

## Solution Sheet 1 – Importance sampling

### Autumn School *Uncertainty Quantification for High-dimensional Problems*

#### **Problem 1** (Warm up)

- a) Let  $f$  be the pdf of the uniform random variable  $U$  on the interval  $[0, 1]$ . Let  $g$  be the pdf of the uniform random variable  $V$  on the interval  $[0, 1/2]$ . Let  $H(u) = u^2$ . Show that  $\mathbb{E}[H(U)] \neq \mathbb{E}[H(V)f(V)/g(V)]$ .
- b) Let  $f$  be the pdf of the univariate standard normal density and  $H(u) = \exp(-(u - 10)^2/2)$ . Find the optimal importance sampling density!
- c) Let  $f$  be the pdf of the univariate standard normal density and  $H(u) = \exp(ku)$ , where  $k \neq 0$ . Find the optimal importance sampling density!

#### **Solution**

a)  $\mathbb{E}[H(U)] = \int_0^1 u^2 du = 1/3$  and  $\mathbb{E}[H(V)f(V)/g(V)] = \frac{2}{2} \int_0^{1/2} u^2 du = 1/24$ .

b) The optimal IS density is (up to a normalizing constant)

$$H(u)f(u) = \exp(-(u - 10)^2/2) \exp(-u^2/2) = \exp(-(u^2 - 10u + 50)) \propto \exp(-(u - 5)^2).$$

This is the normal density with mean  $\mu = 5$  and variance  $\sigma^2 = 1/2$ .

c) The optimal IS density is (up to a normalizing constant)

$$H(u)f(u) = \exp(ku) \exp(-u^2/2) = \exp(-(u^2 - 2ku + k^2 - k^2)/2) \propto \exp(-(u - k)^2/2).$$

This is the normal density with mean  $\mu = k$  and variance  $\sigma^2 = 1$ .

**Problem 2** (Self-normalized importance sampling)

Let  $\mathbf{U} \sim f$  be a random vector with pdf  $f$ . Consider estimating

$$Q := \mathbb{E}[H(\mathbf{U})] = \int_{D_f} H(\mathbf{u})f(\mathbf{u})d\mathbf{u}$$

with the self-normalized importance sampling estimator

$$E_{sn,g}^{IS}[Q] = \frac{\frac{1}{N} \sum_{i=1}^N W(\mathbf{V}^{(i)})H(\mathbf{V}^{(i)})}{\frac{1}{N} \sum_{i=1}^N W(\mathbf{V}^{(i)})},$$

where  $W(\mathbf{u}) = f(\mathbf{u})/g(\mathbf{u})$  is the likelihood ratio and  $\mathbf{V}^{(i)} \sim g$  i.i.d. for  $i = 1, \dots, N$ . In this problem we assume that the density  $g$  dominates the density  $f$ , that is,  $\mathcal{D}_f \subseteq \mathcal{D}_g$ .

- a) Let  $\mathbf{Z}^{(i)}$  be i.i.d. copies of a random vector taking values in  $\mathbb{R}^n$  with distribution  $\mathbb{P}_{\mathbf{Z}}$ . Let  $\bar{\mathbf{Z}} := \frac{1}{N} \sum_{i=1}^N \mathbf{Z}^{(i)}$  denote the Monte Carlo estimator of  $\mathbb{E}[\mathbf{Z}]$ . Let  $v: \mathbb{R}^n \rightarrow \mathbb{R}$  denote a smooth function. The *delta method* approximates  $v(\bar{\mathbf{Z}})$  by a truncated Taylor expansion of  $v$  with anchor point  $v(\mathbb{E}[\mathbf{Z}])$  as follows:

$$\tilde{v}(\bar{\mathbf{Z}}) := v(\mathbb{E}[\mathbf{Z}]) + \nabla v(\mathbb{E}[\mathbf{Z}])^\top (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}]).$$

Show that the variance of  $\tilde{v}(\bar{\mathbf{Z}})$  is given by

$$\text{var}(\tilde{v}(\bar{\mathbf{Z}})) = \frac{1}{N} \nabla v(\mathbb{E}[\mathbf{Z}])^\top \text{Cov}(\mathbf{Z}, \mathbf{Z}) \nabla v(\mathbb{E}[\mathbf{Z}]).$$

