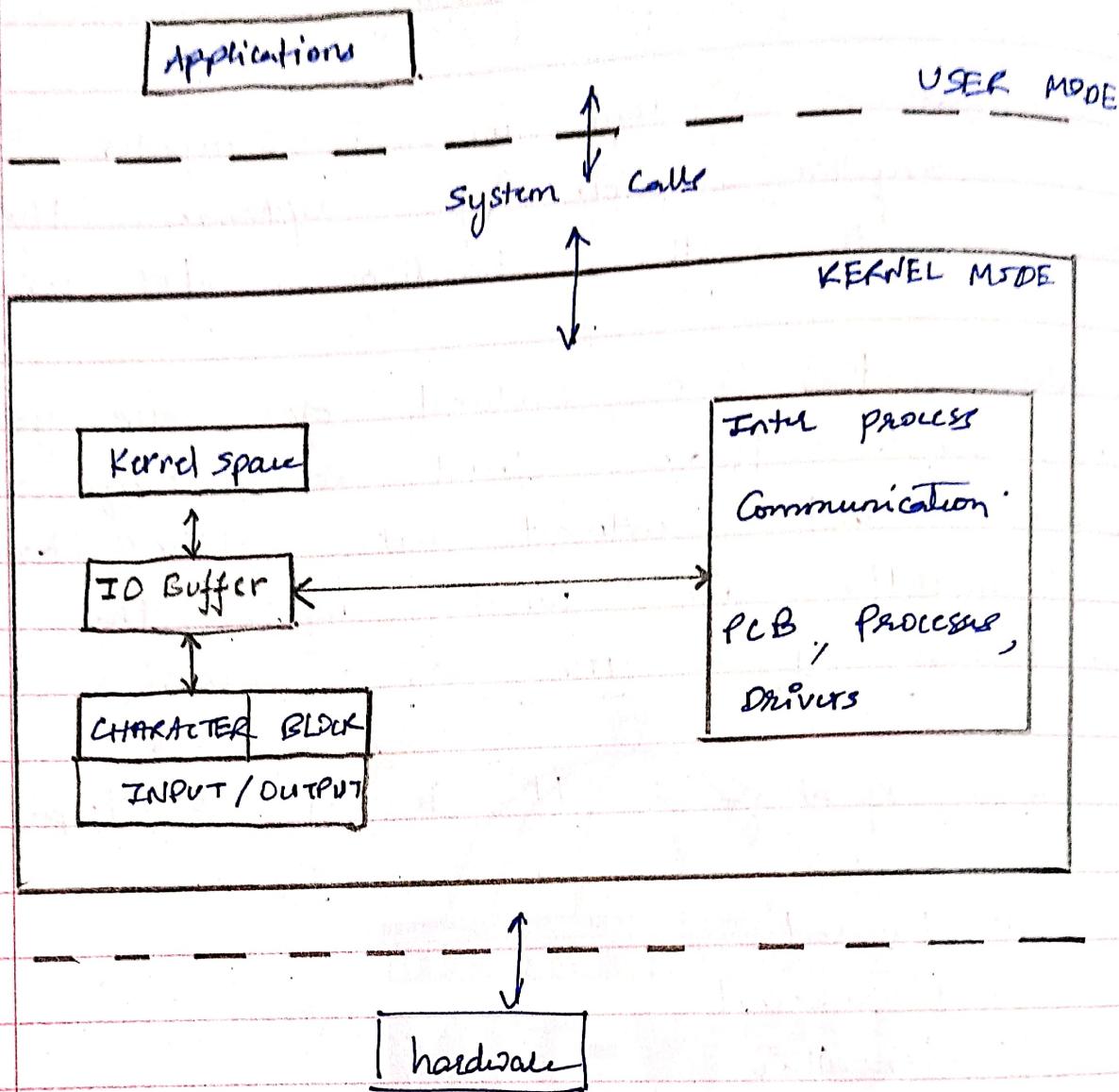


figure: Monolithic kernel Architecture

(\*)

