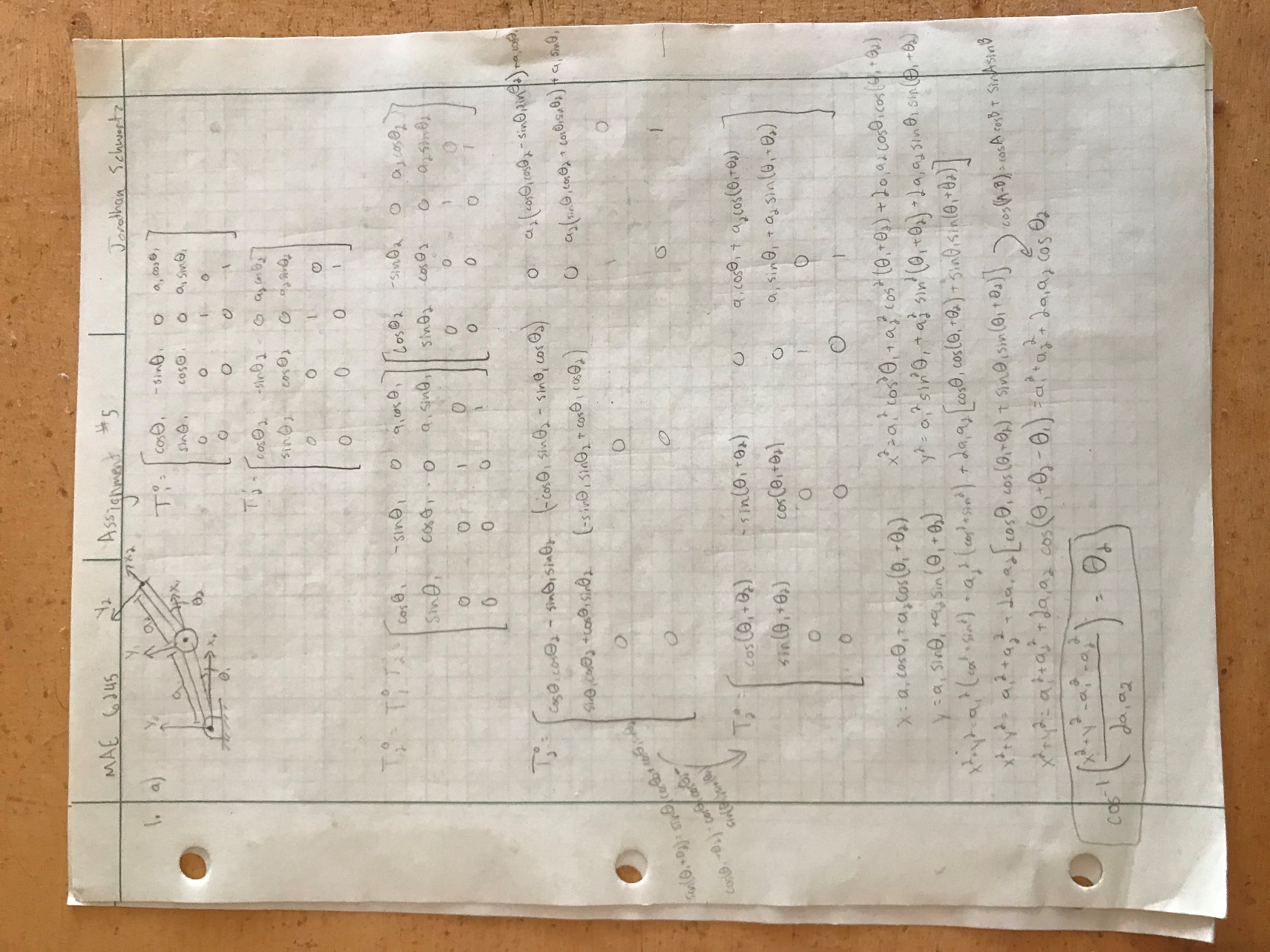
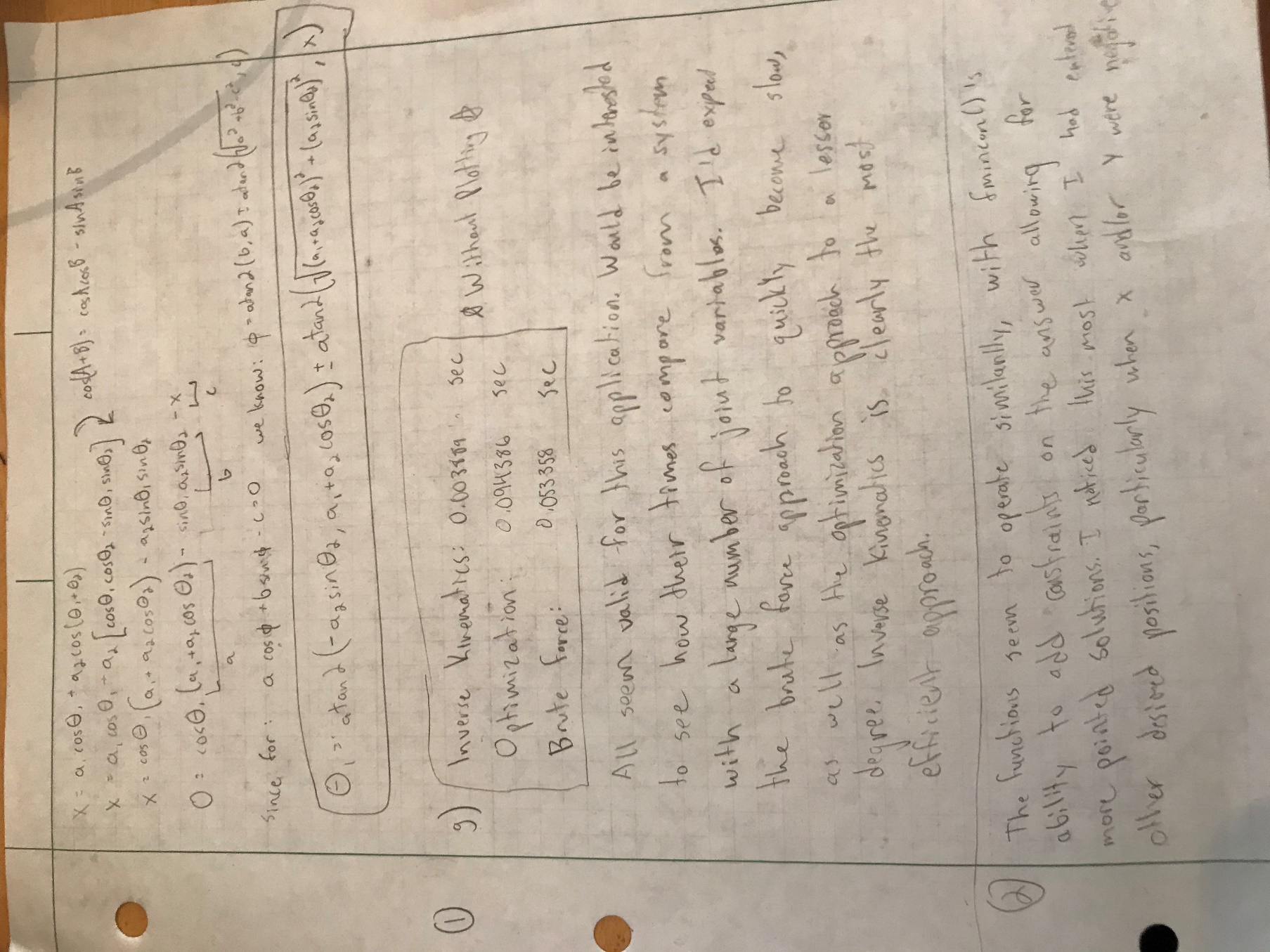
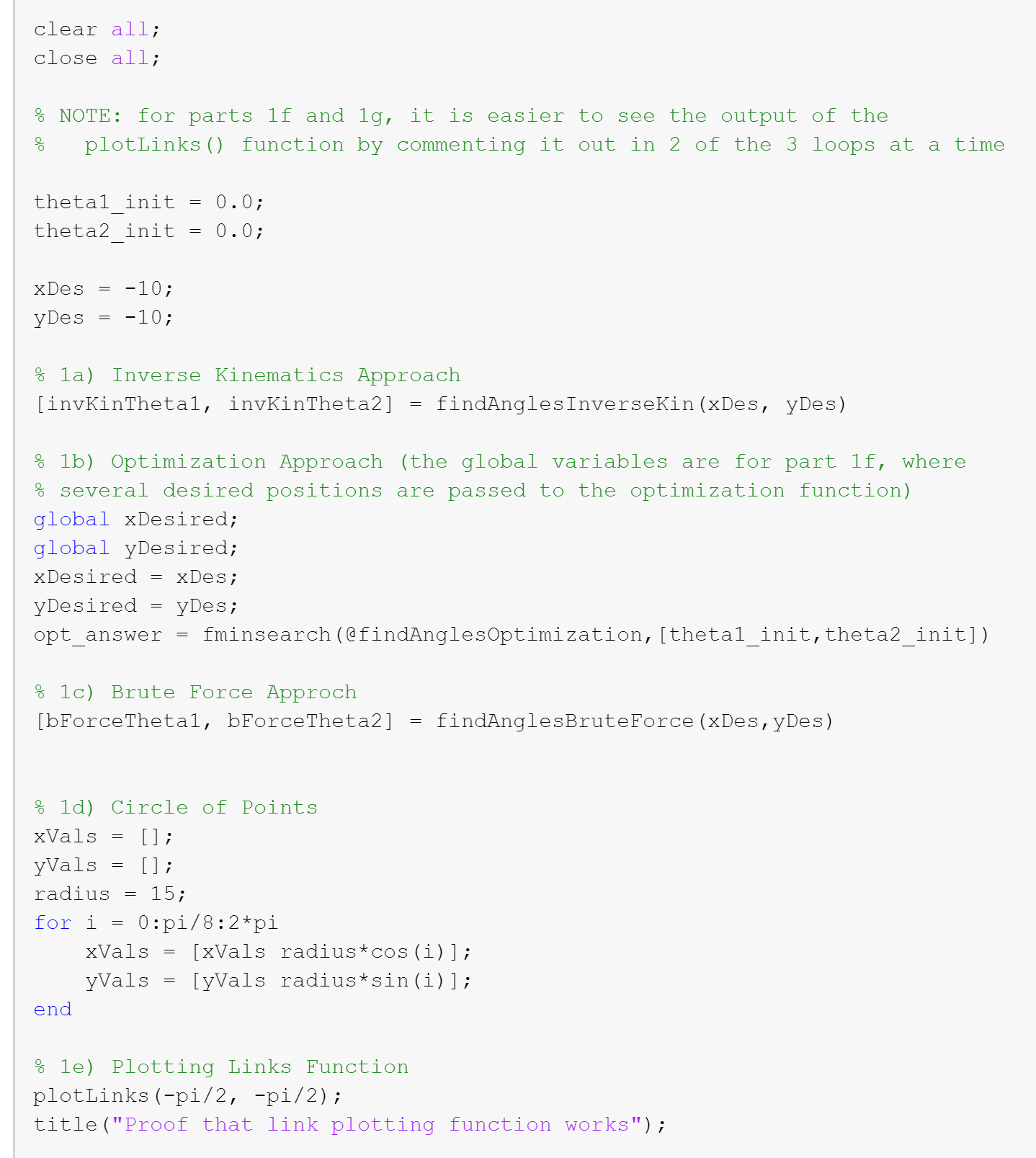