- b) Let  $\sigma_{sn,g}^2 := \mathbb{E}[W(\mathbf{V})^2(H(\mathbf{V}) - Q)^2]$ , where  $\mathbf{V} \sim g$  is a random vector with pdf  $g$ . Show that the delta method approximates the variance of the self-normalized IS estimator as follows

$$\text{var}(E_{sn,g}^{IS}[Q]) \approx \frac{\sigma_{sn,g}^2}{N}. \quad (1)$$

- c) Show that the importance sampling density which minimizes the approximate variance of  $E_{sn,g}^{IS}[Q]$  in (1) is given by

$$g_{opt,sn}(\mathbf{u}) = \frac{|H(\mathbf{u}) - Q|f(\mathbf{u})}{\int |H(\mathbf{u}) - Q|f(\mathbf{u})d\mathbf{u}}.$$

- d) Show that

$$\sigma_{sn,g}^2 \geq \mathbb{E}[|H(\mathbf{U}) - Q|]^2.$$

- e) Finally, let  $H(\mathbf{u}) = \mathbb{1}_{\{G \leq 0\}}(\mathbf{u})$  be the indicator function of a failure domain with probability of failure  $P_f = Q$ . Which lower bound for  $\sigma_{sn,g}^2$  do we obtain in this case? Derive an (approximate) lower bound for the c.o.v. of the self-normalized IS estimator! Compare this bound with the c.o.v. of the standard Monte Carlo estimator for  $P_f$ !

### Solution

a) Note that by construction

$$\mathbb{E}[\tilde{v}(\bar{\mathbf{Z}})] = v(\mathbb{E}[\mathbf{Z}]) + \nabla v(\mathbb{E}[\mathbf{Z}])^\top \underbrace{(\mathbb{E}[\bar{\mathbf{Z}}] - \mathbb{E}[\mathbf{Z}])}_{=\mathbb{E}[\mathbf{Z}]} = v(\mathbb{E}[\mathbf{Z}]) + \mathbf{0} = v(\mathbb{E}[\mathbf{Z}]).$$

Hence we obtain

$$\begin{aligned} \text{var}(\tilde{v}(\bar{\mathbf{Z}})) &= \mathbb{E}[(v(\mathbb{E}[\mathbf{Z}]) + \nabla v(\mathbb{E}[\mathbf{Z}])^\top (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}]) - \mathbb{E}[\tilde{v}(\bar{\mathbf{Z}}))]^2] \\ &= \mathbb{E}[(\nabla v(\mathbb{E}[\mathbf{Z}])^\top (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}]))^2] \\ &= \mathbb{E}[\nabla v(\mathbb{E}[\mathbf{Z}])^\top (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}]) (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}])^\top \nabla v(\mathbb{E}[\mathbf{Z}])] \\ &= \nabla v(\mathbb{E}[\mathbf{Z}])^\top \underbrace{\mathbb{E}[(\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}]) (\bar{\mathbf{Z}} - \mathbb{E}[\mathbf{Z}])^\top]}_{=\text{Cov}(\mathbf{Z}, \mathbf{Z})/N} \nabla v(\mathbb{E}[\mathbf{Z}]) \\ &= \frac{1}{N} \nabla v(\mathbb{E}[\mathbf{Z}])^\top \text{Cov}(\mathbf{Z}, \mathbf{Z}) \nabla v(\mathbb{E}[\mathbf{Z}]). \end{aligned}$$

b) For the self-normalized IS estimator we have  $n = 2$ ,  $v(z_1, z_2) = z_2/z_1$ ,  $\bar{Z}_1 = \frac{1}{N} \sum_{i=1}^N W(\mathbf{V}^{(i)})$  and  $\bar{Z}_2 = \frac{1}{N} \sum_{i=1}^N H(\mathbf{V}^{(i)})W(\mathbf{V}^{(i)})$ , where  $\mathbf{V}, \mathbf{V}^{(i)} \sim g$  i.i.d. Moreover,  $Z_1 = W(\mathbf{V}^{(1)})$ ,  $\mathbb{E}[Z_1] = \mathbb{E}[W(\mathbf{V}^{(1)})] = 1$ ,  $Z_2 = H(\mathbf{V}^{(1)})W(\mathbf{V}^{(1)})$  and  $\mathbb{E}[Z_2] = \mathbb{E}[H(\mathbf{V}^{(1)})W(\mathbf{V}^{(1)})] = \mathbb{E}[H(\mathbf{U})] = Q$ . The gradient

$$\nabla v(\mathbf{z}) = (-z_2/z_1^2, 1/z_1)^\top$$

and

$$\nabla v(\mathbb{E}[\mathbf{Z}]) = (-\mathbb{E}[H(\mathbf{V})W(\mathbf{V})]/\mathbb{E}[W(\mathbf{V})]^2, 1/\mathbb{E}[W(\mathbf{V})])^\top = (-Q, 1)^\top.$$

