

计算物理学作业

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1.(3.10) 用 4 点高斯求积公式编程计算积分

$$I = \int_{1.4}^{2.0} \int_{1.0}^{1.5} \ln(x + 2y) \, dx \, dy \quad (1)$$

解: 将积分区间 $R = \{(x, y) | 1.4 \leq x \leq 2.0, 1.0 \leq y \leq 1.5\}$ 变换到 $R' = \{(u, v) | -1 \leq u \leq 1, -1 \leq v \leq 1\}$, 即有

$$\begin{cases} x = \frac{1}{2}(b_2 + a_2) + \frac{1}{2}(b_2 - a_2)u \\ y = \frac{1}{2}(b_1 + a_1) + \frac{1}{2}(b_1 - a_1)v \end{cases} \quad (2)$$

因此有

$$I = 0.0755 \int_{-1}^1 \int_{-1}^1 \ln(0.3u + 0.5v + 4.2) \, du \, dv \quad (3)$$

使用 $n = 3$ 的 4 点高斯求积公式, 利用 MATLAB 求解得

$$\begin{aligned} I &= \int_{1.4}^{2.0} \int_{1.0}^{1.5} \ln(x + 2y) \, dx \, dy \\ &= 0.429554527717559 \end{aligned} \quad (4)$$

MATLAB 代码如下:

```
% 第一题 用四点高斯求积公式求二重积分
```

```
node = [0.3399810, 0.8611363];
```

```
coef = [0.6521452, 0.3478548];
```

```
u = [-node(2), -node(1), node(1), node(2)];
```

```
v = u;
```

```
A = [coef(2), coef(1), coef(1), coef(2)];
```

```

s = 0;

for i = 1:4
    for j = 1:4
        s = s + A(i)*A(j)*log(0.3*u(i) + 0.5*v(j) + 4.2);
    end
end

l = 0.075 * s;

format long
disp(l)

```

2.(4.7) 应用龙格 -库塔法求初值问题

$$\begin{cases} y'' + 2ty' + t^2y = e^t, & 0 \leq t \leq 1 \\ y(0) = 1, y'(0) = -1 \end{cases} \quad (5)$$

的数值解, 取步长 $h = 0.1$.

解: 令 $y_1 = y, y_2 = y'$, 问题则转化为

$$\begin{cases} y_1' = y_2 \\ y_2' = e^t - 2ty_2 - t^2y_1, & 0 \leq t \leq 1 \\ y_1(0) = 1, y_2(0) = -1 \end{cases} \quad (6)$$

应用龙格 -库塔法求得解如下图所示:

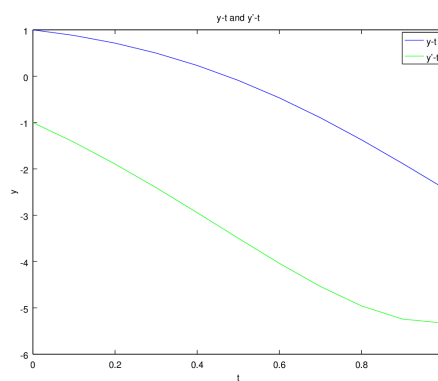


图 1: 龙格 -库塔法求解结果

MATLAB 代码如下:

```
% 第二题 应用龙格-库塔法求初值问题
% 设置初始值
t0 = 0;
h = 0.1;

y1_0 = 1;
y2_0 = -1;

function K = fun(t, y)
    f1 = y(2);
    %f2 = exp(t) - 2*t*y(2) - t^2*y(1);
    f2 = exp(2*t)*sin(t) - 2*y(1) + 2*y(2);
    K = [f1, f2];
endfunction

t = 0:h:1;
n = size(t,2);
Y = zeros(n,2);
Y(1,1) = y1_0;
Y(1,2) = y2_0;

for i = 1:n-1
    K1 = fun(t(i), Y(i,:));
    K2 = fun(t(i) + h/2, Y(i,:) + (h/2)*K1);
    K3 = fun(t(i) + h/2, Y(i,:) + (h/2)*K2);
    K4 = fun(t(i) + h, Y(i,:) + h*K3);
    Y(i+1,:) = Y(i,:) + (K1 + 2*K2 + 2*K3 + K4) * (h/6);
end

% 画图
plot(t, Y(:,1)', 'b', t, Y(:,2)', 'g')
xlabel('t')
ylabel('y')
legend('y-t', 'y'-t")
title('y-t and y'-t")
```