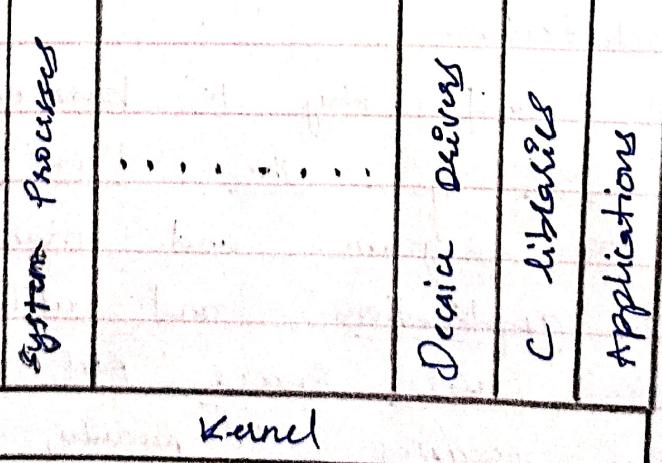


fig: Microkernel Architecture

Q.No.

### Microkernel :

- Only the base interface with the hardware is built into the kernel.
- Most other tasks are performed in user space.
- ~~extremely~~ Modules
- Supports more devices due to its easy modular structure
- eg. Linux, MacOS

### Q.2. Inter - Process Communication

- It is an essential function of the operating system that enables safe sharing of data, and resources between several ~~goes~~ concurrently running processes in the OS.
- A process is simply a program in execution. Several such programs may need to communicate with each other due to reliance on shared resources or functionality. This is achieved safely ~~is~~ by using pipes.
- In C, pipes are defined in `<sys/types.h>` and `<unistd.h>` header files.

Q.No.

\* Pipes act as a simple queue data structure. They are stored in primary memory as files, temporarily located in the /proc directory.

\* They only allow reading or writing at one time.

(\*)

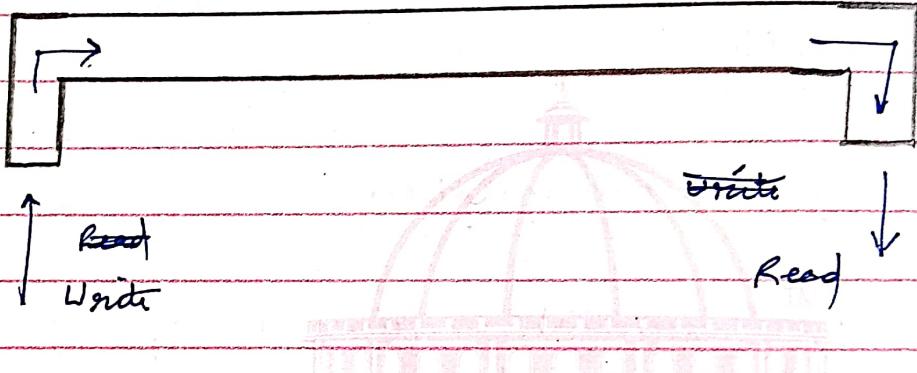
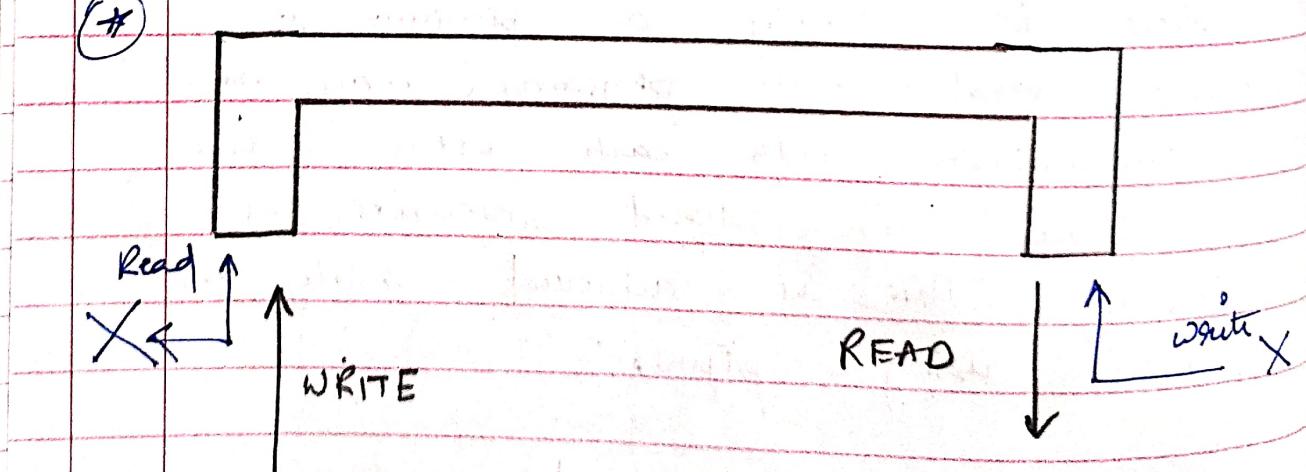