Jonathan Schwartz

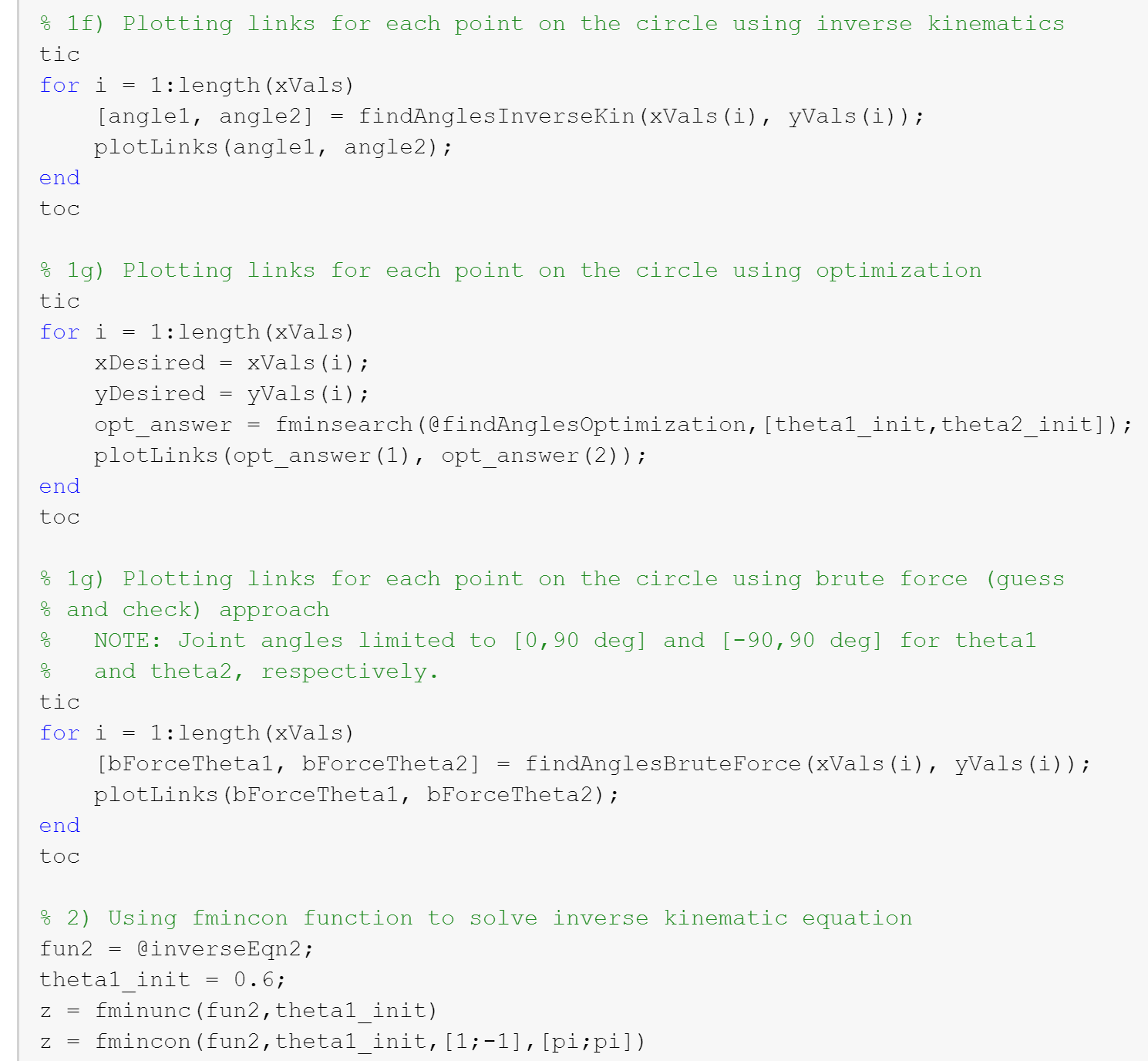
MAE 6245

Assignment #5