3.(8.4) 试采用有限差分法编程求解单位圆域中泊松方程在网格节点处的值

$$\begin{cases} \nabla^2 u = -50r^2 \sin(2\phi) \\ u(1, \phi) = 0 \end{cases} \quad (7)$$

其中 $u(1, \phi) = 0$ 表示半径为 1 的单位圆边界上 u 值为 0. 取 $h = 0.1, \omega = 1.25, \varepsilon = 10^{-5}, M = 16$, 并与解析解 $u = \frac{25}{6}r^2(1 - r^2) \sin(2\phi)$ 作比较.

解: 在极坐标下泊松方程形式为

$$\nabla^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \phi^2} = -50r^2 \sin(2\phi) \quad (8)$$

用一组等角线和等距离同心圆分割区域, 将半径 $N - 1$ 等分, 圆周 $M - 1$ 等分, 即有

$$\begin{cases} \Delta r = h = \frac{r_0}{N - 1} \\ \Delta \phi = \frac{2\pi}{M - 1} \end{cases} \quad (9)$$

用误差为 $O(\Delta r^2)$ 和 $O(\Delta \phi^2)$ 的中心差商代替上式中的微商, 可以得到泊松方程的差分格式为

$$\alpha_0(u_{i,j-1} + u_{i,j+1}) + \alpha_1 u_{i-1,j} + \alpha_2 u_{i+1,j} - 2(1 + \alpha_0)u_{ij} = h^2 f(r_i, \phi_j) \quad (10)$$

其中, $\alpha_0 = [\Delta \phi(i - 1)]^{-2}, \alpha_1 = 1 - (2i - 2)^{-1}, \alpha_2 = 1 + (2i - 2)^{-1}$.

周期性条件有

$$u(r, \phi)u(r, \phi + 2\pi) \quad (11)$$

即满足 $u_{i1} = u_{iM}, u_{i2} = u_{i,M+1}$.

方程(10)不适合于圆心 ($i = 1$). 利用直角坐标系下的五点差分格式, 有

$$\nabla^2 u_0 \approx \frac{1}{h^2}(u_1 + u_2 + u_3 + u_4 - 4u_0) \quad (12)$$

在一般情况下, 可将上式写为

$$\nabla^2 u_0 = \frac{4}{h^2}(\bar{u} - u_0) \quad (13)$$

其中 \bar{u} 是半径为 h 的圆周上各结点的平均值, 即

$$\bar{u} = \frac{1}{M - 1} \sum_{j=2}^M u_{2j}. \quad (14)$$

下面对(10)进行简化, 可得

$$u_{ij} = \frac{\alpha_0(u_{i,j-1} + u_{i,j+1}) + \alpha_1 u_{i-1,j} + \alpha_2 u_{i+1,j} - h^2 f(r_i, \phi_j)}{2 + 2\alpha_0} \quad (15)$$

引入超松弛因子, 进行超松弛迭代

$$u_{ij}^{k+1} = \omega \times \frac{\alpha_0(u_{i,j-1}^{k+1} + u_{i,j+1}^{k+1}) + \alpha_1 u_{i-1,j}^{k+1} + \alpha_2 u_{i+1,j}^{k+1} - h^2 f(r_i, \varphi_j)}{2 + 2\alpha_0} + (1 - \omega) \times u_{ij}^k \quad (16)$$

通过编程求解得结果如下, 与解析解的最大误差为 0.025092.

