

Research question

- How to model and simulate evasion behavior of pedestrians based on empirical observations?
- Therefore, we conducted two controlled experiments in October 2018.

Key findings: Experiment “Evasion behavior”

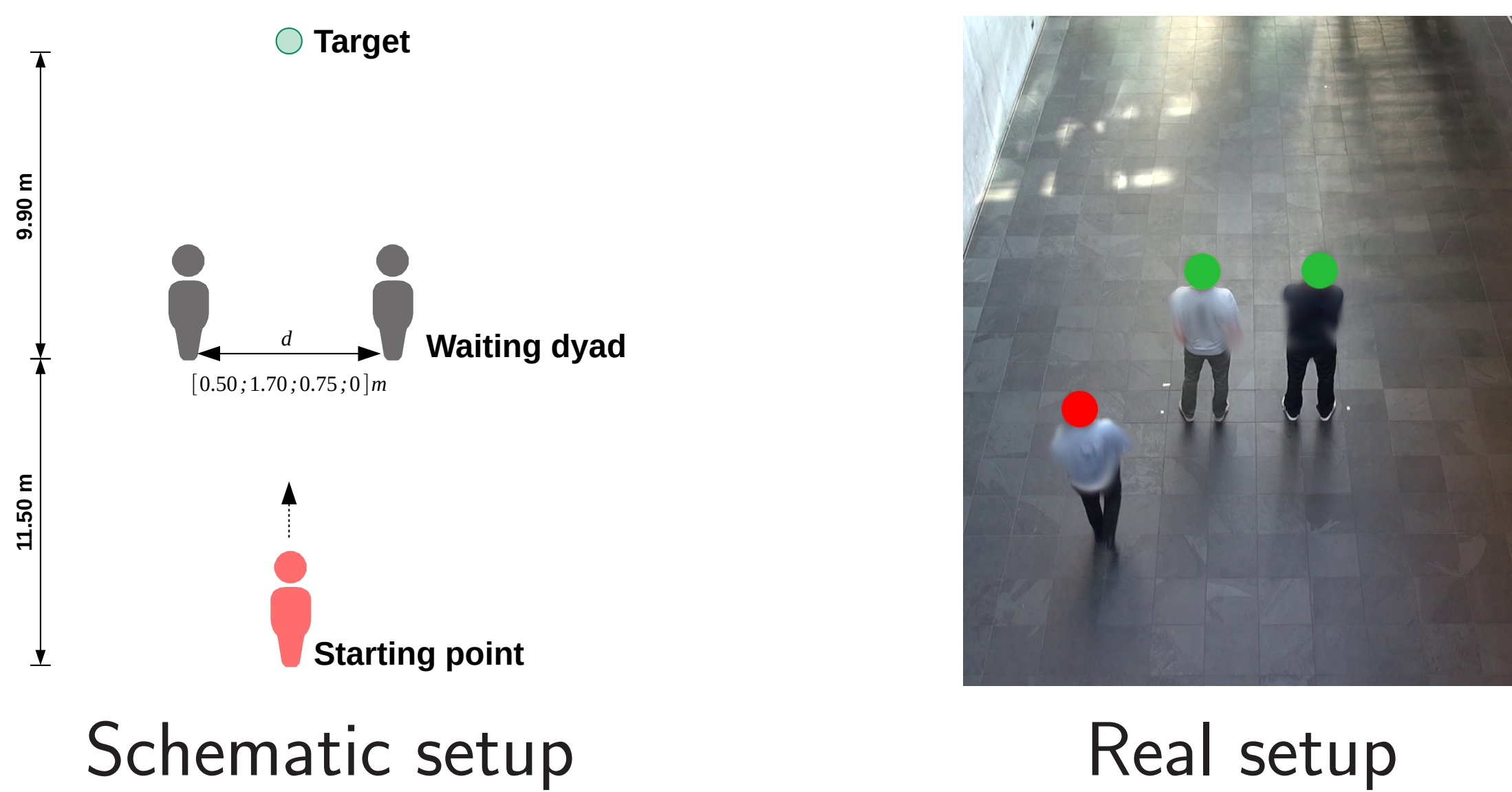
- Quantified evasion distances to validate models: (0.67 ± 0.05) m
- PCA and random forest revealed that dyad distance, size and shoulder width of participants are a good predictor for evasion behavior.