Hence we obtain the (approximate) variance

$$\begin{aligned} \text{var}(\tilde{v}(\bar{\mathbf{Z}})) &= \frac{1}{N} (-Q, 1)^\top \text{Cov}(\mathbf{Z}, \mathbf{Z}) (-Q, 1) \\ &= \frac{1}{N} (Q^2 \text{var}(Z_1) - 2Q \text{Cov}(Z_1, Z_2) + \text{var}(Z_2)) \\ &= \frac{1}{N} \text{var}[(Z_2 - QZ_1)^2] \\ &= \frac{1}{N} \mathbb{E}[(Z_2 - QZ_1)^2] - \frac{1}{N} \underbrace{\mathbb{E}[(Z_2 - QZ_1)]^2}_{=0} \\ &= \frac{1}{N} \mathbb{E}[(H(\mathbf{V})W(\mathbf{V}) - QW(\mathbf{V}))^2] = \frac{1}{N} \mathbb{E}[W(\mathbf{V})^2 (H(\mathbf{V}) - Q)^2]. \end{aligned}$$

c) The proof is analogous to the proof for the (ordinary) importance sampling estimator  $E_g^{IS}[Q]$ , where we minimize  $\mathbb{E}[W(\mathbf{V})^2 H(\mathbf{V})^2]$  with respect to the density  $g$ . For the self-normalized IS estimator we minimize  $\mathbb{E}[W(\mathbf{V})^2 (H(\mathbf{V}) - Q)^2]$  with respect to  $g$ .

d) By choosing  $g = g_{opt}$  derived in c) we obtain a lower bound for  $\sigma_{sn,g}^2$  as follows:

$$\begin{aligned}
\sigma_{sn,g}^2 &= \mathbb{E}[W^2(\mathbf{V})(H(\mathbf{V}) - Q)^2] \\
&\geq \mathbb{E}[f^2(\mathbf{V}_{opt})(H(\mathbf{V}_{opt}) - Q)^2 / g_{opt}(\mathbf{V}_{opt})^2] \\
&= \int_{D_{g_{opt}}} \frac{f(\mathbf{u})^2(H(\mathbf{u}) - Q)^2}{|H(\mathbf{u}) - Q|f(\mathbf{u})} d\mathbf{u} \left( \int_{D_{g_{opt}}} |H(\mathbf{u}) - Q|f(\mathbf{u}) d\mathbf{u} \right) \\
&= \left( \int_{D_{g_{opt}}} |H(\mathbf{u}) - Q|f(\mathbf{u}) d\mathbf{u} \right)^2 \\
&= \left( \int_{D_f} |H(\mathbf{u}) - Q|f(\mathbf{u}) d\mathbf{u} + \int_{D_f^c \cap D_{g_{opt}}} |H(\mathbf{u}) - Q| \underbrace{f(\mathbf{u})}_{=0} d\mathbf{u} \right)^2 \\
&= \mathbb{E}[|H(\mathbf{U}) - Q|^2].
\end{aligned}$$

e) It holds  $\mathbb{E}[|H(\mathbf{U}) - Q|^2] = (|1 - P_f|P_f + |0 - P_f|(1 - P_f))^2 = 4P_f^2(1 - P_f)^2$ . Assuming that  $\mathbb{E}[E_{sn,g}^{IS}[P_f]] = P_f$ , this gives a lower bound for the approximate c.o.v. of  $E_{sn,g}^{IS}[P_f]$  as follows:

$$\text{c. o. v.}(E_{sn,g}^{IS}[P_f]) \geq \sqrt{\frac{4P_f^2(1 - P_f)^2}{P_f^2 N}} = \frac{2(1 - P_f)}{\sqrt{N}}.$$

For the standard Monte Carlo estimator we have

$$\text{c. o. v.}(E^{MC}[P_f]) = \sqrt{\frac{(1 - P_f)}{P_f N}}.$$