fig. → Pipe is used

(\*)



Read & write Both are not allowed at the same time.

Q.No.

pipe (fildes [2]) usually requires the file descriptor of the writer and the reader. Only after the writer closes its file descriptor, can the reader read its written contents.



Reading and writing together are not allowed because of the possibility of sue - conditions.



Race conditions arise due to improper management or miscommunication between 2 or more processes or threads accessing the same shared resource.



The usual mechanism to access shared memory is for the shared resource to be brought into main memory, and have the CPU follow instructions of read / write from processes trying to access that memory.



This usually happens safely without deadlock, circular wait, or sue conditions arising, if the ~~processes~~ processes co-operate with each other rather than compete.

Q.No.

(3) Semaphores: Semaphores are a technique to get around the problem of safely accessing shared resources by processes that are in their critical sections employing mutual exclusion. So it is a solution to the mutual exclusion problem:

The problem:

Say  $P_1$  tries to modify a shared variable  $a$

$$a = 1$$

$$P_1 : a + = 3$$

$$\text{Say } P_2 : a + = (-4)$$

If  $P_3$  : read ( $a$ )

The value read by  $a$  is now dependent on which processes execute first, and how many times. Accuracy is not guaranteed. To avoid this semaphores are used to give time to let  $P_3$  read. This is done using `wait()` and `signal()` mechanism.

```

sem_t s;

Q.No.    wait()
{
    while (s < 0)
    {
        s--;
    }
}

```

```

signal()
{
    while (s > 0)
    {
        s++;
    }
}

```

wait and signal are used to block and release a variable s, that allows other processes information about when to access the shared resource.

eg.	Ready()
	{
	sem_wait(&mutex)
	// Read
	sem_signal(&mutex)
	}

	writer()
	{
	sem_wait(&writer)
	sem_wait(&mutex)
	// write(a)
	sem_signal(&mutex)
	sem_wait(&writer)
	}

Q.No.

(4)

Banker's Algorithm

	Max			Allocation		Need
	R <sub>0</sub>	R <sub>1</sub>	R <sub>2</sub>	To R <sub>1</sub>	To R <sub>2</sub>	R <sub>0</sub> R <sub>1</sub> R <sub>2</sub>
P <sub>0</sub>	4	1	2	1	0	3 1 0
P <sub>1</sub>	1	5	1	0	3	1 2 0
P <sub>2</sub>	1	2	3	1	0	0 2 1

Available (work)

R <sub>0</sub>	R <sub>1</sub>	R <sub>2</sub>
2	2	0

$$\begin{aligned} \text{Total } R_0 &= 2 + 1 + 1 \\ &= 4 \end{aligned}$$

$$R_1 = 3 + 2 = 5$$

$$R_2 = 2 + 1 + 2 + 0 = 5$$

case - 1: as  $[2, 2, 0]$  is available, but  $P_0$  requires  $[3, 1, 0]$ ,

$P_0$  will not be given any more resources.

case - 2: As  $[2, 2, 0]$  is available,  $P_1$  needs  $[1, 2, 0]$  resources will be allocated to  $P_1$ .