Key findings: Experiment “Motion through dense crowd”

- Trajectories of participants at a density of 5.31 persons/ m^2 .
- Speed distributions: inside (0.68 ± 0.31) m/s, outside (1.35 ± 0.23) m/s
- For waiting crowd: Distribution of distances to original positions.

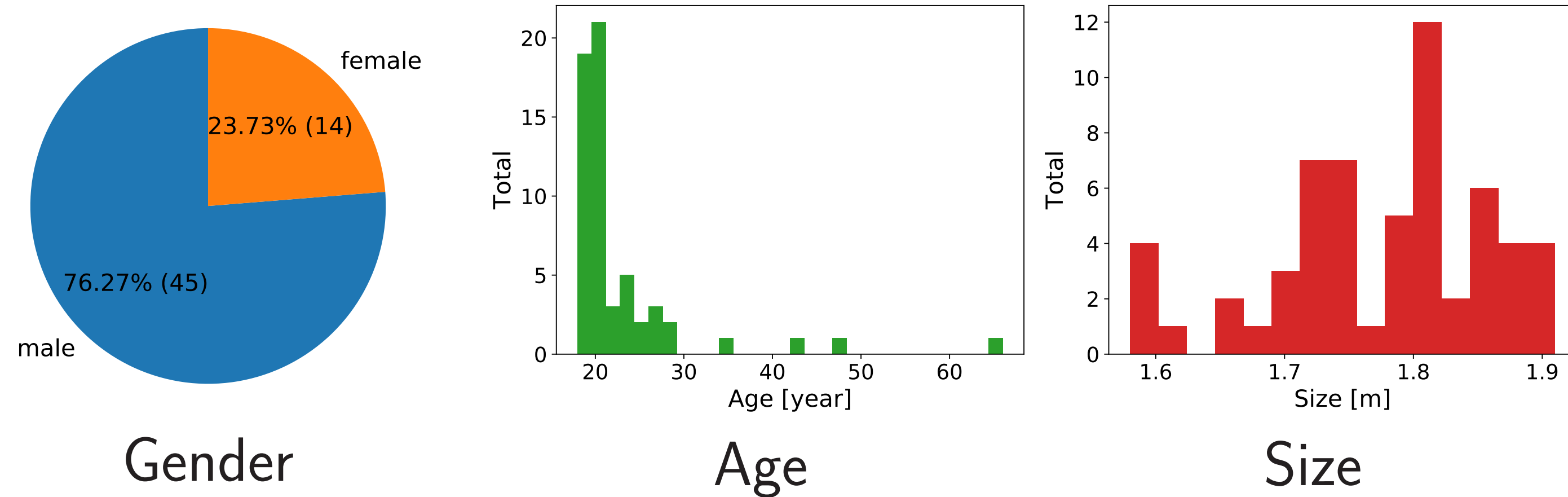
Experiment: Evasion behavior