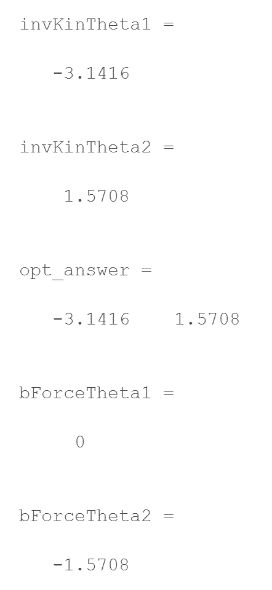
Written answers and derivations:

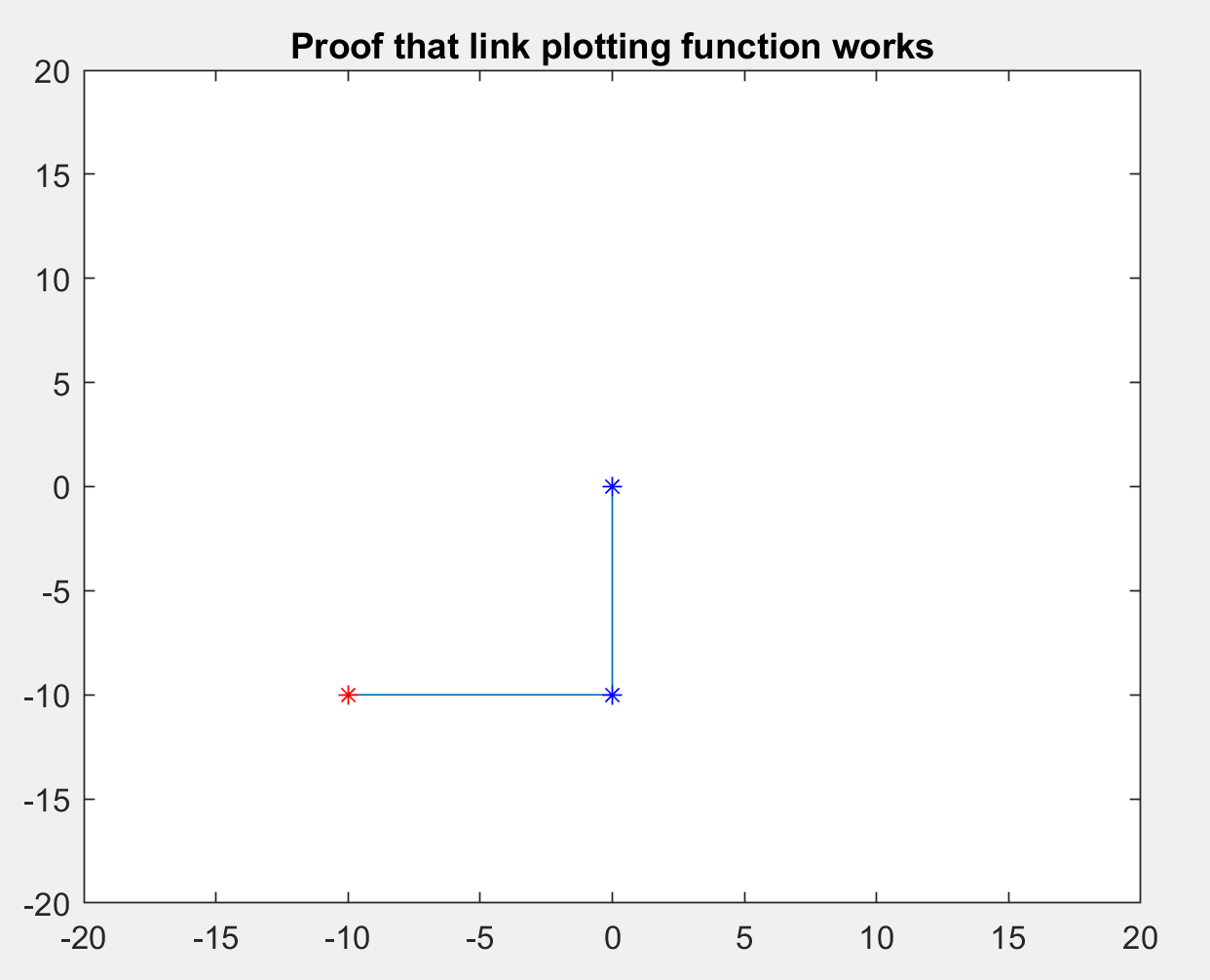