Available would then be  $(1, 0, 2)$ ,

Q.No.

After  $P_1$  finishes execution,  $[1, 5, 1]$  will be returned to OS.

$$\text{so } [1, 0, 0] + [1, 5, 1]$$

$$= [2, 5, 1] \text{ as the new work matrix.}$$

case : 3 :  $P_2$  will be given resources  $[0, 2, 1]$  from available  $[2, 5, 1]$

leaving us  $[2, 3, 0]$  is ~~the~~ work matrix.

case : 4 : After  $\rightarrow P_2$  finishes execution

$$\begin{aligned} \text{work} &= [2, 3, 0] + [1, 2, 3] \\ &= [3, 5, 3] \end{aligned}$$

case : 5 :  $P_0$  is now given resources

$$\text{so } [3, 5, 3] - [3, 1, 0]$$

$$= [0, 4, 3]$$

$$\text{and at last } [0, 4, 3] + [4, 1, 2]$$

$$= [4, 5, 5] = \text{total resources}$$

Safe sequence:  $P_1, \cancel{P_0}, \rightarrow P_0, [P_1, P_2, P_0]$

Q.S Q.No.

(5) To assign memory to load programs into primary memory, it has to be given partitions in order to accommodate several programs at the same time.

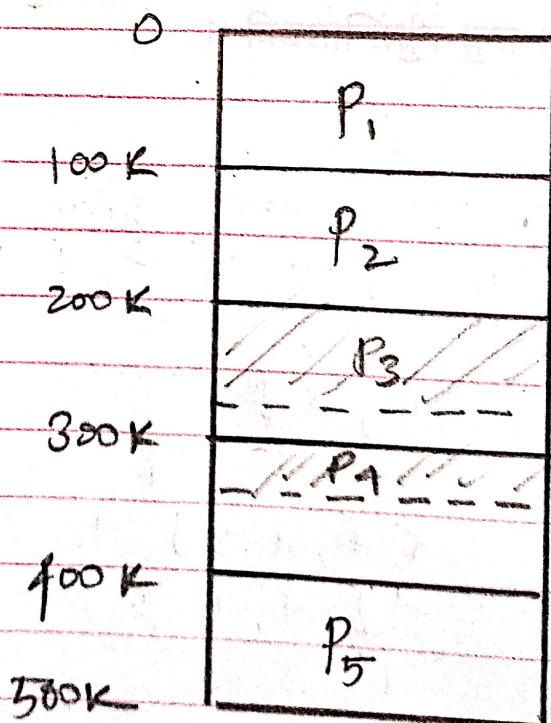
This can be done in 2 ways:

1. fixed
2. Dynamic

Fixed partitioning is of 2 types

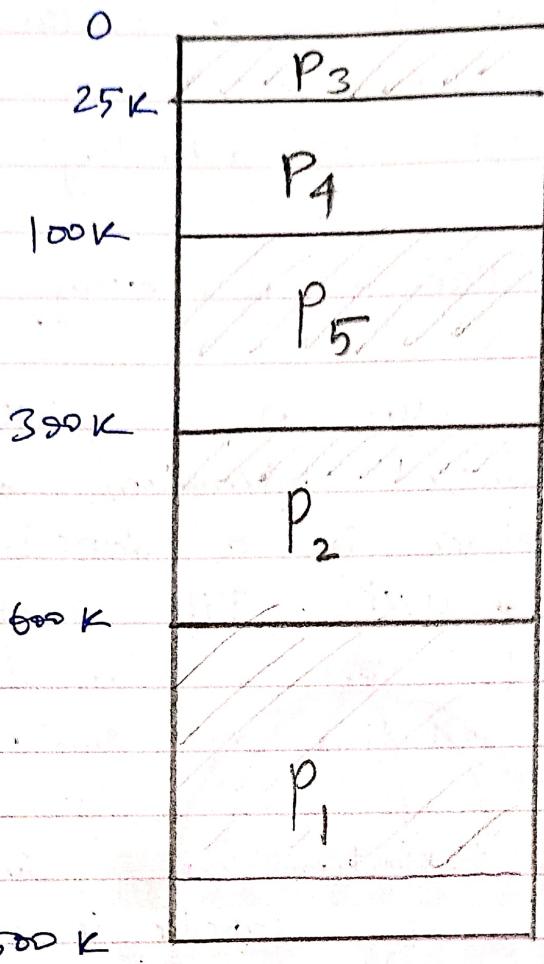
1. Equal Partitions
2. Unequal Partitions