Experiment setup



Test persons

- 59 participants



Analysis of evasion distance

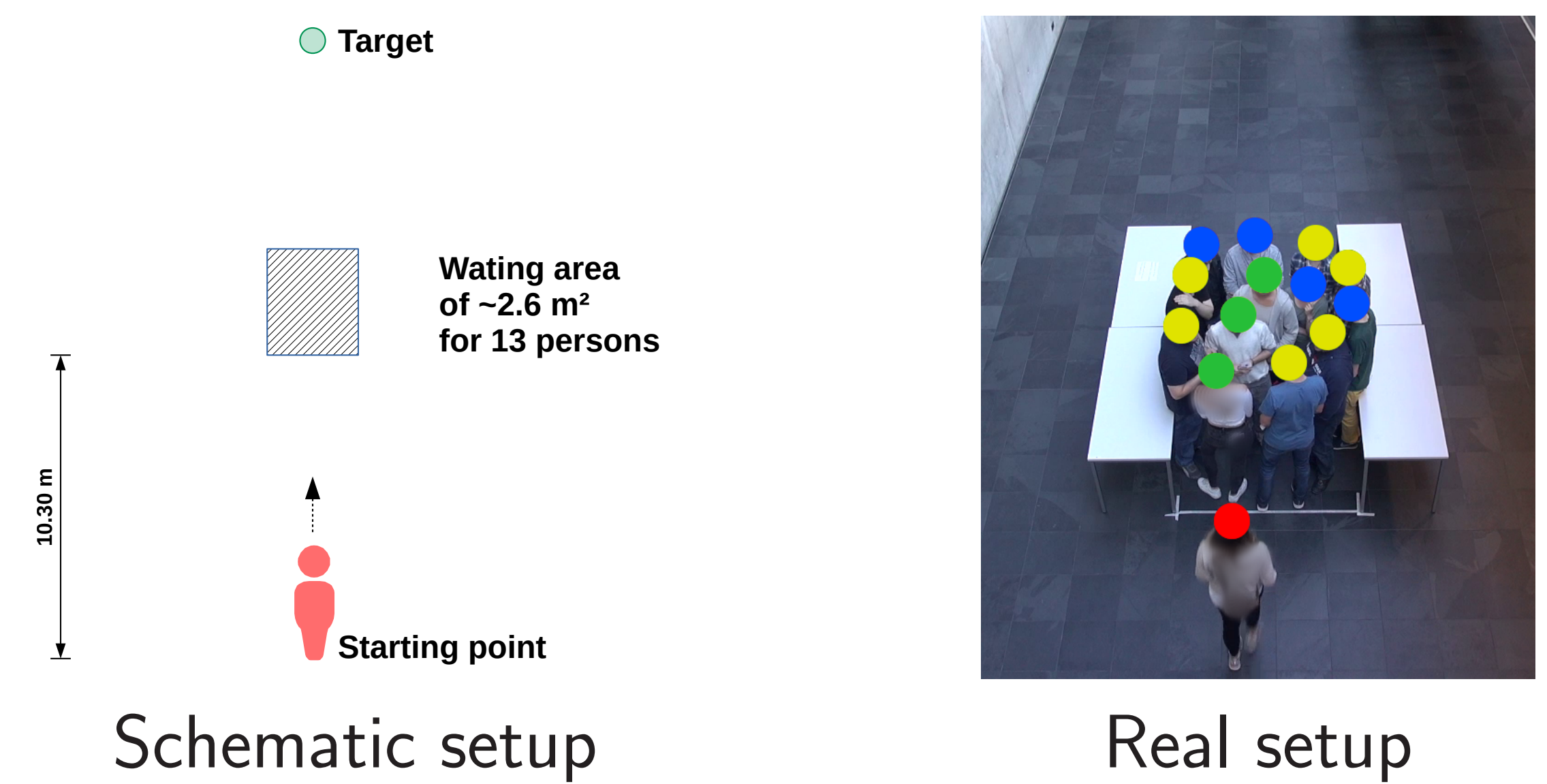
- 135 runs
- 4 different distances d : $[0.50; 1.70; 0.75; 0]$ m
- Extracted evasion distances:

d [m]	Evaded [%]	Evasion Distance Mean [m]	Std [m]
0.00	100	0.75	0.27
0.50	97	0.66	0.28
0.75	67	0.69	0.27
1.70	18	0.60	0.25