MATLAB Main Script

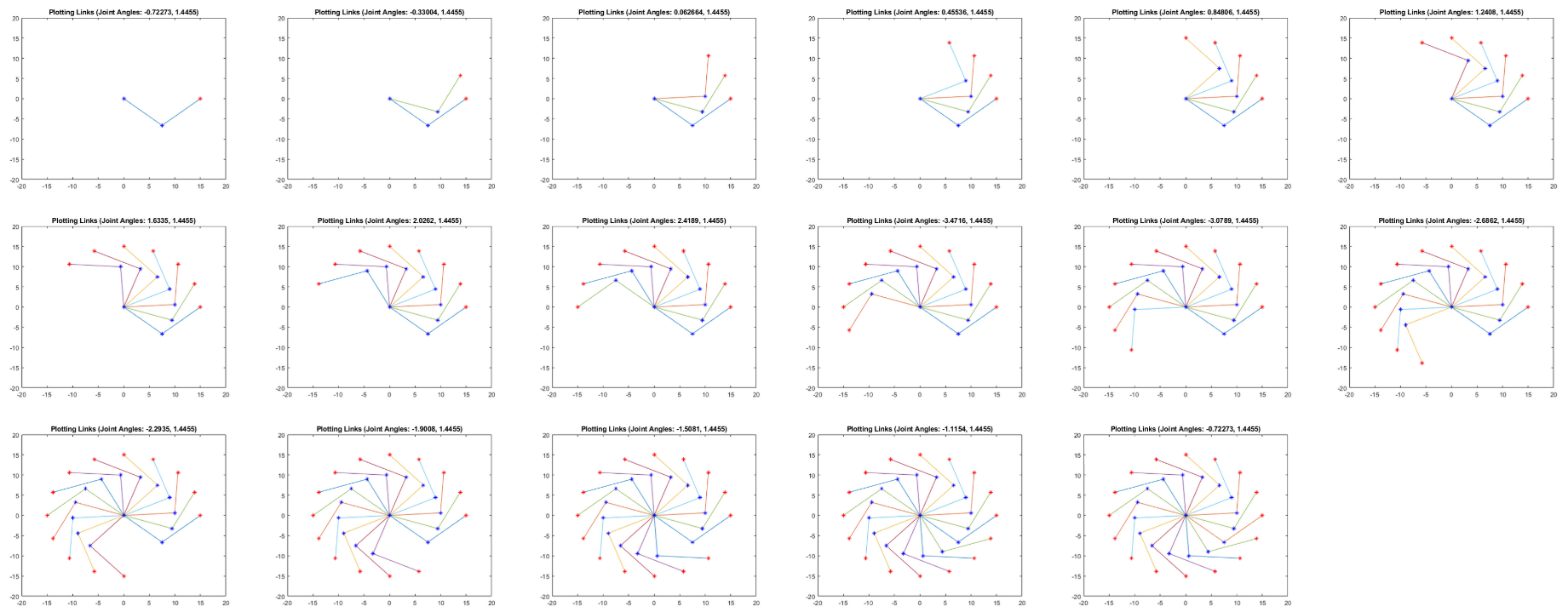


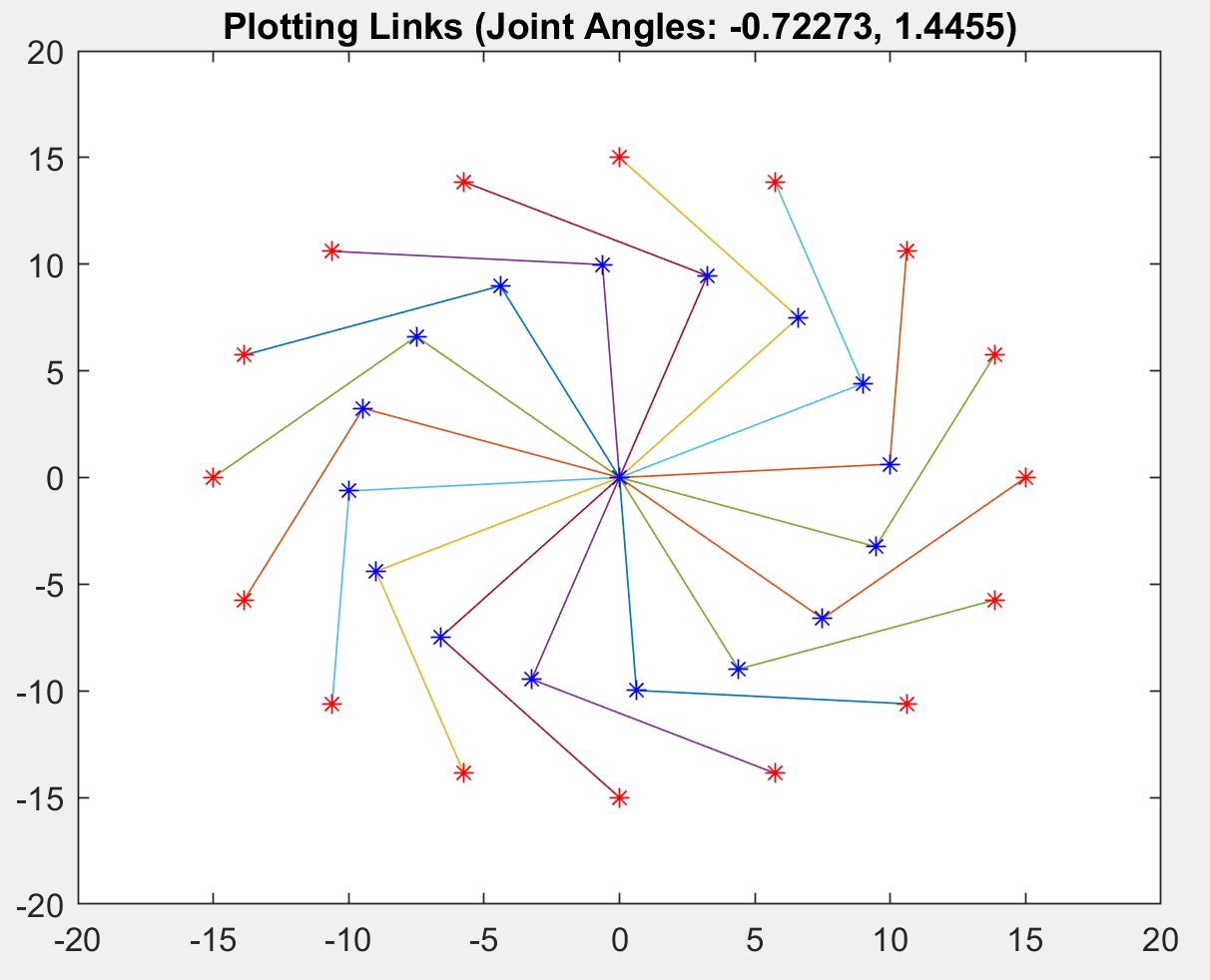