MATLAB 代码如下:

```
% 第三题 用有限差分法求解单位园域中的泊松方程
```

```
% 设置初始值
```

```
omega = 1.25;
```

```
epsilon = 10^(-7);
```

```
r0 = 1.0;
```

```
h = 0.1;
```

```
deltaR = h;
```

```
global N = r0/h+1;
```

```
global M = 16;
```

```
deltaPhi = 2*pi/(M-1);
```

```
R = 0:deltaR:r0;
```

```
Phi = 0:deltaPhi:2*pi;
```

```
U = zeros(N,M);
```

```
% 定义下标i的转换函数, 依据周期性条件
```

```
function newi = subi(i)
```

```
    global N;
```

```
    if i==0
```

```
        newi = N-1;
```

```
    elseif i == N+1
```

```
        newi = 2;
```

```
    elseif i == N
```

```
        newi = 1;
```

```
    else
```

```
        newi = i;
```

```
    end
```

```
endfunction
```

```
% 定义下标j的转换函数, 依据周期性条件
```

```
function newj = subj(j)
```

```
    global M;
```

```
    if j==0
```

```

    newj = M-1;
elseif j == M+1
    newj = 2;
elseif j == M
    newj = 1;
else
    newj = j;
end
endfunction

function y = fun(r, phi)
    y = -50 * r^2 * sin(2*phi);
endfunction

% 进行迭代
do
    maxDiffU = 0;
    for i = (N-1):-1:1
        if i==1 % 判断是否为圆心
            oldU = U(1,1);
            meanU = mean(U(2,1:(M-1)));
            U0 = omega*(meanU - h^2/4*fun(R(i),Phi(j))) + (1-omega)*oldU;
            U(1,:) = U0;
            diffU = abs(U(1,1)-oldU);
            if diffU > maxDiffU
                maxDiffU = diffU;
            end
        else
            for j = 1:M-1
                oldU = U(i,j);
                alpha_0 = (deltaPhi*(i-1))^( -2);
                alpha_1 = 1 - (2*i-2)^( -1);
                alpha_2 = 1 + (2*i-2)^( -1);
                fenmu = 2*(1+alpha_0);

                temp1 = alpha_0 * ( U(subi(i),subj(j-1)) + \
                    U(subi(i),subj(j+1)) );

```

```

temp2 = alpha_1 * U(subi(i-1),subj(j));
temp3 = alpha_2 * U(subi(i+1),subj(j));
U(i,j) = omega*(temp1 + temp2 + temp3 - \
                h^2*fun(R(i),Phi(j)) )/fenmu + (1-omega)*U(i,j);
diffU = abs(U(i,j) - oldU);
if diffU > maxDiffU
    maxDiffU = diffU;
end
end
U(i,M) = U(i,1);
end
end
until maxDiffU < epsilon
% 计算解析解
realU = zeros(size(U));
for i = 1:N
    for j = 1:M
        realU(i,j) = 25/6*(R(i))^2*(1-(R(i))^2)*sin(2*Phi(j));
    end
end
% 输出结果
disp(max(max(abs(U-realU))))
save -ascii U.dat U
save -ascii realU.dat realU

```

4.(11.1) 编程计算例 11.1 中点 3 的电势和 1,2 两点的电量 (见图 11.9).

解: 取每个边即为边界元. 首先计算对角线元素 H_{ii}, G_{ii} . 由于

$$H_{ii} = -C_i = -\pi \quad (i \in \Gamma \text{光滑点}) \quad (17)$$

$$G_{ii} = \int_{\Gamma_i} u^* ds = \int_{\Gamma_i} \ln r ds = 2 \int_0^{s_i/2} \ln r dr = s_i (\ln \frac{s_i}{2} - 1) \quad (18)$$

然后根据下式计算 H_{ij} 非对角元:

$$H_{ij} = \int_{\Gamma_j} q^* ds = \int_{\Gamma_j} \frac{\partial \ln r}{\partial n} ds = \frac{r_d}{|r_d|} \theta_j = \pm \theta_j. \quad (19)$$

根据下式计算 G_{ij} 非对角元:

$$\begin{aligned} G_{ij} &= \int_0^{s_j} \ln r \, ds = \frac{1}{2} \int_0^{s_j} \ln[r_d^2 + (s-d)^2] \, ds \\ &= (s_j - d) \ln r_2 + d \ln r_1 - s_j + |r_d| \theta_j \end{aligned} \quad (20)$$