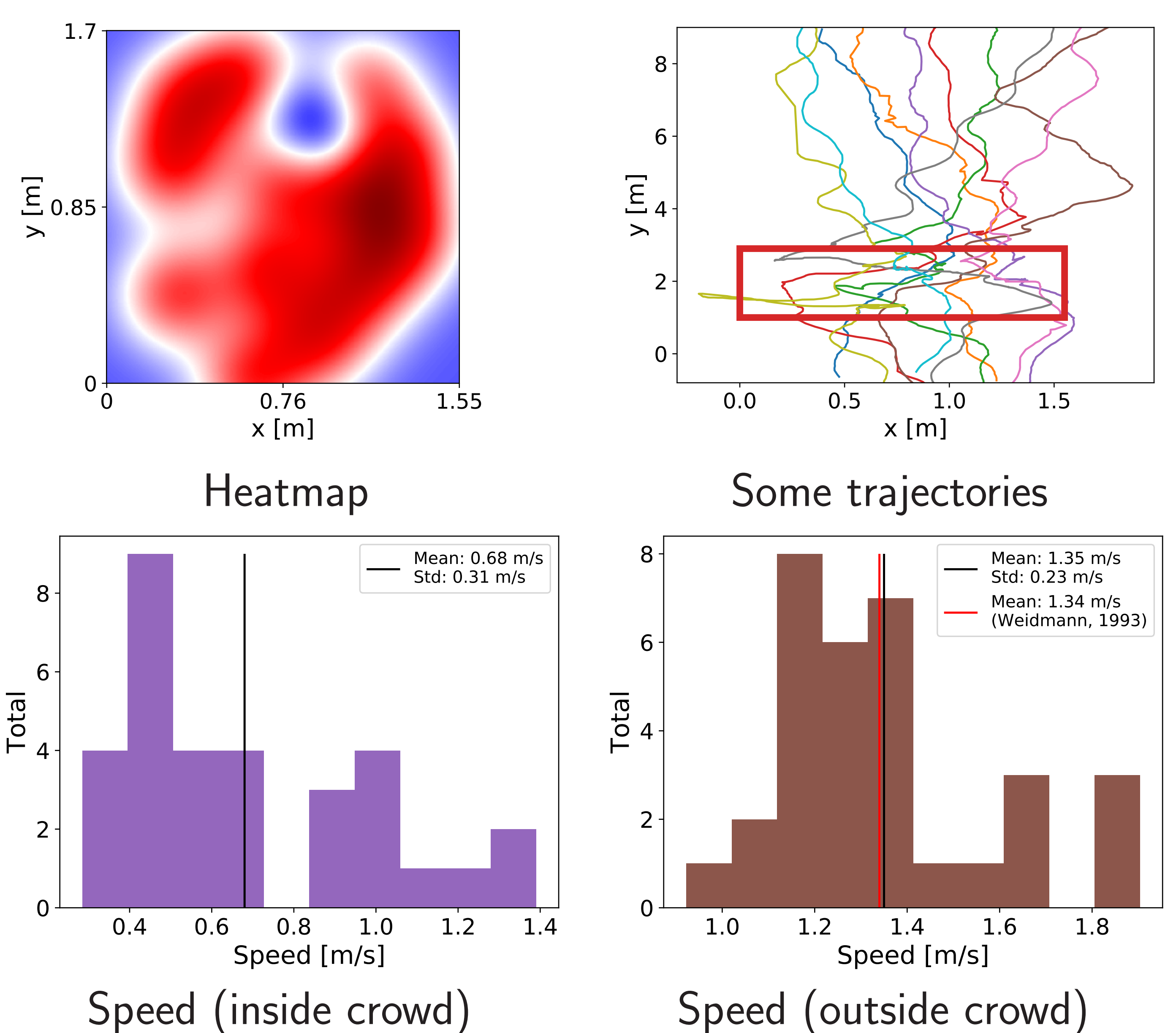
- Further analysis: PCA, random forest and logistic regression

Experiment: Motion through dense crowd

Experiment setup



Analysis of motion through dense crowd



Conclusion

Observations can only be explained by **different** behaviors.

Outlook

Implement observed evasion behaviors in the simulation framework Vadere.