Script Output:

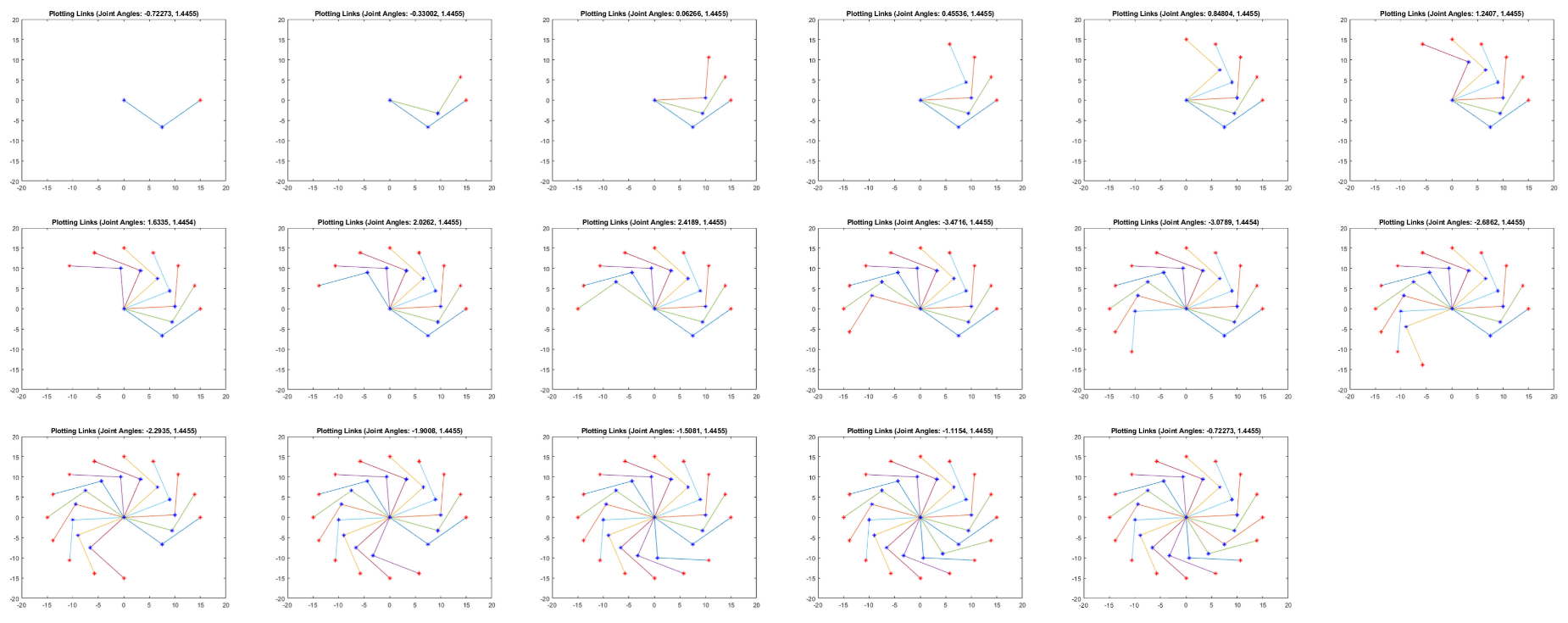


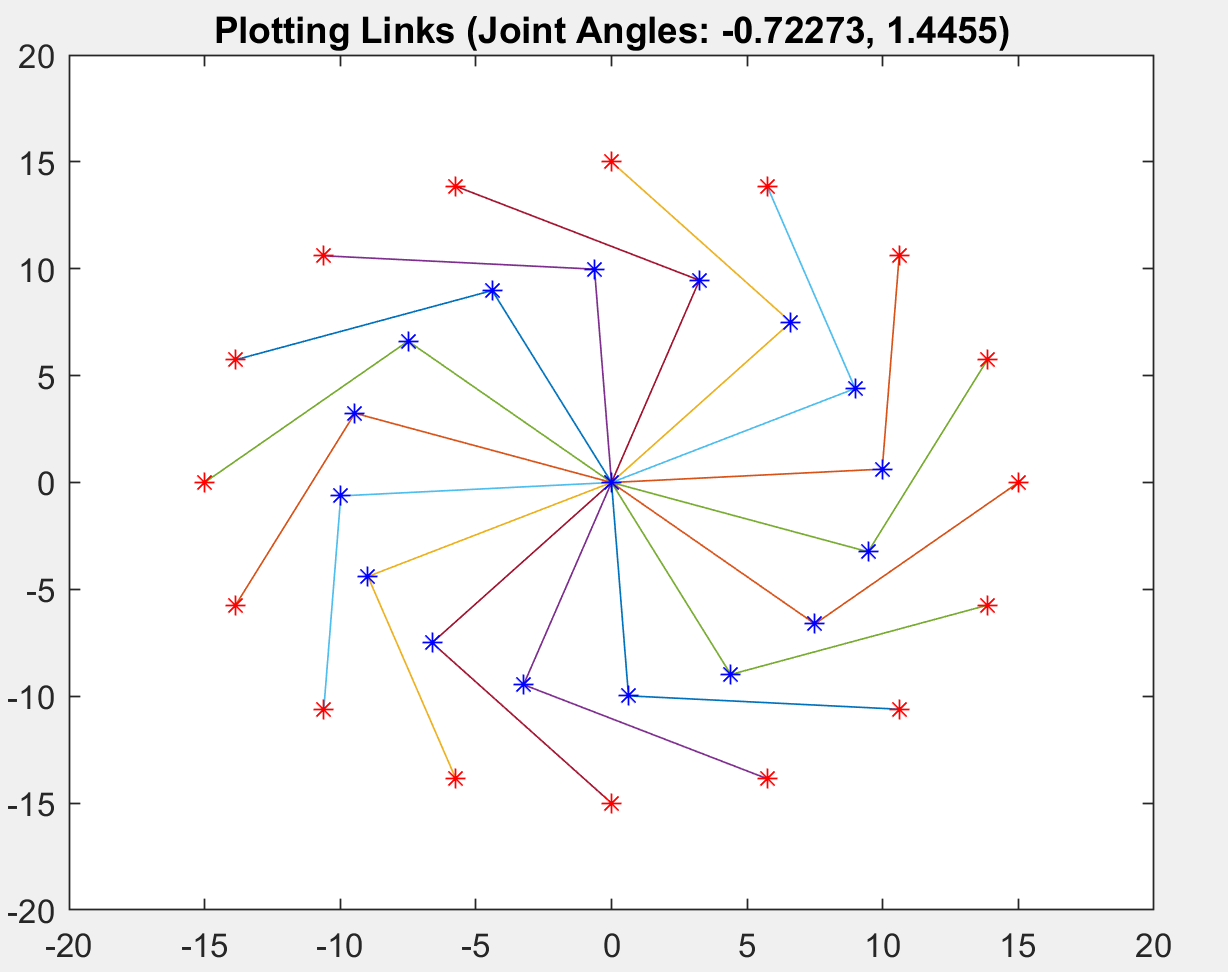