通过计算出来的 H_{ij}, G_{ij} 形成方程

$$\mathbf{A}\mathbf{X} = \mathbf{R}. \quad (21)$$

通过求解方程组求得:

$$q_1 = -2.580, \quad q_2 = 1.72965, \quad u_3 = 0.82492. \quad (22)$$

MATLAB 代码如下:

```
% 第四题 边界元法求解泊松方程的混合边值问题
% 初始化变量
n = 3;
H = zeros(n);
G = zeros(n);
% 计算相关参数
function [d, rd, theta, r1, r2, s] = parafun(i,j)
endPointx = [0,1; 1,0; 0,0];
endPointy = [0,0; 0,1; 1,0];
midPointx = [0.5, 0.5, 0];
midPointy = [0, 0.5, 0.5];
xi = midPointx(i);
yi = midPointy(i);
x1 = endPointx(j,1);
x2 = endPointx(j,2);
y1 = endPointy(j,1);
y2 = endPointy(j,2);
r1Vec = [x1-xi, y1-yi];
r2Vec = [x2-xi, y2-yi];
r21Vec = [x2-x1, y2-y1];
s = sqrt(sum(r21Vec.^2));
r1 = sqrt(sum(r1Vec.^2));
r2 = sqrt(sum(r2Vec.^2));
d = -dot(r1Vec, r21Vec./s);
```



```

nVec = [(y2-y1)/s, (x1-x2)/s];
rd = dot(r1Vec, nVec);
theta = acos(dot(r1Vec, r2Vec)/(r1*r2));
endfunction

sVec = [1, sqrt(2), 1];

for i = 1:n
    for j = 1:n
        if i == j % 计算对角元素
            H(i,i) = -pi;
            G(i,i) = sVec(i)*(log(sVec(i)/2) - 1);
        else % 计算非对角元素
            [d, rd, theta, r1, r2, s] = parafun(i,j);
            H(i,j) = theta;
            G(i,j) = (s-d)*log(r2) + d*log(r1) - s + abs(rd)*theta;
        end
    end
end

% 计算A和R
A = [G(:,1:2), -H(:,3)];
R = [H(:,1:2), -G(:,3)]*[0;1;0];
uq = inv(A)*R;
disp(uq)

```

5.(12.9) 采用蒙特卡罗方法编程求解一下方程.

(1) $e^{-x^3} - \tan x + 800 = 0 \quad (0 < x < \pi/2);$

(2) $x + 5e^{-x} - 5 = 0 \quad (0 < x < 10).$

解: 利用逐步逼近的方法寻找方程 $f(x) = 0$ 的近似根 x_0 , 使得 $f(x_0) \leq \varepsilon$, 其中 ε 是事先指定的小量.

首先取一初值 x_0 , 令 $x_1 = x_0 + b(2R - 1)$, 则有 $x_0 - b < x_1 < x_0 + b$. 即以 x_0 为中心, 以 b 为半径, 随机游走到 x_1 , 若 $|f(x_1)| < |f(x_0)|$, 就再以 x_1 为中心继续游走, 直至 $|f(x)| \leq \varepsilon$ 为止, 则 x 为所求根.

具体操作时, 刚开始 b 可取得大一些, 然后逐渐减小, 压缩 x 的游动范围. 为了防止无休止的游动, 可先设置一个较大的整数 N , 当游走步数 $m = N$ 时, 若 $|f(x)| \leq \varepsilon$ 仍不满足, 则减小 b .

通过 MATLAB 求解得方程 (1) 和方程 (2) 的根分别为:

$$x_1 = 1.569546360148, \quad x_2 = 4.965106989195 \quad (23)$$

MATLAB 代码如下:

```
% 第五题 采用蒙特卡罗法解方程

root1 = 0;
root2 = 0;
% 定义函数
function y = fun1(x)
    y = exp(-x^3) - tan(x) + 800;
endfunction

function y = fun2(x)
    y = x + 5*exp(-x) - 5;
endfunction

function root = findRoot(x0, b, N, epsilon, fun)
    m = 0;
    x = x0;

    f = feval(fun,x);
    if abs(f) < epsilon
        return
    end

    do
        xtemp = x + b*(2*rand()-1);
        ftemp = feval(fun,xtemp);
        m = m + 1;
        if m == N
            b = b/2;
            m = 0;
        end
    end
```

```
end
if abs(ftemp) < abs(f)
    f = ftemp;
    x = xtemp;
end
until abs(f)<epsilon
    root = x;
endfunction

f = @fun1;
root1 = findRoot(1, 0.2, 20, 10−5, f);
disp(root1)
disp(fun1(root1))

f = @fun2;
root2 = findRoot(5, 0.3, 20, 10−5, f);
disp(root2)
disp(fun2(root2))
```