1. Equal : Diagram.



Q.No.

2. Unequal : Diagram



### Equal

1. Less CPU overhead
2. Takes more time as programs have to be scanned and reordered
3. Less waste of space
4. Divides available memory into equal partitions
5. ~~process Fragmentation~~ Higher

### Unequal

1. More overhead
2. Takes lesser time as programs don't need to be moved so often
3. Space may be wasted for smaller programs
4. Divides into unequal partitions
5. ~~process Fragmentation~~ High ~~process Fragmentation~~ Low

1. Field: A field is an entry of data. This is the position of the file where data is actually stored. It is an attribute of every file.
2. Record: Any entry of a particular table of organized information within a database is a record. With respect to a UNIX File System, a record can be a file, or even a collection of smaller files.
3. Database: A collection of similar files or records is called a database. If it often contains many files, records, data fields, and sometimes even directories stored on the file system.
4. Address Information: It can refer to the pathname of each record or file within a database. With respect to UNIX structure however, it can mean information about which frame is the page table the particular file is stored.

Q.No. 5' Access Control Information: every file in the file system (NTFS, ext4 etc) has security parameters associated with it.

It is only accessible to those users who created it or the root user. Every file can be accessed, read, written or executed based only on its access control information.

eg.    7 7 7      file.txt  
      ↓

111 111 111      for each group, user  
rwX rwX rwX      and root.

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Q.No.

(7)

## Characteristics of Unix File System -

1. All entities, data, commands, drivers, devices and libraries are files in Unix. — everything is a file.
2. All files have access control permission associated with them. They can be read, written or executed only by those users with permissions.
3. Unix supports ext4, exFAT, FAT, ext3, NTFS, FAT32 etc Btrfs, ZFS etc — all kinds of file systems.
4. The usual directories in UNIX are:
  1. /boot — for kernel and GRUB bootloader menu entries.
  2. /home — for user files like desktop, downloads etc.
  3. /opt — optional programs
  4. /bin — programs essential to OS commands like ls, passwd
  5. /sbin — system binaries
  6. /usr — user downloaded program files
  7. /etc — configuration files
  8. /dev — devices, buffers.

Q.No.

5' Unix files are case sensitive.

downloads ≠ Downloads.

Q8

Pathnames →

Address or path of a file  
(leaf node) in the tree.

① Absolute : irrespective to current directory

> /home / user / .config / pacman / open -git

② Relative : Relative only to current directory :

e.g. > ./a.out  
> ./a  
etc.

Q.No.

Applications

Uses span

System - calls Interface

Kernel space

kernel libraries

Schedulers

JPC -  
inter process

character Block

communication

I/O Buffers

Devices

Processes

Kernel space

Hardware

UNIX Block diagram

- It consists of several blocks functioning concurrently with each other
- It is divided into user p span and kernel space.

Q.No.

- The application layers are in user space.
- To communicate with Kernel or hardware, user programs have to perform system calls.
- The Kernel interacts with hardware using device drivers from the Kernel space.
- Unix follows a monolithic Kernel design architecture.
- System libraries in C, device drivers, I/O buffers are all parts of the Kernel space itself.
- The programs communicate within themselves using Kernel space inter process communication.