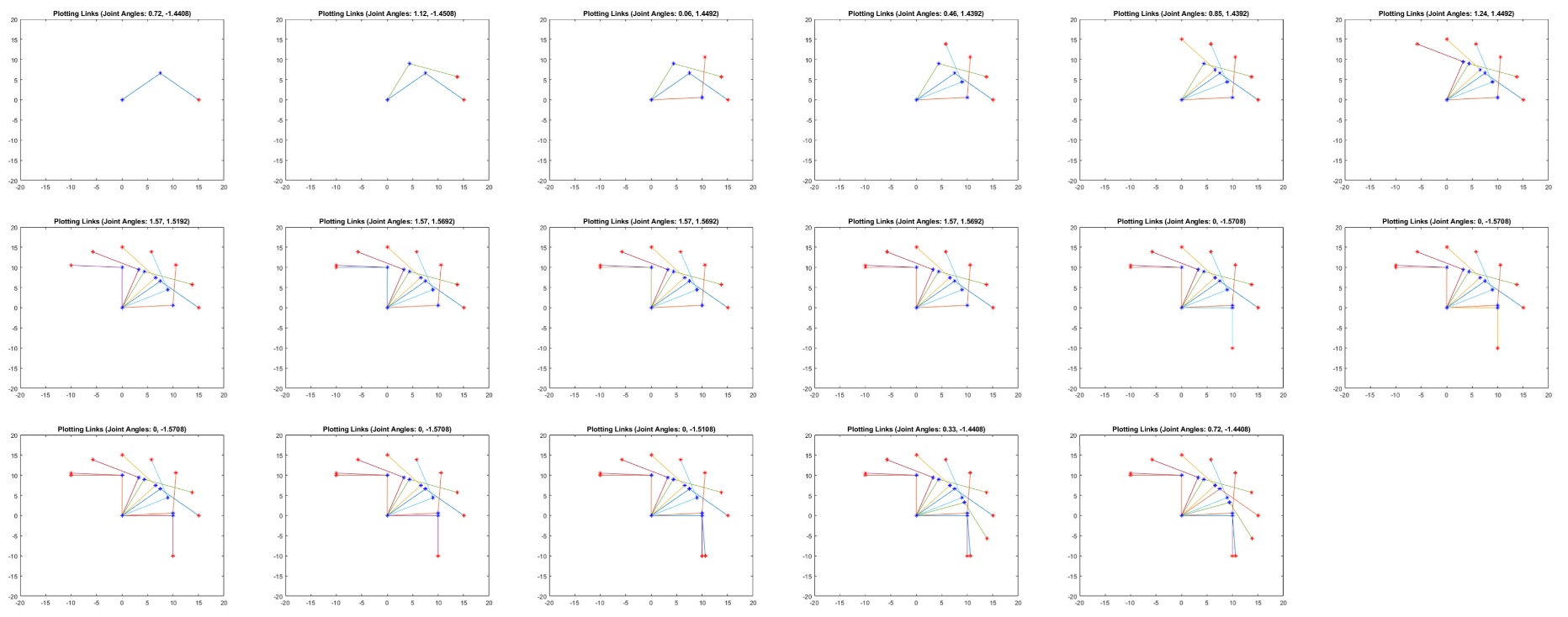
***Note:*** *Joint angles for this test were*

***Inverse Kinematic Approach*** *(Circle with Radius of 15)*



***Optimization Approach*** *(Circle with Radius of 15)*



***Brute Force Approach*** *(Radius of 15, joint 1 limited to [0,90o], joint 2 limited to [-90,90o]*

